# Today

- General solution for complex eigenvalues case.
- Shapes of solutions for complex eigenvalues case.

### Calculating eigenvalues - trace/det shortcut

For the general matrix

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

• find the characteristic equation and solve it to find the eigenvalues.

(A) 
$$\lambda^2 + (ad - bc)\lambda + a + d = 0$$

(B) 
$$\lambda^2 + (b+c)\lambda + ac - bd = 0$$

(C) 
$$\lambda^2 - (a+d)\lambda + ad - bc = 0$$

(D) 
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$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

• find the characteristic equation and solve it to find the eigenvalues.

(A) 
$$\lambda^2$$
 
$$\lambda^2 - \operatorname{tr}(A)\lambda + \det(A) = 0$$
 (B)  $\lambda^2 + (\upsilon + c)\lambda + ac - \upsilon a = 0$ 

$$(C) \lambda^2 - (a+d)\lambda + ad - bc = 0$$

(D) 
$$\lambda^2 + (a - d)\lambda + ad + bc = 0$$

- ullet Find the general solution to  $\mathbf{x}' = \begin{pmatrix} 1 & 1 \\ -4 & 1 \end{pmatrix} \mathbf{x}$  .
  - The eigenvalues are

(A) 
$$\lambda = 1 \pm 2i$$

(B) 
$$\lambda = -1, 3$$

(C) 
$$\lambda = 2 \pm 4i$$

(D) 
$$\lambda = -2, 6$$

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• The eigenvectors are . . .

$$A - \lambda_1 I = \begin{pmatrix} 1 - (1+2i) & 1 \\ -4 & 1 - (1+2i) \end{pmatrix}$$
$$= \begin{pmatrix} -2i & 1 \\ -4 & -2i \end{pmatrix} \times \frac{1}{2}i$$
$$\sim \begin{pmatrix} -2i & 1 \\ -2i & 1 \end{pmatrix}$$
$$\mathbf{v_1} = \begin{pmatrix} 1 \\ 2i \end{pmatrix}$$

$$\mathbf{v_2} = \begin{pmatrix} 1 \\ -2i \end{pmatrix}$$

• We could just write down a (complex valued) general solution:

$$\mathbf{x}(\mathbf{t}) = C_1 e^{(1+2i)t} \begin{pmatrix} 1\\2i \end{pmatrix} + C_2 e^{(1-2i)t} \begin{pmatrix} 1\\-2i \end{pmatrix}$$

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$$\mathbf{x}' = \begin{pmatrix} 1 & 1 \\ -4 & 1 \end{pmatrix} \mathbf{x} \qquad \Rightarrow \qquad \begin{aligned} x_1' &= x_1 + x_2 \\ x_2' &= -4x_1 + x_2 \end{aligned}$$



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$$x''_{1} = x'_{1} + x'_{2}$$

$$x''_{1} = x'_{1} - 4x_{1} + x_{2}$$

$$x''_{1} = x'_{1} - 4x_{1} + x'_{2}$$

$$x''_{1} = x'_{1} - 4x_{1} + x'_{1} - x_{1}$$

$$x''_{1} - 2x'_{1} + 5x_{1} = 0$$

$$r^{2} - 2r + 5 = 0$$

$$r = 1 \pm 2i$$

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$$\mathbf{x}' = \begin{pmatrix} 1 & 1 \\ -4 & 1 \end{pmatrix} \mathbf{x} \Rightarrow \begin{cases} x_1' = x_1 + x_2 \\ x_2' = -4x_1 + x_2 \end{cases}$$

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$$r = 1 \pm 2i$$
  $x_1(t) = e^t(C_1\cos(2t) + C_2\sin(2t))$ 



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$$r = 1 \pm 2i x_1(t) = e^t (C_1 \cos(2t) + C_2 \sin(2t))$$

$$x'_1(t) = e^t (-2C_1 \sin(2t) + 2C_2 \cos(2t))$$

$$+e^t (C_1 \cos(2t) + C_2 \sin(2t))$$

$$x_2 = x'_1 - x_1 = e^t (-2C_1 \sin(2t) + 2C_2 \cos(2t))$$

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$$\mathbf{x}' = \begin{pmatrix} 1 & 1 \\ -4 & 1 \end{pmatrix} \mathbf{x} \implies \begin{aligned} x'_1 &= x_1 + x_2 \\ x'_2 &= -4x_1 + x_2 \\ x_1(t) &= e^t (C_1 \cos(2t) + C_2 \sin(2t)) \\ x_2(t) &= e^t (-2C_1 \sin(2t) + 2C_2 \cos(2t)) \end{aligned}$$

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If we want real valued solutions. 
$$\mathbf{x}' = \begin{pmatrix} 1 & 1 \\ -4 & 1 \end{pmatrix} \mathbf{x} \quad \Rightarrow \quad \begin{aligned} x_1' &= x_1 + x_2 \\ x_2' &= -4x_1 + x_2 \end{aligned} \begin{pmatrix} 1 \\ 2i \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 2 \end{pmatrix} i \\ x_2(t) &= e^t (C_1 \cos(2t) + C_2 \sin(2t)) \\ x_2(t) &= e^t (-2C_1 \sin(2t) + 2C_2 \cos(2t)) \\ \mathbf{x}(\mathbf{t}) &= e^t \left( C_1 \left( \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2t) - \begin{pmatrix} 0 \\ 2 \end{pmatrix} \sin(2t) \right) \\ + C_2 \left( \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2t) + \begin{pmatrix} 0 \\ 2 \end{pmatrix} \cos(2t) \right) \right) \end{aligned}$$

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 Alternatively, multiply out the complex solution and extract real and imaginary parts:

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• Simple case:  $C_1 = 1, \ C_2 = 0$ 

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$$\mathbf{x}(\mathbf{t}) = e^{(1+2i)t} \begin{pmatrix} 1\\2i \end{pmatrix}$$

$$= e^{t} (\cos(2t) + i\sin(2t)) \left( \begin{pmatrix} 1\\0 \end{pmatrix} + \begin{pmatrix} 0\\2 \end{pmatrix} i \right)$$

$$= e^{t} \left[ \begin{pmatrix} 1\\0 \end{pmatrix} \cos(2t) - \begin{pmatrix} 0\\2 \end{pmatrix} \sin(2t) \right]$$

$$+ e^{t} \left[ \begin{pmatrix} 1\\0 \end{pmatrix} \sin(2t) + \begin{pmatrix} 0\\2 \end{pmatrix} \cos(2t) \right] i$$

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ullet Find e-values,  $\lambda=lpha\pmeta i$  , and e-vectors,  $\mathbf{v}=egin{pmatrix} a_1\ a_2 \end{pmatrix}\pm i egin{pmatrix} b_1\ b_2 \end{pmatrix}$  .

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$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[ C_1 \left( \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \cos(\beta t) - \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \sin(\beta t) \right) + C_2 \left( \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \sin(\beta t) + \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \cos(\beta t) \right) \right]$$

• Find e-values,  $\lambda=\alpha\pm\beta i$  , and e-vectors,  ${f v}=\begin{pmatrix} a_1\\a_2\end{pmatrix}\pm i\begin{pmatrix} b_1\\b_2\end{pmatrix}$ .  $={f a}+i{f b}$ 

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[ C_1 \left( \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \cos(\beta t) - \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \sin(\beta t) \right) + C_2 \left( \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \sin(\beta t) + \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \cos(\beta t) \right) \right]$$

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[ C_1 \left( \mathbf{a} \cos(\beta t) - \mathbf{b} \sin(\beta t) \right) + C_2 \left( \mathbf{a} \sin(\beta t) + \mathbf{b} \cos(\beta t) \right) \right]$$

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• Suppose you find eigenvalue  $\lambda=2\pi i$  and eigenvector  ${\bf v}=\begin{pmatrix}1\\i\end{pmatrix}$  . Which of the following is a solution to the original equation?

(A) 
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

(B) 
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t)$$

(C) 
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t)$$

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(B) 
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t)$$

$$(\mathbf{C}) \quad \mathbf{x}(\mathbf{t}) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t)$$

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$$\overline{\mathbf{x}}(\mathbf{t}) = e^{2\pi i t} \begin{pmatrix} 1 \\ i \end{pmatrix}$$

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$$\overline{\mathbf{x}}(\mathbf{t}) = e^{2\pi i t} \begin{pmatrix} 1 \\ i \end{pmatrix} \\
= (\cos(2\pi t) + i\sin(2\pi t)) \begin{pmatrix} 1 \\ i \end{pmatrix} \\
= \begin{pmatrix} \cos(2\pi t) + i\sin(2\pi t) \\ -\sin(2\pi t) + i\cos(2\pi t) \end{pmatrix} \\
= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t) \\
+i \left[ \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) \right]$$

• Suppose you find eigenvalue  $\lambda=2\pi i$  and eigenvector  ${\bf v}=\begin{pmatrix}1\\i\end{pmatrix}$  . Which of the following is a solution to the original equation?

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= \begin{pmatrix} \cos(2\pi t) + i\sin(2\pi t) \\ -\sin(2\pi t) + i\cos(2\pi t) \end{pmatrix} \\
= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t) \\
+i \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t)$$

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$$egin{aligned} \overline{\mathbf{x}}(\mathbf{t}) &= e^{2\pi i t} egin{pmatrix} 1 \ i \end{pmatrix} \ &= \left(\cos(2\pi t) + i\sin(2\pi t)\right) egin{pmatrix} 1 \ i \end{pmatrix} \ &= \left(\frac{\cos(2\pi t) + i\sin(2\pi t)}{-\sin(2\pi t) + i\cos(2\pi t)}\right) \end{aligned}$$

 Sum and difference trick lets us take the Real and Imaginary parts as two indep.
 solutions

$$= \begin{bmatrix} 1 \\ 0 \end{bmatrix} \cos(2\pi t) + i \cos(2\pi t)$$

$$= \begin{bmatrix} 1 \\ 0 \end{bmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{bmatrix} \sin(2\pi t)$$

$$+i \begin{bmatrix} 0 \\ 1 \end{bmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{bmatrix} \sin(2\pi t)$$

ullet But what about  $\lambda_2=-2\pi i$  and  ${f v_2}=\left(egin{array}{c}1\\-i\end{array}
ight)$ ?

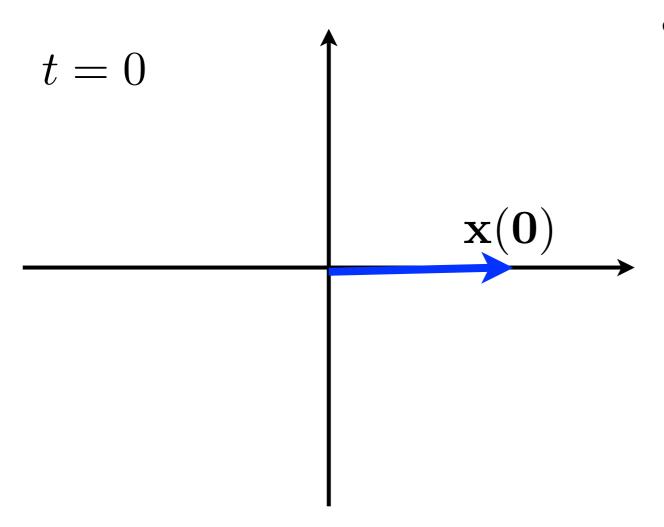
$$\overline{\mathbf{x}}(\mathbf{t}) = e^{-2\pi i t} \begin{pmatrix} 1 \\ -i \end{pmatrix} 
= (\cos(-2\pi t) + i\sin(-2\pi t)) \begin{pmatrix} 1 \\ -i \end{pmatrix} 
= \begin{pmatrix} \cos(2\pi t) - i\sin(2\pi t)) \\ -\sin(2\pi t) - i\cos(2\pi t)) \end{pmatrix} 
= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t) 
-i \begin{bmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) \end{bmatrix}$$

$$ullet$$
 But what about  $\lambda_2 = -2\pi i$  and  $\mathbf{v_2} = \begin{pmatrix} 1 \\ -i \end{pmatrix}$ ?

$$\overline{\mathbf{x}}(\mathbf{t}) = e^{-2\pi i t} \begin{pmatrix} 1 \\ -i \end{pmatrix} \\
= (\cos(-2\pi t) + i\sin(-2\pi t)) \begin{pmatrix} 1 \\ -i \end{pmatrix} \\
= \begin{pmatrix} \cos(2\pi t) - i\sin(2\pi t) \\ -\sin(2\pi t) - i\cos(2\pi t) \end{pmatrix} \\
= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t) \\
-i \begin{bmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) \end{bmatrix}$$

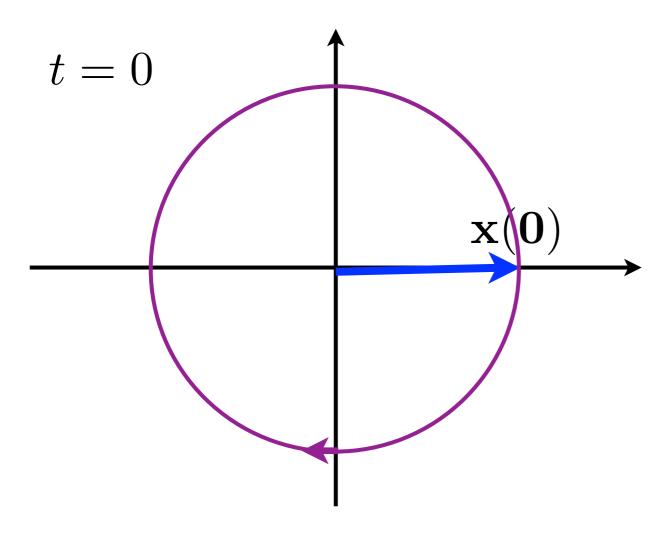
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



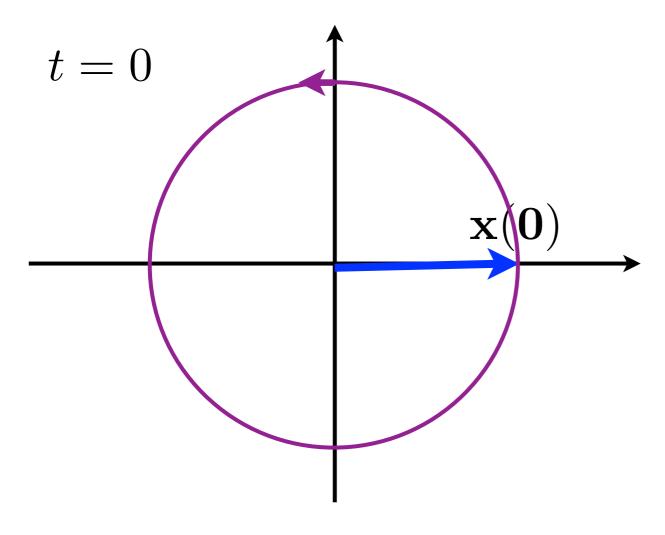
What happens as t increases?

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



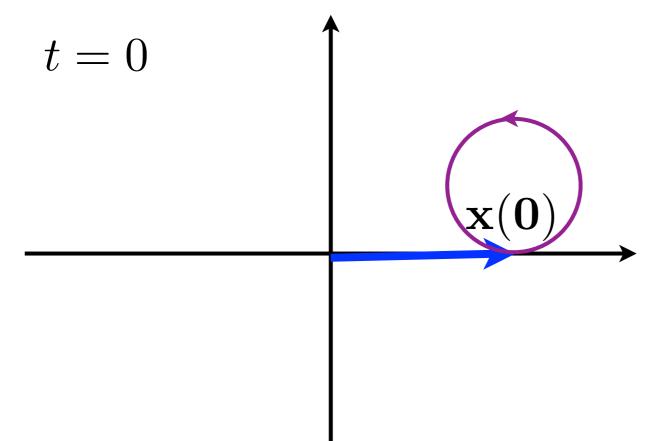
- What happens as t increases?
  - (A) The vector rotates clockwise.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



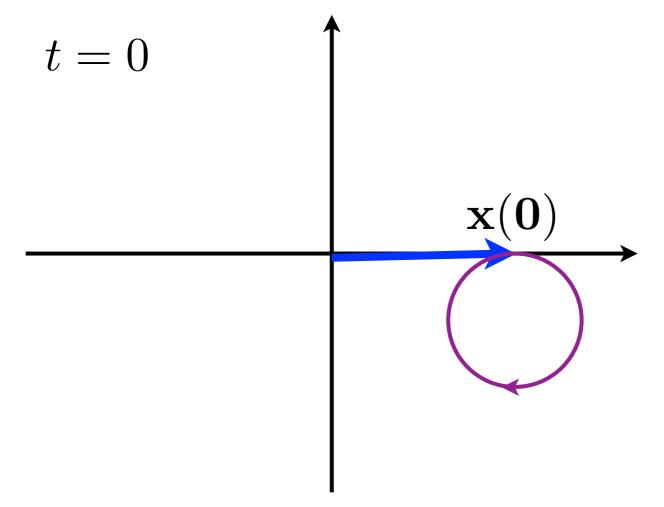
- What happens as t increases?
  - (A) The vector rotates clockwise.
  - (B) The vector rotates counterclockwise.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



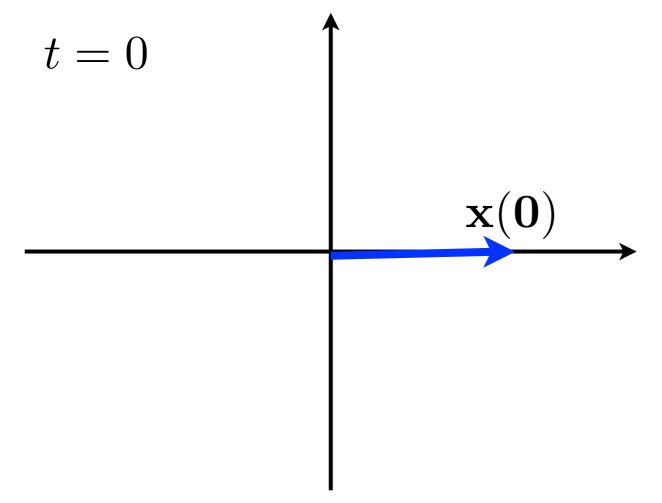
- What happens as t increases?
  - (A) The vector rotates clockwise.
  - (B) The vector rotates counterclockwise.
  - (C) The tip of the vector maps out a circle in the first quadrant.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



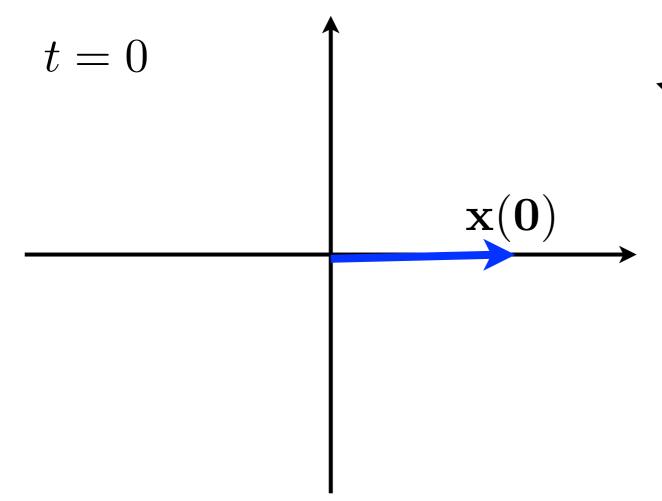
- What happens as t increases?
  - (A) The vector rotates clockwise.
  - (B) The vector rotates counterclockwise.
  - (C) The tip of the vector maps out a circle in the first quadrant.
  - (D) The tip of the vector maps out a circle in the fourth quadrant.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



- What happens as t increases?
  - (A) The vector rotates clockwise.
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  - (C) The tip of the vector maps out a circle in the first quadrant.
  - (D) The tip of the vector maps out a circle in the fourth quadrant.
  - (E) Explain please.

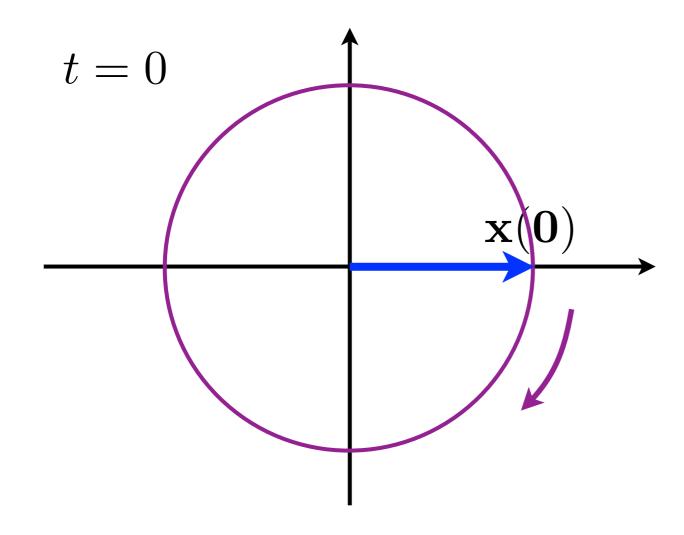
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



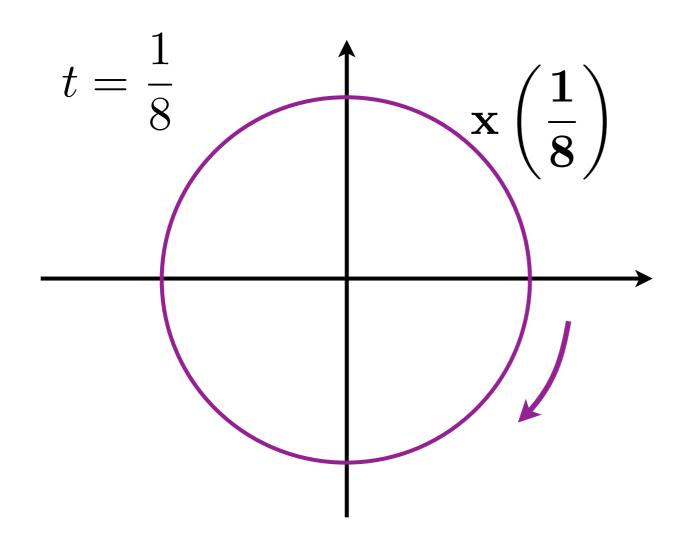
What happens as t increases?

- (A) The vector rotates clockwise.
  - (B) The vector rotates counterclockwise.
  - (C) The tip of the vector maps out a circle in the first quadrant.
  - (D) The tip of the vector maps out a circle in the fourth quadrant.
  - (E) Explain please.

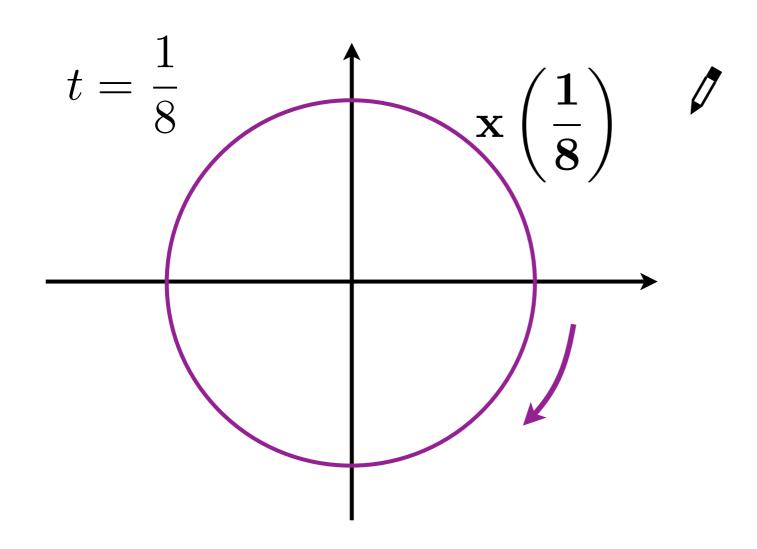
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



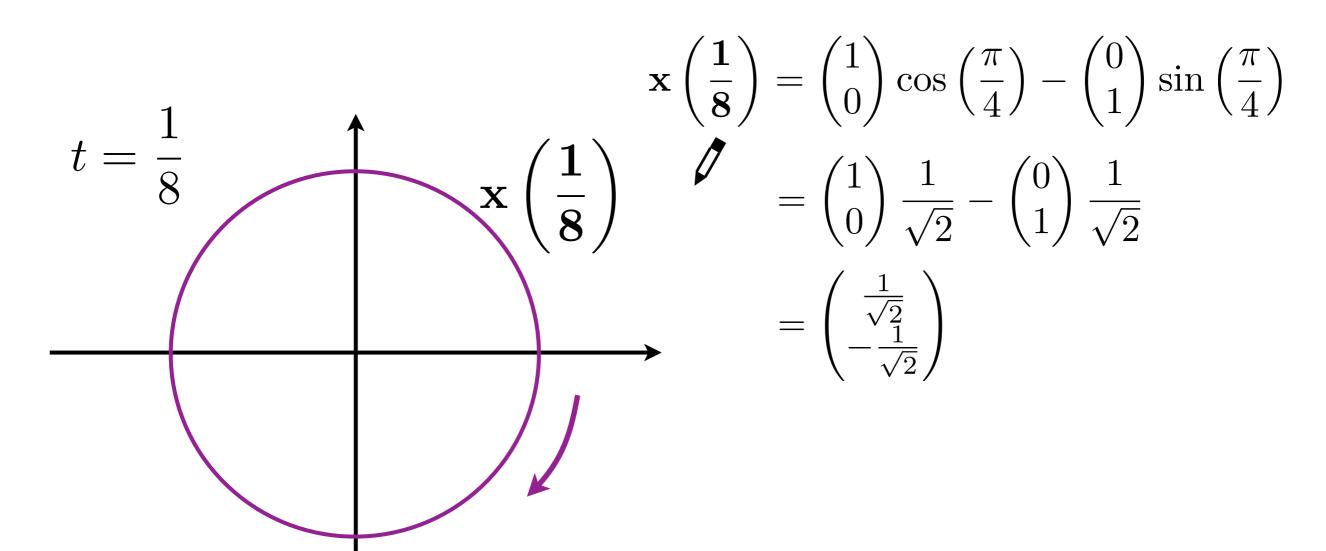
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



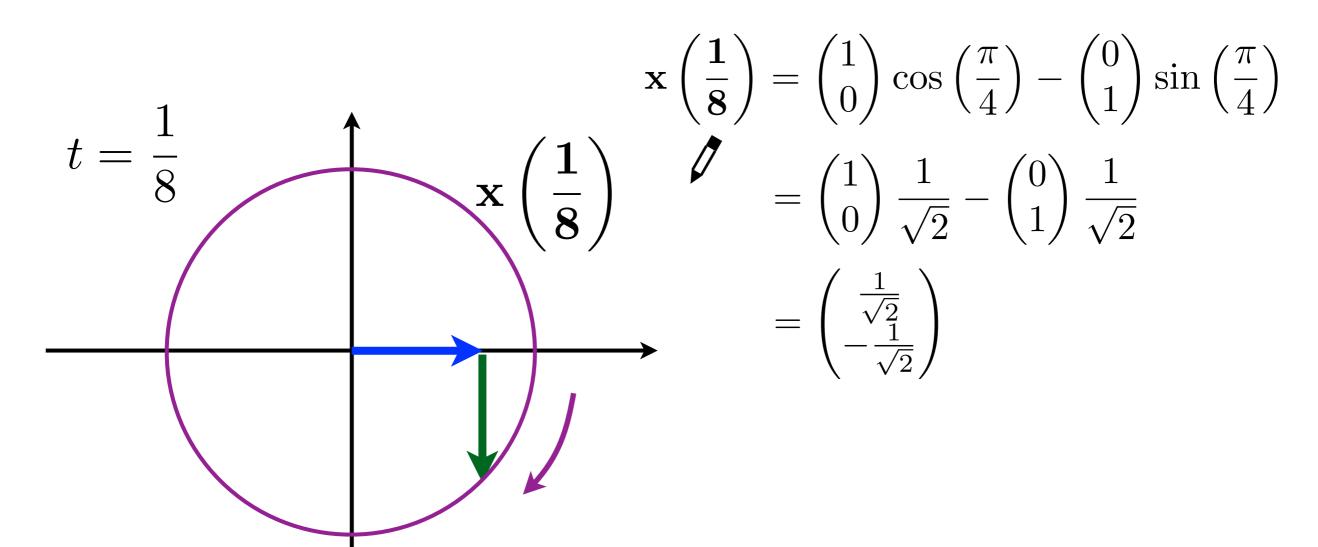
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



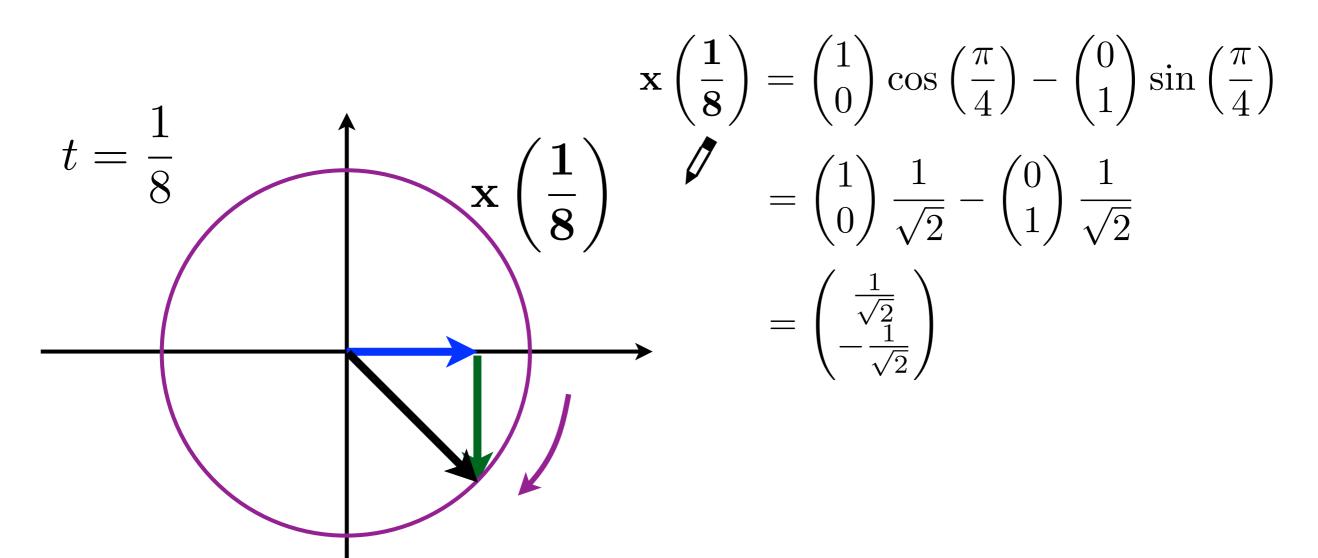
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



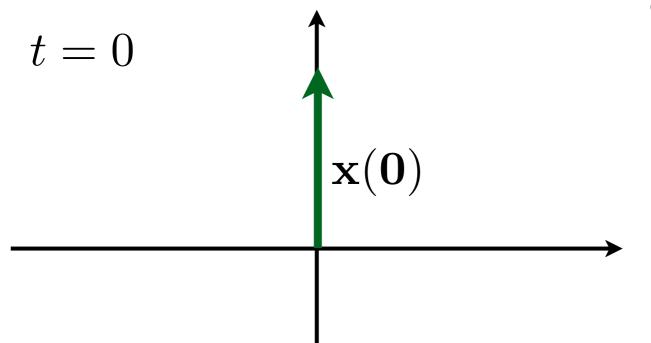
Same equation, initial condition chosen so that C₁=0 and C₂=1.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t)$$

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[ C_1 \left( \mathbf{a} \cos(\beta t) - \mathbf{b} \sin(\beta t) \right) + C_2 \left( \mathbf{a} \sin(\beta t) + \mathbf{b} \cos(\beta t) \right) \right]$$

Same equation, initial condition chosen so that C₁=0 and C₂=1.

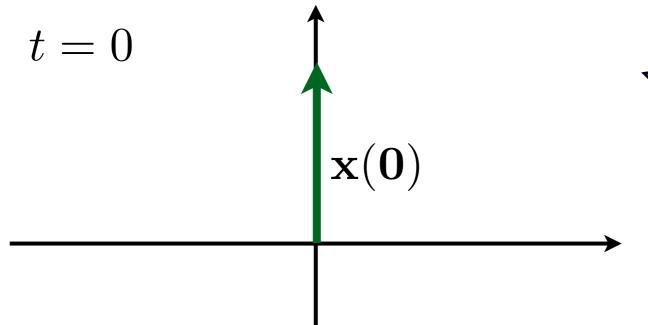
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t)$$



- What happens as t increases?
  - (A) The vector rotates clockwise.
  - (B) The vector rotates counterclockwise.
  - (C) The tip of the vector maps out a circle in the first quadrant.
  - (D) The tip of the vector maps out a circle in the second quadrant.
  - (E) Explain please.

Same equation, initial condition chosen so that C₁=0 and C₂=1.

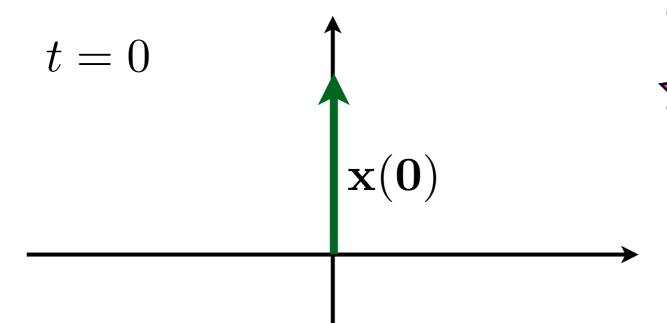
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t)$$



- What happens as t increases?
- (A) The vector rotates clockwise.
  - (B) The vector rotates counterclockwise.
  - (C) The tip of the vector maps out a circle in the first quadrant.
  - (D) The tip of the vector maps out a circle in the second quadrant.
  - (E) Explain please.

Same equation, initial condition chosen so that C₁=0 and C₂=1.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t)$$



"Same" solution as before, just π/2 delayed.

- What happens as t increases?
- (A) The vector rotates clockwise.
  - (B) The vector rotates counterclockwise.
  - (C) The tip of the vector maps out a circle in the first quadrant.
  - (D) The tip of the vector maps out a circle in the second quadrant.
  - (E) Explain please.

Looking at the general solution again...

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[ C_1 \left( \mathbf{a} \cos(\beta t) - \mathbf{b} \sin(\beta t) \right) + C_2 \left( \mathbf{a} \sin(\beta t) + \mathbf{b} \cos(\beta t) \right) \right]$$

Looking at the general solution again...

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[ C_1 \left( \mathbf{a} \cos(\beta t) - \mathbf{b} \sin(\beta t) \right) + C_2 \left( \mathbf{a} \sin(\beta t) + \mathbf{b} \cos(\beta t) \right) \right]$$

• Both parts rotate in the exact same way but the C<sub>2</sub> part is delayed by a quarter phase.

Looking at the general solution again...

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[ C_1 \left( \mathbf{a} \cos(\beta t) - \mathbf{b} \sin(\beta t) \right) + C_2 \left( \mathbf{a} \sin(\beta t) + \mathbf{b} \cos(\beta t) \right) \right]$$

- Both parts rotate in the exact same way but the C<sub>2</sub> part is delayed by a quarter phase.
- If an initial condition lies neither parallel to vector a nor to vector b, C<sub>1</sub>
   and C2 allow for intermediate phases to be achieved.

Looking at the general solution again...

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[ C_1 \left( \mathbf{a} \cos(\beta t) - \mathbf{b} \sin(\beta t) \right) + C_2 \left( \mathbf{a} \sin(\beta t) + \mathbf{b} \cos(\beta t) \right) \right]$$

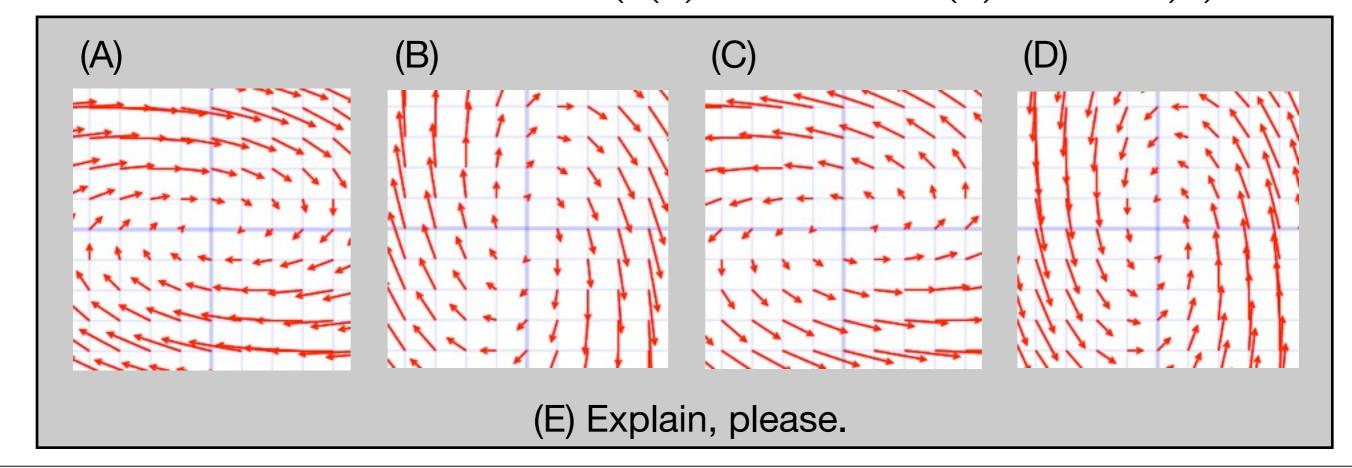
- Both parts rotate in the exact same way but the C<sub>2</sub> part is delayed by a quarter phase.
- If an initial condition lies neither parallel to vector a nor to vector b, C<sub>1</sub>
   and C2 allow for intermediate phases to be achieved.
- x(t) can be rewritten (using trig identities) as

$$\mathbf{x}(\mathbf{t}) = Me^{\alpha t} \left( \mathbf{a} \cos(\beta t - \phi) - \mathbf{b} \sin(\beta t - \phi) \right)$$

where M and  $\phi$  are constants to replace  $C_1$  and  $C_2$ .

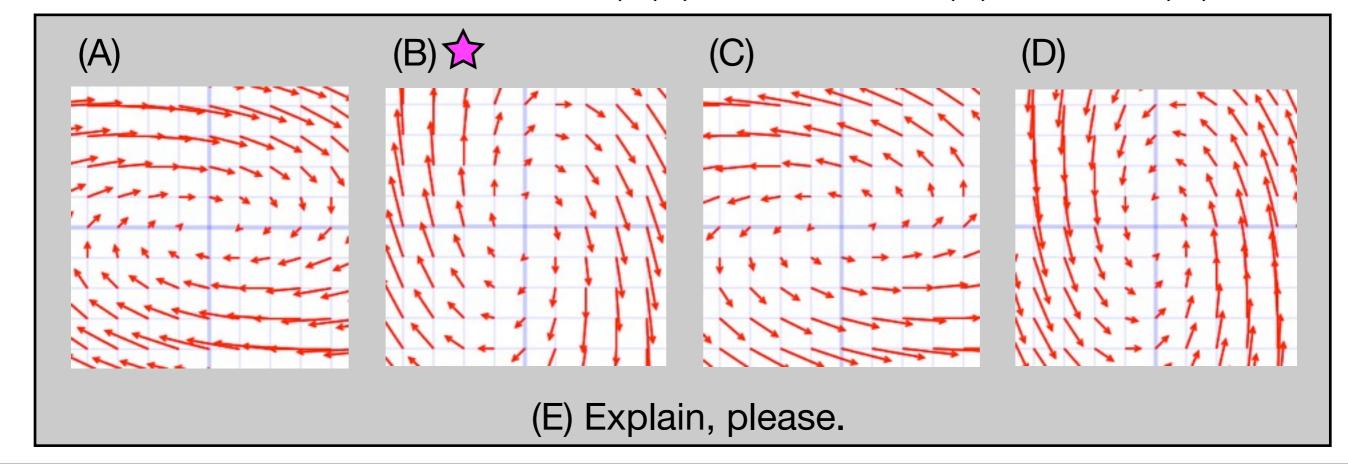
Back to our earlier example where we found the general solution

$$\mathbf{x}(\mathbf{t}) = e^t \left( C_1 \left( \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2t) - \begin{pmatrix} 0 \\ 2 \end{pmatrix} \sin(2t) \right) + C_2 \left( \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2t) + \begin{pmatrix} 0 \\ 2 \end{pmatrix} \cos(2t) \right) \right)$$



Back to our earlier example where we found the general solution

$$\mathbf{x}(\mathbf{t}) = e^t \left( C_1 \left( \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2t) - \begin{pmatrix} 0 \\ 2 \end{pmatrix} \sin(2t) \right) + C_2 \left( \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2t) + \begin{pmatrix} 0 \\ 2 \end{pmatrix} \cos(2t) \right) \right)$$



Back to our earlier example where we found the general solution

$$\mathbf{x}(\mathbf{t}) = e^t \left( C_1 \left( \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2t) - \begin{pmatrix} 0 \\ 2 \end{pmatrix} \sin(2t) \right) + C_2 \left( \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2t) + \begin{pmatrix} 0 \\ 2 \end{pmatrix} \cos(2t) \right) \right)$$

