Today

- General solution for complex eigenvalues case.
- Shapes of solutions for complex eigenvalues case.

Calculating eigenvalues - trace/det shortcut

For the general matrix

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

• find the characteristic equation and solve it to find the eigenvalues.

(A)
$$\lambda^2 + (ad - bc)\lambda + a + d = 0$$

(B)
$$\lambda^2 + (b+c)\lambda + ac - bd = 0$$

(C)
$$\lambda^2 - (a+d)\lambda + ad - bc = 0$$

(D)
$$\lambda^2 + (a - d)\lambda + ad + bc = 0$$

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$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

• find the characteristic equation and solve it to find the eigenvalues.

(A)
$$\lambda^2$$

$$\lambda^2 - \operatorname{tr}(A)\lambda + \det(A) = 0$$
 (B) $\lambda^2 + (\upsilon + c)\lambda + ac - \upsilon a = 0$

$$(C) \lambda^2 - (a+d)\lambda + ad - bc = 0$$

(D)
$$\lambda^2 + (a - d)\lambda + ad + bc = 0$$

- ullet Find the general solution to $\mathbf{x}' = \begin{pmatrix} 1 & 1 \\ -4 & 1 \end{pmatrix} \mathbf{x}$.
 - The eigenvalues are

(A)
$$\lambda = 1 \pm 2i$$

(B)
$$\lambda = -1, 3$$

(C)
$$\lambda = 2 \pm 4i$$

(D)
$$\lambda = -2, 6$$

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• The eigenvectors are . . .

$$A - \lambda_1 I = \begin{pmatrix} 1 - (1+2i) & 1 \\ -4 & 1 - (1+2i) \end{pmatrix}$$
$$= \begin{pmatrix} -2i & 1 \\ -4 & -2i \end{pmatrix} \times \frac{1}{2}i$$
$$\sim \begin{pmatrix} -2i & 1 \\ -2i & 1 \end{pmatrix}$$
$$\mathbf{v_1} = \begin{pmatrix} 1 \\ 2i \end{pmatrix}$$

$$\mathbf{v_2} = \begin{pmatrix} 1 \\ -2i \end{pmatrix}$$

• We could just write down a (complex valued) general solution:

$$\mathbf{x}(\mathbf{t}) = C_1 e^{(1+2i)t} \begin{pmatrix} 1\\2i \end{pmatrix} + C_2 e^{(1-2i)t} \begin{pmatrix} 1\\-2i \end{pmatrix}$$

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But we want real valued solutions. Two options:

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 - Convert to a second order equation as we did for real roots case.

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- But we want real valued solutions. Two options:
 - Convert to a second order equation as we did for real roots case.
 - Recall the sum and difference trick it says that real and imaginary parts of a complex solution are themselves solutions.

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$$\mathbf{x}' = \begin{pmatrix} 1 & 1 \\ -4 & 1 \end{pmatrix} \mathbf{x} \qquad \Rightarrow \qquad \begin{aligned} x_1' &= x_1 + x_2 \\ x_2' &= -4x_1 + x_2 \end{aligned}$$



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$$x''_{1} = x'_{1} + x'_{2}$$

$$x''_{1} = x'_{1} - 4x_{1} + x_{2}$$

$$x''_{1} = x'_{1} - 4x_{1} + x'_{2}$$

$$x''_{1} = x'_{1} - 4x_{1} + x'_{1} - x_{1}$$

$$x''_{1} - 2x'_{1} + 5x_{1} = 0$$

$$r^{2} - 2r + 5 = 0$$

$$r = 1 \pm 2i$$

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$$r = 1 \pm 2i$$
 $x_1(t) = e^t(C_1\cos(2t) + C_2\sin(2t))$



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$$r = 1 \pm 2i x_1(t) = e^t (C_1 \cos(2t) + C_2 \sin(2t))$$

$$x'_1(t) = e^t (-2C_1 \sin(2t) + 2C_2 \cos(2t))$$

$$+e^t (C_1 \cos(2t) + C_2 \sin(2t))$$

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$$\mathbf{x}' = \begin{pmatrix} 1 & 1 \\ -4 & 1 \end{pmatrix} \mathbf{x} \Rightarrow \begin{aligned} x_1' &= x_1 + x_2 \\ x_2' &= -4x_1 + x_2 \end{aligned} \begin{pmatrix} 1 \\ 2i \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 2 \end{pmatrix} i \\ x_2' &= -4x_1 + x_2 \end{aligned}$$
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 Alternatively, multiply out the complex solution and extract real and imaginary parts:

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Complex eigenvalues - general case

ullet Find e-values, $\lambda=lpha\pmeta i$, and e-vectors, ${f v}=inom{a_1}{a_2}\pm i\,inom{b_1}{b_2}$.

• Write down solution (or use method on previous slide for formula-free):

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$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[C_1 \left(\begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \cos(\beta t) - \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \sin(\beta t) \right) + C_2 \left(\begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \sin(\beta t) + \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \cos(\beta t) \right) \right]$$

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• Find e-values, $\lambda=\alpha\pm\beta i$, and e-vectors, ${\bf v}=\begin{pmatrix}a_1\\a_2\end{pmatrix}\pm i\begin{pmatrix}b_1\\b_2\end{pmatrix}$.

Write down solution (or use method on previous slide for formula-free):

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[C_1 \left(\begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \cos(\beta t) - \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \sin(\beta t) \right) + C_2 \left(\begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \sin(\beta t) + \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \cos(\beta t) \right) \right]$$

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[C_1 \left(\mathbf{a} \cos(\beta t) - \mathbf{b} \sin(\beta t) \right) + C_2 \left(\mathbf{a} \sin(\beta t) + \mathbf{b} \cos(\beta t) \right) \right]$$

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• Suppose you find eigenvalue $\lambda=2\pi i$ and eigenvector ${\bf v}=\begin{pmatrix}1\\i\end{pmatrix}$. Which of the following is a solution to the original equation?

(A)
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

(B)
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t)$$

(C)
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t)$$

(D)
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

• Suppose you find eigenvalue $\lambda=2\pi i$ and eigenvector ${\bf v}=\begin{pmatrix}1\\i\end{pmatrix}$. Which of the following is a solution to the original equation?

$$\mathbf{x}$$
 (A) $\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$

(B)
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t)$$

$$(\mathbf{C}) \quad \mathbf{x}(\mathbf{t}) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t)$$

(D)
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

• Suppose you find eigenvalue $\lambda=2\pi i$ and eigenvector ${\bf v}=\begin{pmatrix} 1\\i \end{pmatrix}$. Which of the following is a solution to the original equation?

$$\overline{\mathbf{x}}(\mathbf{t}) = e^{2\pi i t} \begin{pmatrix} 1 \\ i \end{pmatrix}$$

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• Suppose you find eigenvalue $\lambda=2\pi i$ and eigenvector $\mathbf{v}=\begin{pmatrix}1\\i\end{pmatrix}$. Which of the following is a solution to the original equation?

$$\overline{\mathbf{x}}(\mathbf{t}) = e^{2\pi i t} \begin{pmatrix} 1 \\ i \end{pmatrix} \\
= (\cos(2\pi t) + i\sin(2\pi t)) \begin{pmatrix} 1 \\ i \end{pmatrix} \\
= \begin{pmatrix} \cos(2\pi t) + i\sin(2\pi t)) \\ -\sin(2\pi t) + i\cos(2\pi t)) \end{pmatrix} \\
= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t) \\
+i \left[\begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) \right]$$

• Suppose you find eigenvalue $\lambda=2\pi i$ and eigenvector $\mathbf{v}=\begin{pmatrix}1\\i\end{pmatrix}$. Which of the following is a solution to the original equation?

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= (\cos(2\pi t) + i\sin(2\pi t)) \begin{pmatrix} 1 \\ i \end{pmatrix} \\
= \begin{pmatrix} \cos(2\pi t) + i\sin(2\pi t) \\ -\sin(2\pi t) + i\cos(2\pi t) \end{pmatrix} \\
= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t) \\
+i \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t)$$

• Suppose you find eigenvalue $\lambda=2\pi i$ and eigenvector ${f v}=\left(\begin{smallmatrix} 1 \\ i \end{smallmatrix} \right)$. Which of the following is a solution to the original equation?

$$\overline{\mathbf{x}}(\mathbf{t}) = e^{2\pi i t} \begin{pmatrix} 1 \\ i \end{pmatrix}$$
$$= (\cos(2\pi t) + i\sin(2\pi t)) \begin{pmatrix} 1 \\ i \end{pmatrix}$$

 $\sin(2\pi t)$

 $= \begin{pmatrix} \cos(2\pi t) + i\sin(2\pi t) \\ -\sin(2\pi t) + i\cos(2\pi t) \end{pmatrix}$ Sum and difference trick lets us take the $\cos(2\pi t) - {0 \choose 1}\sin(2\pi t)$ Real and Imaginary parts as two indep. $\cos(2\pi t) +$

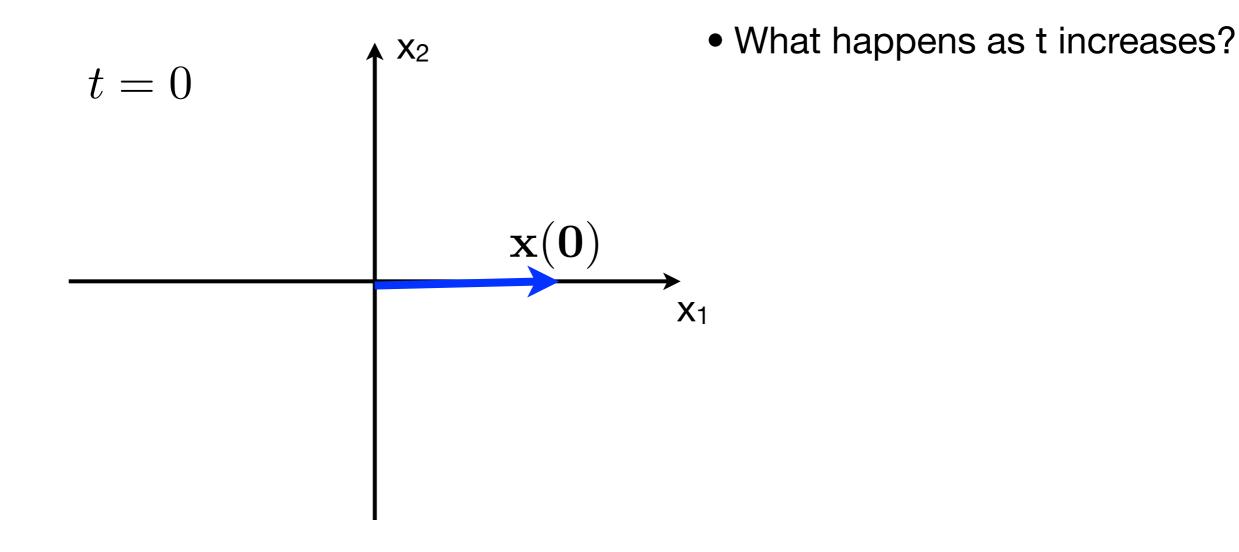
solutions

ullet But what about $\lambda_2=-2\pi i$ and ${f v_2}=\left(egin{array}{c}1\\-i\end{array}
ight)$? $\overline{\mathbf{x}}(\mathbf{t}) = e^{-2\pi i t} \begin{pmatrix} 1 \\ -i \end{pmatrix}$ $= (\cos(-2\pi t) + i\sin(-2\pi t)) \begin{pmatrix} 1\\ -i \end{pmatrix}$ $= \begin{pmatrix} \cos(2\pi t) - i\sin(2\pi t) \\ -\sin(2\pi t) - i\cos(2\pi t) \end{pmatrix}$ $= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$ $-i \left| \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) \right|$

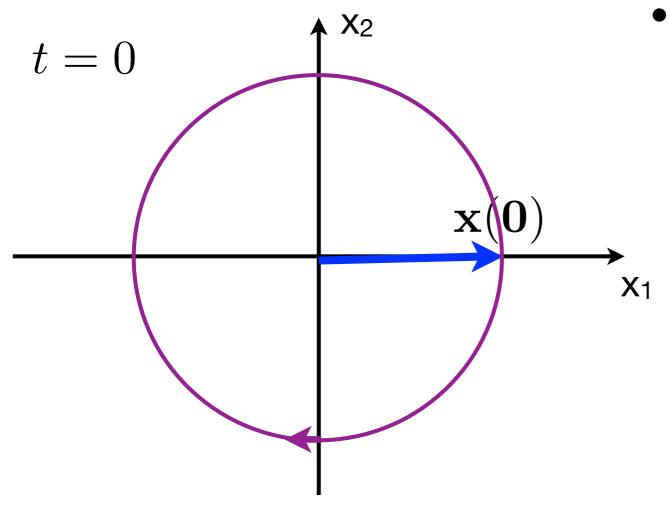
• But what about
$$\lambda_2 = -2\pi i$$
 and $\mathbf{v_2} = \begin{pmatrix} 1 \\ -i \end{pmatrix}$?
$$\overline{\mathbf{x}}(\mathbf{t}) = e^{-2\pi i t} \begin{pmatrix} 1 \\ -i \end{pmatrix} \\ = (\cos(-2\pi t) + i\sin(-2\pi t)) \begin{pmatrix} 1 \\ -i \end{pmatrix} \\ = \begin{pmatrix} \cos(2\pi t) - i\sin(2\pi t) \\ -\sin(2\pi t) - i\cos(2\pi t) \end{pmatrix} \\ = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t) \\ -i \end{pmatrix}$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



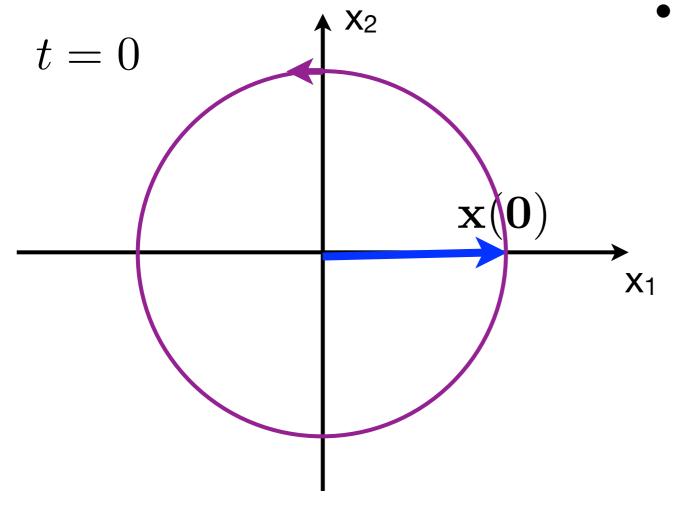
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



What happens as t increases?

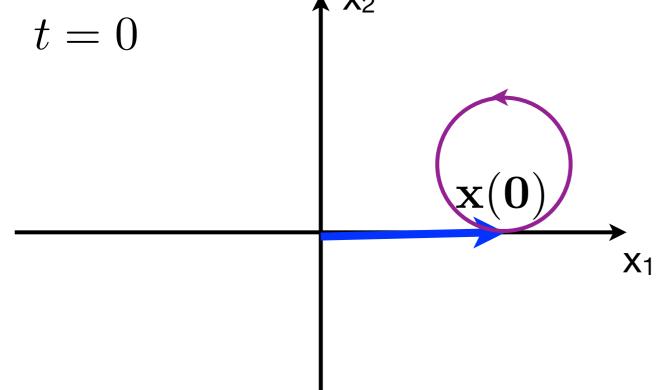
(A) The vector rotates clockwise.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



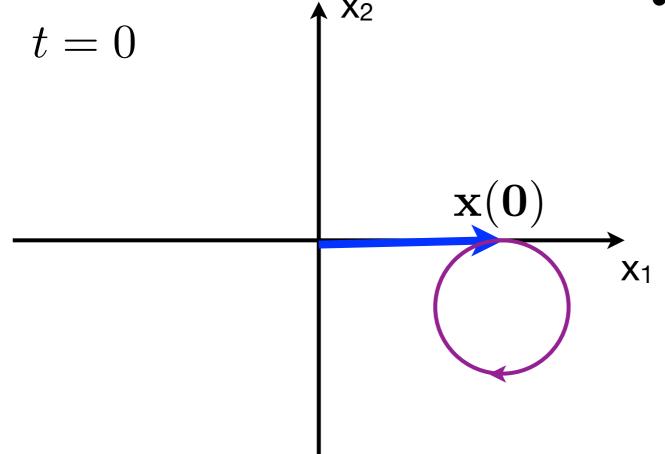
- What happens as t increases?
 - (A) The vector rotates clockwise.
 - (B) The vector rotates counterclockwise.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



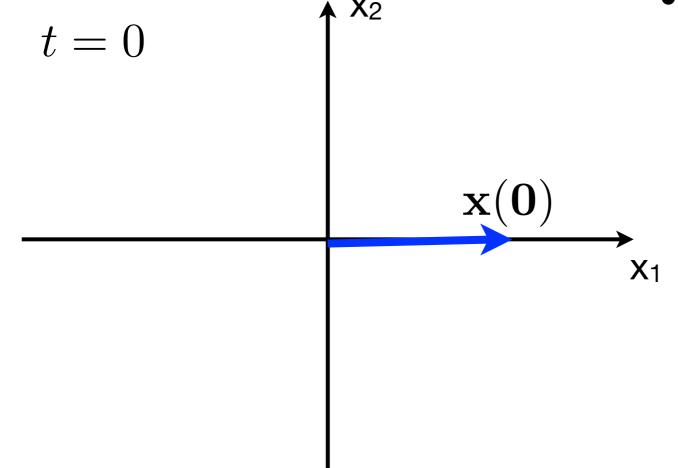
- What happens as t increases?
 - (A) The vector rotates clockwise.
 - (B) The vector rotates counterclockwise.
 - (C) The tip of the vector maps out a circle in the first quadrant.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



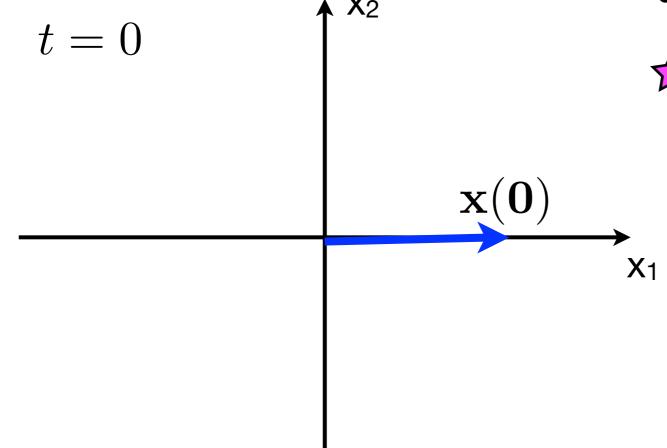
- What happens as t increases?
 - (A) The vector rotates clockwise.
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 - (C) The tip of the vector maps out a circle in the first quadrant.
 - (D) The tip of the vector maps out a circle in the fourth quadrant.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



- What happens as t increases?
 - (A) The vector rotates clockwise.
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 - (D) The tip of the vector maps out a circle in the fourth quadrant.
 - (E) Explain please.

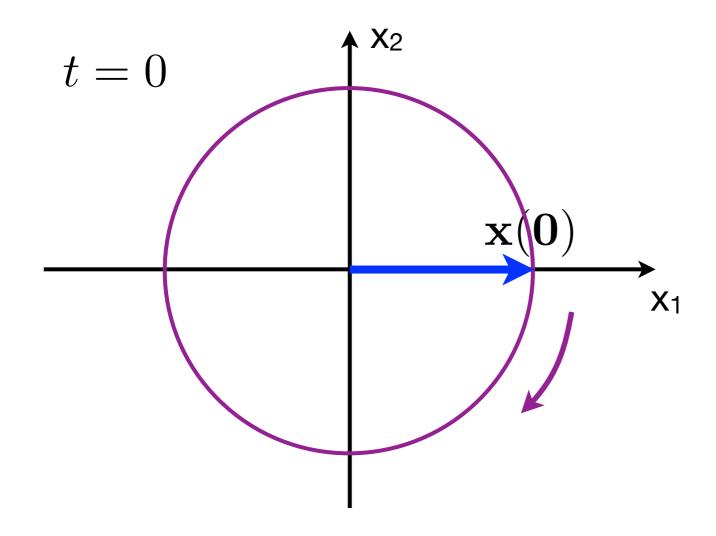
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



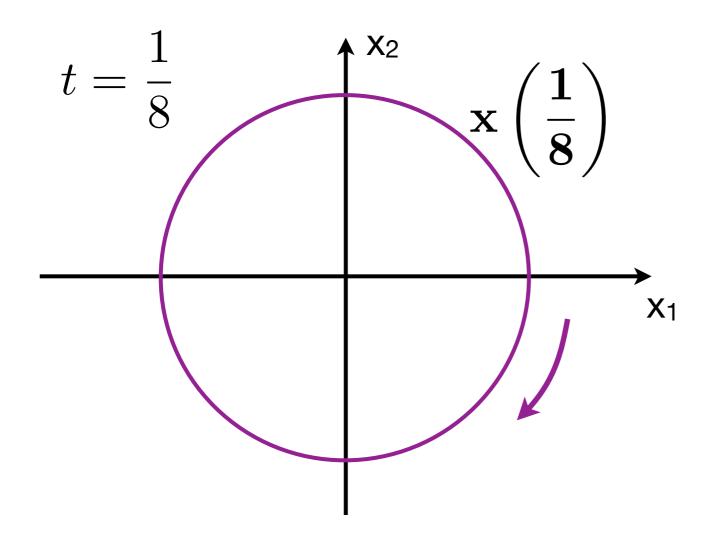
What happens as t increases?

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 - (E) Explain please.

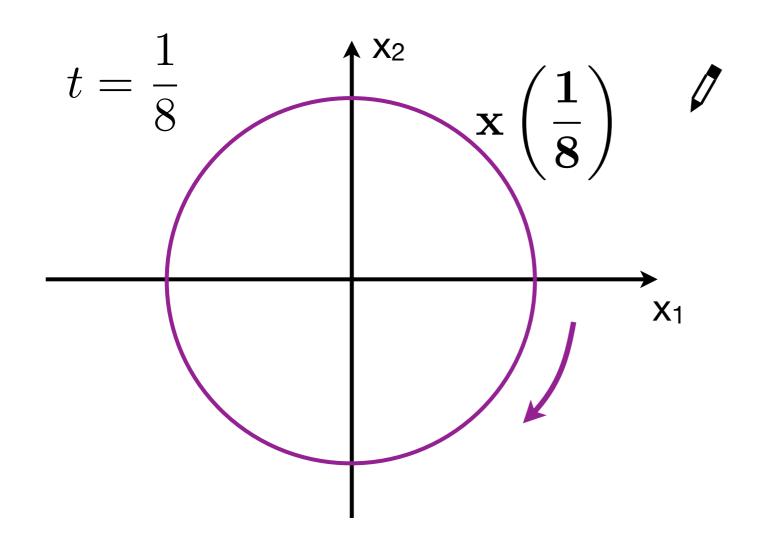
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



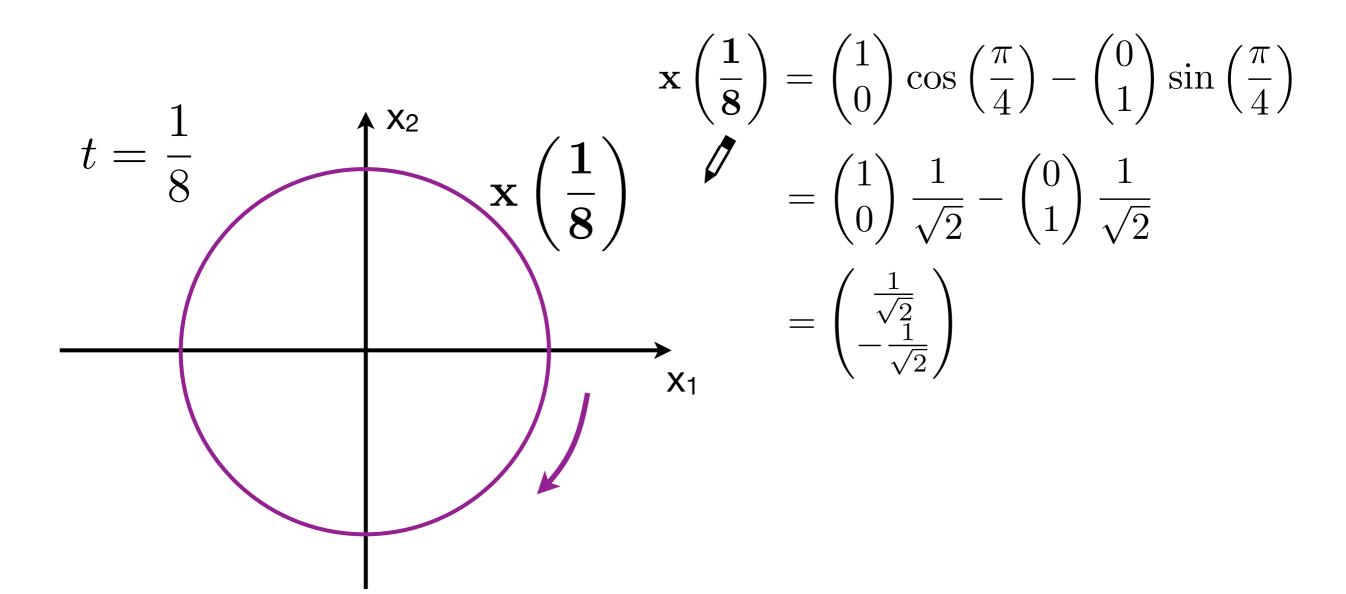
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



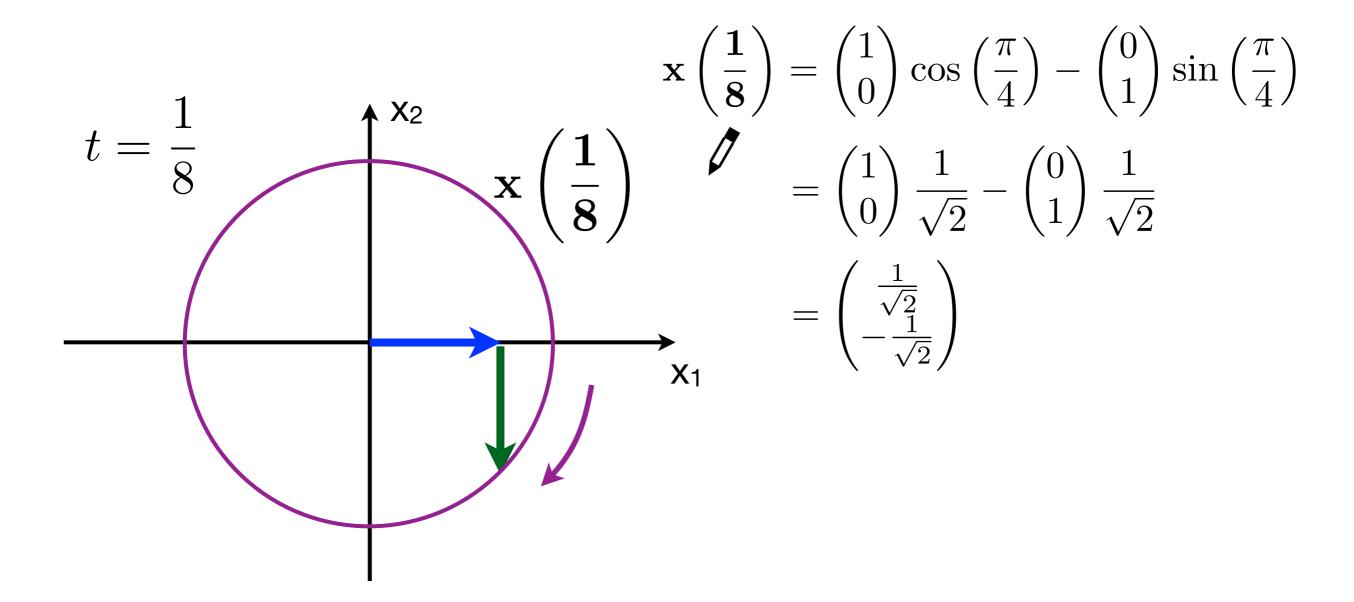
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



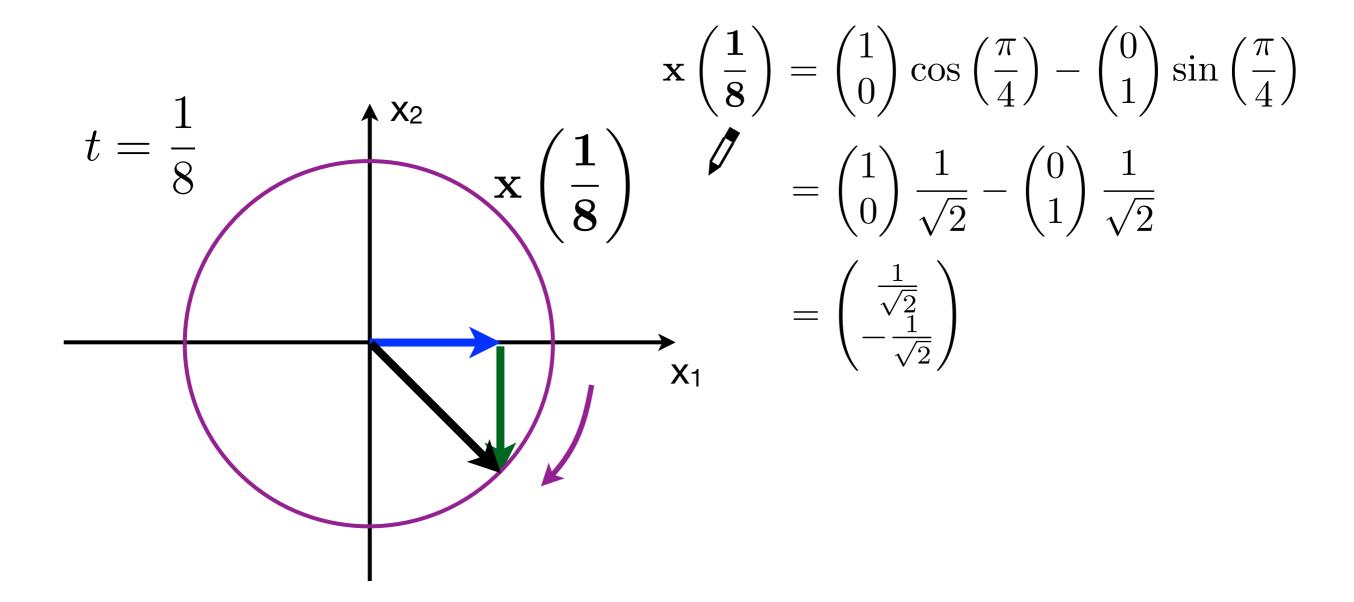
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



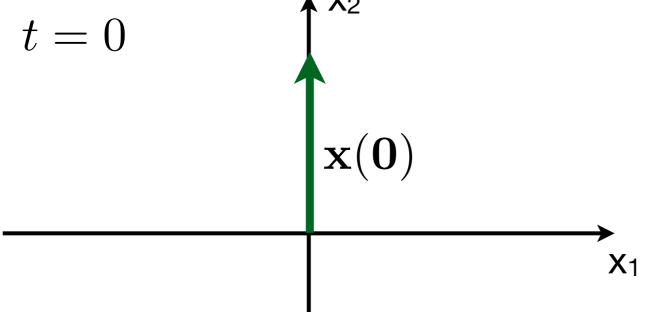
• Same equation, initial condition chosen so that C₁=0 and C₂=1.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t)$$

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[C_1 \left(\mathbf{a} \cos(\beta t) - \mathbf{b} \sin(\beta t) \right) + C_2 \left(\mathbf{a} \sin(\beta t) + \mathbf{b} \cos(\beta t) \right) \right]$$

Same equation, initial condition chosen so that C₁=0 and C₂=1.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t)$$



- What happens as t increases?
 - (A) The vector rotates clockwise.
 - (B) The vector rotates counterclockwise.
 - (C) The tip of the vector maps out a circle in the first quadrant.
 - (D) The tip of the vector maps out a circle in the second quadrant.
 - (E) Explain please.

Same equation, initial condition chosen so that C₁=0 and C₂=1.

- (B) The vector rotates counterclockwise.
- (C) The tip of the vector maps out a circle in the first quadrant.
- (D) The tip of the vector maps out a circle in the second quadrant.
- (E) Explain please.

Same equation, initial condition chosen so that C₁=0 and C₂=1.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t)$$

- t = 0 $\mathbf{x}(\mathbf{0})$
 - **X**1
- "Same" solution as before, just π/2 delayed.

- What happens as t increases?
- (A) The vector rotates clockwise.
 - (B) The vector rotates counterclockwise.
 - (C) The tip of the vector maps out a circle in the first quadrant.
 - (D) The tip of the vector maps out a circle in the second quadrant.
 - (E) Explain please.

Looking at the general solution again...

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[C_1 \left(\mathbf{a} \cos(\beta t) - \mathbf{b} \sin(\beta t) \right) + C_2 \left(\mathbf{a} \sin(\beta t) + \mathbf{b} \cos(\beta t) \right) \right]$$

Looking at the general solution again...

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• Both parts rotate in the exact same way but the C₂ part is delayed by a quarter phase.

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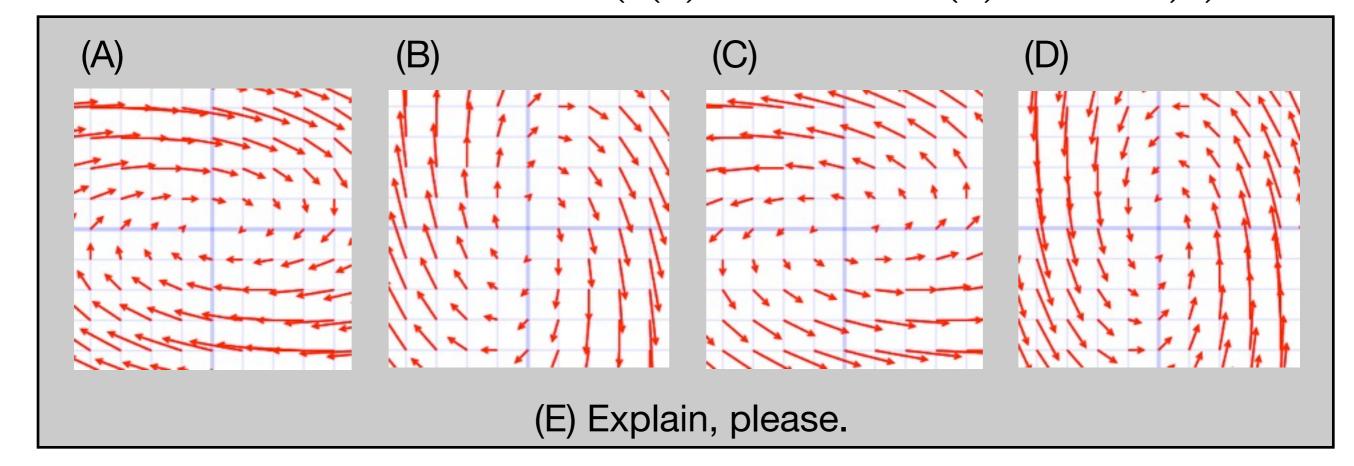
- Both parts rotate in the exact same way but the C₂ part is delayed by a quarter phase.
- If an initial condition lies neither parallel to vector **a** nor to vector **b**, C₁ and C2 allow for intermediate phases to be achieved.
- x(t) can be rewritten (using trig identities) as

$$\mathbf{x}(\mathbf{t}) = Me^{\alpha t} \left(\mathbf{a} \cos(\beta t - \phi) - \mathbf{b} \sin(\beta t - \phi) \right)$$

where M and ϕ are constants to replace C_1 and C_2 .

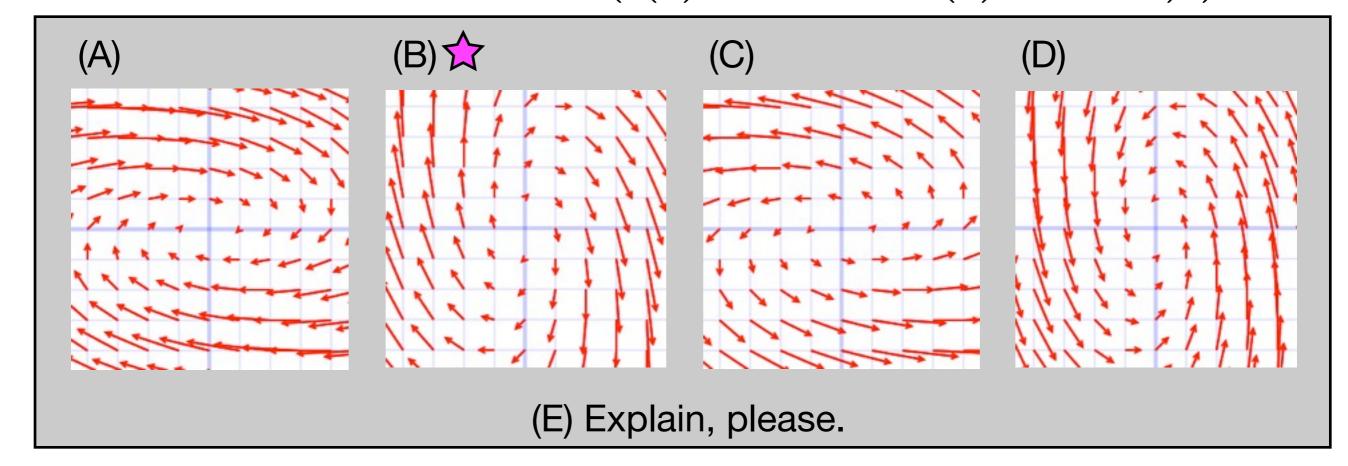
Back to our earlier example where we found the general solution

$$\mathbf{x}(\mathbf{t}) = e^t \left(C_1 \left(\begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2t) - \begin{pmatrix} 0 \\ 2 \end{pmatrix} \sin(2t) \right) + C_2 \left(\begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2t) + \begin{pmatrix} 0 \\ 2 \end{pmatrix} \cos(2t) \right) \right)$$



Back to our earlier example where we found the general solution

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Back to our earlier example where we found the general solution

$$\mathbf{x}(\mathbf{t}) = e^{t} \left(C_{1} \left(\begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2t) - \begin{pmatrix} 0 \\ 2 \end{pmatrix} \sin(2t) \right) + C_{2} \left(\begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2t) + \begin{pmatrix} 0 \\ 2 \end{pmatrix} \cos(2t) \right) \right)$$

