Today

- Step and ramp functions (continued)
- The Dirac Delta function and impulse force
- Modeling with delta-function forcing

Solve using Laplace transforms:

$$y'' + 2y' + 10y = g(t) = \begin{cases} 0 & \text{for } t < 2 \text{ and } t \ge 5, \\ 1 & \text{for } 2 \le t < 5. \end{cases}$$
$$y(0) = 0, \ y'(0) = 0.$$

The transformed equation is

$$s^{2}Y(s) + 2sY(s) + 10Y(s) = \frac{e^{-2s}}{s} - \frac{e^{-5s}}{s}.$$

$$Y(s) = \frac{e^{-2s} - e^{-5s}}{s(s^{2} + 2s + 10)} = (e^{-2s} - e^{-5s})H(s).$$

$$H(s) = \frac{1}{s(s^{2} + 2s + 10)}$$

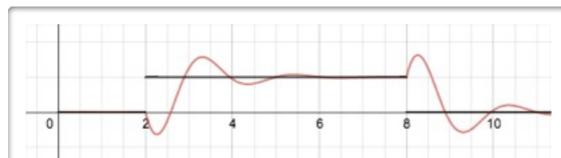
• Recall that $\mathcal{L}\{u_c(t)f(t-c)\}=e^{-sc}F(s)$

$$y(t) = u_2(t)h(t-2) - u_5(t)h(t-5)$$

So we just need h(t) and we're done.

- Inverting H(s) to get h(t): $H(s) = \frac{1}{s(s^2+2s+10)}$
- Partial fraction decomposition!

•Does
$$H(s) = \frac{1}{s}$$
 g(t) in black, y(t) in red.



$$y(t) = u_2(t)h(t-2) - u_5(t)h(t-5)$$

• See St., lculation (pdf and video): https://wiki.math.ubc.ca/mathbook/M256/Resources

ors.

An example with a ramped forcing function:

Two methods:

1. Build from left to right, adding/subtracting what you need to make the next section:

$$g(t) = u_5(t)\frac{1}{5}(t-5) - u_{10}(t)\frac{1}{5}(t-10)$$

2. Build each section independently:

$$g(t) = (u_5(t) - u_{10}(t)) \frac{1}{5}(t-5) + u_{10}(t) \cdot 1$$

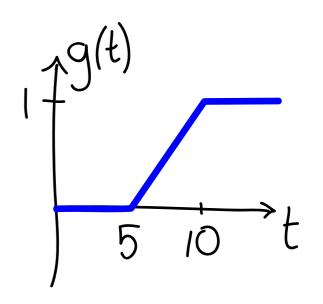
$$\Rightarrow$$
 (C) $g(t) = (u_5(t)(t-5) - u_{10}(t)(t-10))/5$

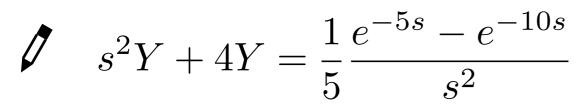
(D)
$$g(t) = (u_5(t)(t-5) - u_{10}(t)(t-10))/10$$

• An example with a ramped forcing function:

$$y'' + 4y = u_5(t)\frac{1}{5}(t - 5) - u_{10}(t)\frac{1}{5}(t - 10)$$

$$y(0) = 0, \ y'(0) = 0.$$





$$Y(s) = \frac{1}{5} \frac{e^{-5s} - e^{-10s}}{s^2(s^2 + 4)} = \frac{1}{5} (e^{-5s} - e^{-10s}) H(s)$$

$$y(t) = \frac{1}{5} [u_5(t)h(t-5) - u_{10}(t)h(t-10)]$$



$$h(t) = \frac{1}{4}t - \frac{1}{8}\sin(2t)$$

Delta-function forcing (6.5)

Suppose a mass is sitting at position x and a force g(t) acts on it:

$$mx'' = g(t)$$

To find x(t), integrate up:

$$\int_{a}^{b} mx'' dt = \int_{a}^{b} g(t) dt$$

$$mx' \Big|_{a}^{b} = \int_{a}^{b} g(t) dt$$

$$mv(b) - mv(a) = \int_{a}^{b} g(t) dt$$

- $\int_{a}^{b} g(t) dt$ is the change in momentum of the mass called impulse.
- If the force is large and sudden (say a hammer hitting the mass), maybe we just need to get this integral correct and the details don't matter.

Delta-function forcing (6.5)

• Let's assume
$$g(t) = \begin{cases} \frac{I_0}{2\tau} & -\tau < t < \tau \\ 0 & \text{otherwise} \end{cases}$$

impulse =
$$\Delta$$
momentum = $\int_{-\infty}^{\infty} g(t) dt = \int_{-\tau}^{\tau} \frac{I_0}{2\tau} dt = I_0$

 For general purposes (any property that might change quickly, not just momentum), we define the Dirac Delta "function" as follows:

$$d_{\tau}(t) = \begin{cases} \frac{1}{2\tau} & -\tau < t < \tau \\ 0 & \text{otherwise} \end{cases}$$

$$\delta(t) = \lim_{\tau \to 0} d_{\tau}(t) = \begin{cases} \text{"\infty"} & \text{for } t = 0, \\ 0 & \text{for } t \neq 0. \end{cases}$$

$$g(t) = I_0 d_{\tau}(t)$$

- I₀ can be replaced by any type of quantity
- e.g. m₀ mass added to tank suddenly

Some facts about the Delta "function"

$$\begin{split} \int_a^b \delta(t) \ dt &= 1 \qquad a < 0, \ b > 0 \quad \text{and} = \text{0 otherwise.} \\ \int_a^b f(t) \delta(t) \ dt &= \lim_{\tau \to 0} \frac{1}{2\tau} \int_{-\tau}^{\tau} f(t) \ dt \\ &= \lim_{\tau \to 0} \frac{F(\tau) - F(-\tau)}{2\tau} \qquad F'(t) = f(t) \\ &= F'(0) = f(0) \\ \int_a^b f(t) \delta(t) \ dt = f(0) \qquad a < 0, \ b > 0 \quad \text{and} = \text{0 otherwise.} \\ \delta(t-c) &= \text{shift of } \delta(t) \text{ by c} \\ \mathcal{L}\{\delta(t-c)\} &= \int_0^\infty e^{-st} \delta(t-c) \ dt \\ &= \int_{-c}^\infty e^{-s(u+c)} \delta(u) \ du \ = e^{-sc} \text{ for } c > 0 \end{split}$$