

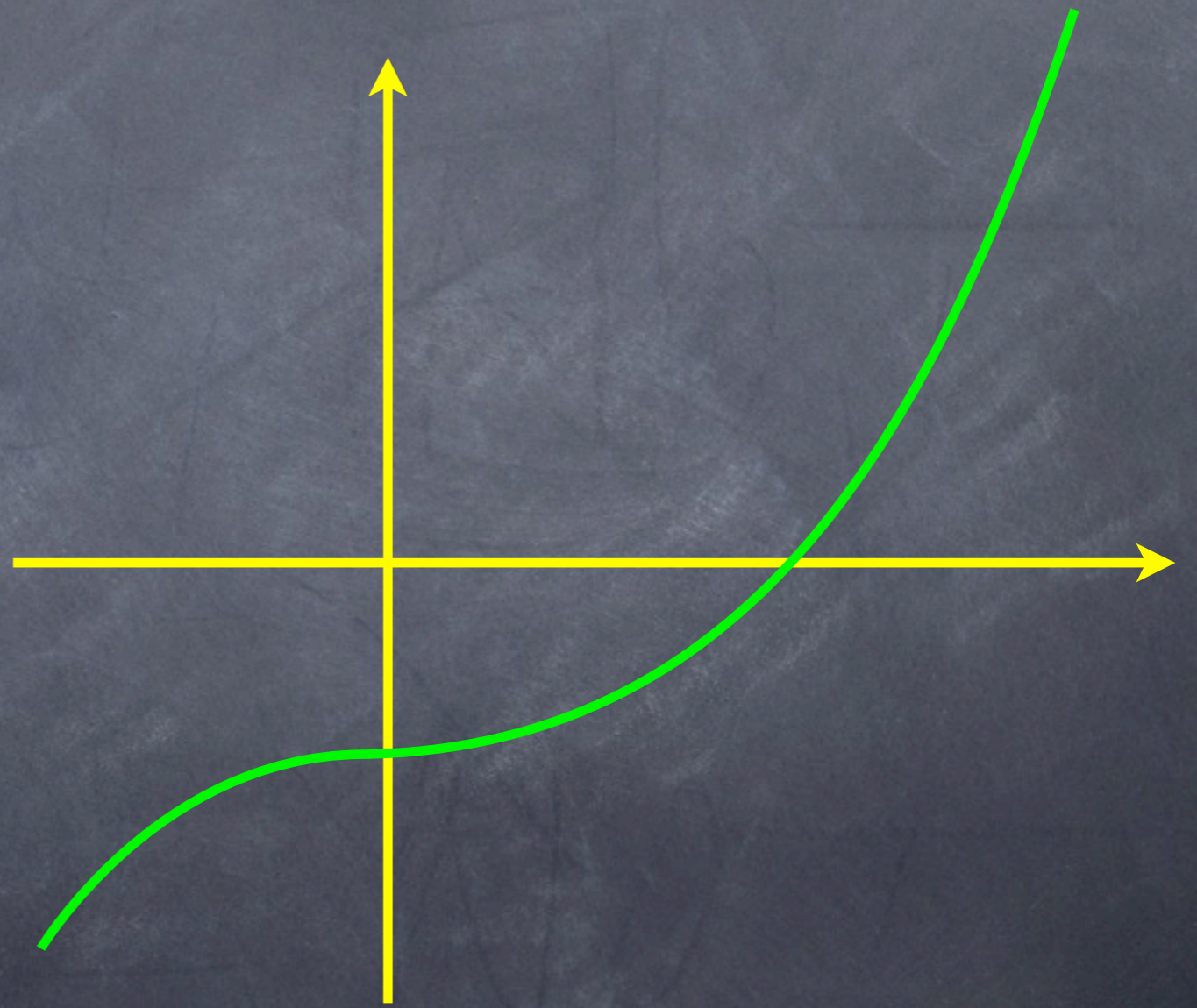
Today

- Newton's method (cont)
- Qualitative analysis of differential equations
 - Steady states
 - Slope fields
 - Stability of steady states
 - Velocity (y') versus position (y)

Newton's method

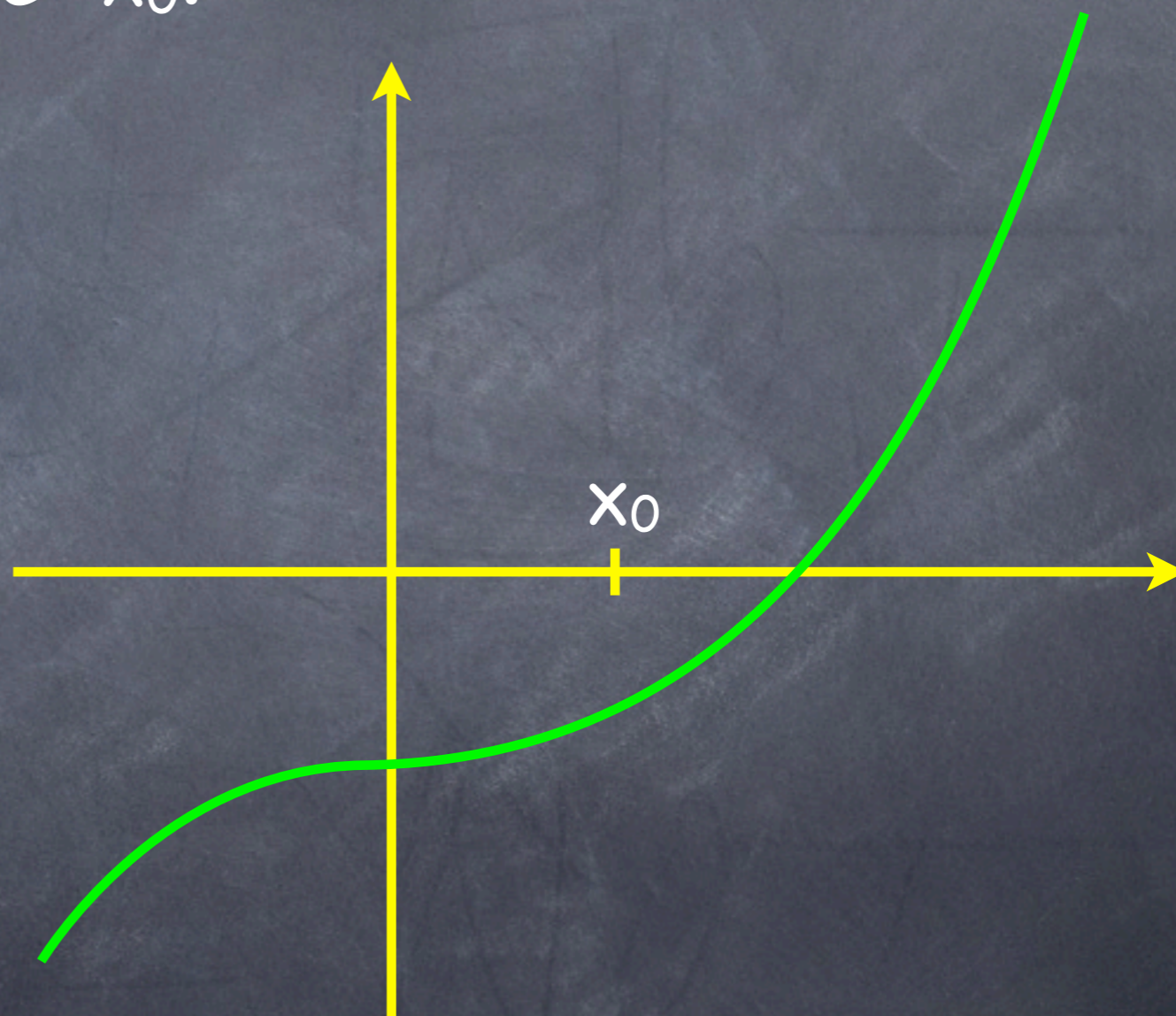
- NM is used to find zeros of a function: $f(x)=0$.
- It can be applied to finding approximates of
 - **critical points** of a function $g(x)$:
 - define $f(x)=g'(x)$,
 - **intersections** of functions, $g(x)=h(x)$:
 - define $f(x) = g(x)-h(x)$,
 - **irrational numbers**: e.g. $\sqrt{2}$:
 - define $f(x)=x^2-2$.

Find the zero of $f(x)=x^3-2$.



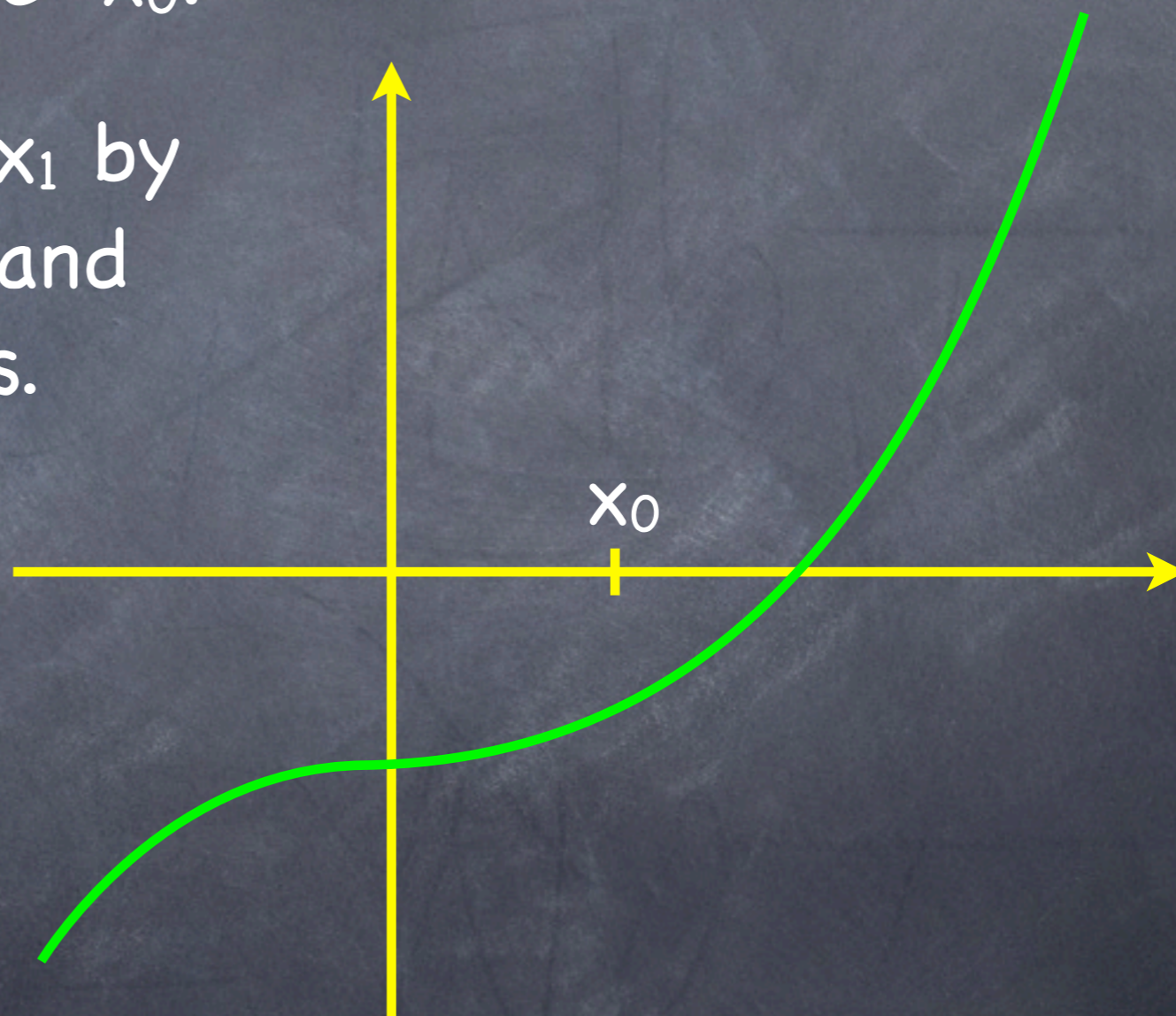
Find the zero of $f(x)=x^3-2$.

- Start with a "guesstimate" x_0 .



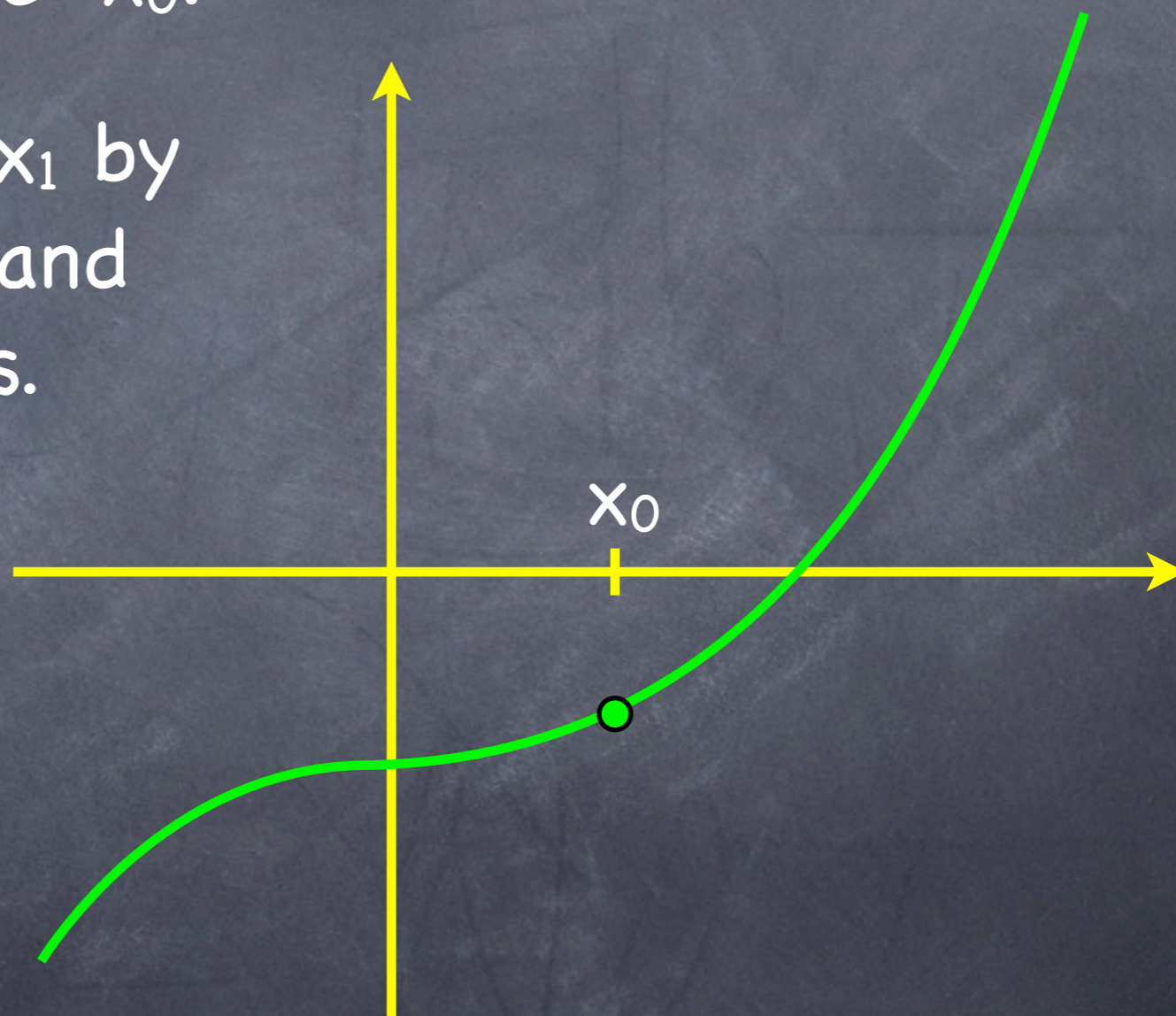
Find the zero of $f(x)=x^3-2$.

- Start with a "guesstimate" x_0 .
- Get a "better" estimate x_1 by finding the tangent line and following it to the x -axis.



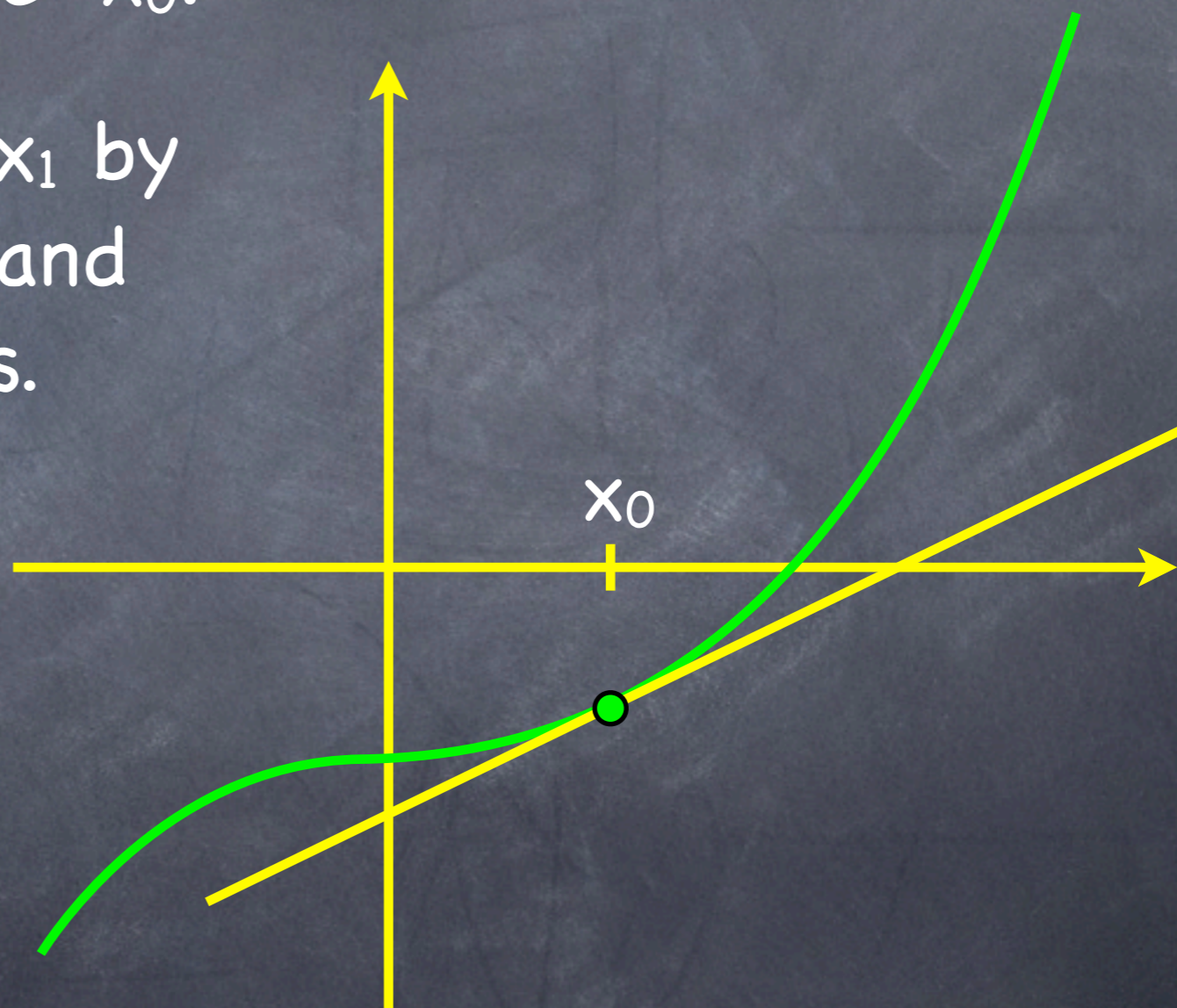
Find the zero of $f(x)=x^3-2$.

- Start with a "guesstimate" x_0 .
- Get a "better" estimate x_1 by finding the tangent line and following it to the x -axis.



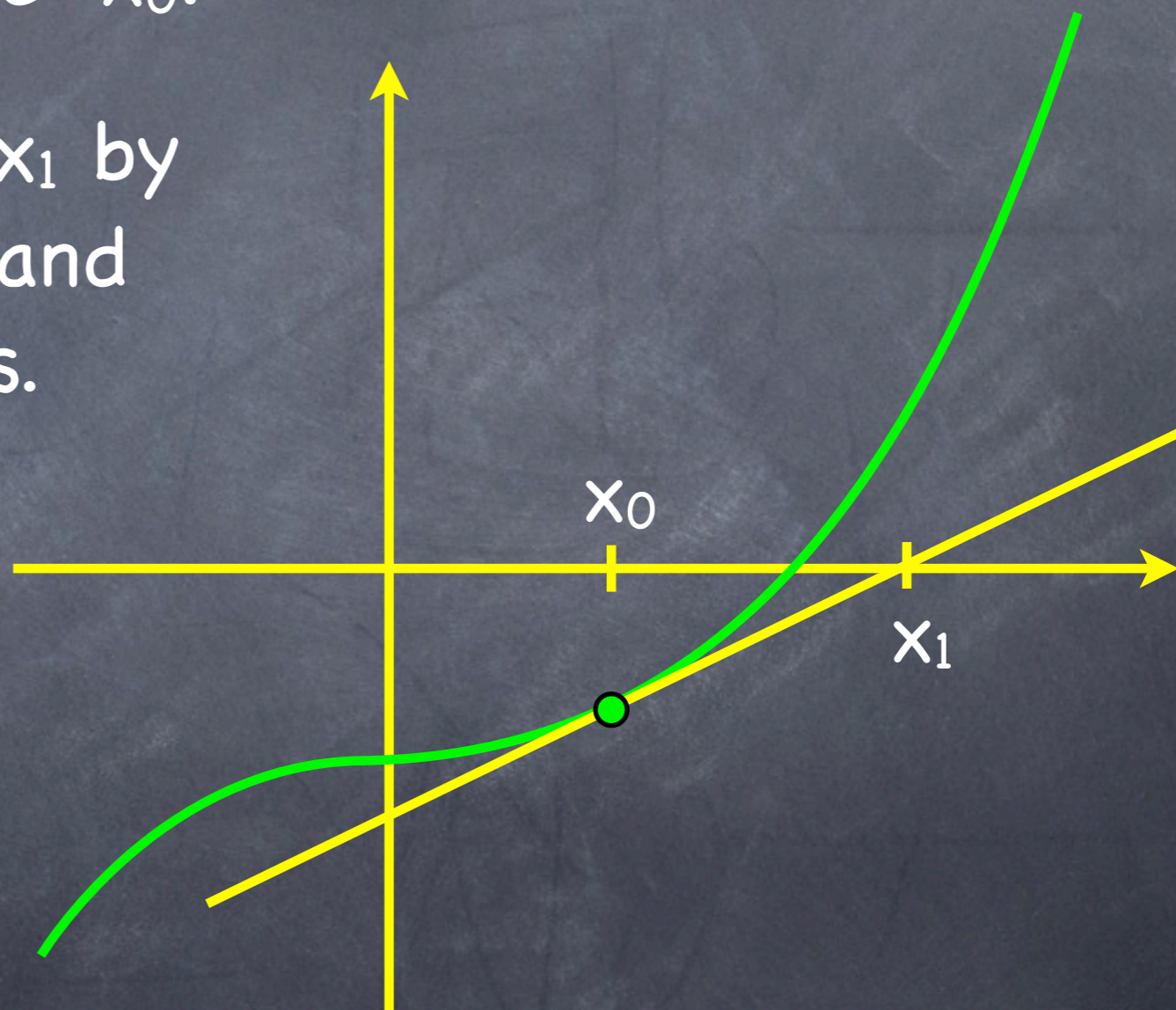
Find the zero of $f(x)=x^3-2$.

- Start with a "guesstimate" x_0 .
- Get a "better" estimate x_1 by finding the tangent line and following it to the x -axis.



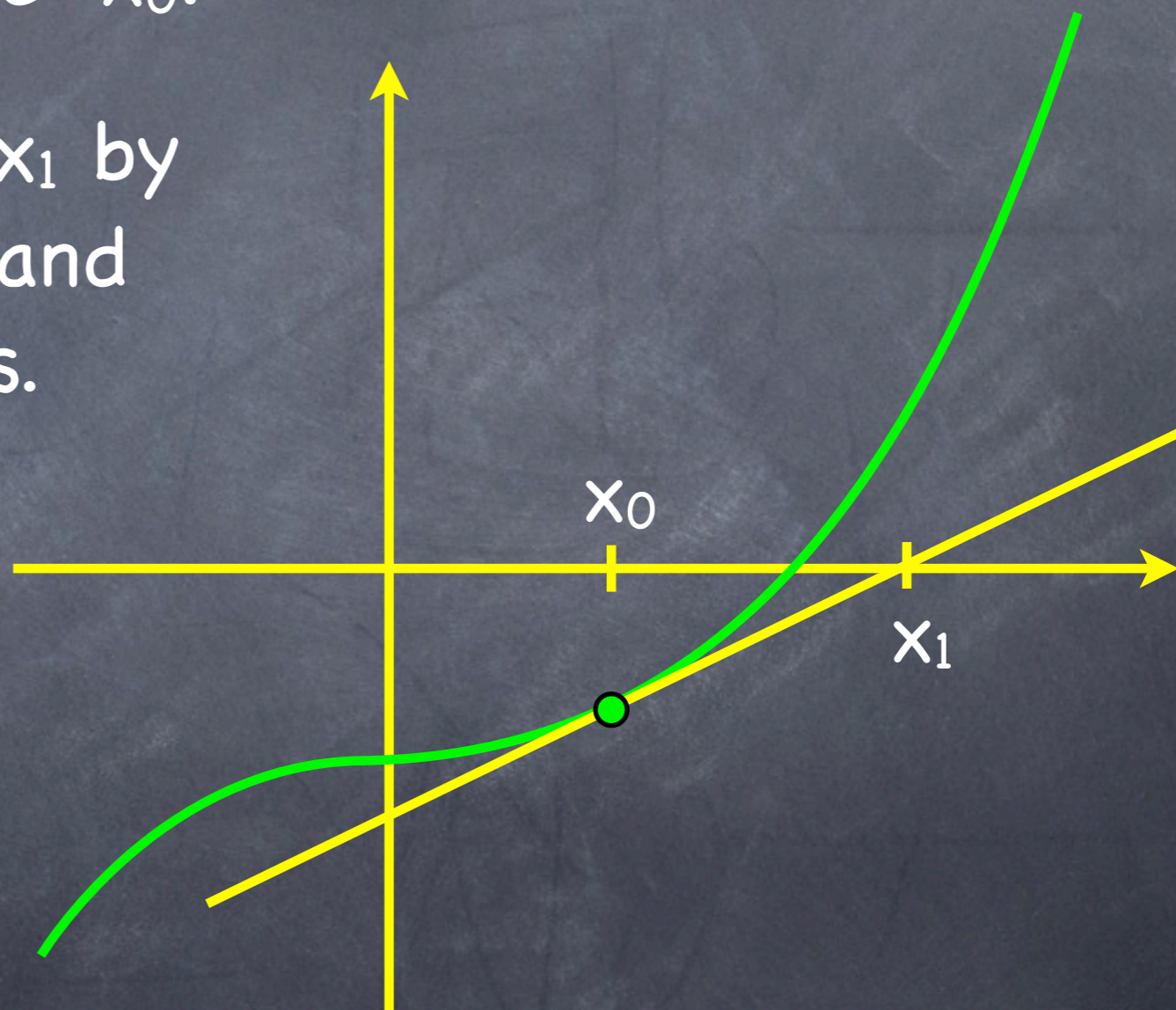
Find the zero of $f(x)=x^3-2$.

- Start with a "guesstimate" x_0 .
- Get a "better" estimate x_1 by finding the tangent line and following it to the x -axis.



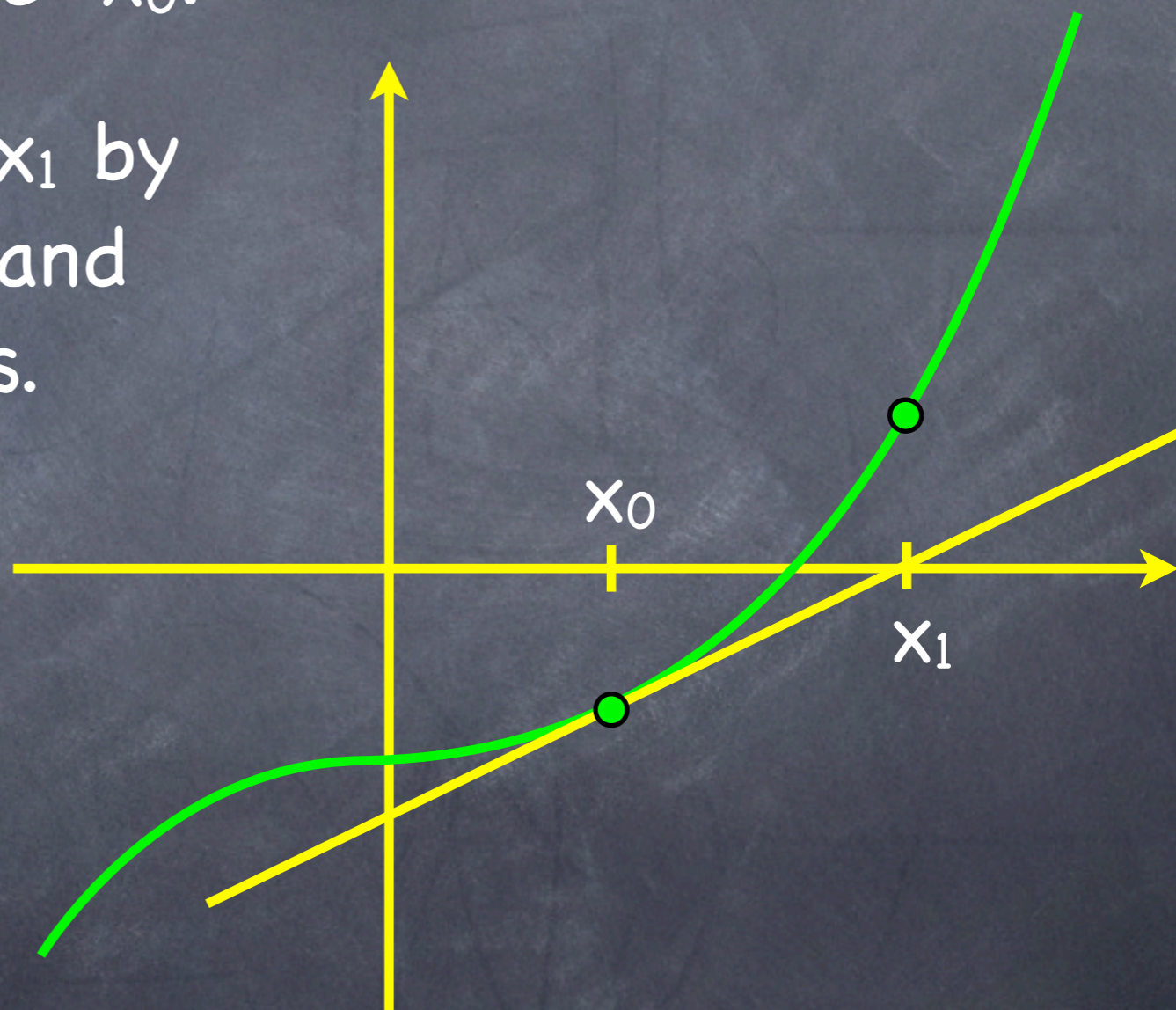
Find the zero of $f(x)=x^3-2$.

- Start with a "guesstimate" x_0 .
- Get a "better" estimate x_1 by finding the tangent line and following it to the x -axis.
- Repeat to get x_2 ...



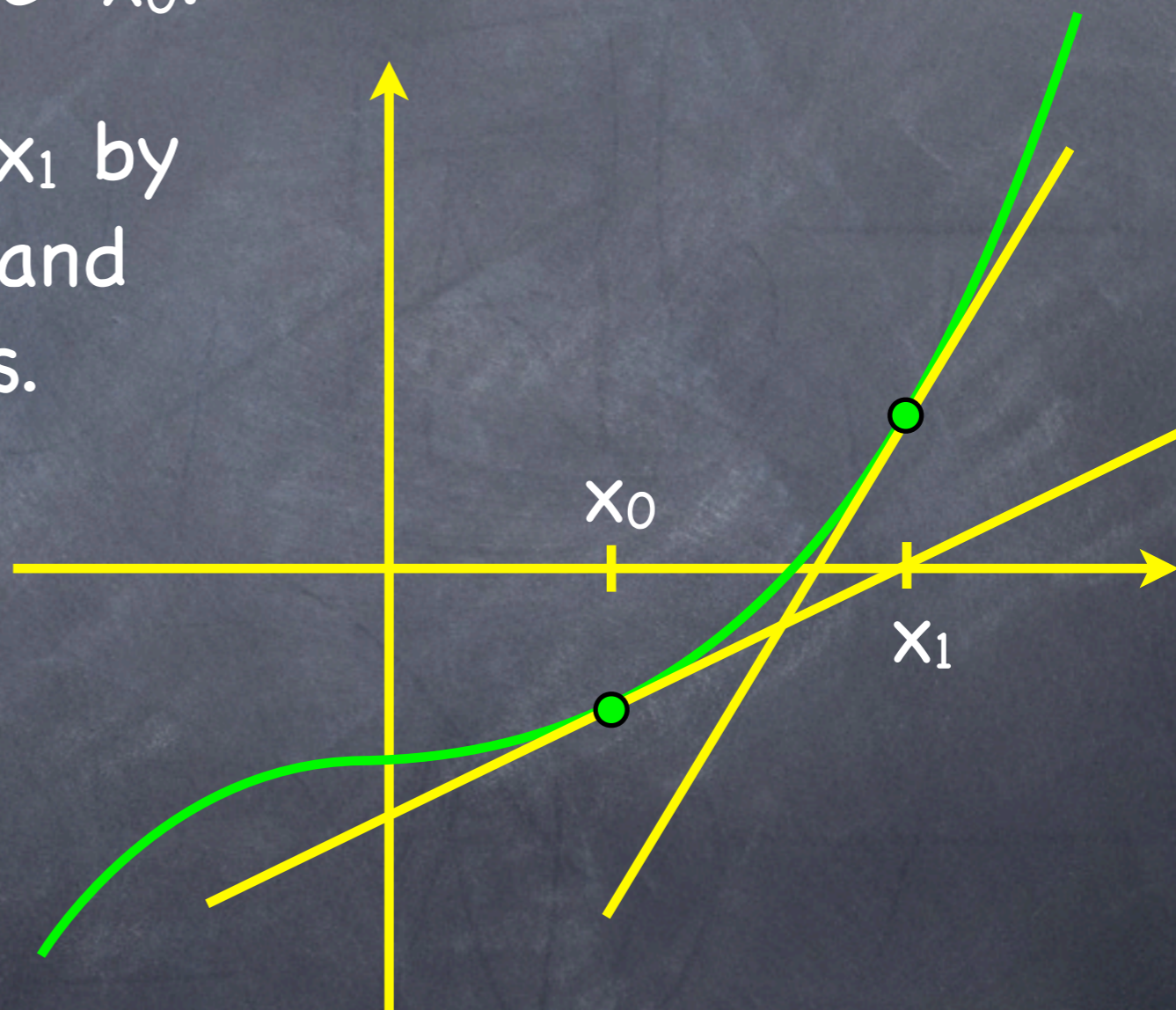
Find the zero of $f(x)=x^3-2$.

- Start with a "guesstimate" x_0 .
- Get a "better" estimate x_1 by finding the tangent line and following it to the x -axis.
- Repeat to get x_2 ...



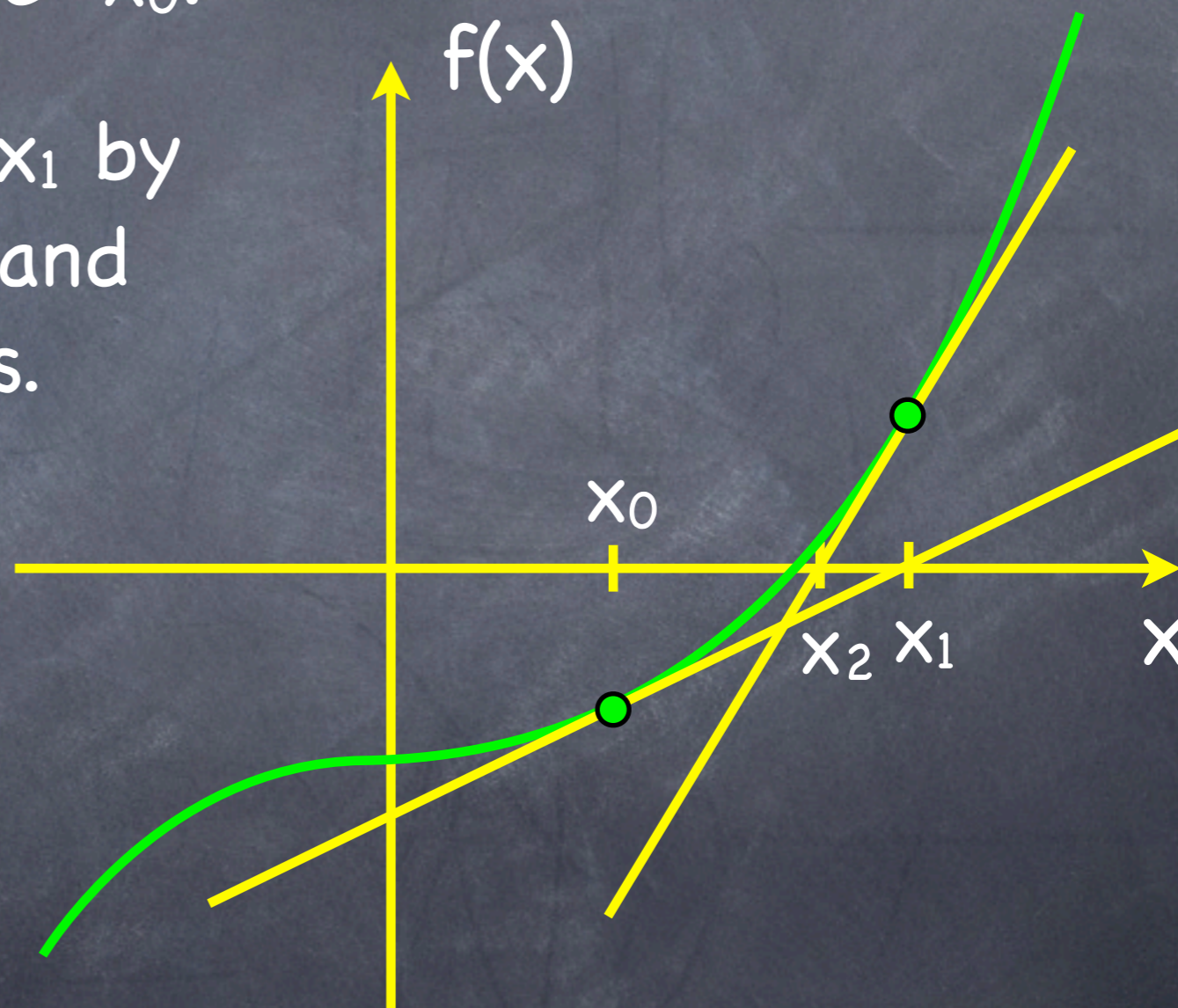
Find the zero of $f(x)=x^3-2$.

- Start with a "guesstimate" x_0 .
- Get a "better" estimate x_1 by finding the tangent line and following it to the x -axis.
- Repeat to get x_2 ...

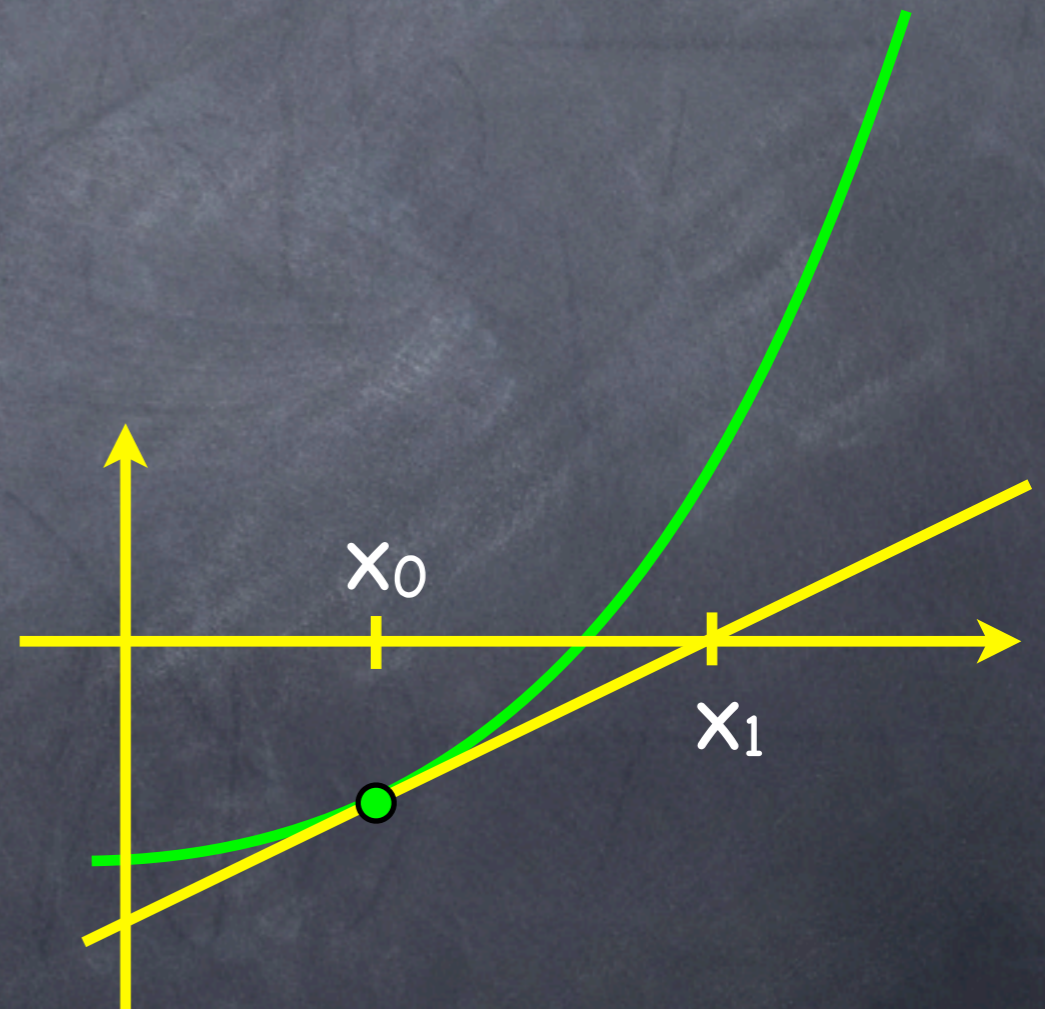


Find the zero of $f(x)=x^3-2$.

- Start with a "guesstimate" x_0 .
- Get a "better" estimate x_1 by finding the tangent line and following it to the x -axis.
- Repeat to get x_2 ...



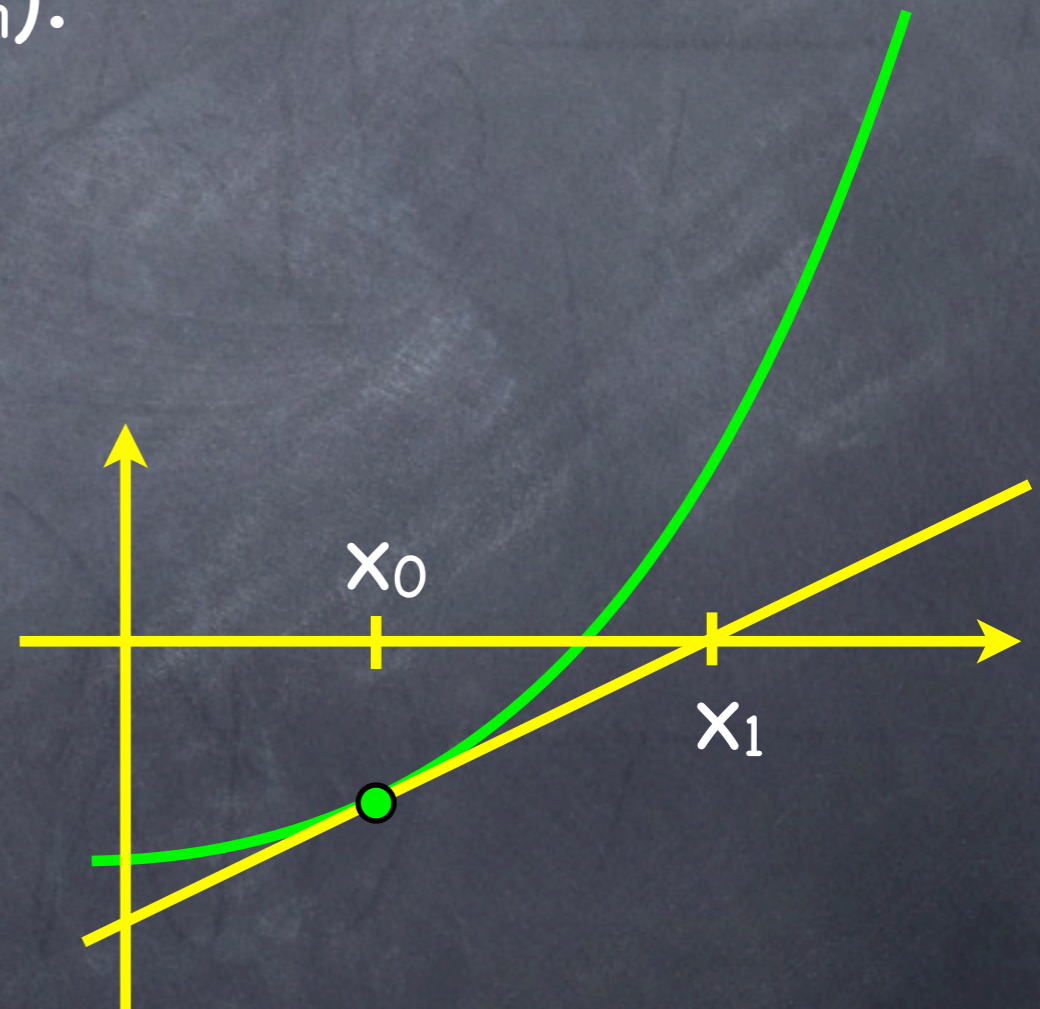
Calculating successive estimates



Calculating successive estimates

- First, find tangent line at x_n :

- $L(x) = f(x_n) + f'(x_n)(x - x_n).$



Calculating successive estimates

• First, find tangent line at x_n :

• $L(x) = f(x_n) + f'(x_n)(x - x_n).$

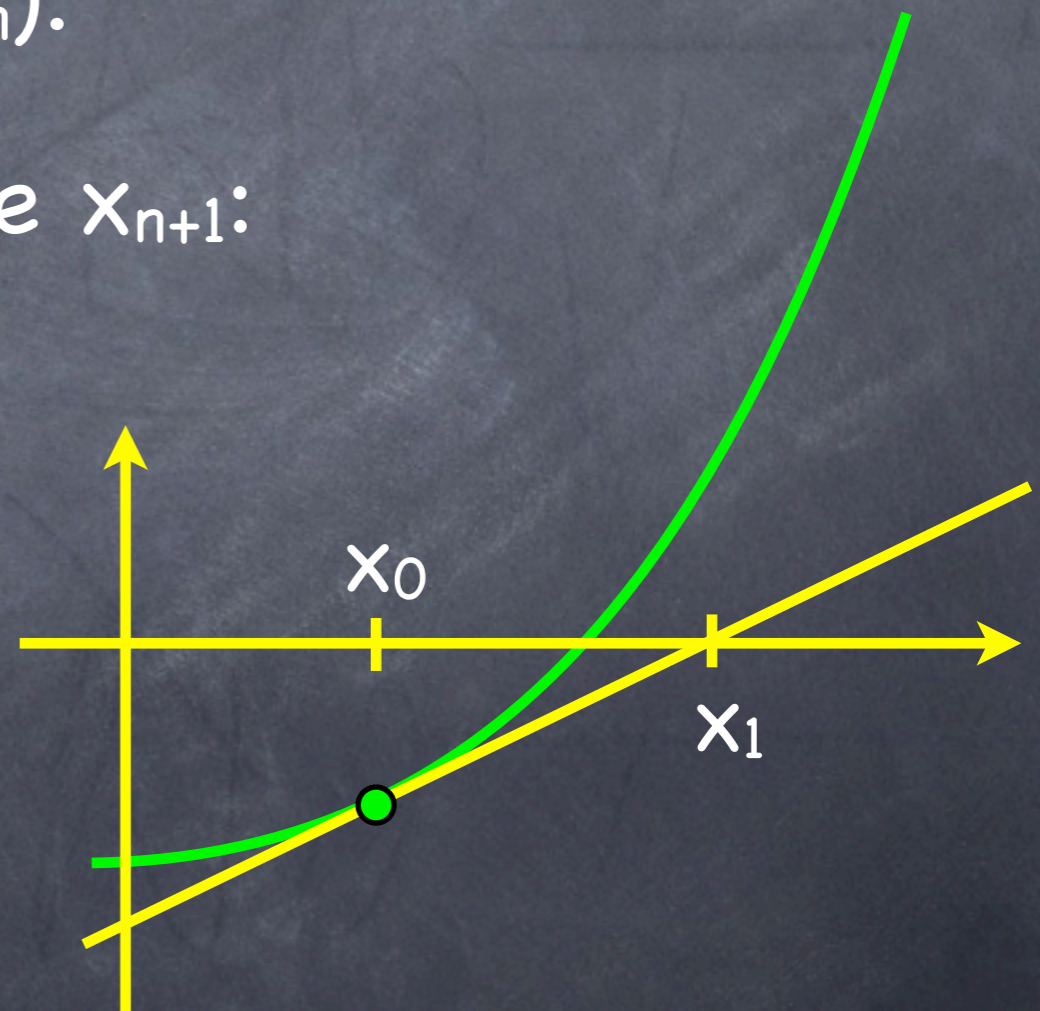
• Find x -intercept, that will be x_{n+1} :

(A) $x_{n+1} = x_n + f(x_n) / f'(x_n).$

(B) $x_{n+1} = x_n - f(x_n) / f'(x_n).$

(C) $x_{n+1} = x_n - f'(x_n) / f(x_n).$

(D) $x_{n+1} = x_n + f'(x_n) / f(x_n).$



Calculating successive estimates

• First, find tangent line at x_n :

• $L(x) = f(x_n) + f'(x_n)(x - x_n).$

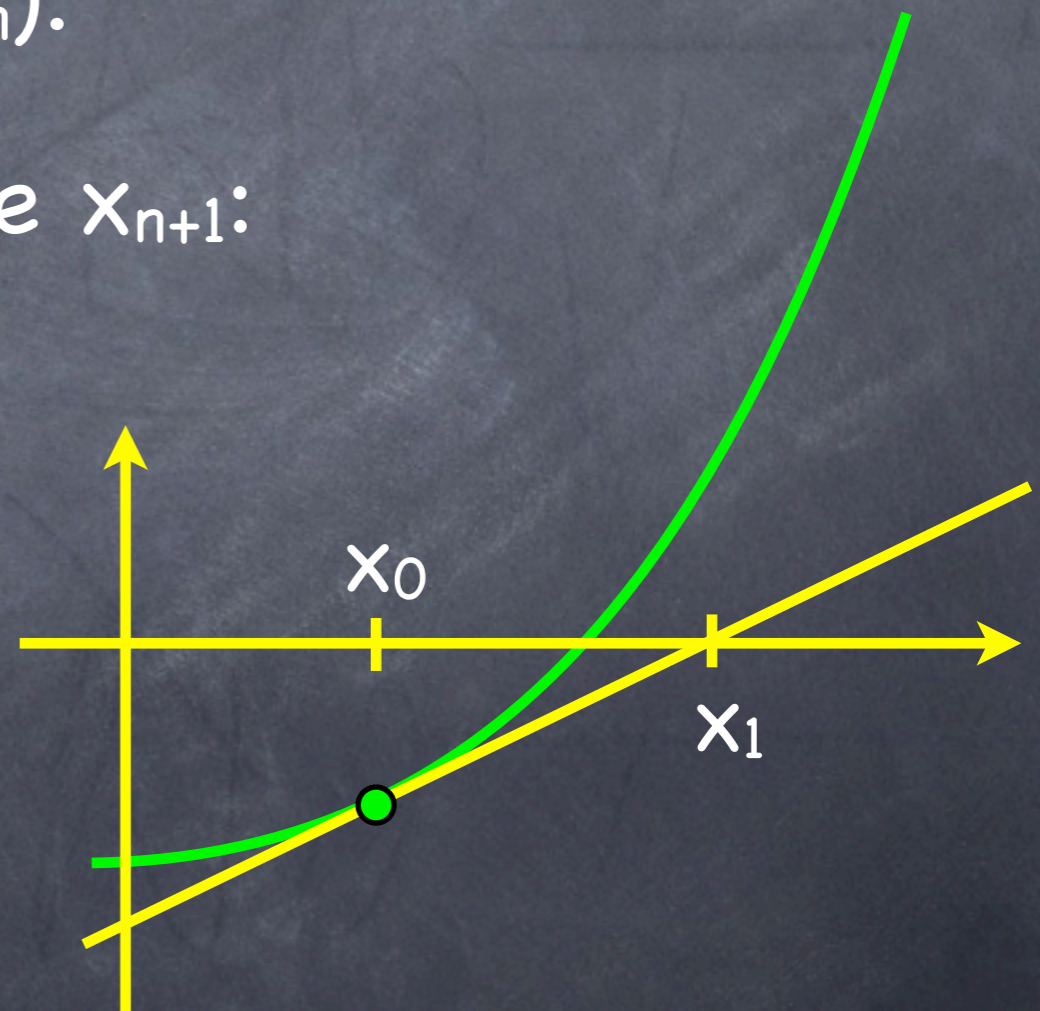
• Find x -intercept, that will be x_{n+1} :

(A) $x_{n+1} = x_n + f(x_n) / f'(x_n).$

(B) $x_{n+1} = x_n - f(x_n) / f'(x_n).$

(C) $x_{n+1} = x_n - f'(x_n) / f(x_n).$

(D) $x_{n+1} = x_n + f'(x_n) / f(x_n).$



To estimate $\sqrt{3}$, which function would you apply Newton's method to?

(A) $f(x) = x^{1/2}$

(B) $f(x) = x^{1/2} - 3$

(C) $f(x) = x^2$

(D) $f(x) = x^2 - 3$

(E) $f(x) = (x-3)^{1/2}$

To estimate $\sqrt{3}$, which function would you apply Newton's method to?

(A) $f(x) = x^{1/2}$

(B) $f(x) = x^{1/2} - 3$

(C) $f(x) = x^2$

(D) $f(x) = x^2 - 3$ ←--- This one has a root at $\sqrt{3}$.

(E) $f(x) = (x-3)^{1/2}$

Estimate $\sqrt{3}$ using Newton's method with initial guess $x_0=2$.

(A) $7/4$

(B) $97/56$

(C) 1.7

(D) 1.73205080757

$$x_{n+1} = x_n - f(x_n) / f'(x_n).$$

Finished already? Now use linear approximation.
Which approach is better?

Estimate $\sqrt{3}$ using Newton's method with initial guess $x_0=2$.

(A) $7/4 = 1.75 \leftarrow x_1$

(B) $97/56 = 1.73214 \leftarrow x_2$

(C) 1.7

(D) 1.73205080757 \leftarrow first 11 digits of $\sqrt{3}$.

Qualitative analysis of differential equations

Qualitative analysis of differential equations

- Finding a general solution to a DE is ideal but what if you can't?

Qualitative analysis of differential equations

- Finding a general solution to a DE is ideal but what if you can't?
- Qualitative analysis - extract information about the general solution without solving.

Qualitative analysis of differential equations

- Finding a general solution to a DE is ideal but what if you can't?
- Qualitative analysis - extract information about the general solution without solving.
 - Steady states
 - Slope fields
 - Stability of steady states
 - Plotting y' versus y (phase line)

$$x' = x(1 - x)$$

↑ velocity ↑ position

• **Steady state.** Where can you stand so that the DE tells you not to move?

(A) $x = -1$

(B) $x = 0$

(C) $x = 1/2$

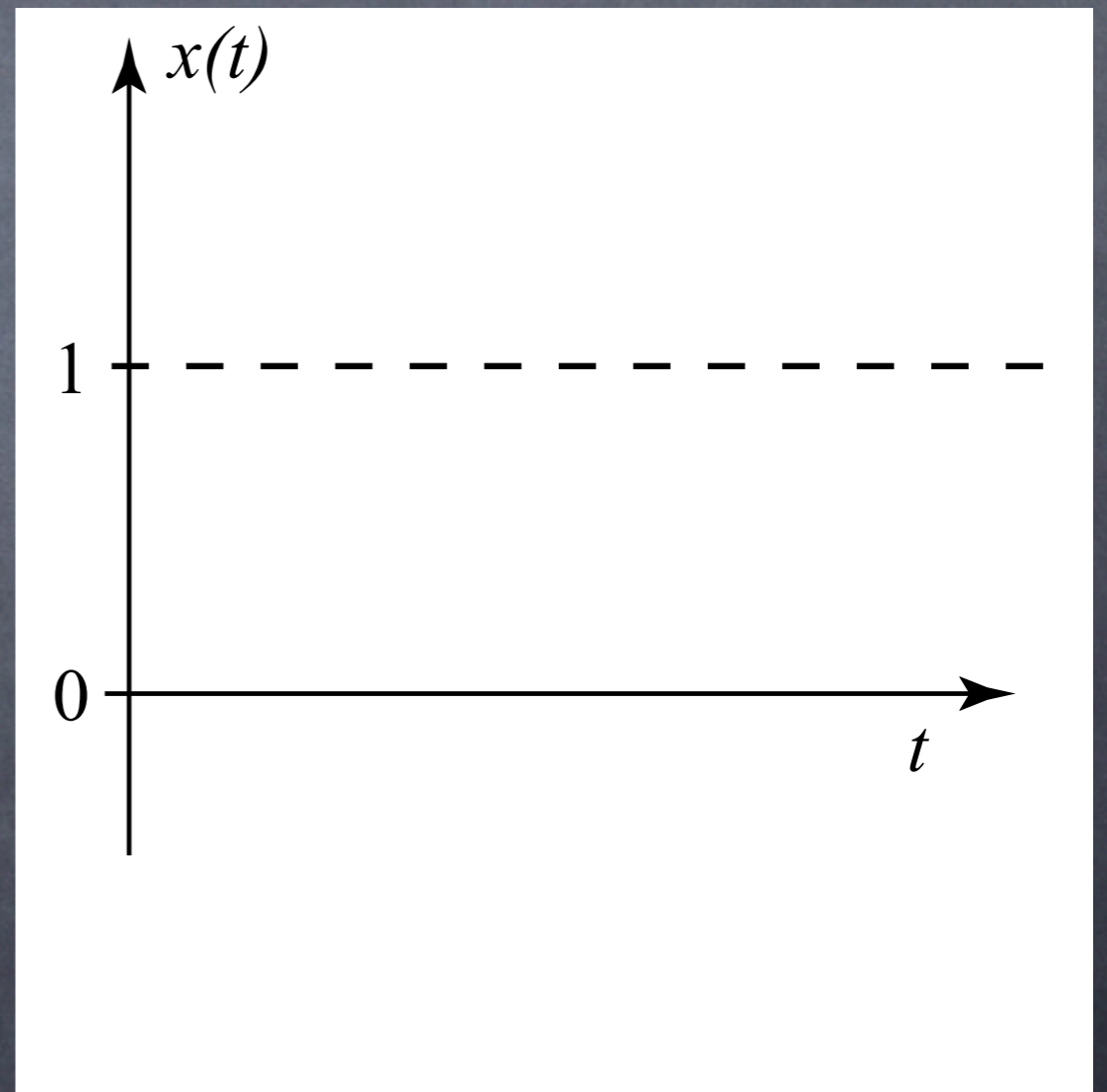
(D) $x = 1$

$$x' = x(1 - x)$$

↑ velocity ↑ position

• **Steady state.** Where can you stand so that the DE tells you not to move?

- (A) $x = -1$
- (B) $x = 0$
- (C) $x = 1/2$
- (D) $x = 1$

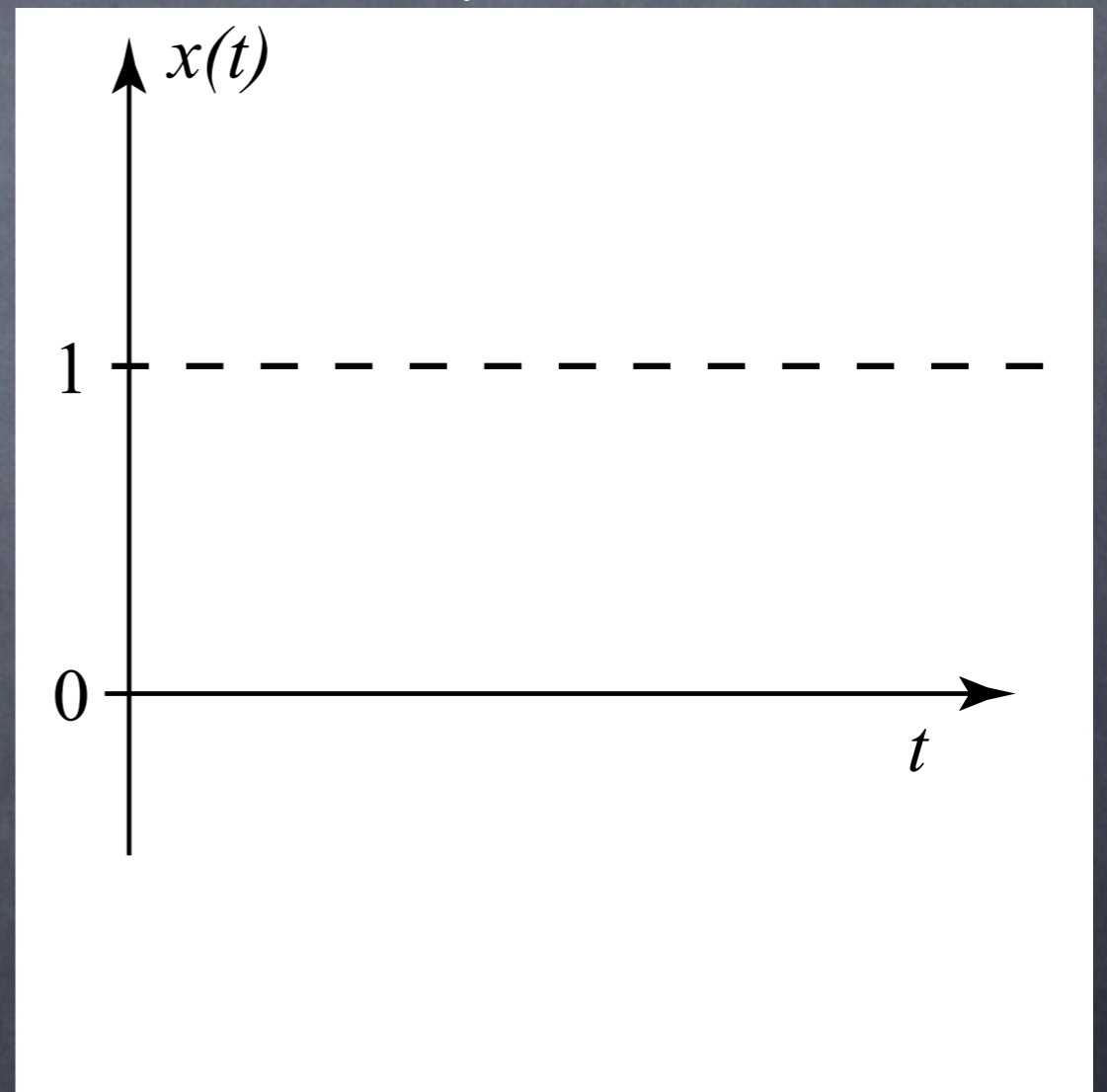


A **steady state** is a constant solution.

$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

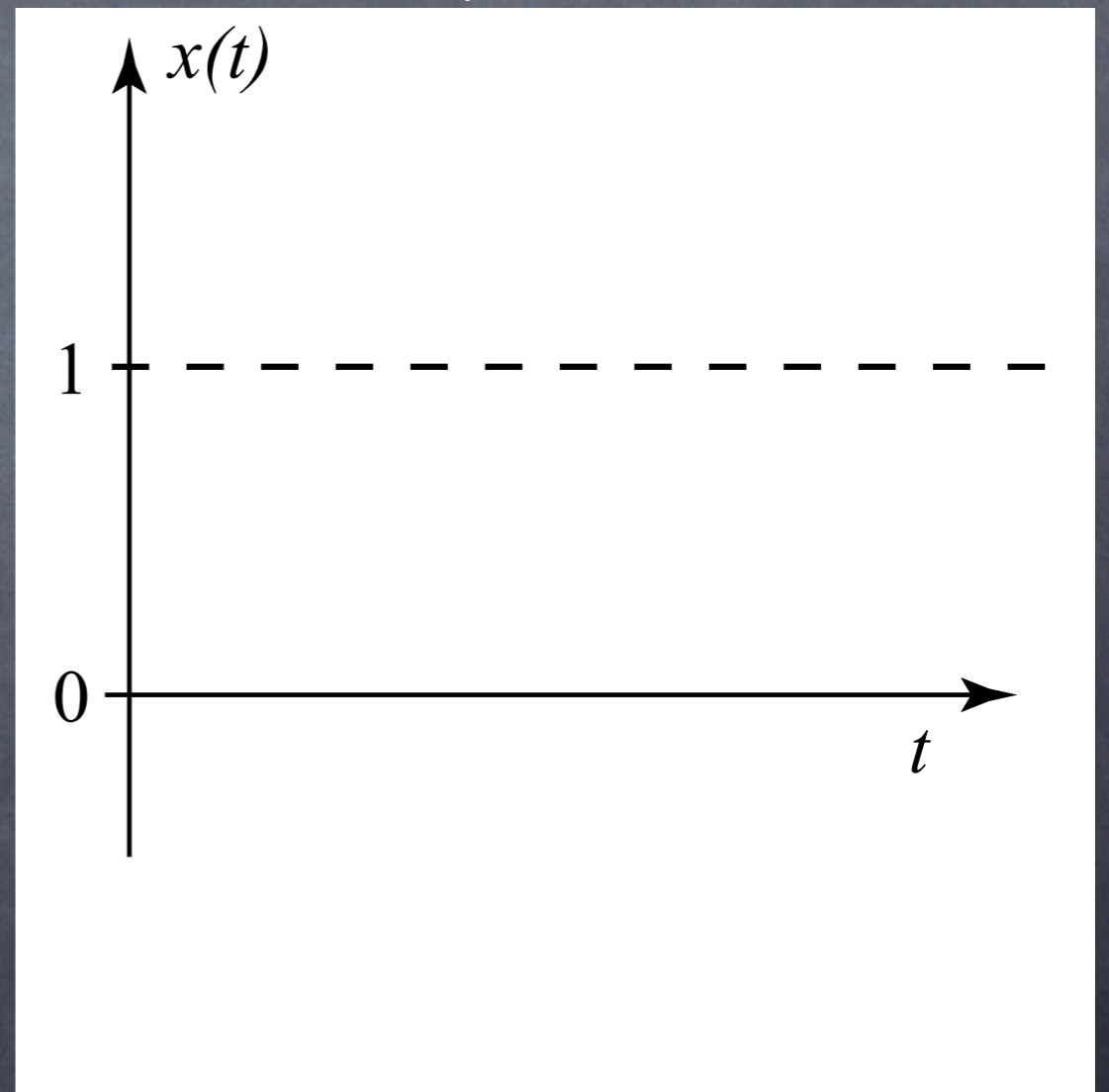


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

• Slope field.

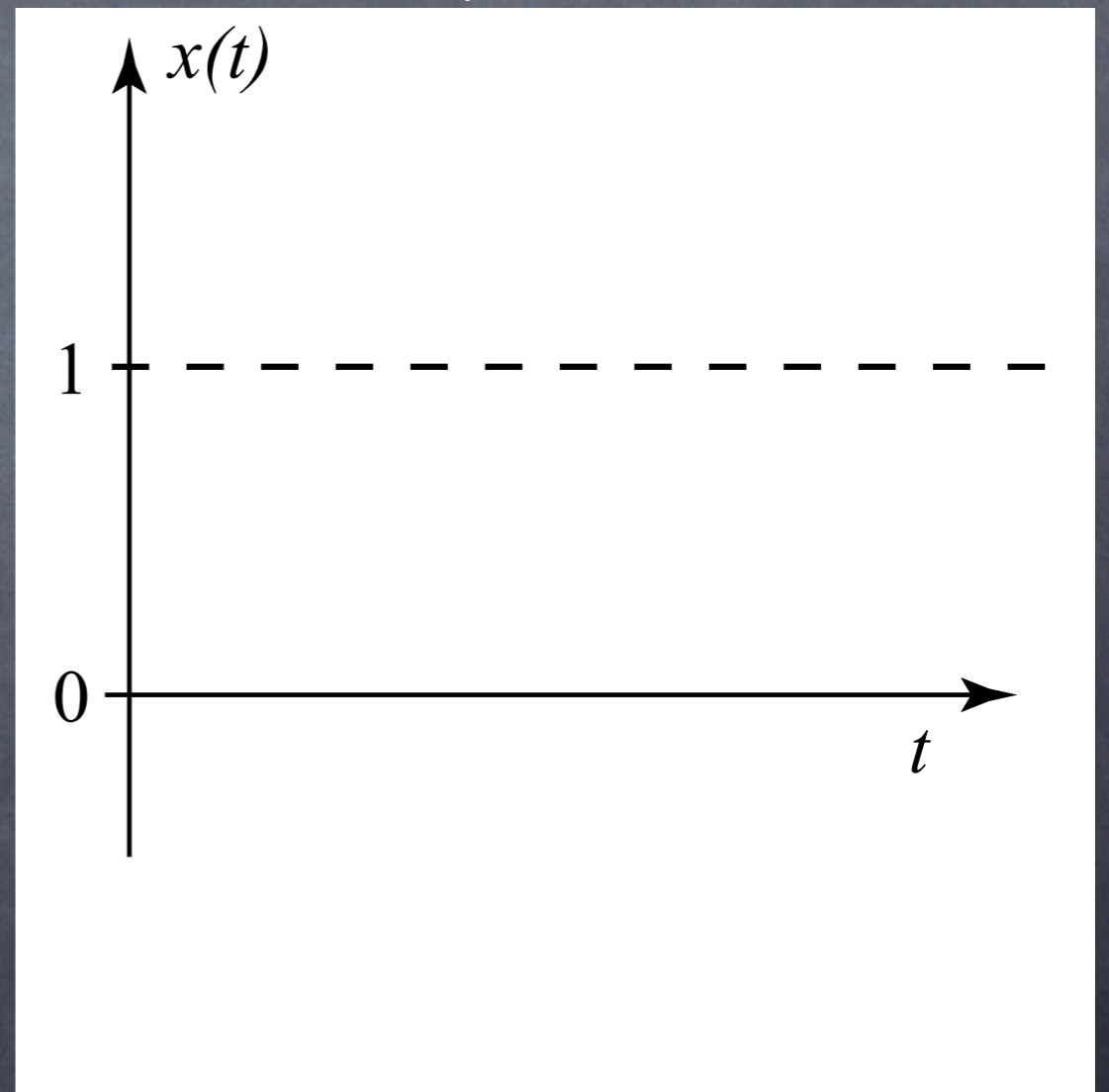


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values

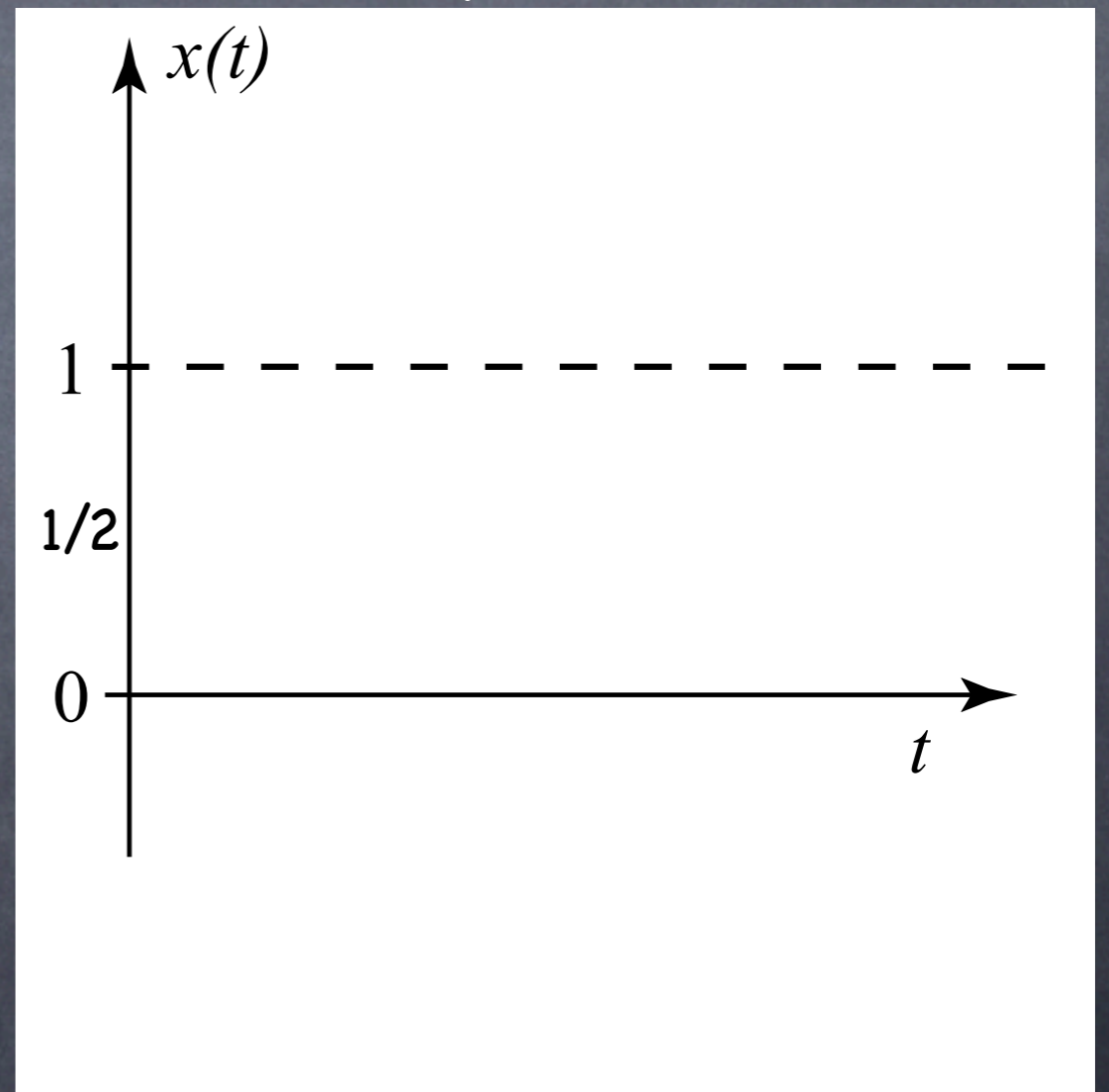


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values
 - When $x(t)=1/2$ what is x' ?
 - (A) 0
 - (B) 1/4
 - (C) 1/2
 - (D) 1

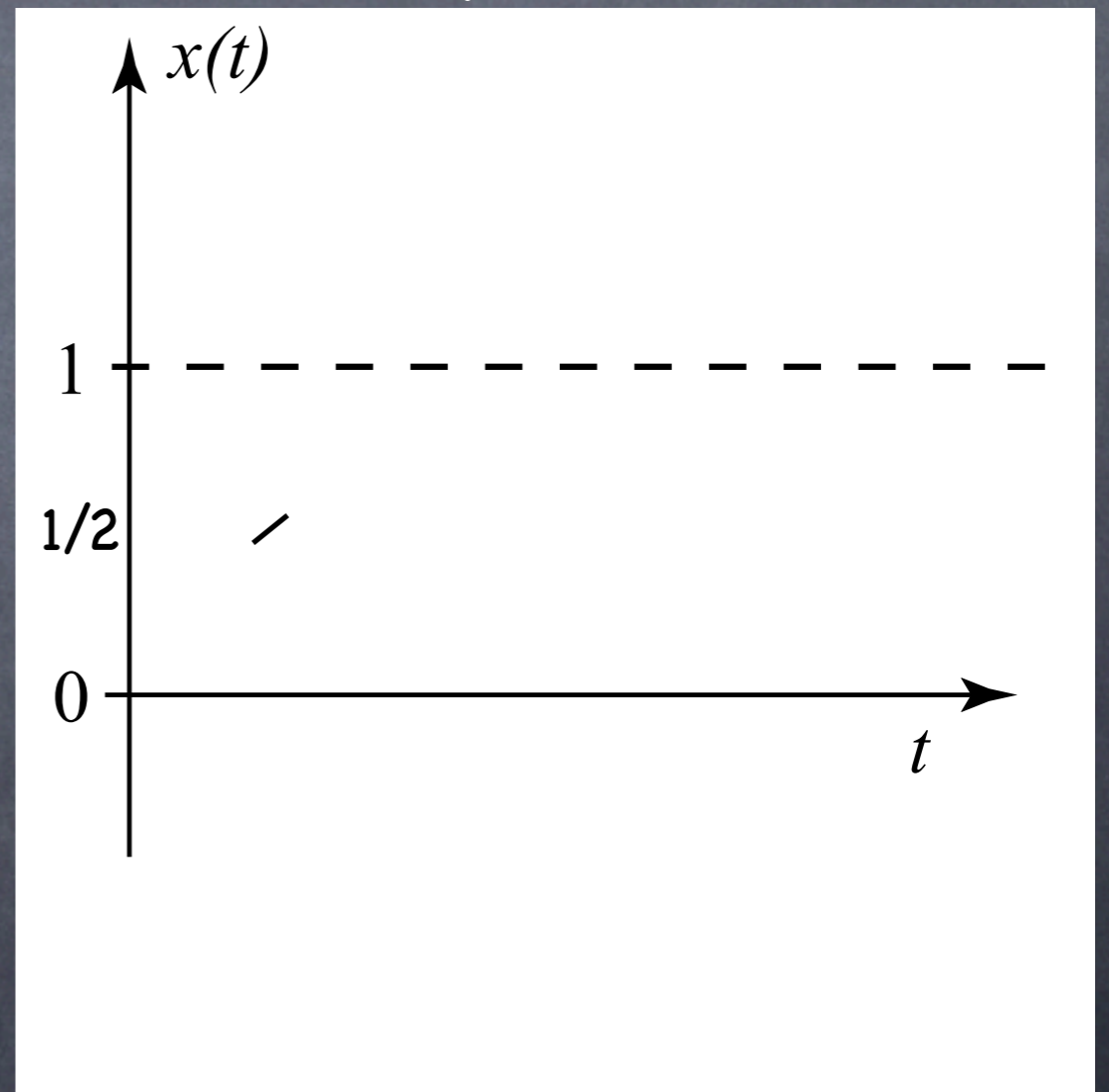


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values

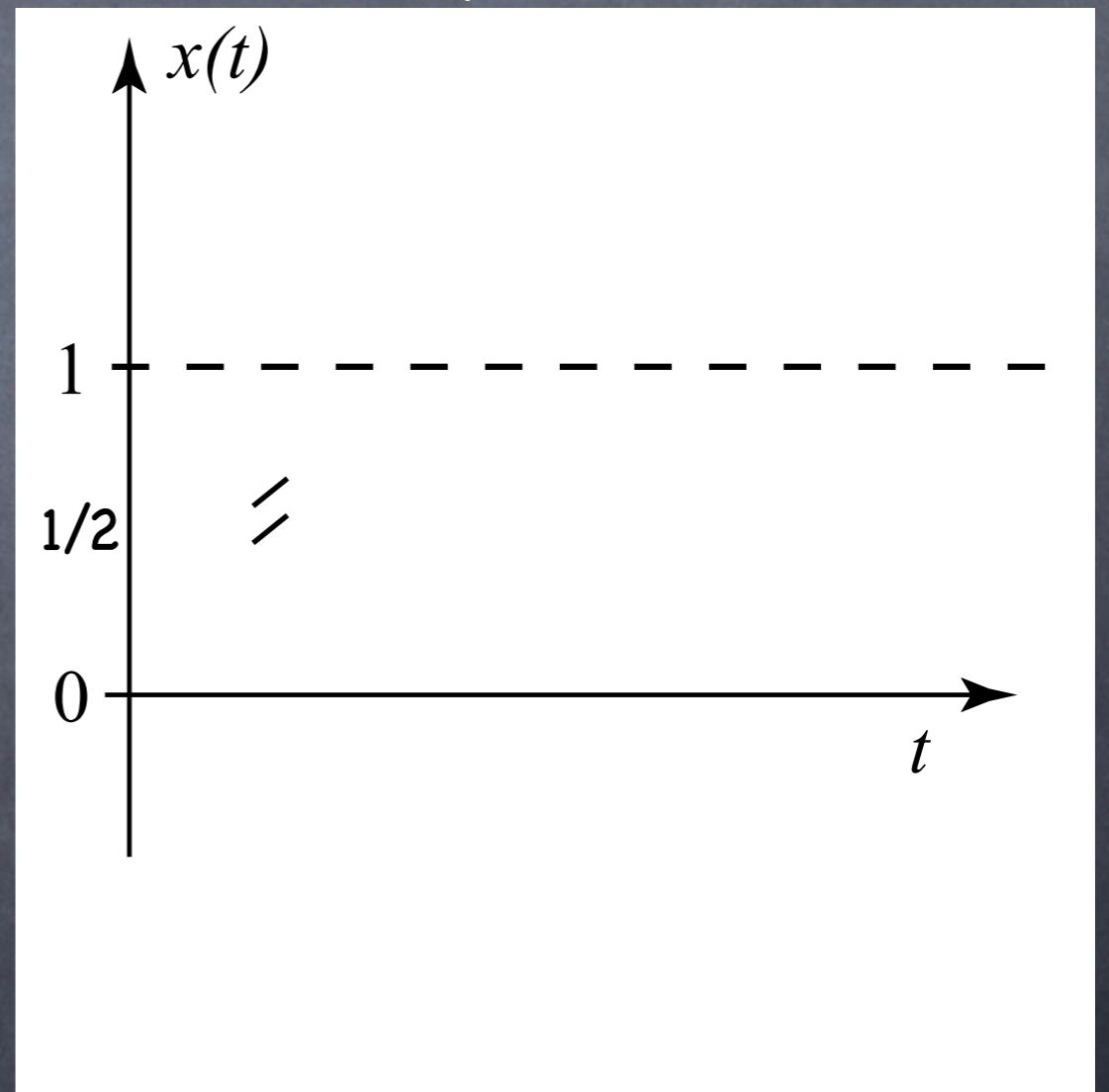


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values

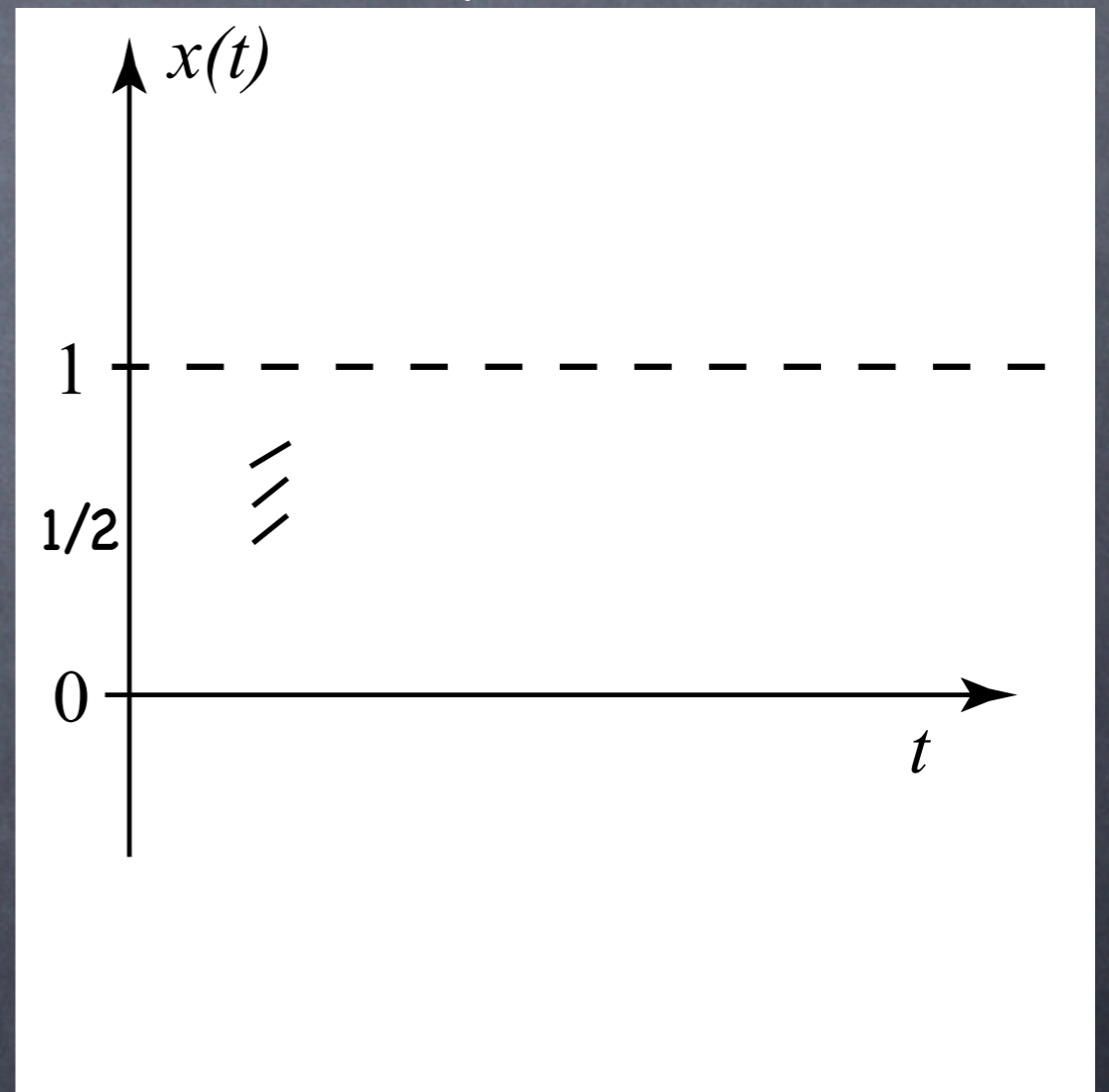


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values

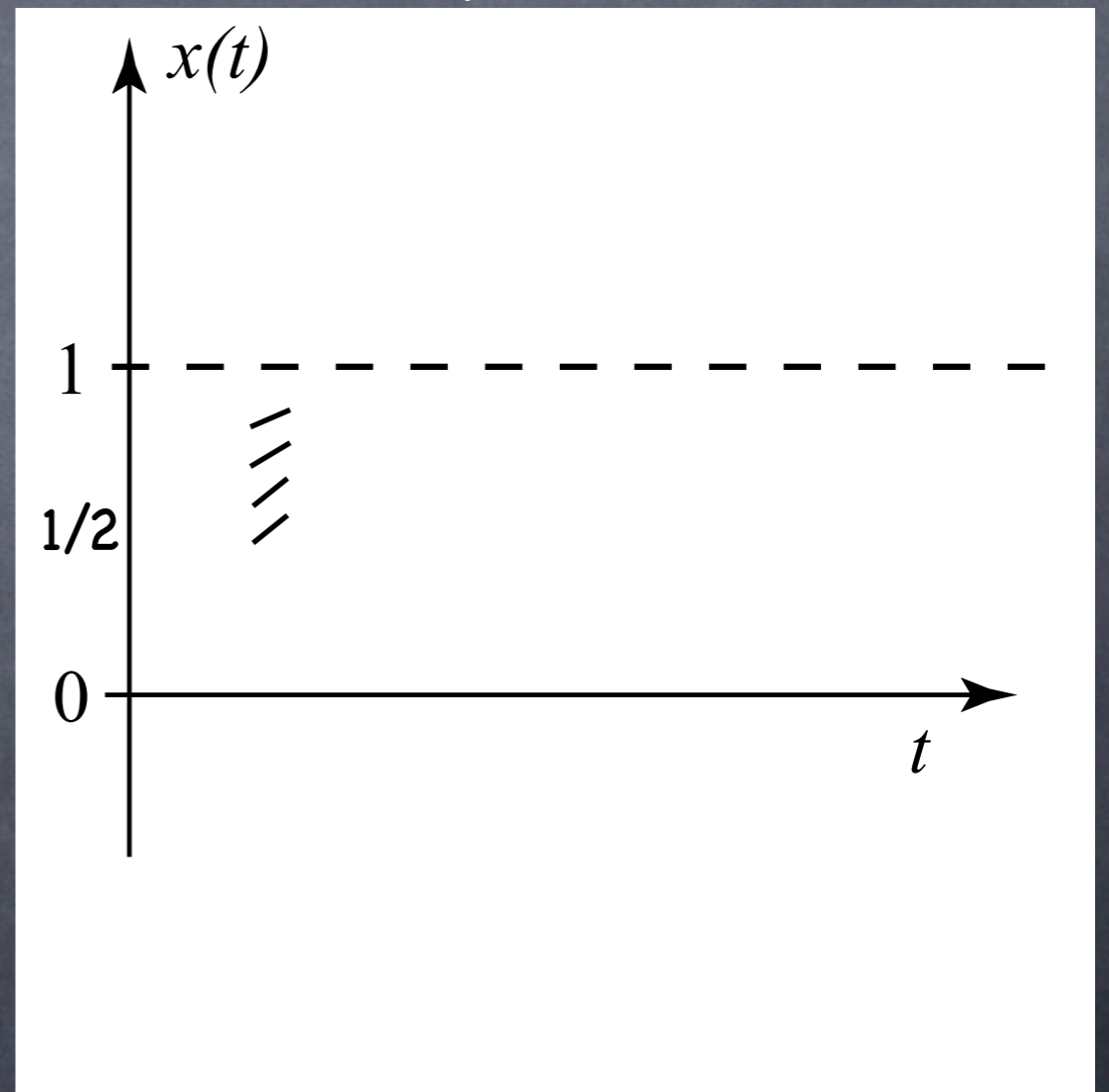


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values

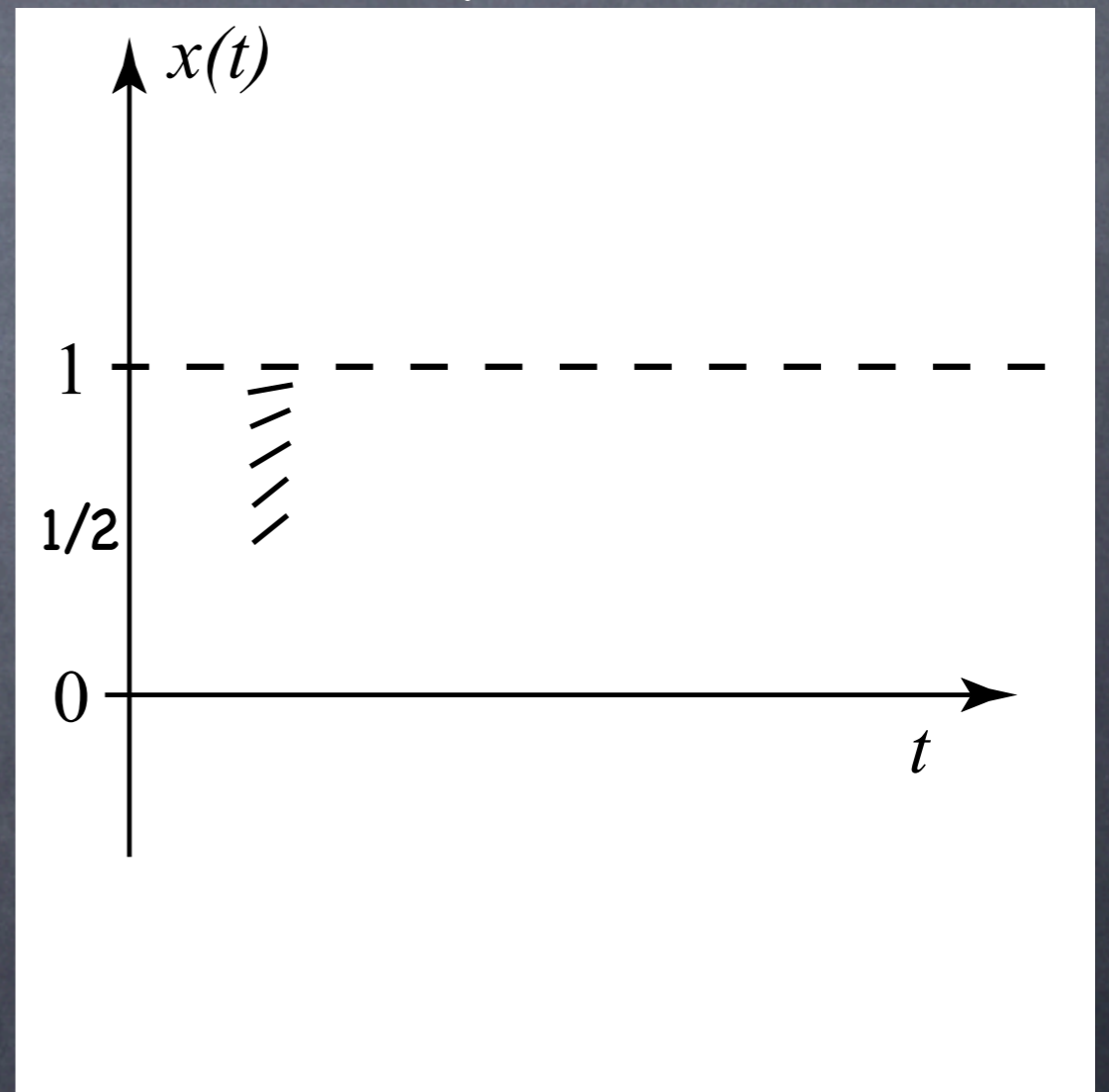


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values

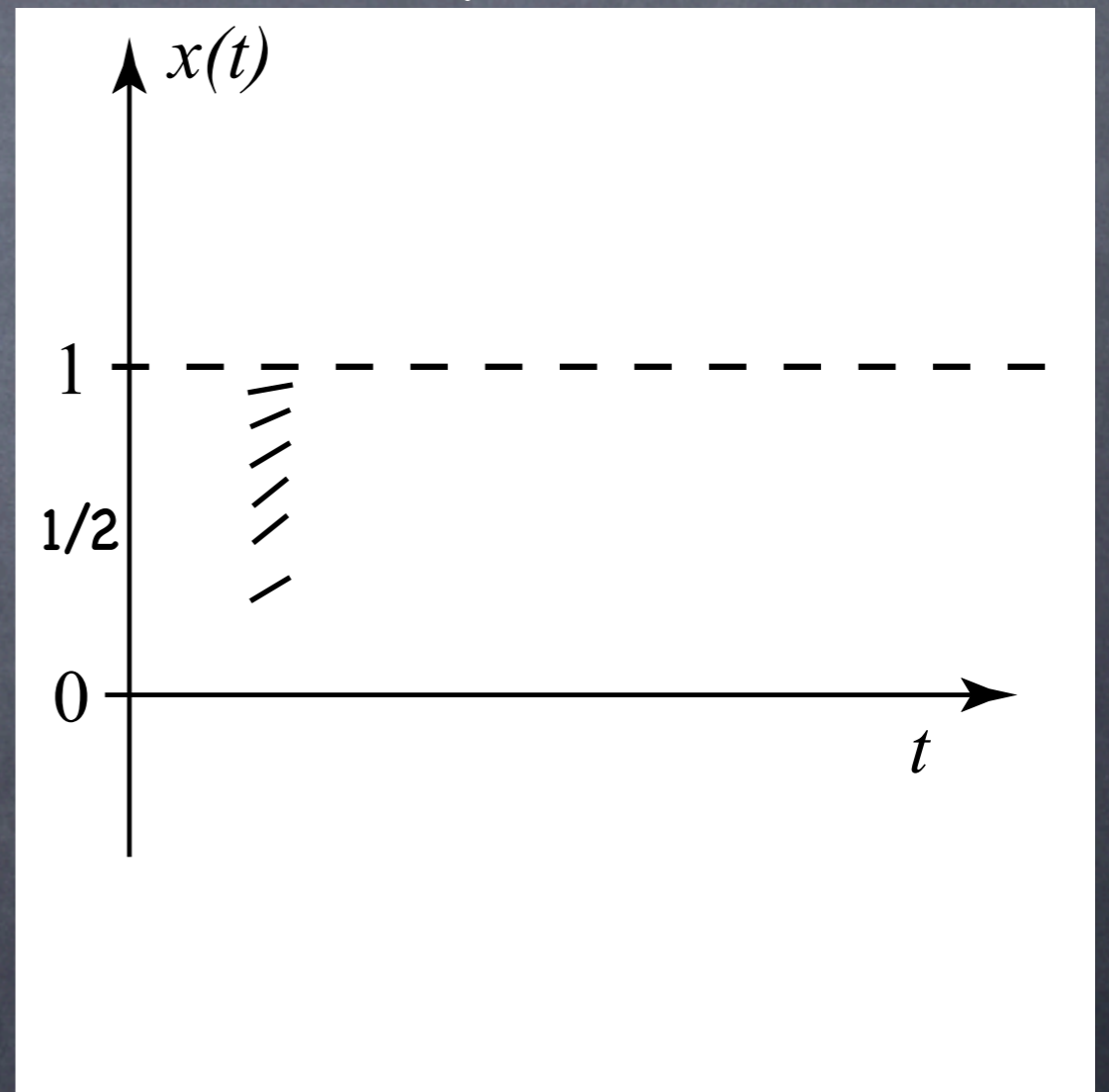


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values

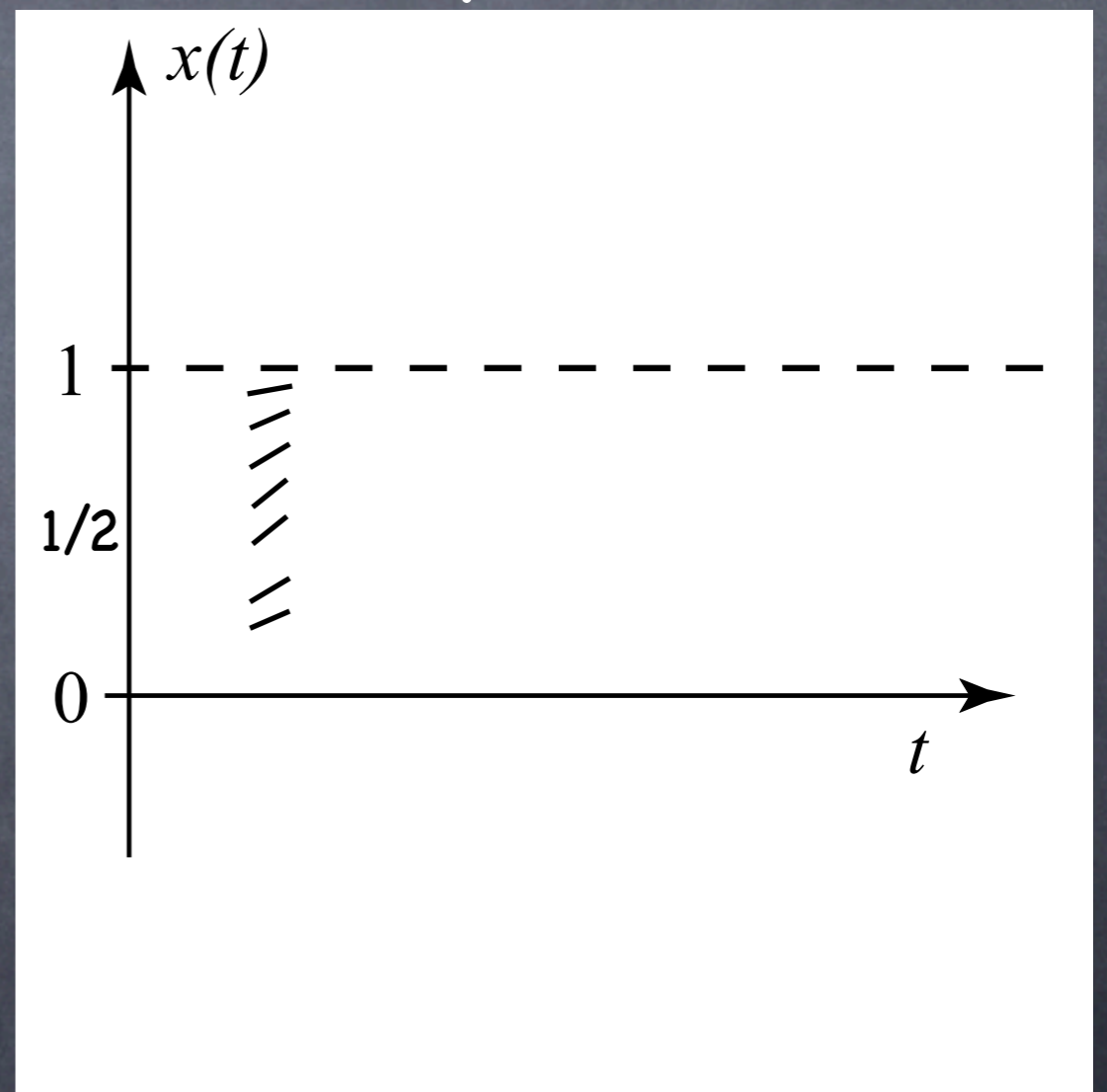


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values

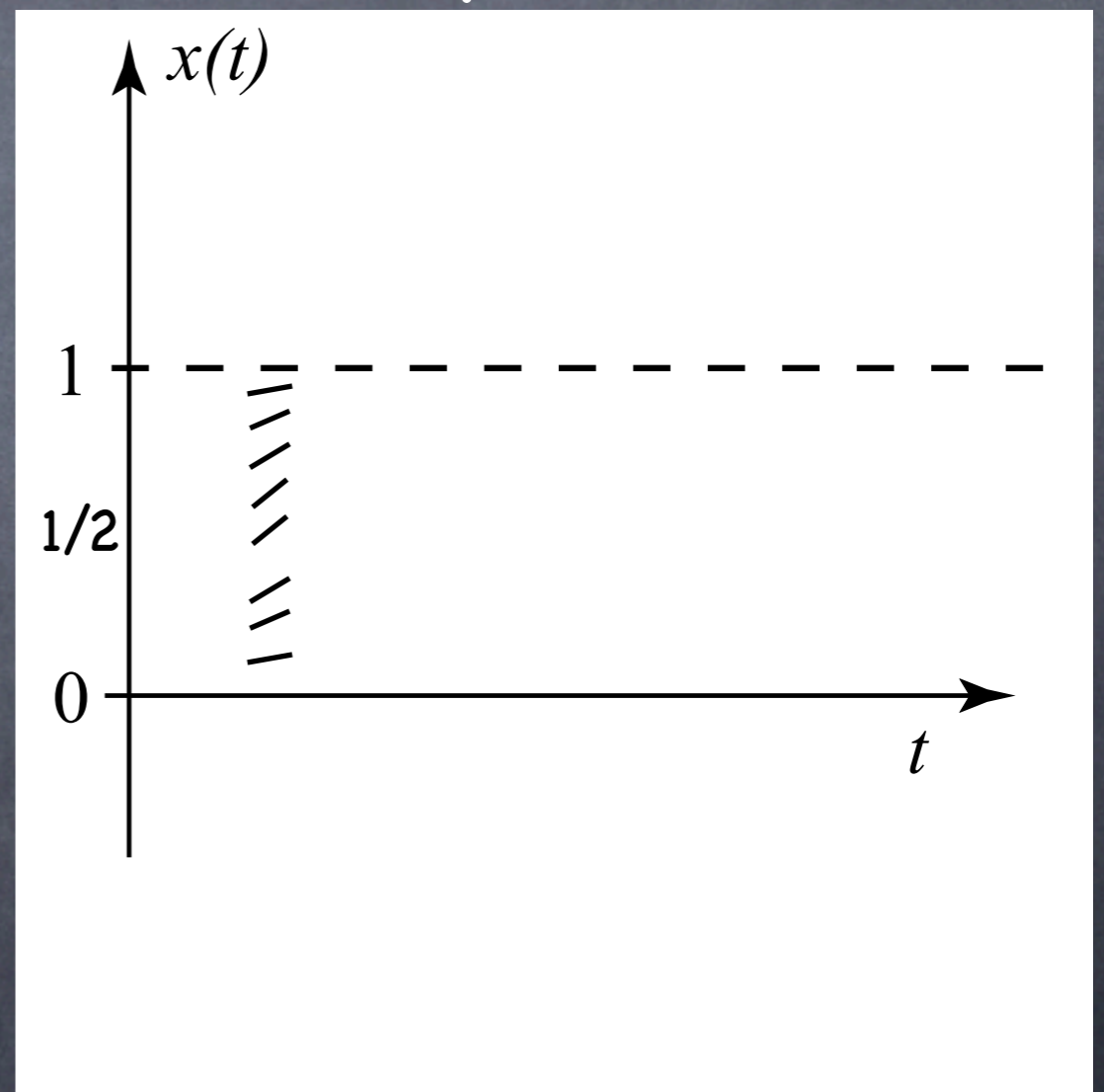


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values

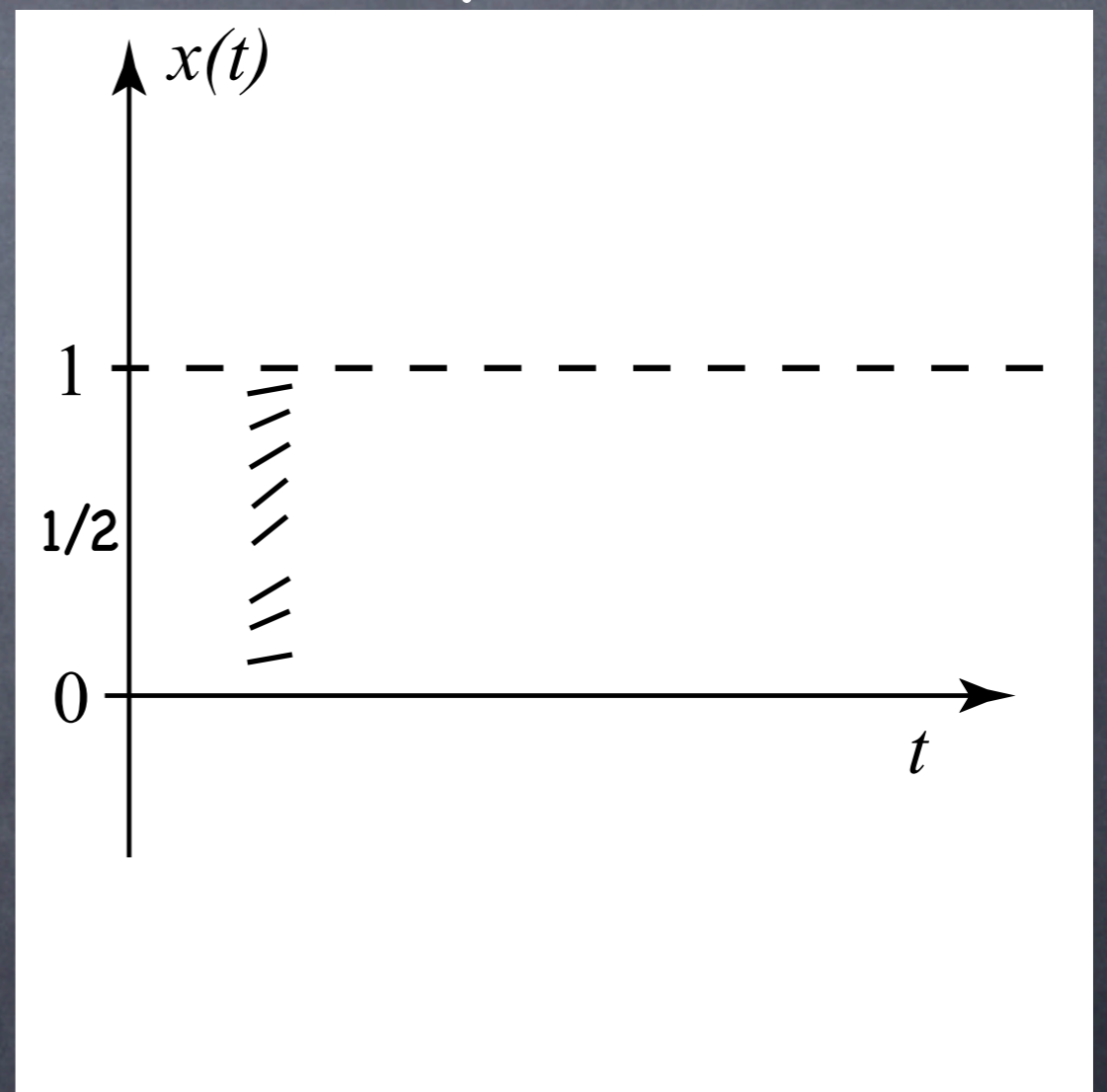


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values
- Now draw them for all t .

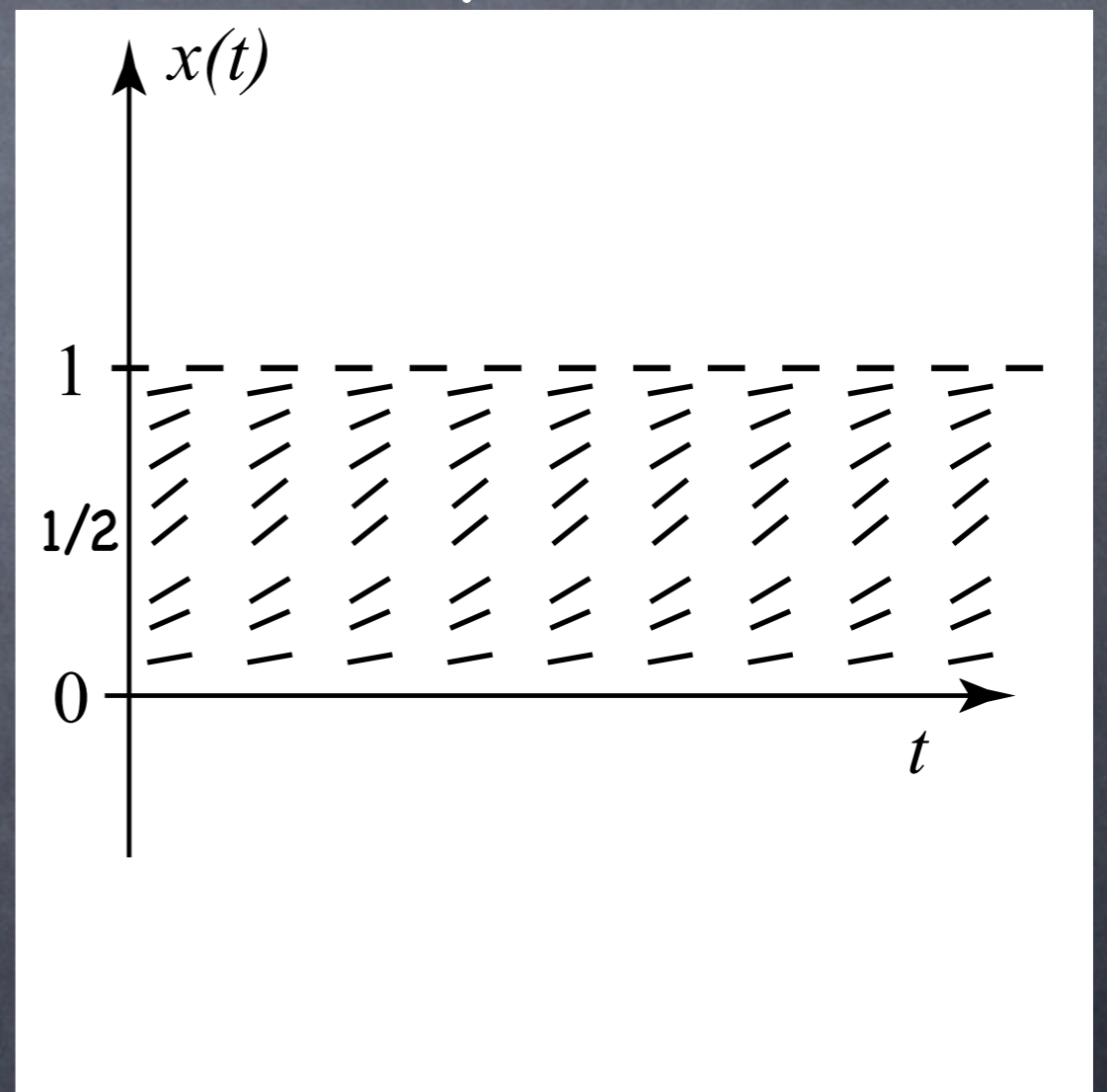


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values
- Now draw them for all t .

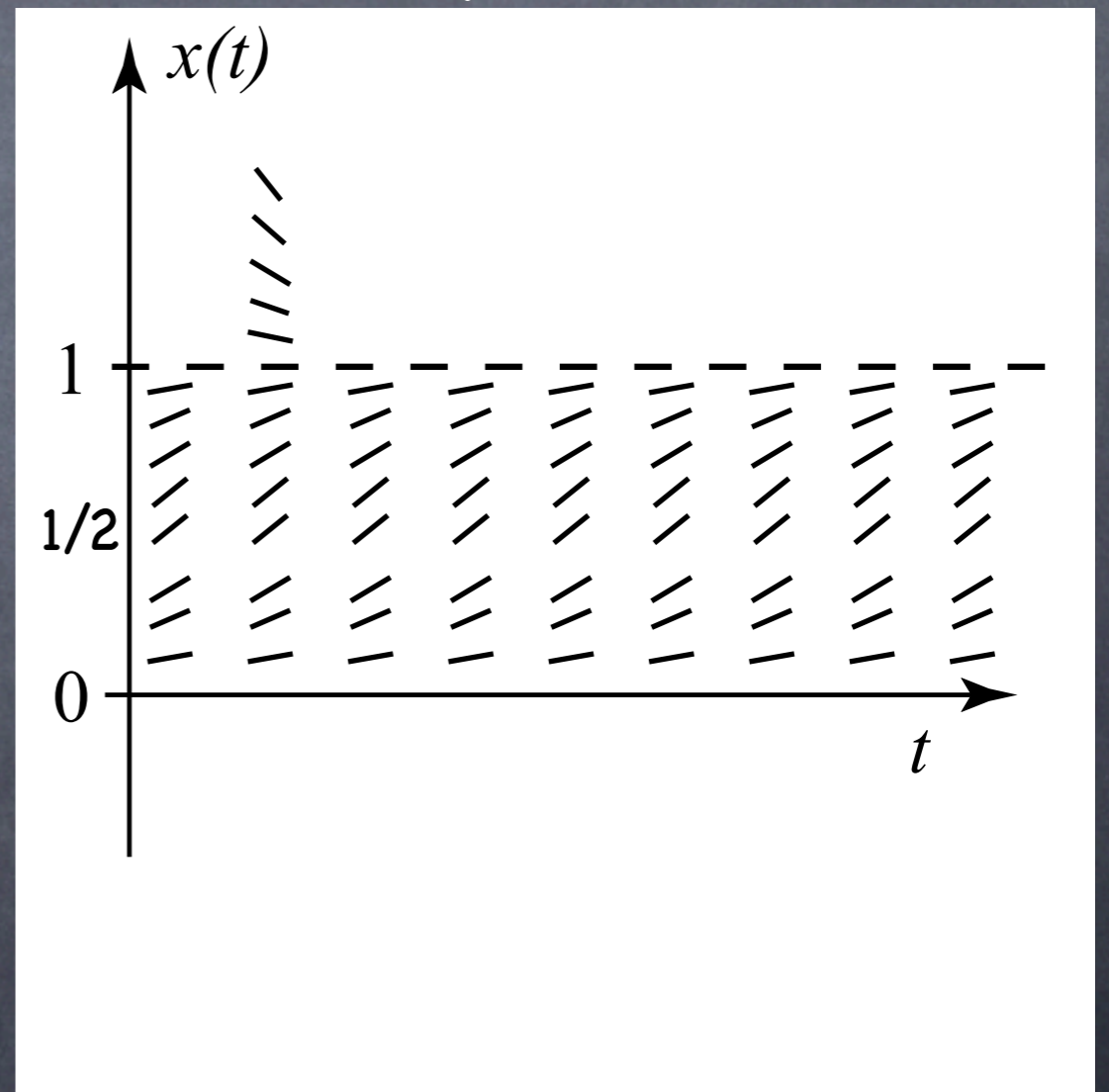


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values
- Now draw them for all t .

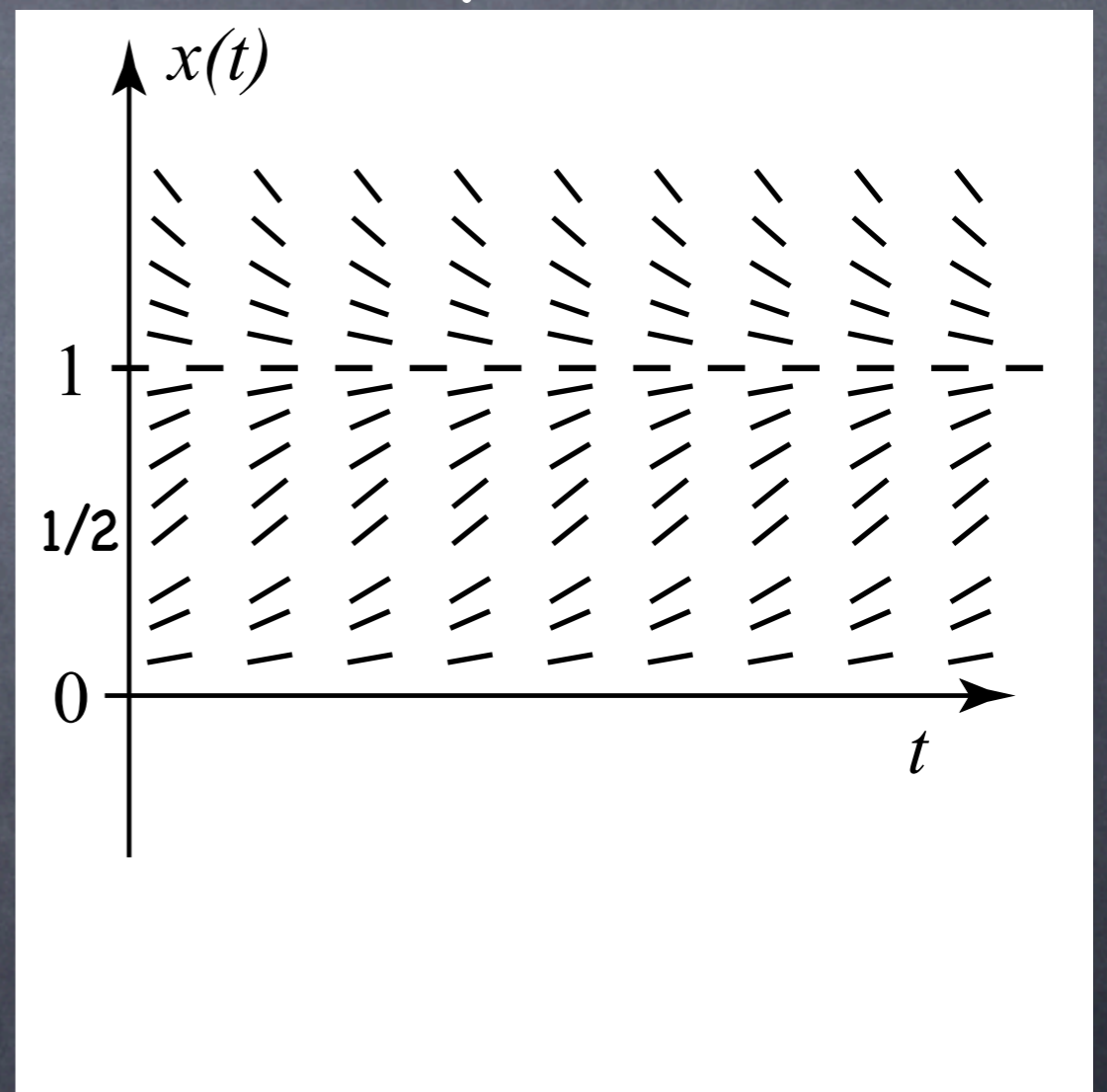


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values
- Now draw them for all t .

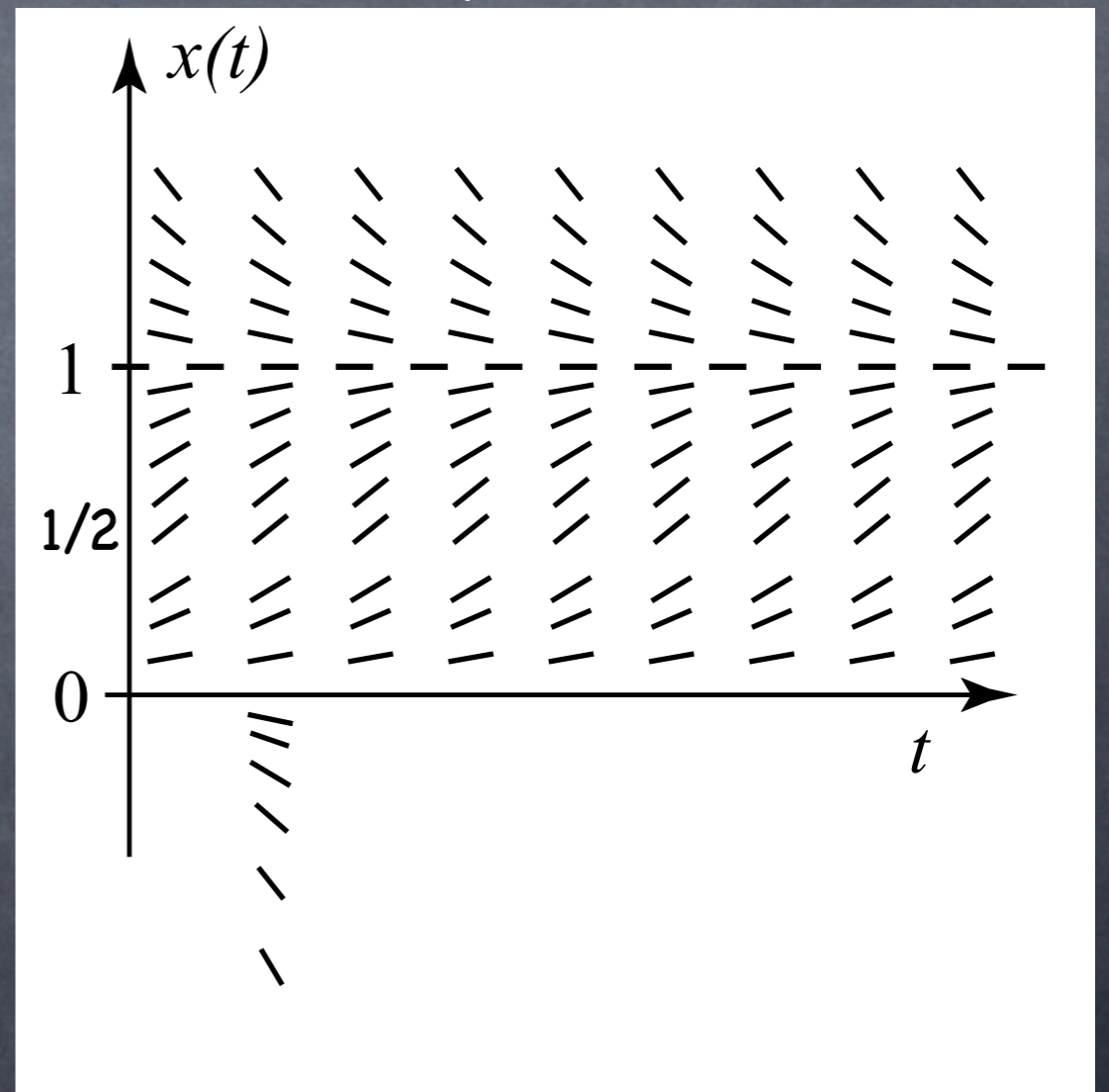


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values
- Now draw them for all t .

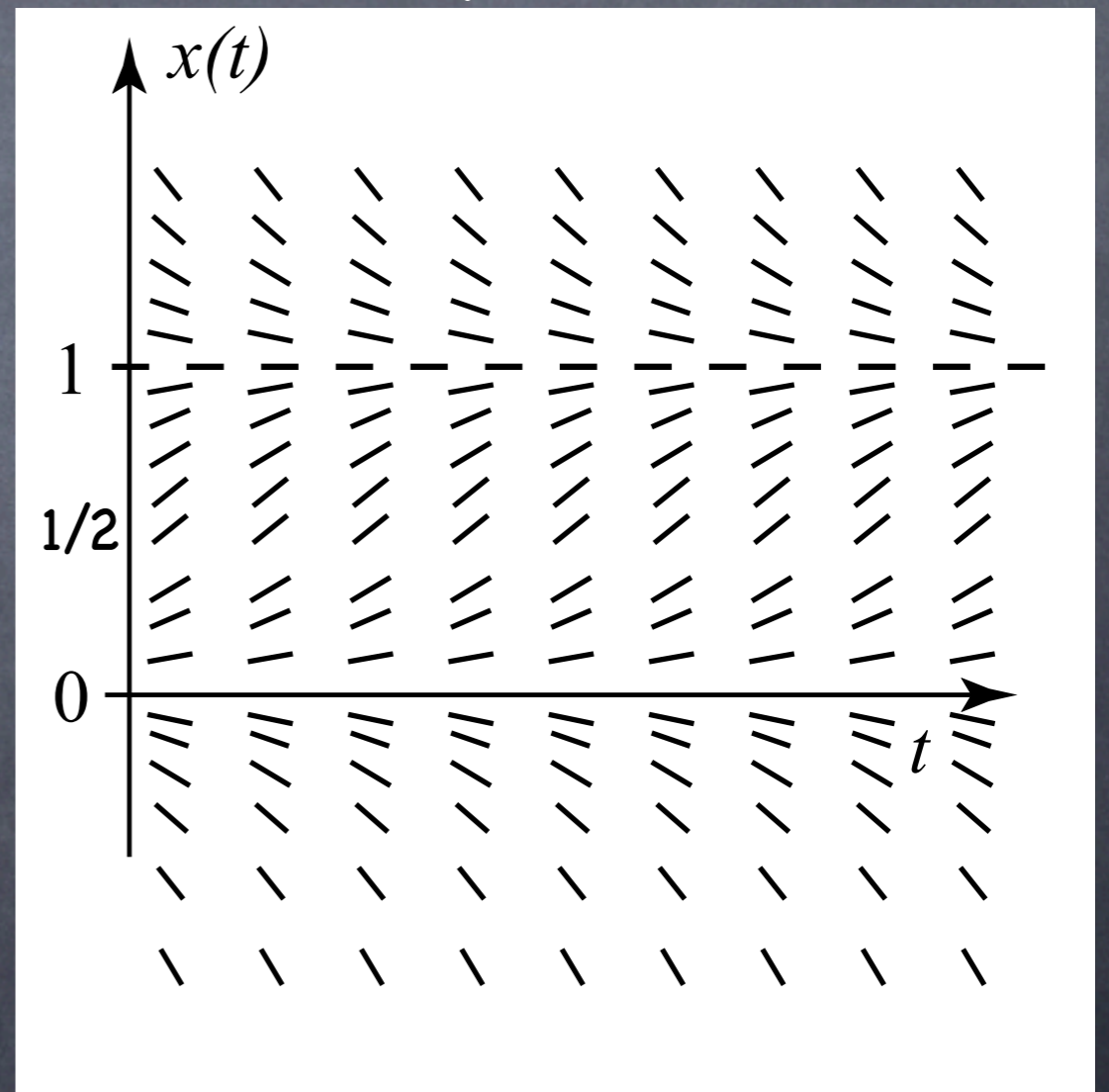


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values
- Now draw them for all t .

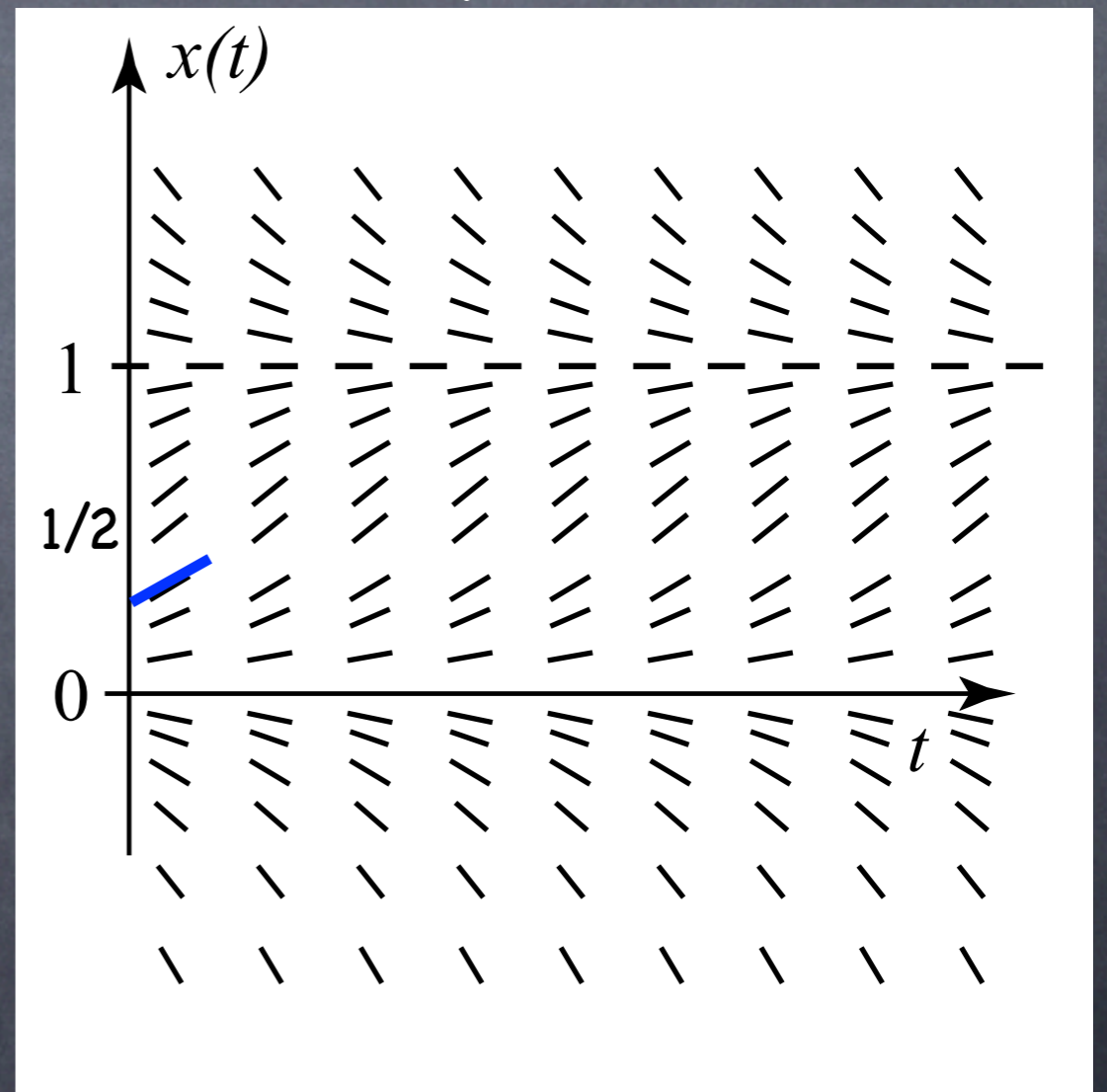


$$x' = x(1 - x)$$

↑
velocity
↑
position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values
- Now draw them for all t .
- Solution curves must be tangent to slope field everywhere.

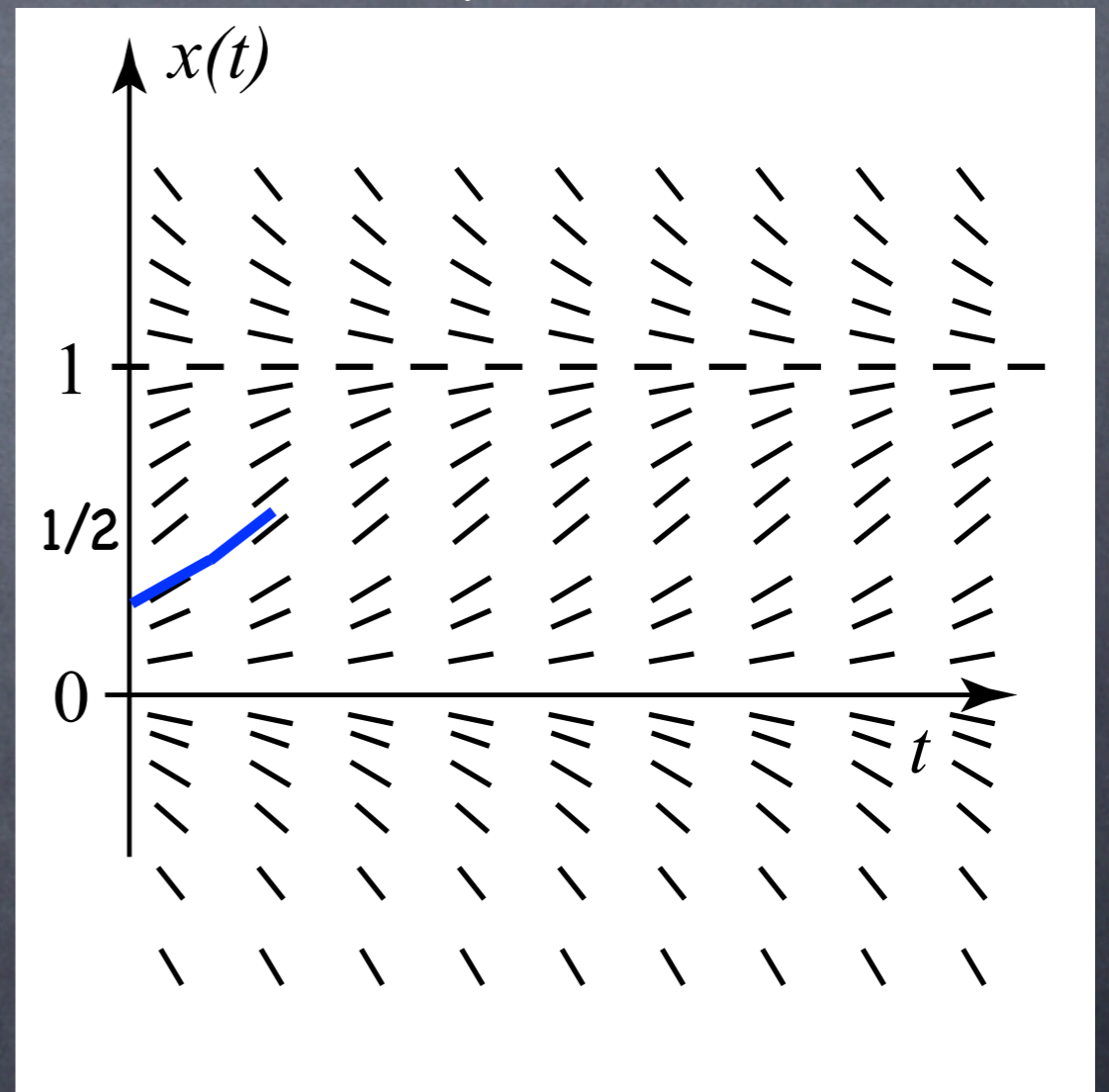


$$x' = x(1 - x)$$

↑
velocity
↑
position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values
- Now draw them for all t .
- Solution curves must be tangent to slope field everywhere.

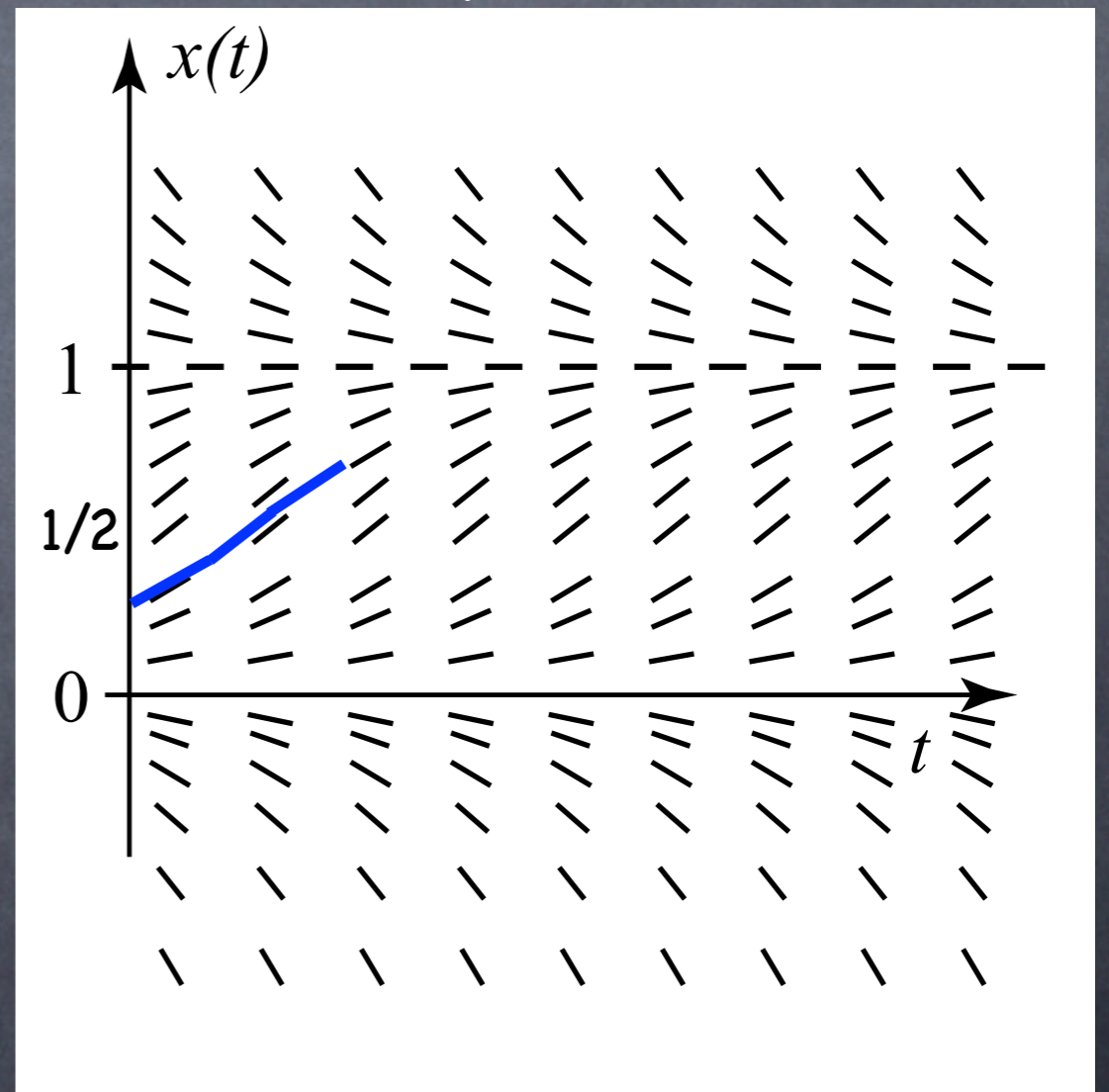


$$x' = x(1 - x)$$

↑
velocity
↑
position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values
- Now draw them for all t .
- Solution curves must be tangent to slope field everywhere.

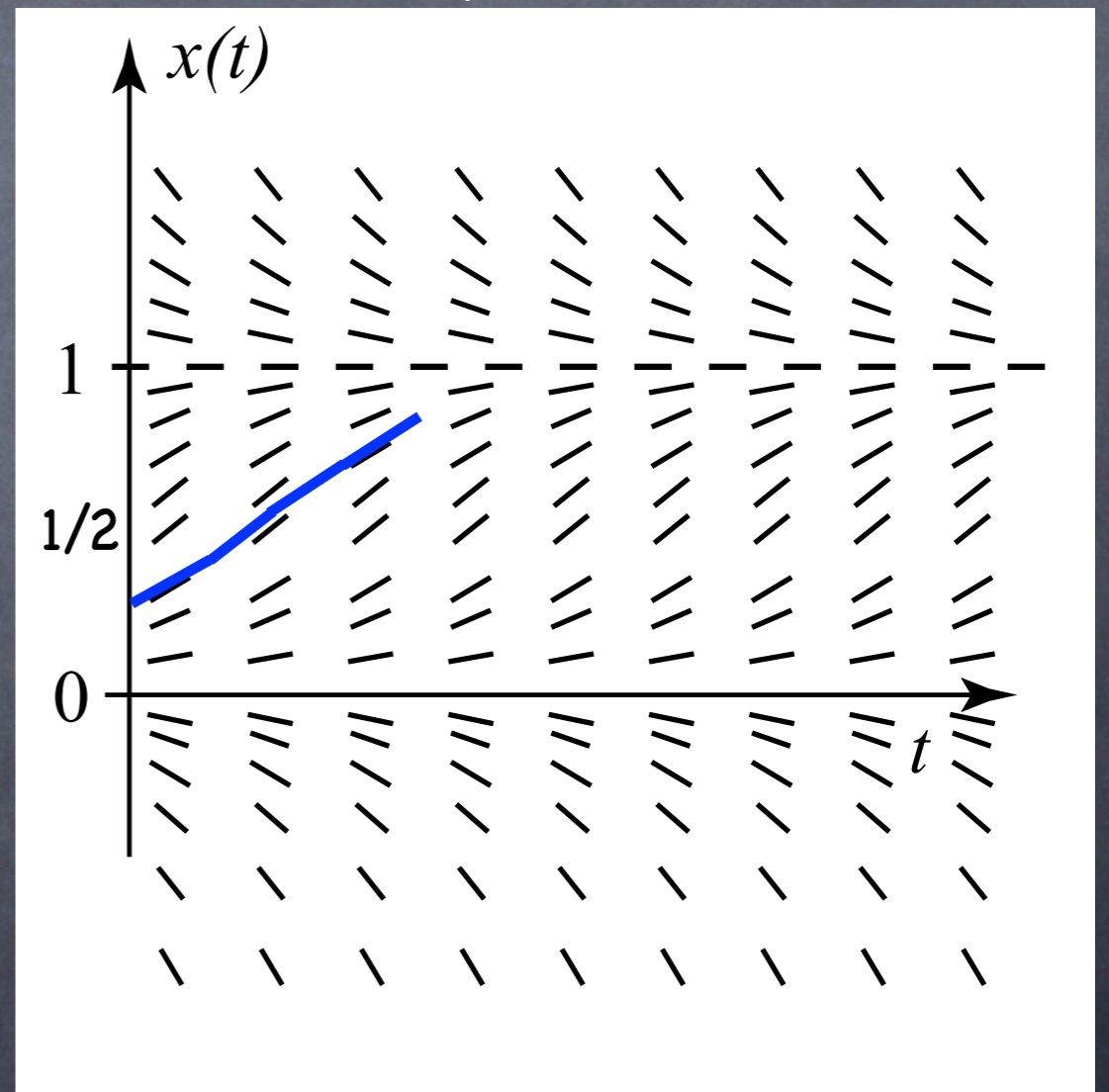


$$x' = x(1 - x)$$

↑ velocity ↑ position

Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values
- Now draw them for all t .
- Solution curves must be tangent to slope field everywhere.

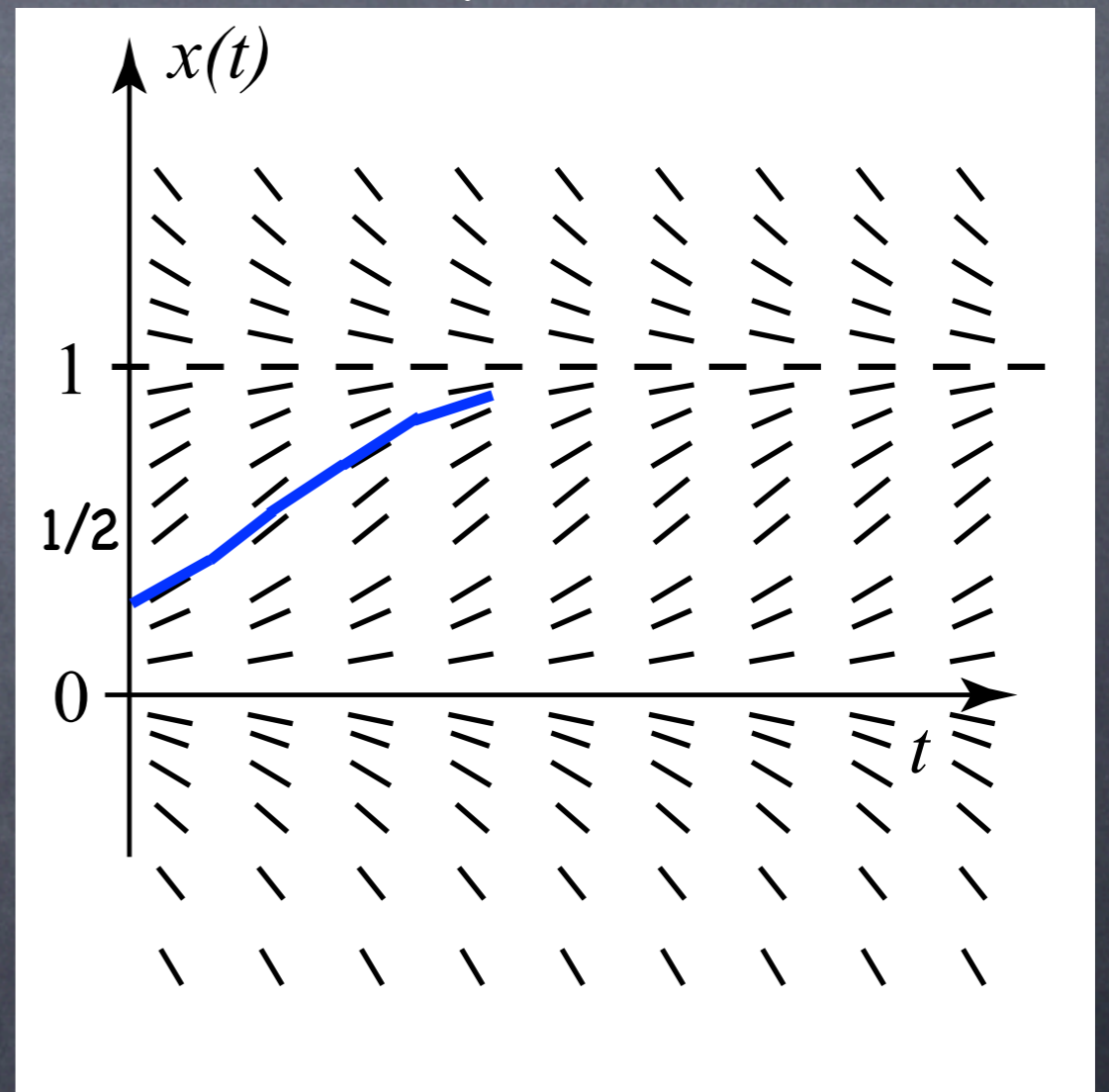


$$x' = x(1 - x)$$

↑
velocity
↑
position

Slope field

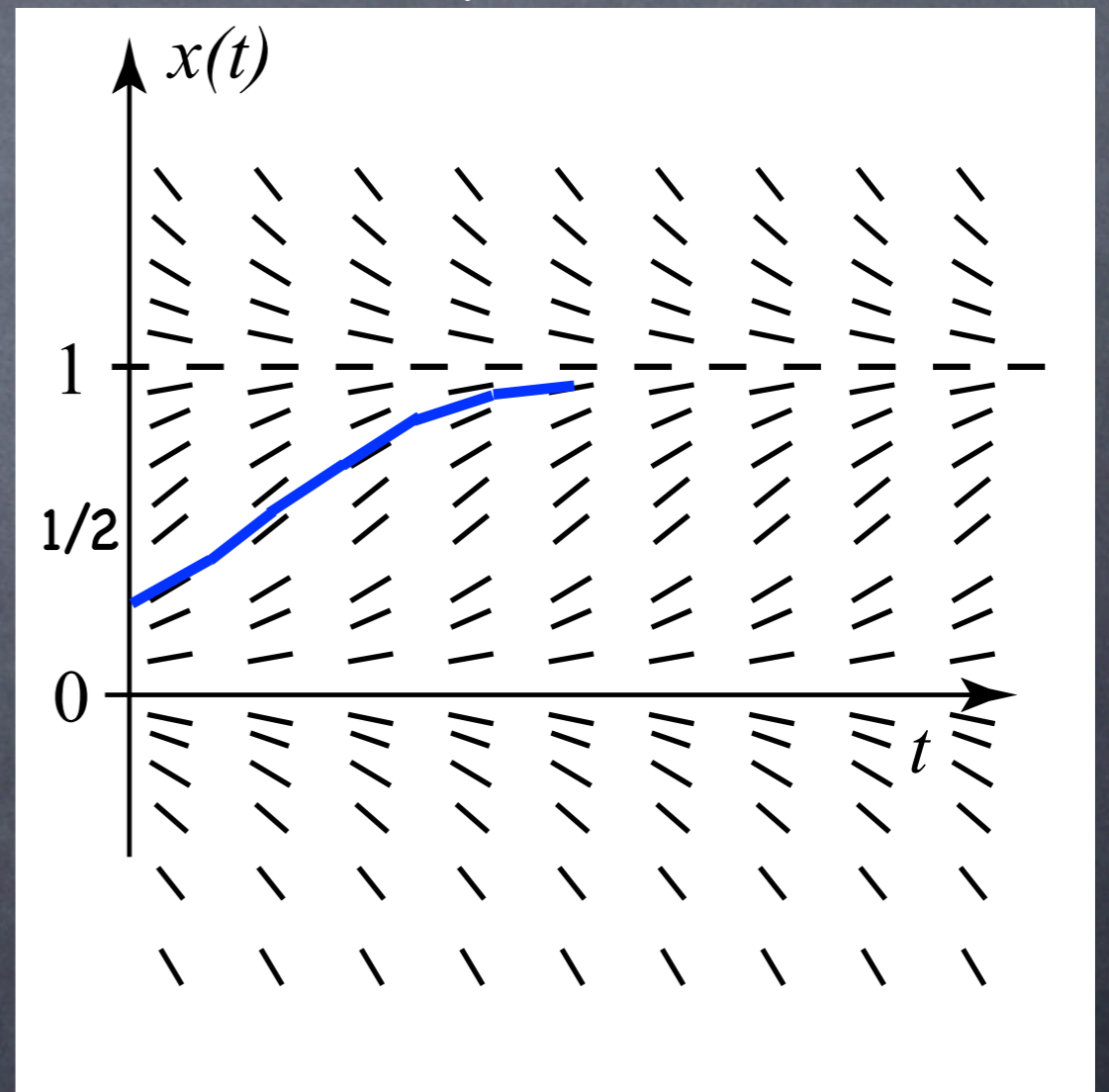
- Slope field.
- At any t , don't know x yet so plot all possible x' values
- Now draw them for all t .
- Solution curves must be tangent to slope field everywhere.



$$\underset{\substack{\uparrow \\ \text{velocity}}}{x'} = x(1 - \underset{\substack{\uparrow \\ \text{position}}}{x})$$

Slope field

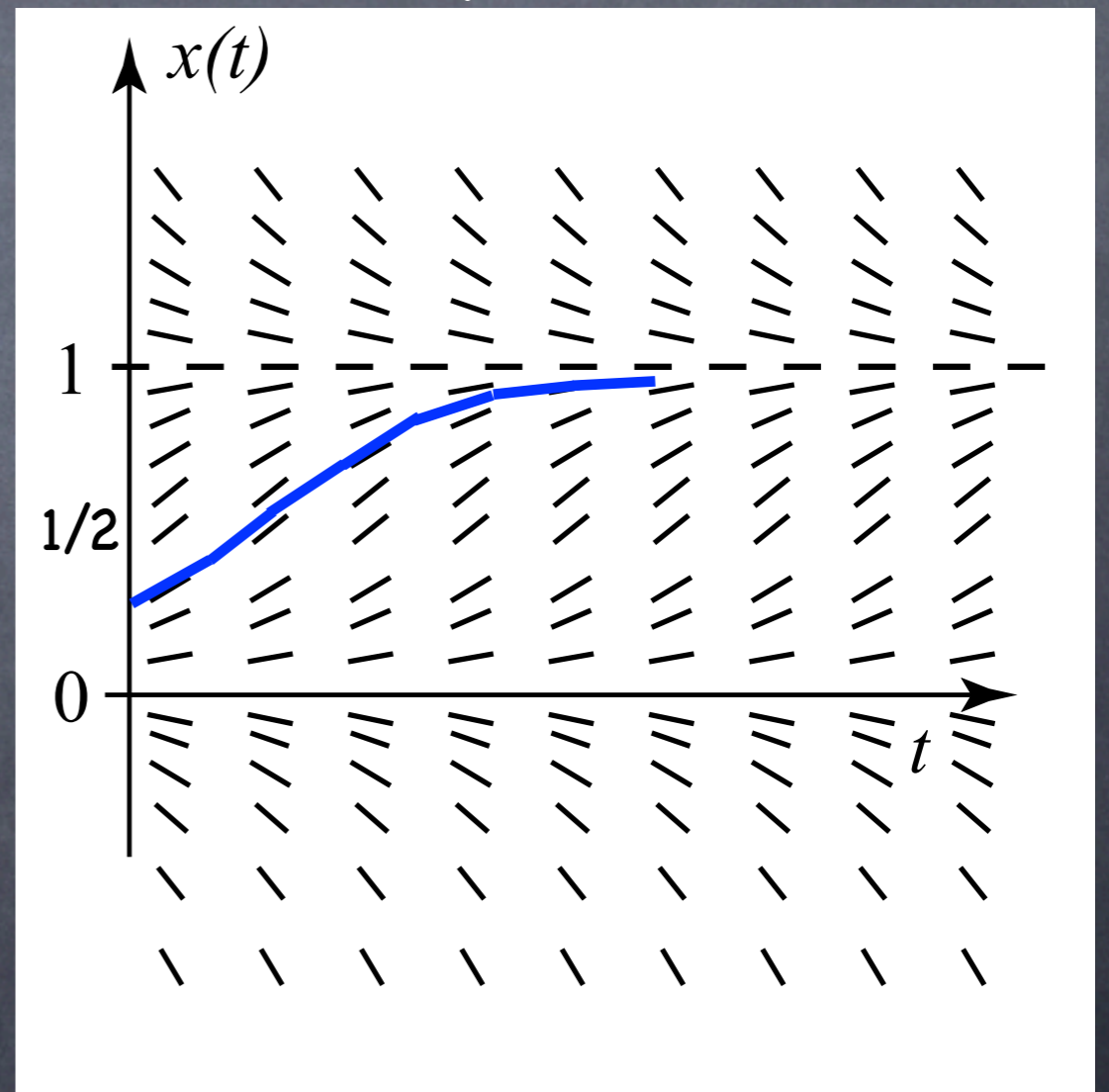
- Slope field.
- At any t , don't know x yet so plot all possible x' values
- Now draw them for all t .
- Solution curves must be tangent to slope field everywhere.



$$\underset{\substack{\uparrow \\ \text{velocity}}}{x'} = x(1 - \underset{\substack{\uparrow \\ \text{position}}}{x})$$

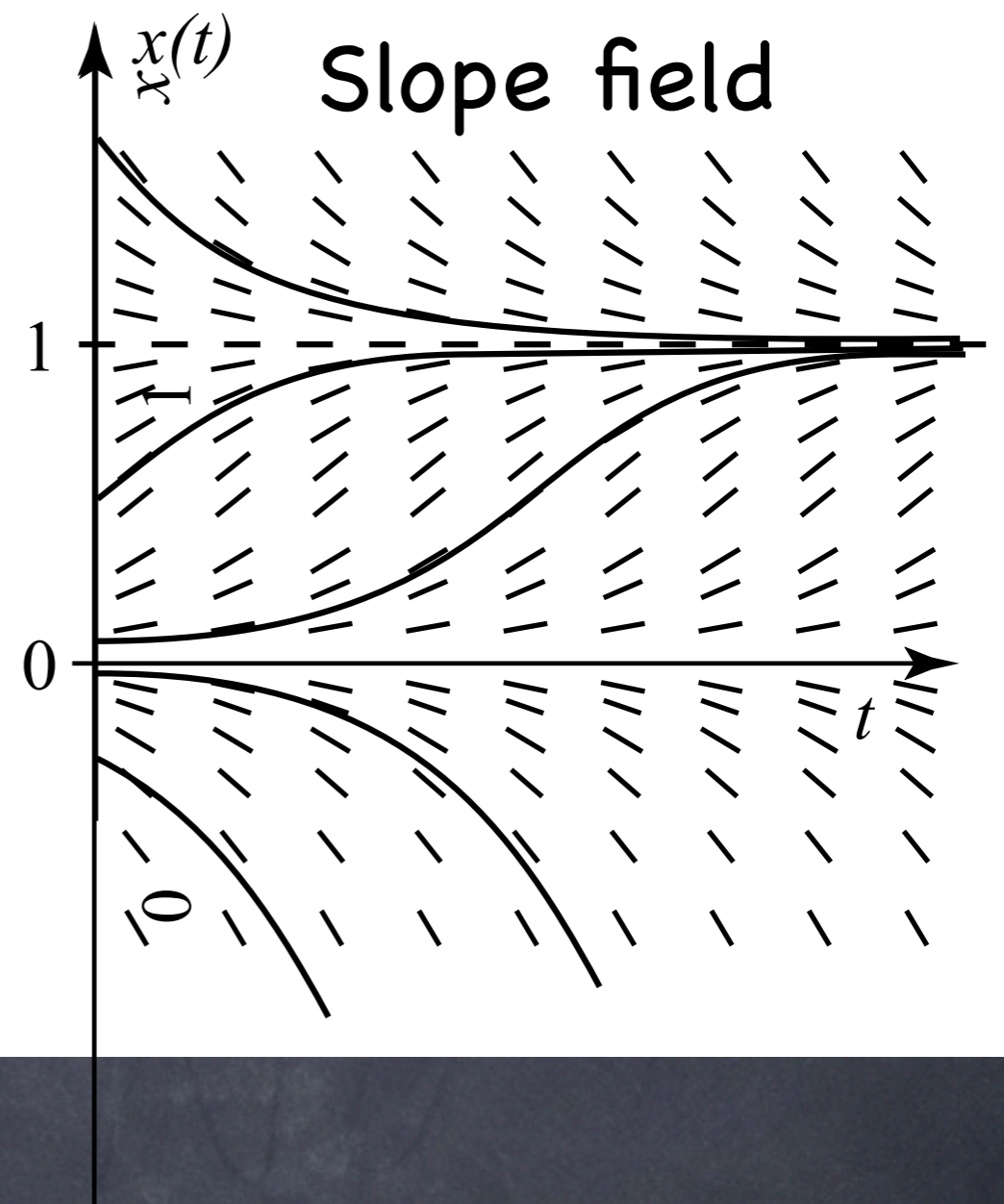
Slope field

- Slope field.
- At any t , don't know x yet so plot all possible x' values
- Now draw them for all t .
- Solution curves must be tangent to slope field everywhere.



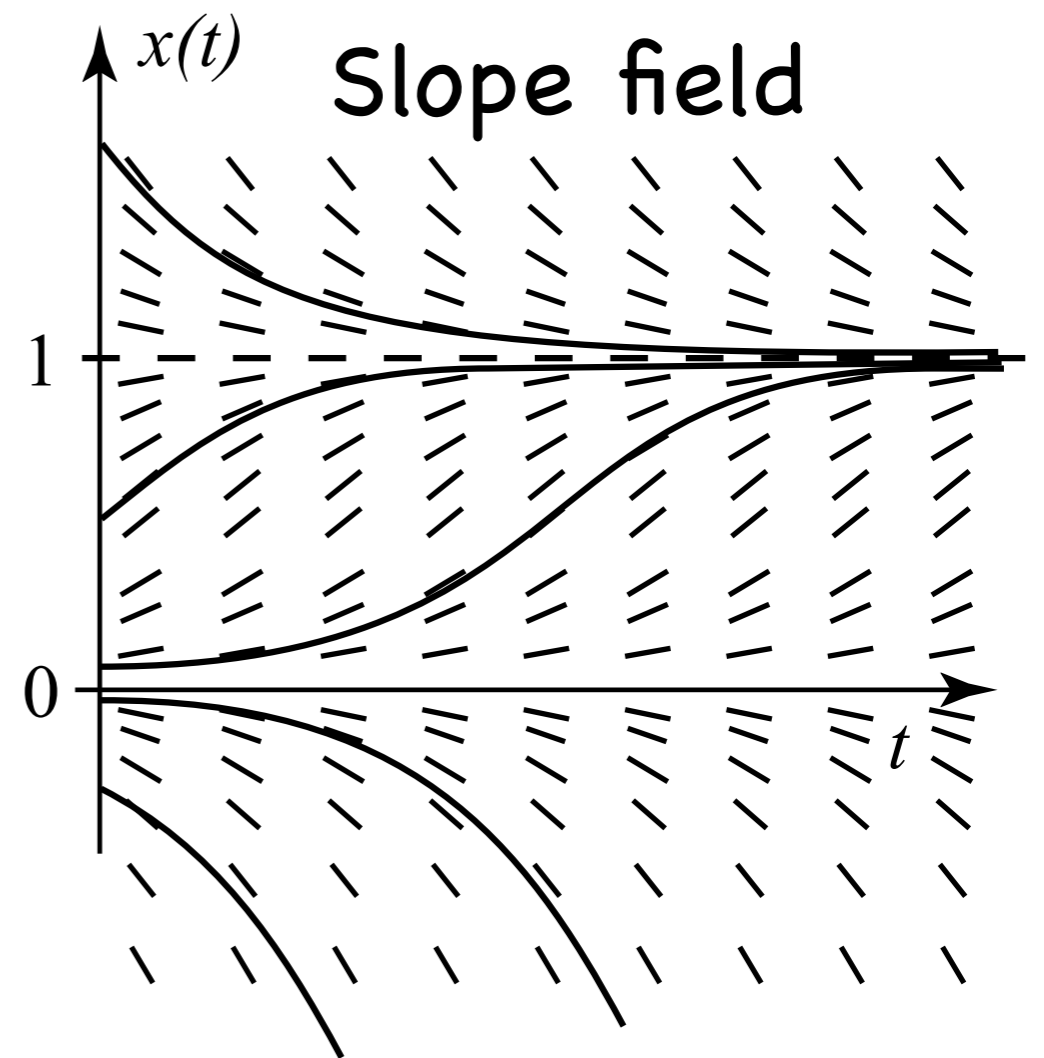
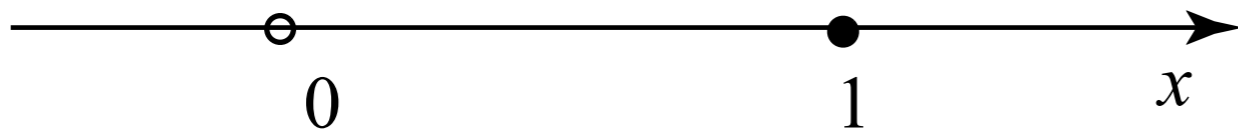
Velocity versus position

Velocity (x') vs. position (x)



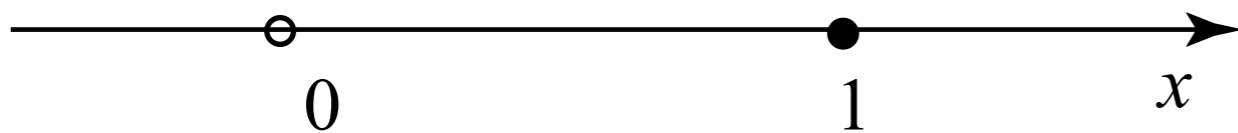
Velocity versus position

Velocity (x') vs. position (x)

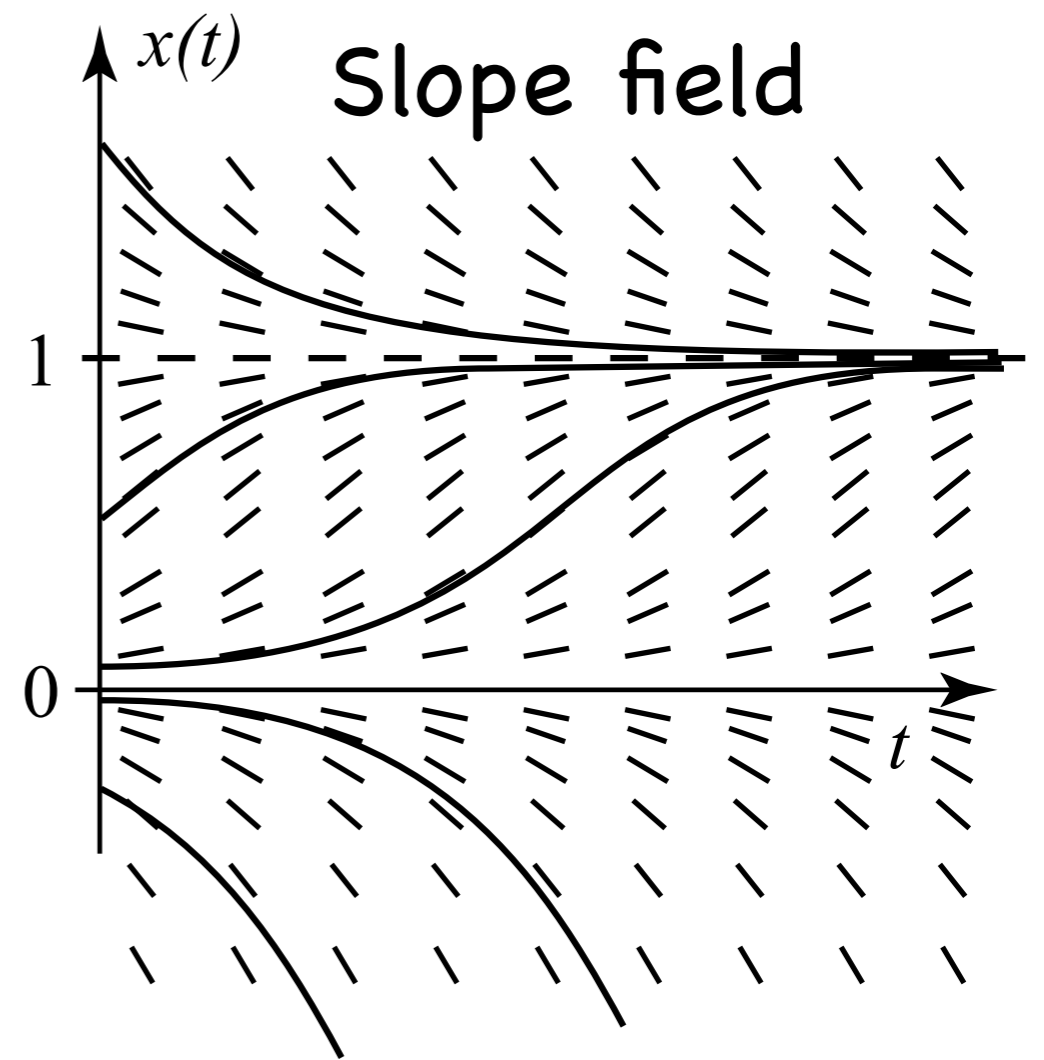


Velocity versus position

Velocity (x') vs. position (x)

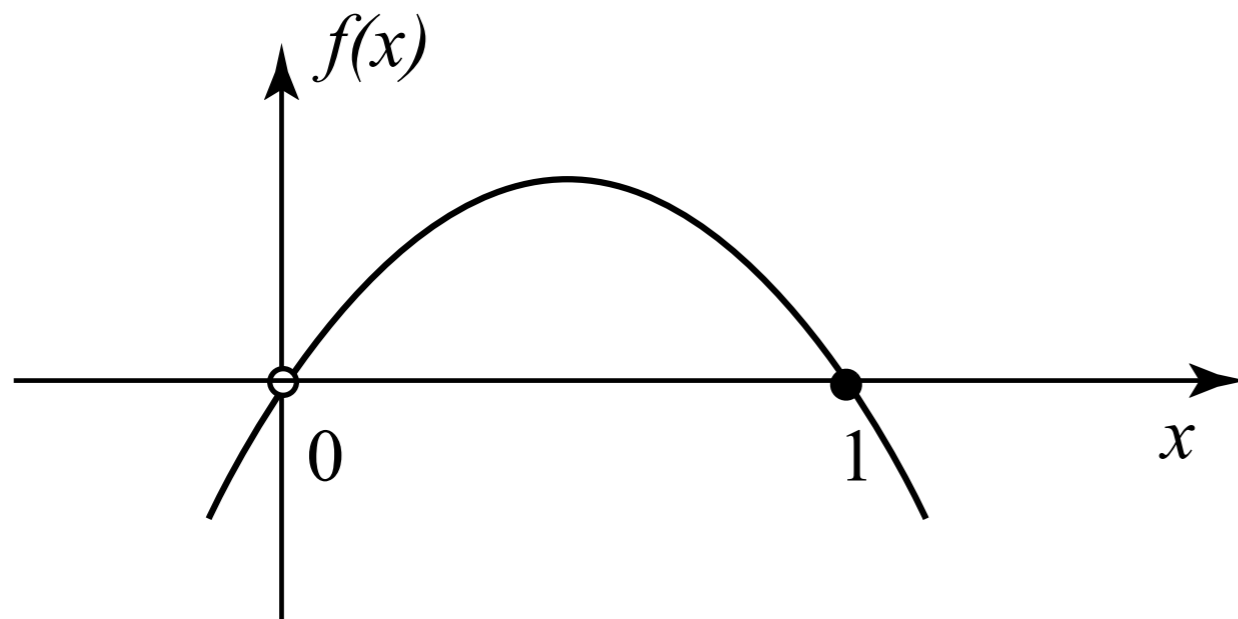


$$x' = f(x) = x(1-x)$$

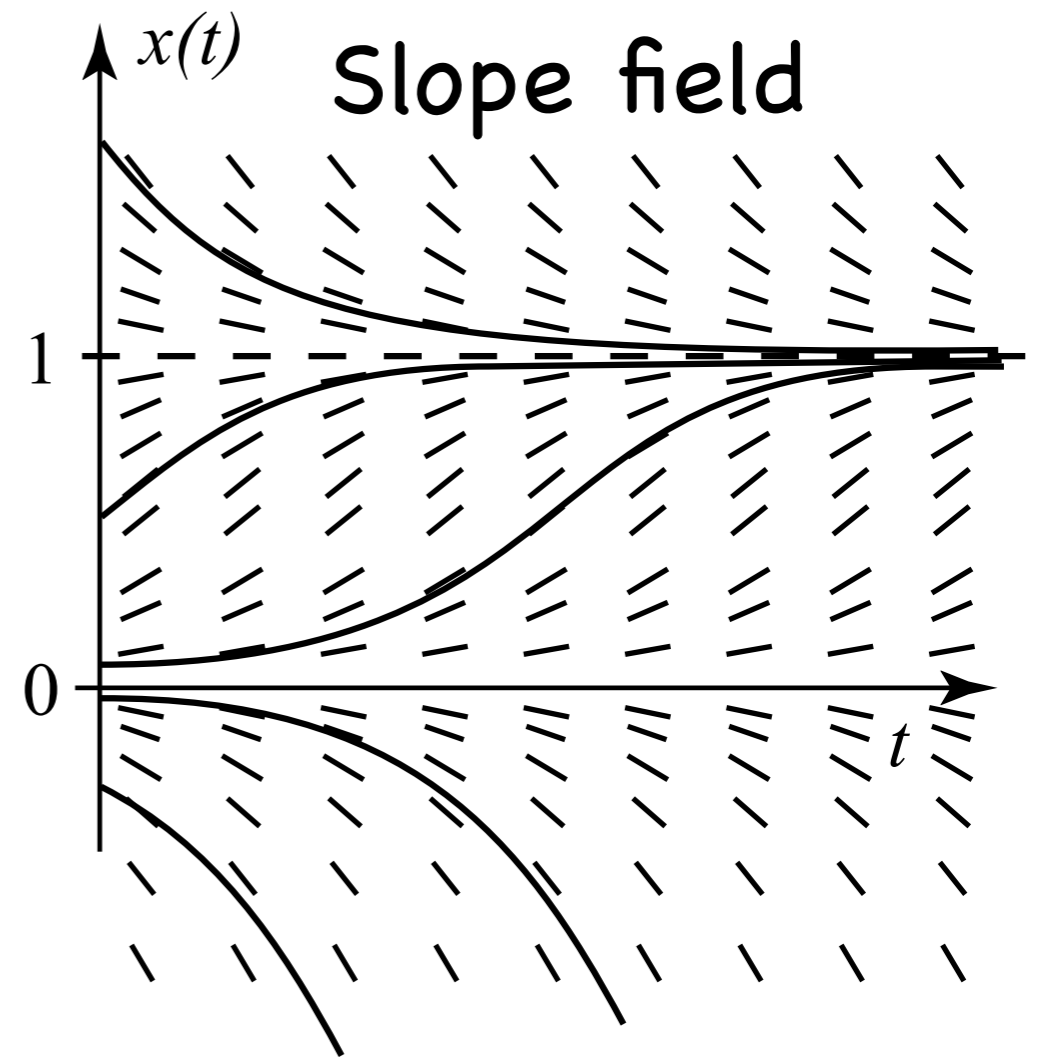


Velocity versus position

Velocity (x') vs. position (x)

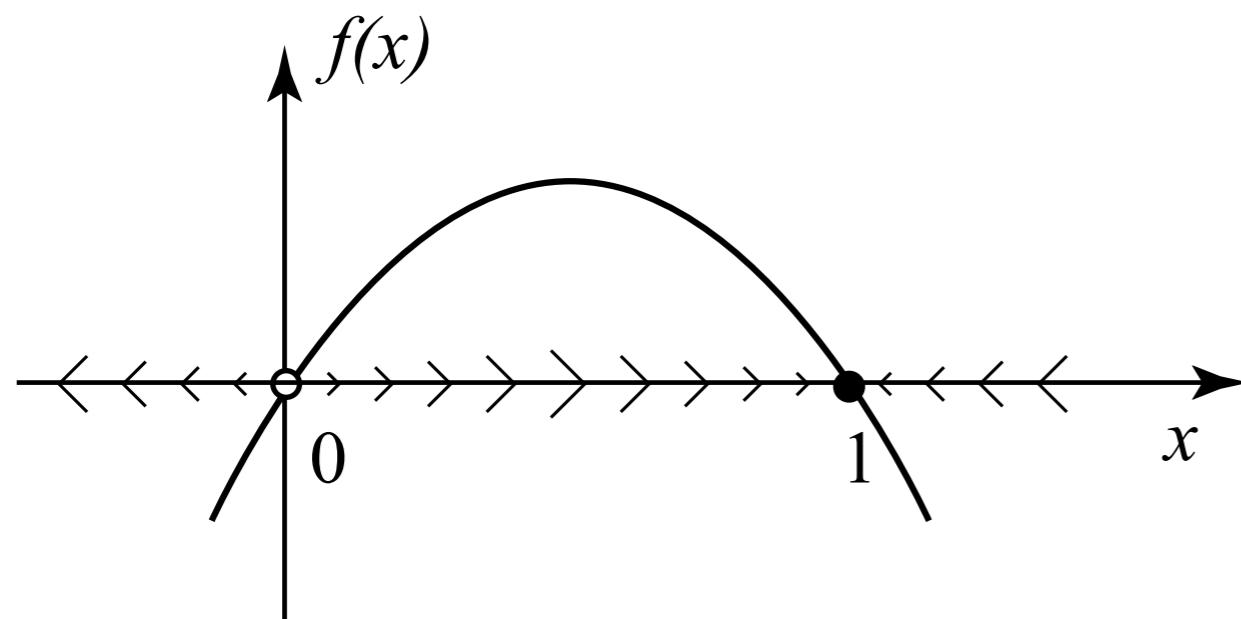


$$x' = f(x) = x(1-x)$$

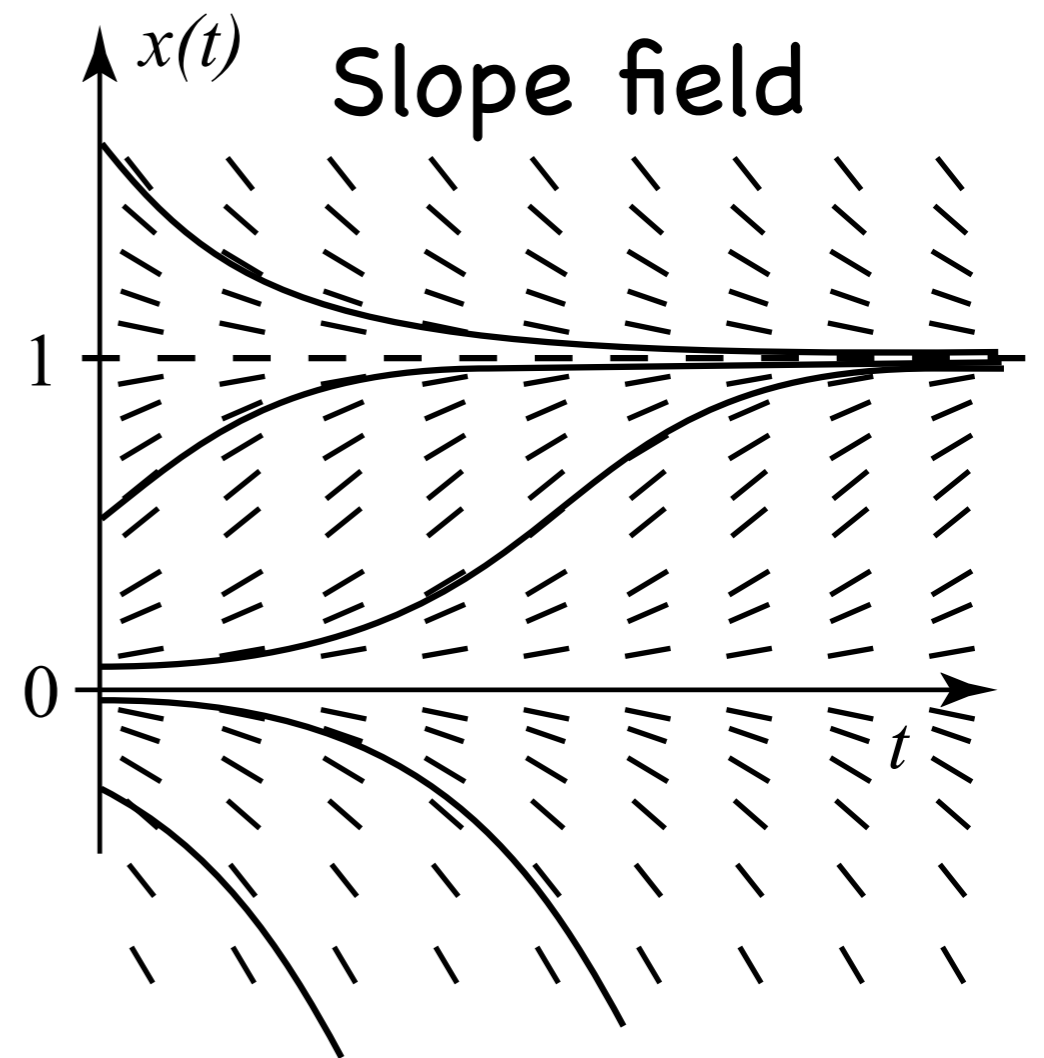


Velocity versus position

Velocity (x') vs. position (x)

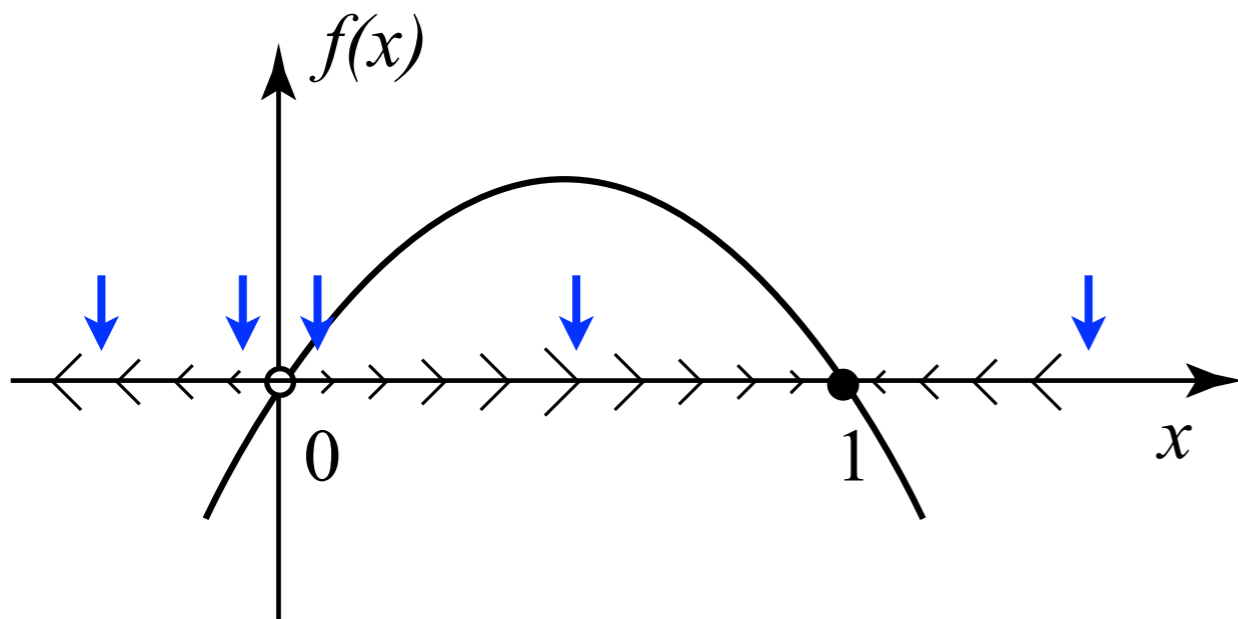


$$x' = f(x) = x(1-x)$$

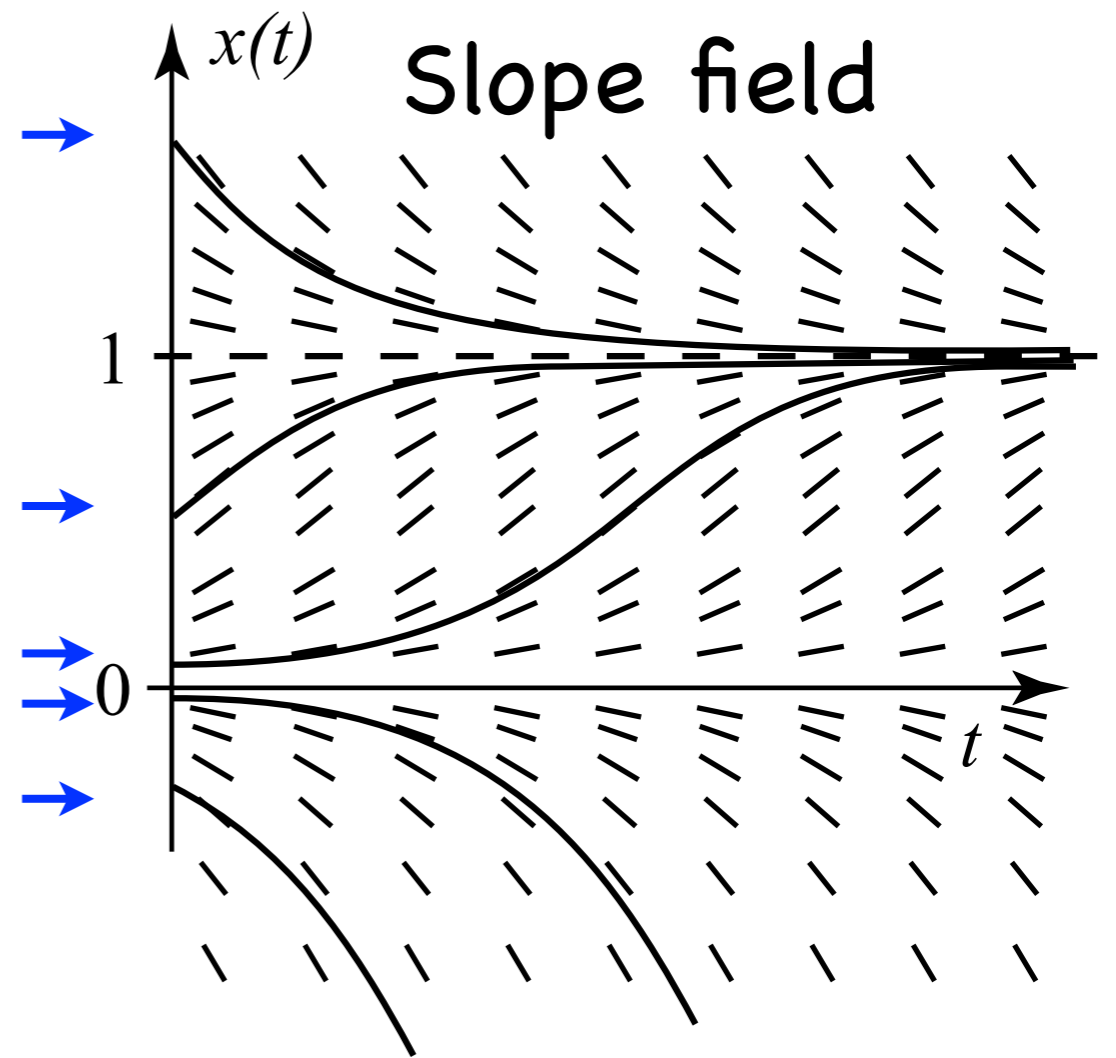


Velocity versus position

Velocity (x') vs. position (x)

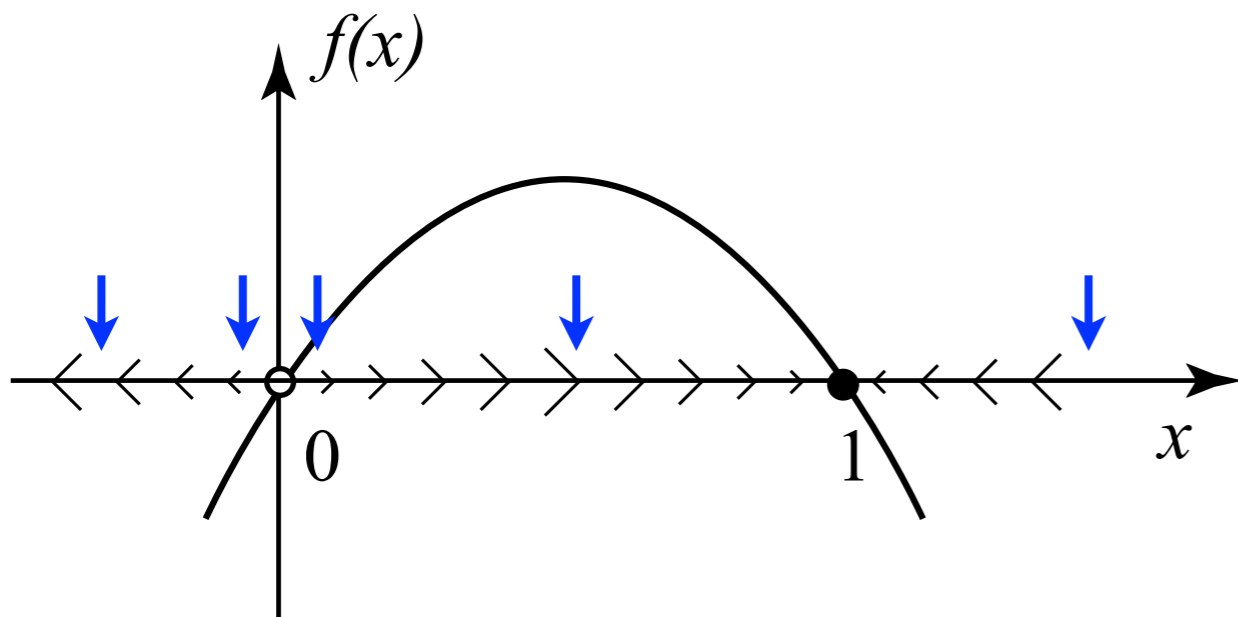


$$x' = f(x) = x(1-x)$$

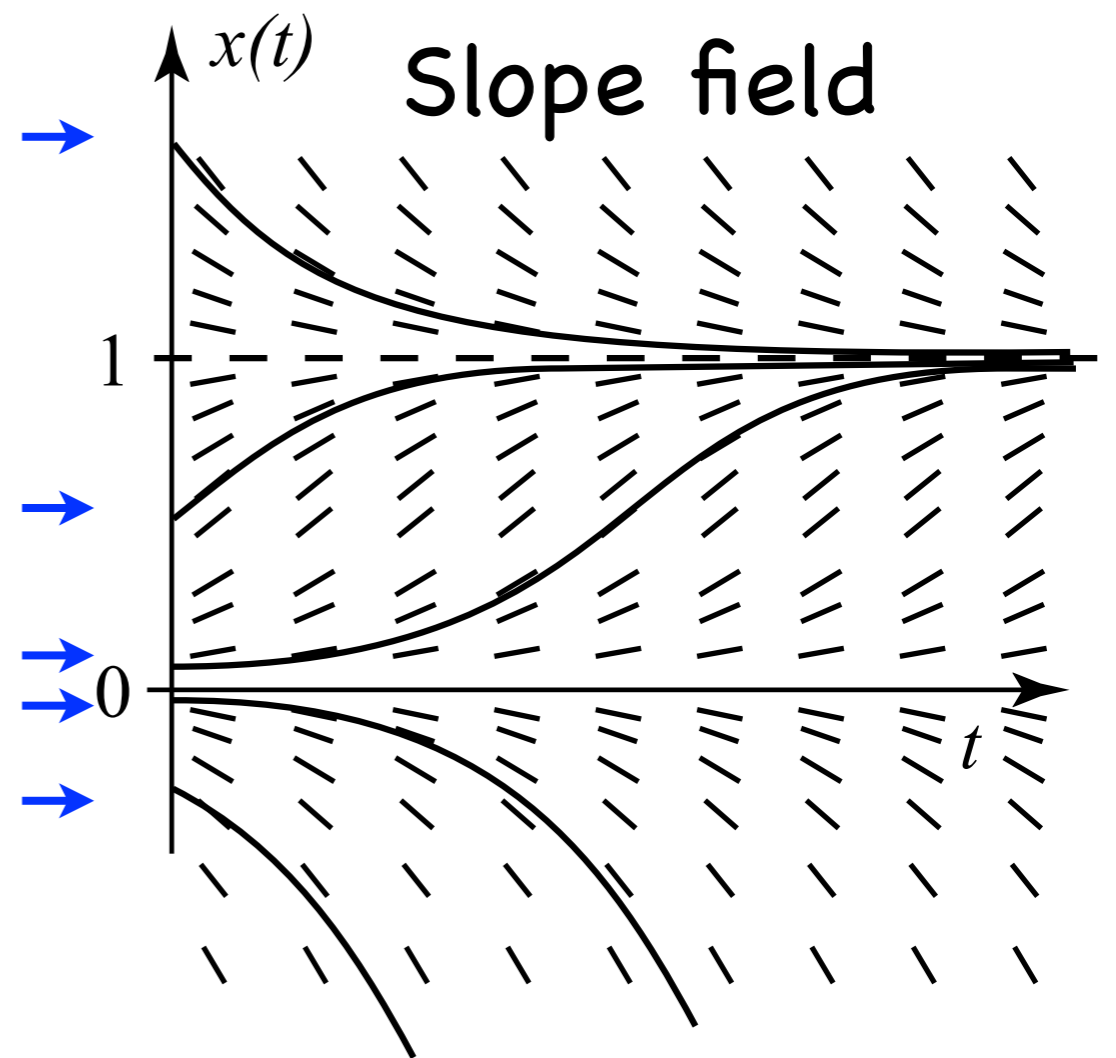


Velocity versus position

Velocity (x') vs. position (x)



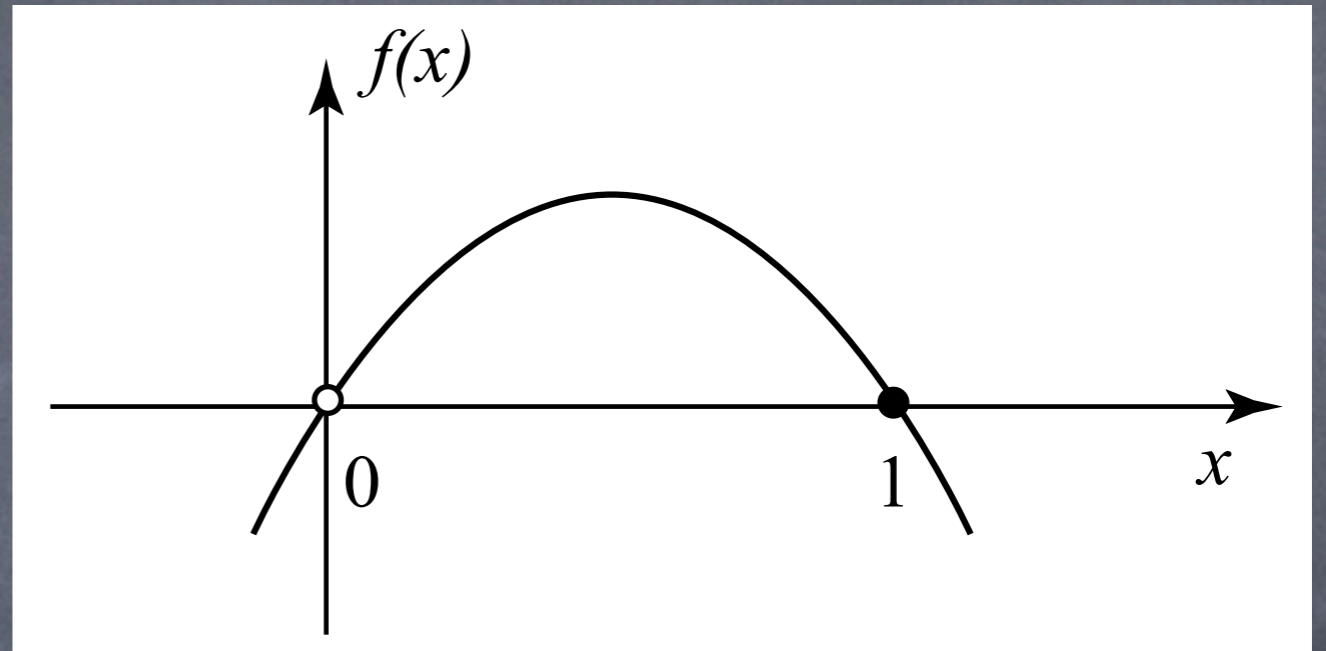
$$x' = f(x) = x(1-x)$$



Stable steady state- all nearby solutions approach
Unstable steady state - not stable

Determine stability

$$x' = x(1 - x)$$



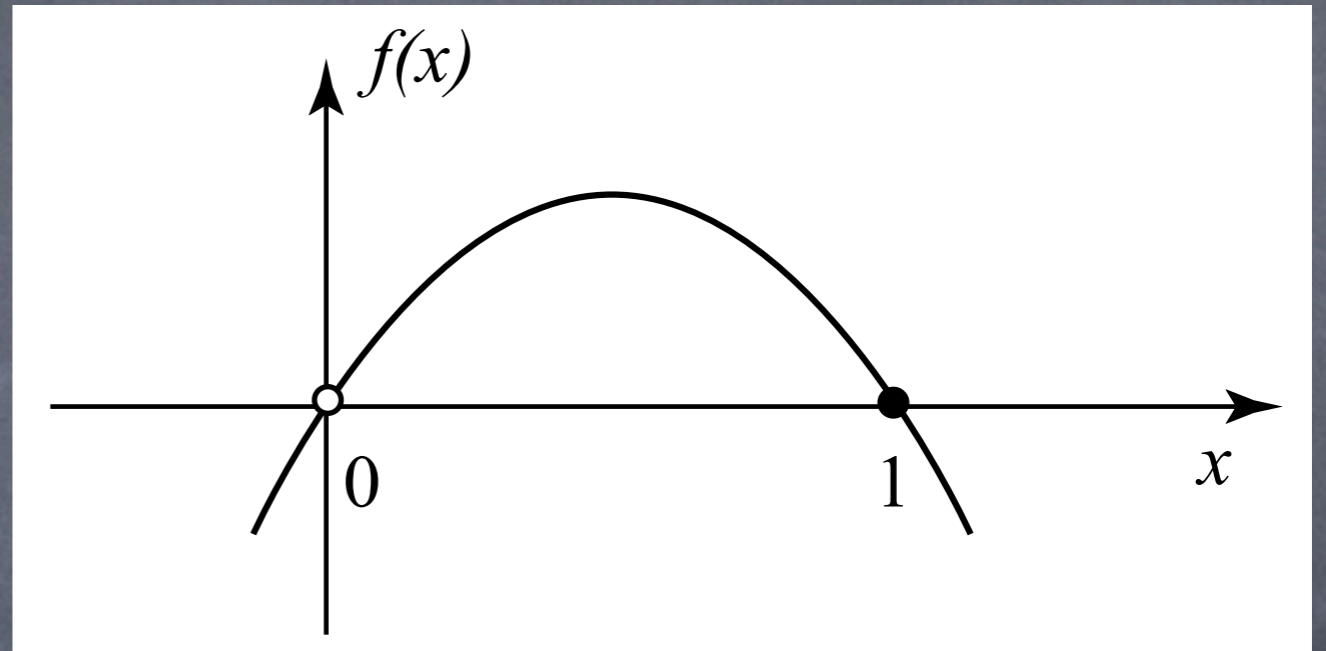
• If you start at $x(0) = -0.01$, the solution

(A) increases

(B) decreases

Determine stability

$$x' = x(1 - x)$$



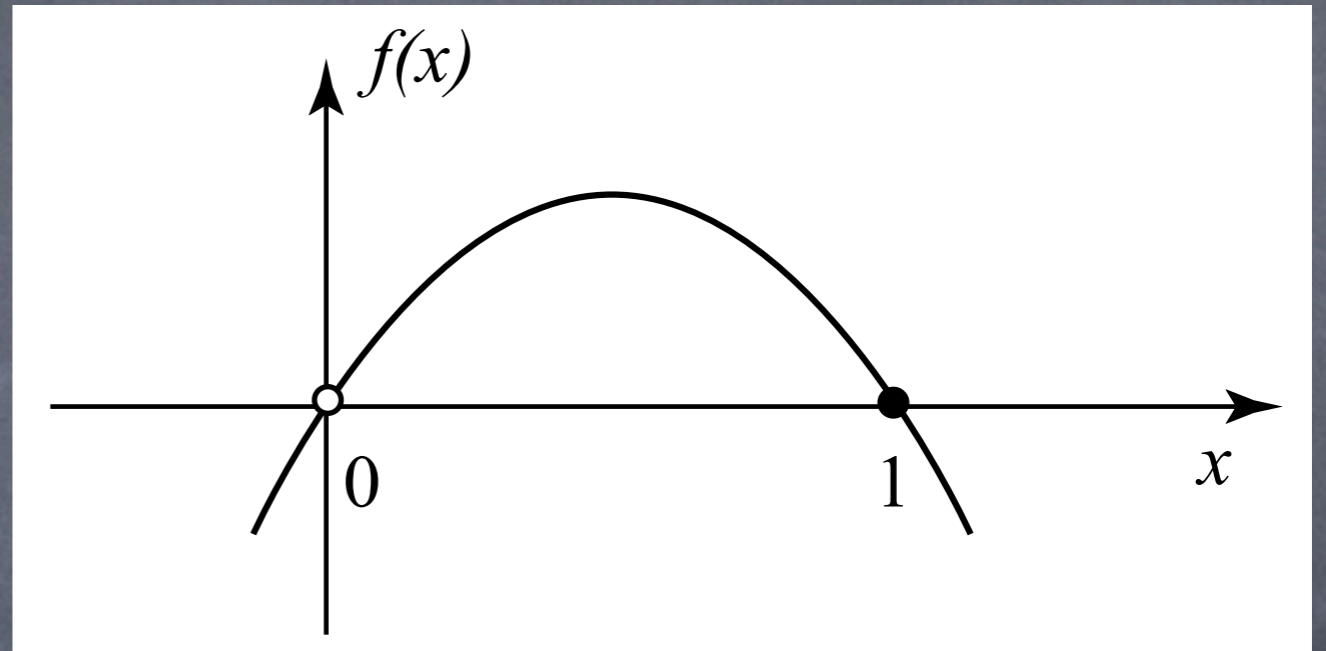
• If you start at $x(0)=0.01$, the solution

(A) increases

(B) decreases

Determine stability

$$x' = x(1 - x)$$



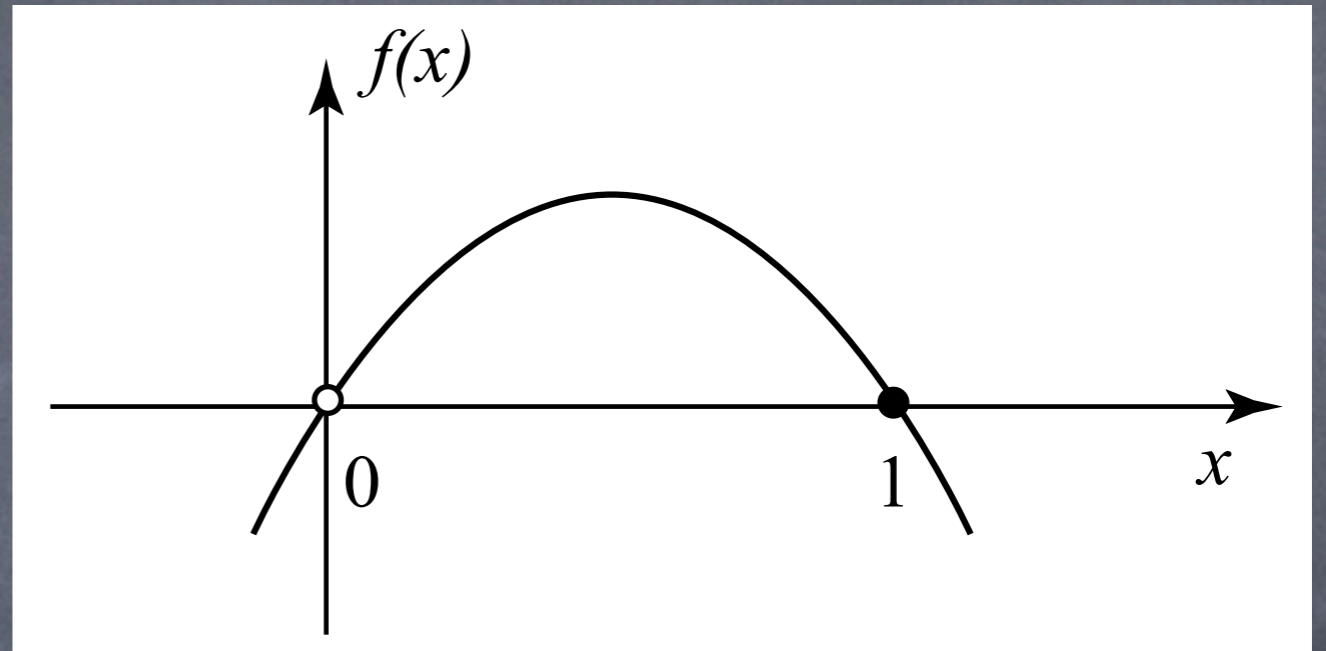
• If you start at $x(0)=0.99$, the solution

(A) increases

(B) decreases

Determine stability

$$x' = x(1 - x)$$



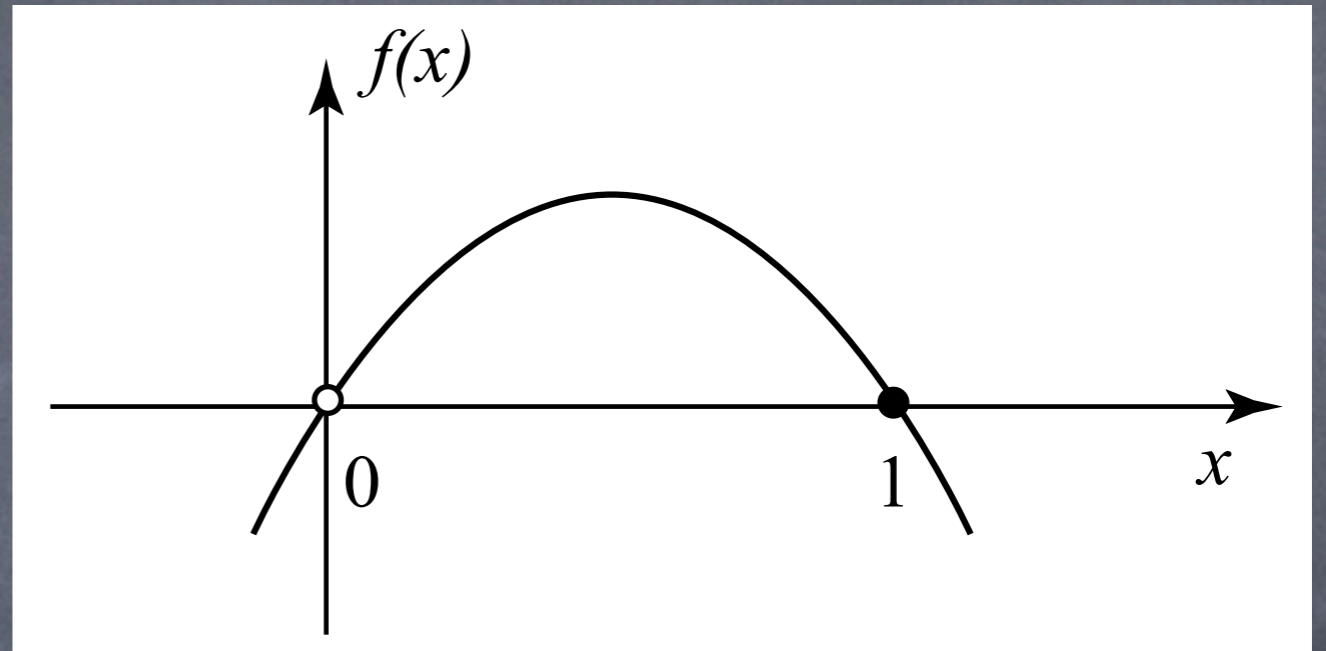
• If you start at $x(0)=1.01$, the solution

(A) increases

(B) decreases

Determine stability

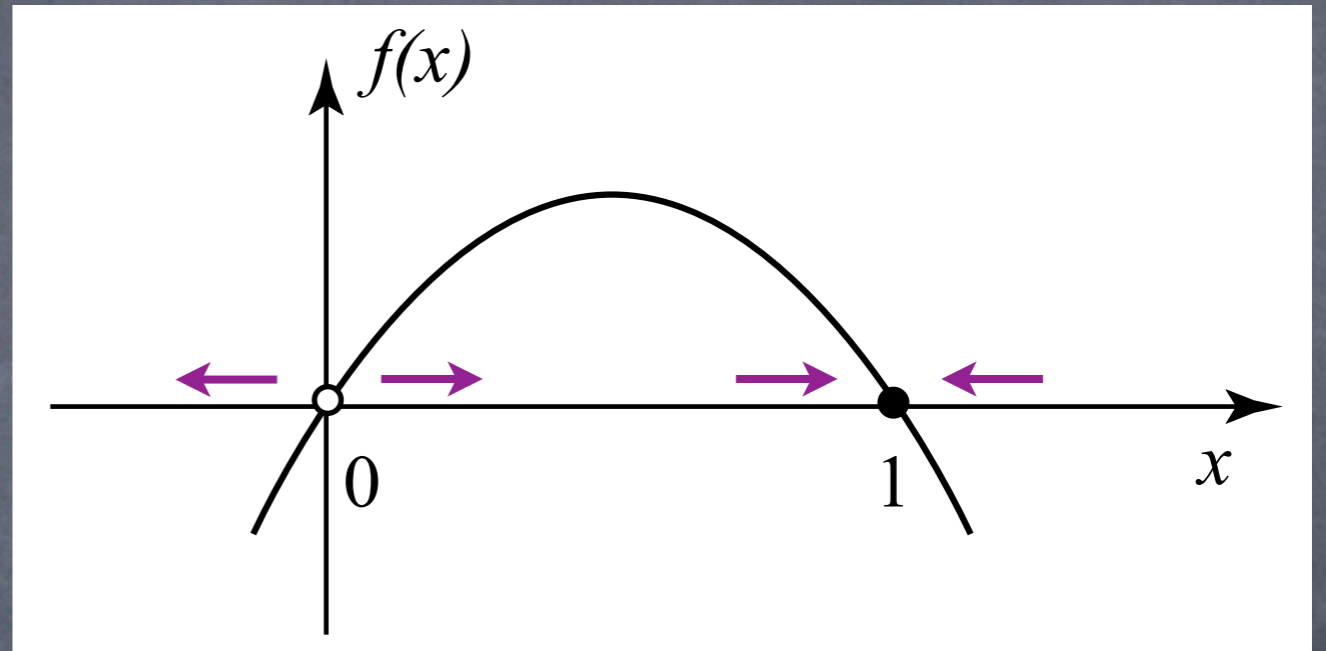
$$x' = x(1 - x)$$



- (A) Both $x(t)=0$ and $x(t)=1$ are stable steady states.
- (B) $x(t)=0$ is stable and $x(t)=1$ is unstable.
- (C) $x(t)=0$ is unstable and $x(t)=1$ is stable.
- (D) Both $x(t)=0$ and $x(t)=1$ are unstable steady states.

Determine stability

$$x' = x(1 - x)$$



- (A) Both $x(t)=0$ and $x(t)=1$ are stable steady states.
- (B) $x(t)=0$ is stable and $x(t)=1$ is unstable.
- (C) $x(t)=0$ is unstable and $x(t)=1$ is stable.
- (D) Both $x(t)=0$ and $x(t)=1$ are unstable steady states.

Stable - solid dot. Unstable - empty dot.