Today

- The geometry of homogeneous and nonhomogeneous matrix equations
- Solving nonhomogeneous equations
 - Method of undetermined coefficients

(A) Hand out worksheet on Friday, print and hand in during tutorial.

(B) Hand out worksheet during tutorial, hand in during Tuesday class.

Second order, linear, constant coeff, **non**homogeneous (3.5)

 Our next goal is to figure out how to find solutions to nonhomogeneous equations like this one:

$$y'' - 6y' + 8y = \sin(2t)$$

• But first, a bit more on the connections between matrix algebra and differential equations . . .

• An mxn matrix is a gizmo that takes an n-vector and returns an m-vector: $\overline{\alpha} = A\overline{\alpha}$

$$\overline{y} = A\overline{x}$$

• An mxn matrix is a gizmo that takes an n-vector and returns an m-vector: vector: $\overline{a_1} = A\overline{a_2}$

$$\overline{y} = A\overline{x}$$

• It is called a linear operator because it has the following properties:

$$A(c\overline{x}) = cA\overline{x}$$
$$A(\overline{x} + \overline{y}) = A\overline{x} + A\overline{y}$$

• An mxn matrix is a gizmo that takes an n-vector and returns an m-vector: vector: $\overline{\pi} = A\overline{\pi}$

$$\overline{y} = A\overline{x}$$

• It is called a linear operator because it has the following properties:

$$A(c\overline{x}) = cA\overline{x}$$
$$A(\overline{x} + \overline{y}) = A\overline{x} + A\overline{y}$$

 Not all operators work on vectors. Derivative operators take a function and return a new function. For example,

$$z = L[y] = \frac{d^2y}{dt^2} - 2\frac{dy}{dt} + y$$

• An mxn matrix is a gizmo that takes an n-vector and returns an m-vector: vector: $\overline{\pi} = A\overline{\pi}$

$$\overline{y} = A\overline{x}$$

• It is called a linear operator because it has the following properties:

$$A(c\overline{x}) = cA\overline{x}$$
$$A(\overline{x} + \overline{y}) = A\overline{x} + A\overline{y}$$

 Not all operators work on vectors. Derivative operators take a function and return a new function. For example,

$$z = L[y] = \frac{d^2y}{dt^2} - 2\frac{dy}{dt} + y$$

• This one is linear because

$$L[cy] = cL[y]$$
 Note: y, z are functions
of t and c is a constant
 $y + z] = L[y] + L[z]$ 4

• A homogeneous matrix equation has the form

$$A\overline{x} = \overline{0}$$

A homogeneous matrix equation has the form

$$A\overline{x} = \overline{0}$$

• A non-homogeneous matrix equation has the form

$$A\overline{x} = \overline{b}$$

• A homogeneous matrix equation has the form

$$A\overline{x} = \overline{0}$$

A non-homogeneous matrix equation has the form

$$A\overline{x} = \overline{b}$$

• A homogeneous differential equation has the form

$$L[y] = 0$$

A homogeneous matrix equation has the form

$$A\overline{x} = \overline{0}$$

A non-homogeneous matrix equation has the form

$$A\overline{x} = \overline{b}$$

• A homogeneous differential equation has the form

$$L[y] = 0$$

• A non-homogeneous differential equation has the form

$$L[y] = g(t)$$

• The matrix equation $A\overline{x} = \overline{0}$ could have (depending on A)

(A) no solutions.

(B) exactly one solution.

(C) a one-parameter family of solutions.

(D) an n-parameter family of solutions.

• The matrix equation $A\overline{x} = \overline{0}$ could have (depending on A)

 \bigstar (A) no solutions.

(B) exactly one solution.

(C) a one-parameter family of solutions.

(D) an n-parameter family of solutions.

• The matrix equation $A\overline{x} = \overline{0}$ could have (depending on A)

 \bigstar (A) no solutions.

(B) exactly one solution.

(C) a one-parameter family of solutions.

(D) an n-parameter family of solutions.

Possibilities:

• The matrix equation $A\overline{x} = \overline{0}$ could have (depending on A)

 \bigstar (A) no solutions.



(B) exactly one solution.

(C) a one-parameter family of solutions.

(D) an n-parameter family of solutions.

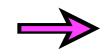
Possibilities:

 $\overline{x} = \overline{0}$

• The matrix equation $A\overline{x} = \overline{0}$ could have (depending on A)

 \bigstar (A) no solutions.

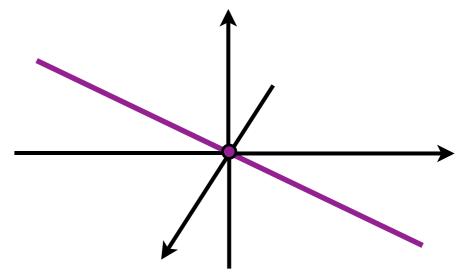
(B) exactly one solution.



(C) a one-parameter family of solutions.

(D) an n-parameter family of solutions.

Choose the answer that is incorrect.



Possibilities: $\overline{x} = C \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$

• The matrix equation $A\overline{x} = \overline{0}$ could have (depending on A)

 \bigstar (A) no solutions.

(B) exactly one solution.

(C) a one-parameter family of solutions.

 \rightarrow

(D) an n-parameter family of solutions.

utions

 $\overline{x} = C_1 \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} + C_2 \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix}$

Possibilities:

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix}$$

• Example 1. Solve the equation $A\overline{x} = \overline{0}$ where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix}$$

Each equation describes a plane.

• Example 1. Solve the equation $A\overline{x} = \overline{0}$ where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix}$$

Each equation describes a plane.

Row reduction gives

$$A \sim \begin{pmatrix} 1 & 0 & -1/3 \\ 0 & 1 & 5/3 \\ 0 & 0 & 0 \end{pmatrix}$$

• Example 1. Solve the equation $A\overline{x} = \overline{0}$ where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix}$$

Each equation describes a plane.

Row reduction gives

$$A \sim \begin{pmatrix} 1 & 0 & -1/3 \\ 0 & 1 & 5/3 \\ 0 & 0 & 0 \end{pmatrix}$$

In this case, only two of them really matter.

• Example 1. Solve the equation $A\overline{x} = \overline{0}$ where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix}$$

Row reduction gives

$$A \sim \begin{pmatrix} 1 & 0 & -1/3 \\ 0 & 1 & 5/3 \\ 0 & 0 & 0 \end{pmatrix}$$

In this case, only two of them really matter.

• so $x_1 - \frac{1}{3}x_3 = 0$ and $x_2 + \frac{5}{3}x_3 = 0$ and x_3 can be whatever

(because it doesn't have a leading one).

• so
$$x_1 - \frac{1}{3}x_3 = 0$$
 and $x_2 + \frac{5}{3}x_3 = 0$ and x_3 can be whatever.

• so
$$x_1 - \frac{1}{3}x_3 = 0$$
 and $x_2 + \frac{5}{3}x_3 = 0$ and x_3 can be whatever. $x_1 = \frac{1}{3}x_3$

• so
$$x_1 - \frac{1}{3}x_3 = 0$$
 and $x_2 + \frac{5}{3}x_3 = 0$ and x_3 can be whatever.
 $x_1 = \frac{1}{3}x_3$
 $x_2 = -\frac{5}{3}x_3$

• so
$$x_1 - \frac{1}{3}x_3 = 0$$
 and $x_2 + \frac{5}{3}x_3 = 0$ and x_3 can be whatever.
 $x_1 = \frac{1}{3}x_3$
 $x_2 = -\frac{5}{3}x_3$
 $x_3 = C$

• so
$$x_1 - \frac{1}{3}x_3 = 0$$
 and $x_2 + \frac{5}{3}x_3 = 0$ and x_3 can be whatever.
 $x_1 = \frac{1}{3}x_3$ $x_1 = \frac{1}{3}C$
 $x_2 = -\frac{5}{3}x_3$
 $x_3 = C$

• so
$$x_1 - \frac{1}{3}x_3 = 0$$
 and $x_2 + \frac{5}{3}x_3 = 0$ and x_3 can be whatever.
 $x_1 = \frac{1}{3}x_3$ $x_1 = \frac{1}{3}C$
 $x_2 = -\frac{5}{3}x_3$ $x_2 = -\frac{5}{3}C$
 $x_3 = C$

• so
$$x_1 - \frac{1}{3}x_3 = 0$$
 and $x_2 + \frac{5}{3}x_3 = 0$ and x_3 can be whatever.
 $x_1 = \frac{1}{3}x_3$ $x_1 = \frac{1}{3}C$
 $x_2 = -\frac{5}{3}x_3$ $x_2 = -\frac{5}{3}C$
 $x_3 = C$

• Example 1. Solve the equation $A\overline{x} = \overline{0}$.

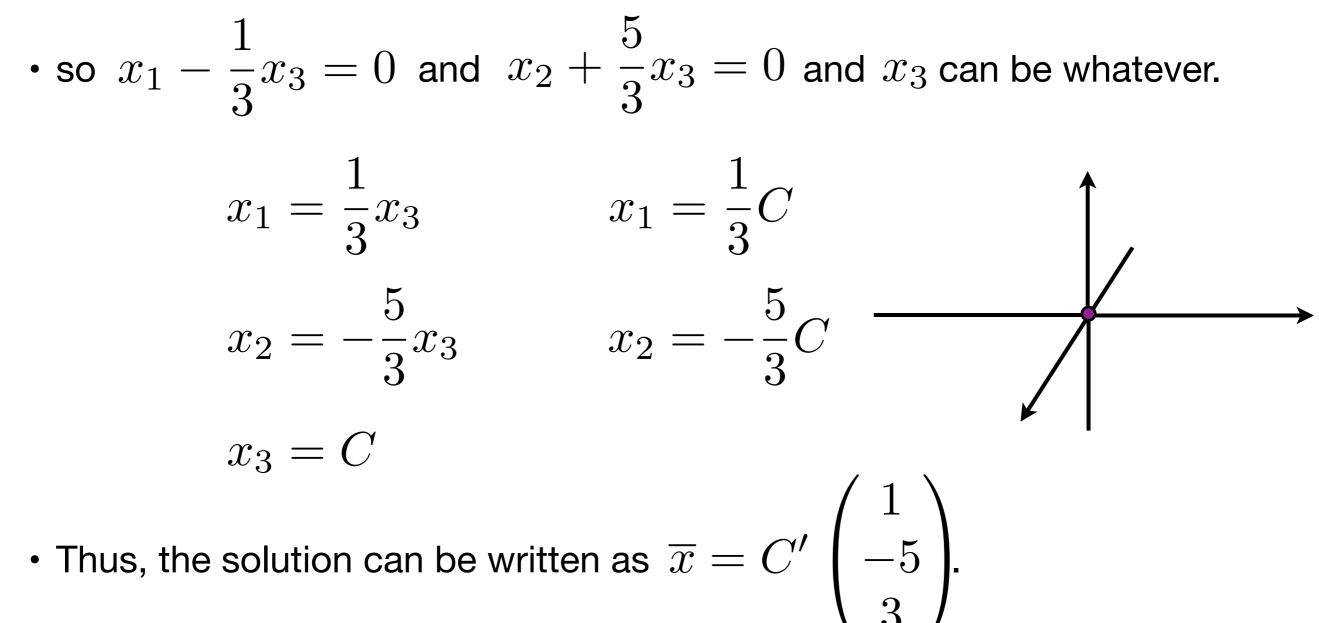
• so
$$x_1 - \frac{1}{3}x_3 = 0$$
 and $x_2 + \frac{5}{3}x_3 = 0$ and x_3 can be whatever.
 $x_1 = \frac{1}{3}x_3$ $x_1 = \frac{1}{3}C$
 $x_2 = -\frac{5}{3}x_3$ $x_2 = -\frac{5}{3}C$
 $x_3 = C$

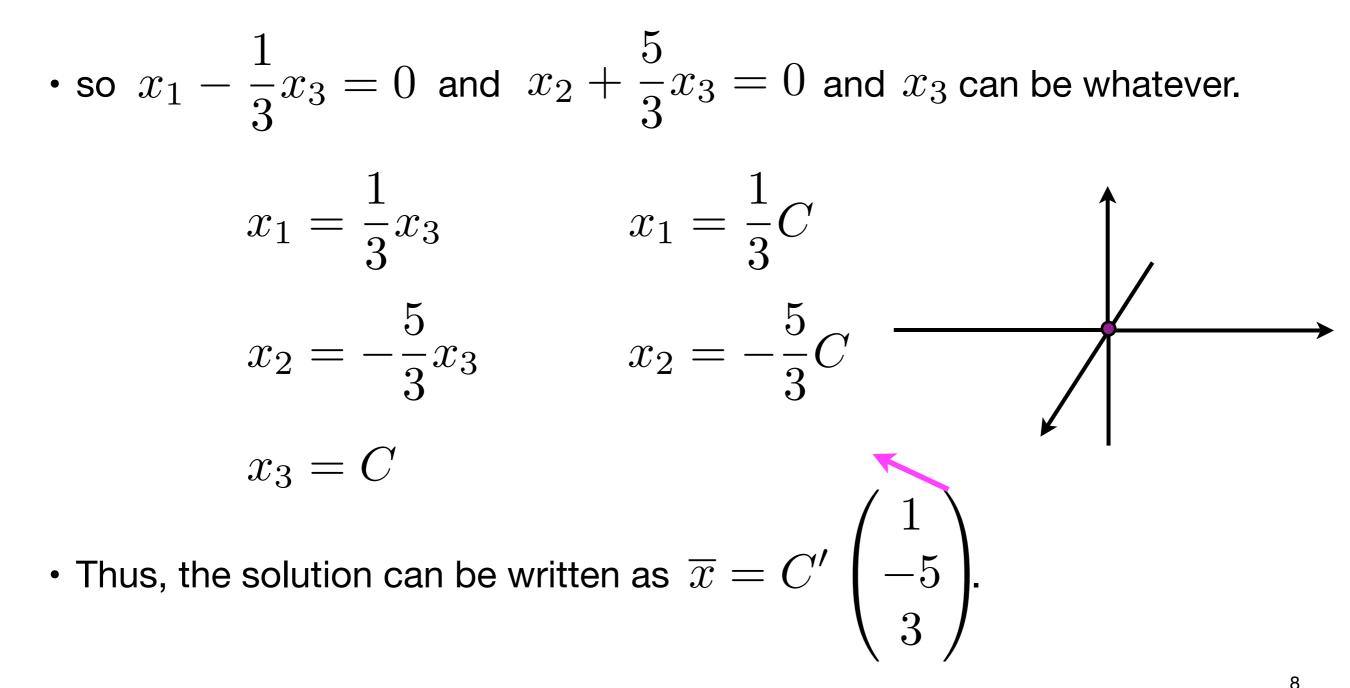
• Thus, the solution can be written as $\overline{x} = \frac{C}{3} \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix}$.

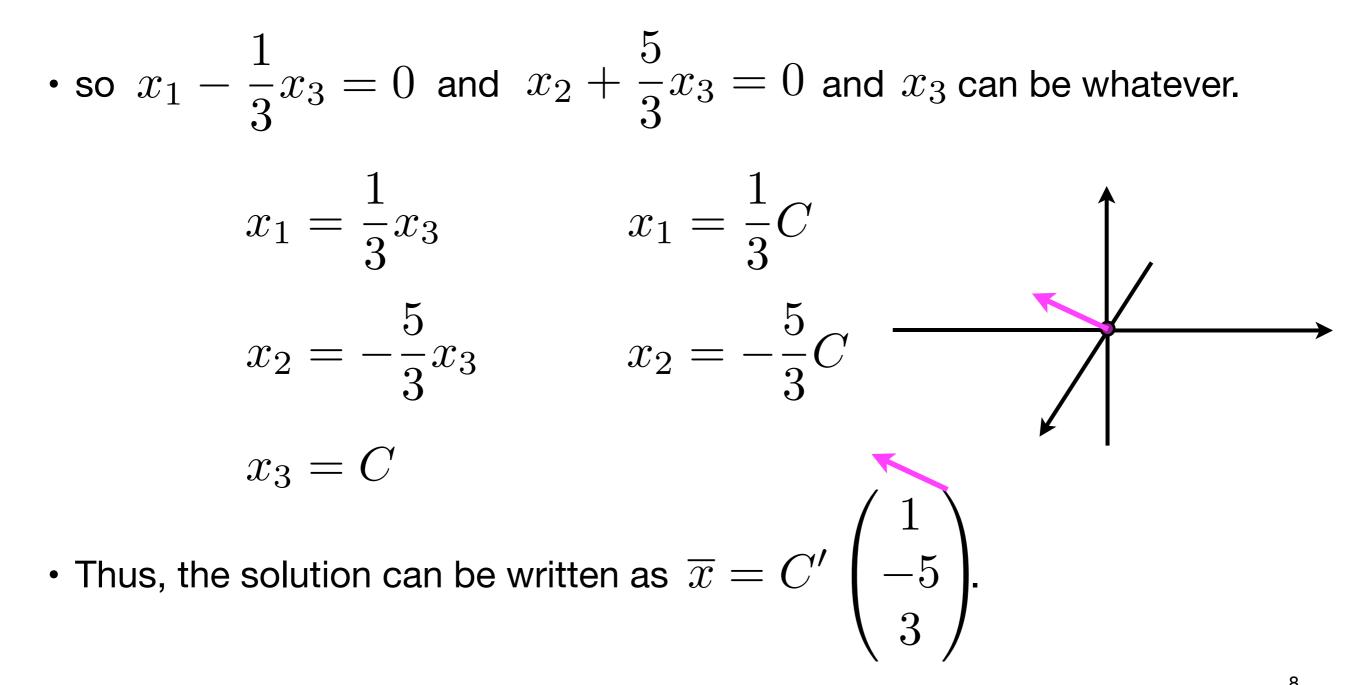
• Example 1. Solve the equation $A\overline{x} = \overline{0}$.

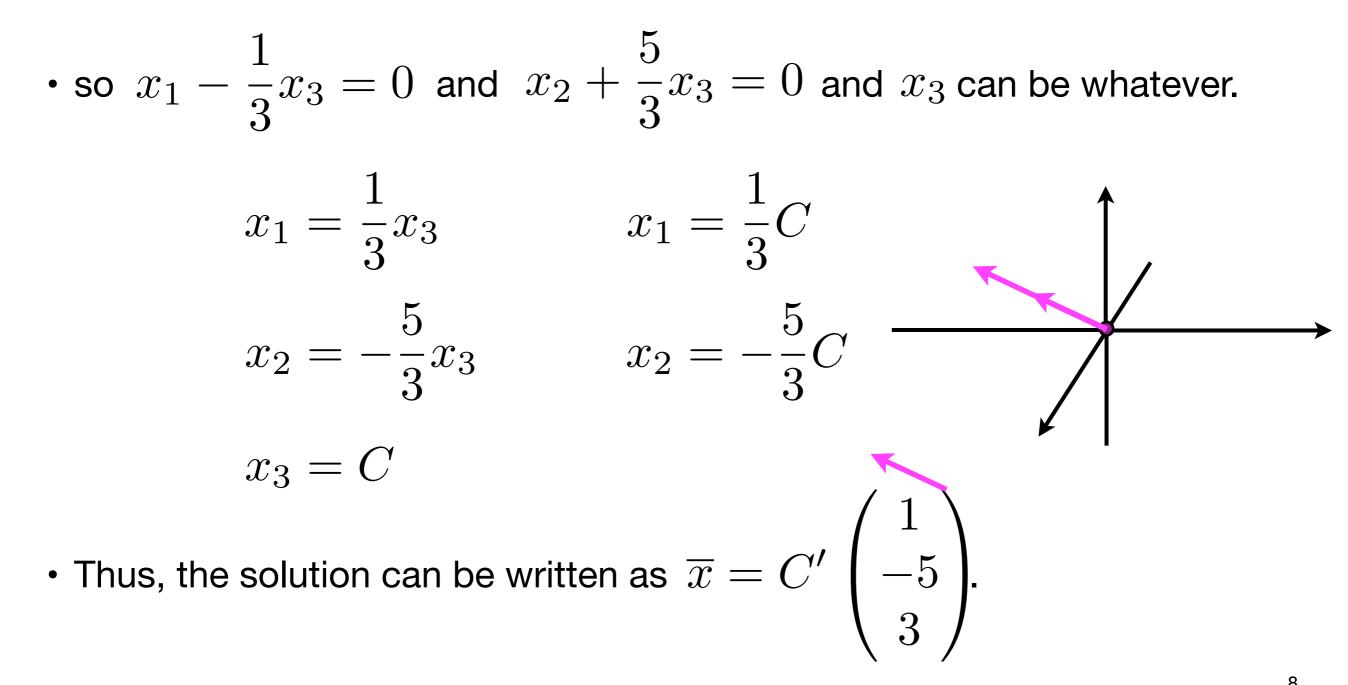
• so
$$x_1 - \frac{1}{3}x_3 = 0$$
 and $x_2 + \frac{5}{3}x_3 = 0$ and x_3 can be whatever.
 $x_1 = \frac{1}{3}x_3$ $x_1 = \frac{1}{3}C$
 $x_2 = -\frac{5}{3}x_3$ $x_2 = -\frac{5}{3}C$
 $x_3 = C$

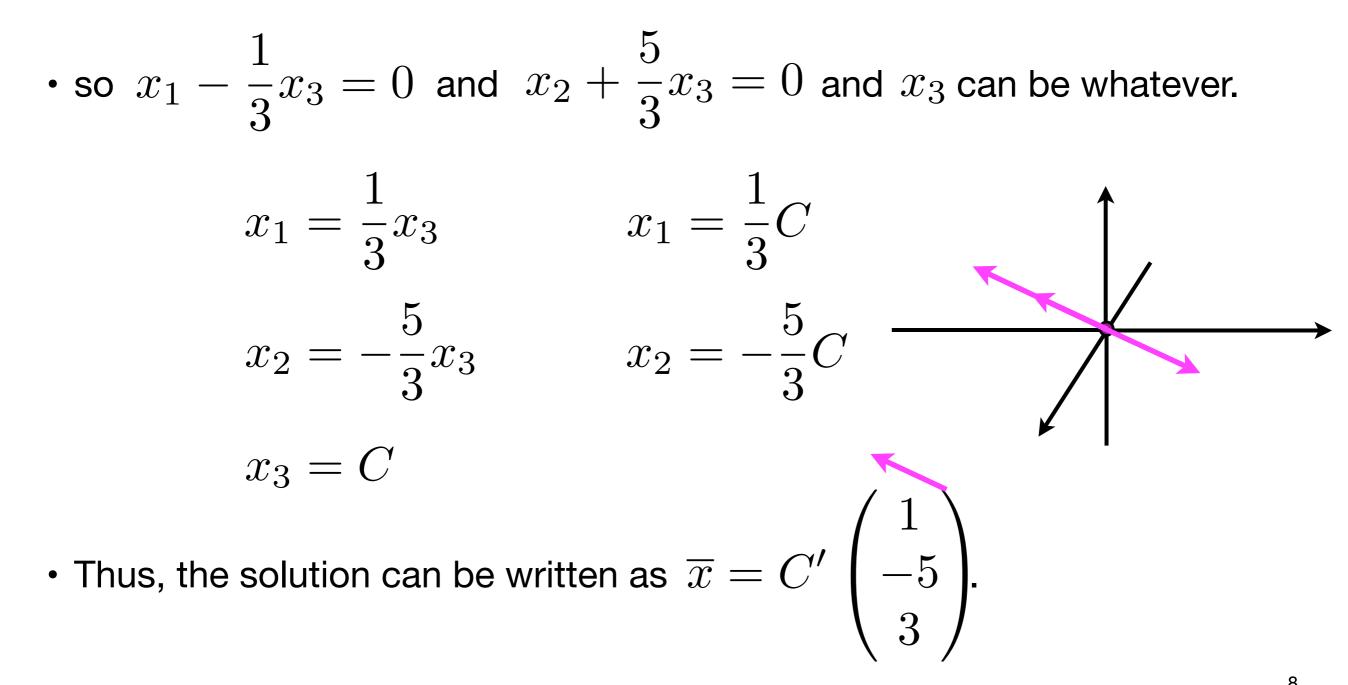
• Thus, the solution can be written as $\overline{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix}$.











• Example 1. Solve the equation $A\overline{x} = \overline{0}$.

• so
$$x_1 - \frac{1}{3}x_3 = 0$$
 and $x_2 + \frac{5}{3}x_3 = 0$ and x_3 can be whatever.

$$x_1 = \frac{1}{3}x_3 \qquad x_1 = \frac{1}{3}C$$

$$x_2 = -\frac{5}{3}x_3 \qquad x_2 = -\frac{5}{3}C$$

$$x_3 = C$$
• Thus, the solution can be written as $\overline{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix}$.

• Example 2. Solve the equation $A\overline{x} = \overline{0}$ where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \\ -1 & 2 & -1 \end{pmatrix}$$

• Example 2. Solve the equation $A\overline{x} = \overline{0}$ where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \\ -1 & 2 & -1 \end{pmatrix}$$

• Example 2. Solve the equation $A\overline{x} = \overline{0}$ where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \\ -1 & 2 & -1 \end{pmatrix}$$

$$A \sim \begin{pmatrix} 1 & -2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

• Example 2. Solve the equation $A\overline{x} = \overline{0}$ where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \\ -1 & 2 & -1 \end{pmatrix}$$

Row reduction gives

$$A \sim \begin{pmatrix} 1 & -2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

• so $x_1 - 2x_2 + x_3 = 0$ and both x_2 and x_3 can be whatever.

• Example 2. Solve the equation $A\overline{x} = \overline{0}$ where

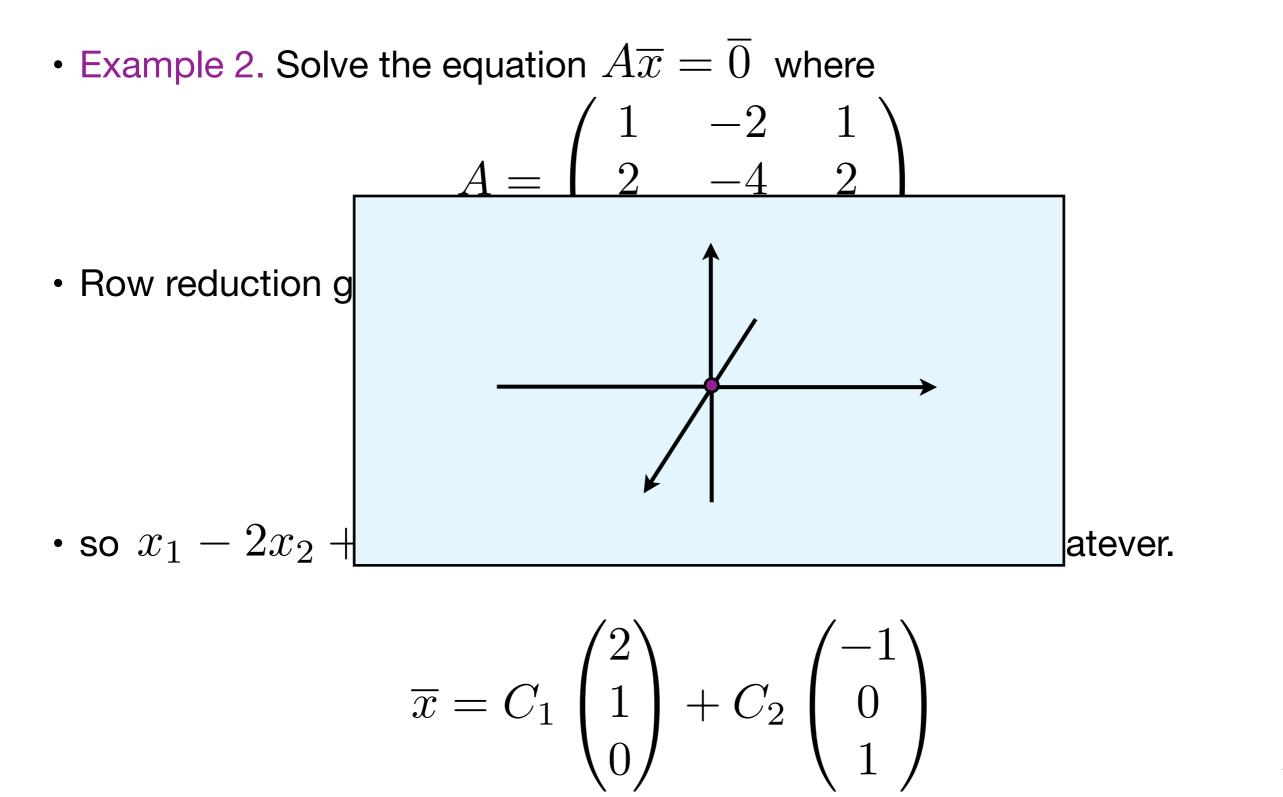
$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \\ -1 & 2 & -1 \end{pmatrix}$$

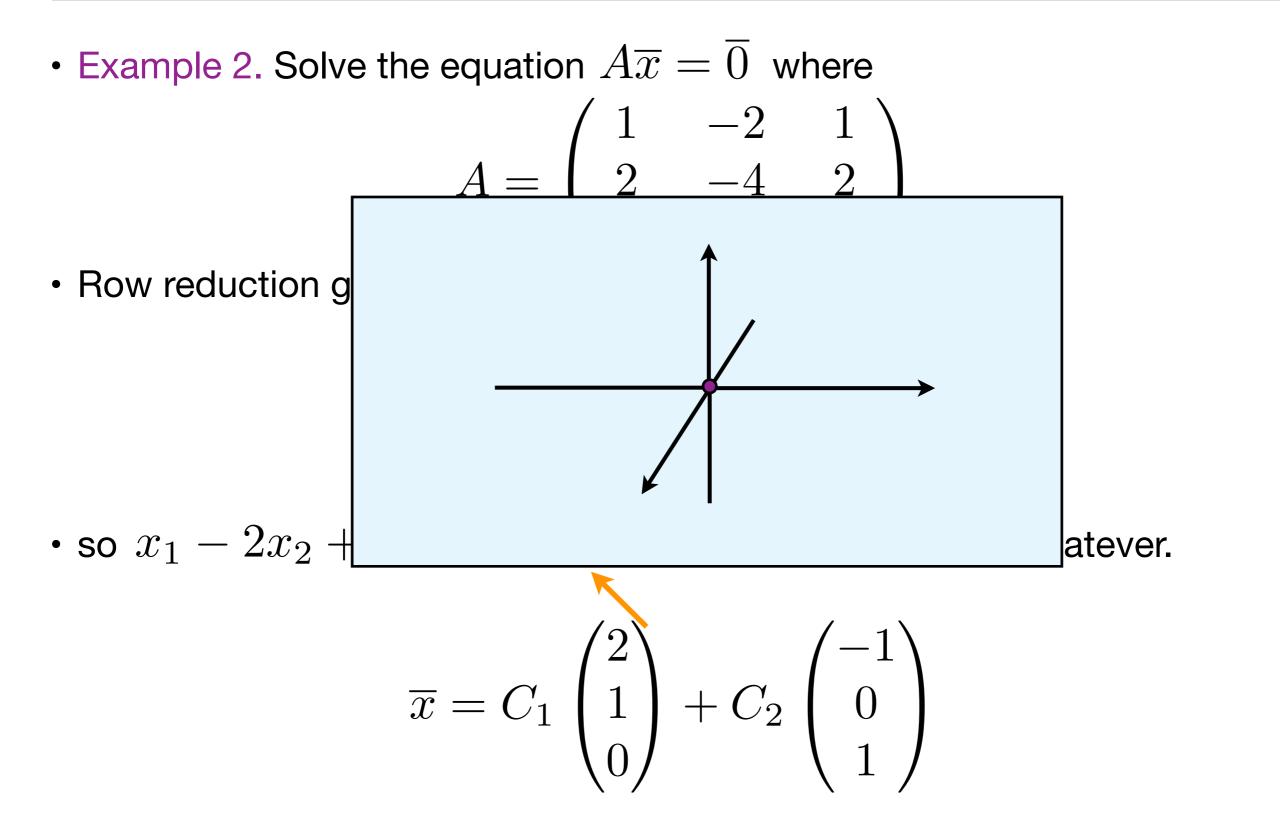
Row reduction gives

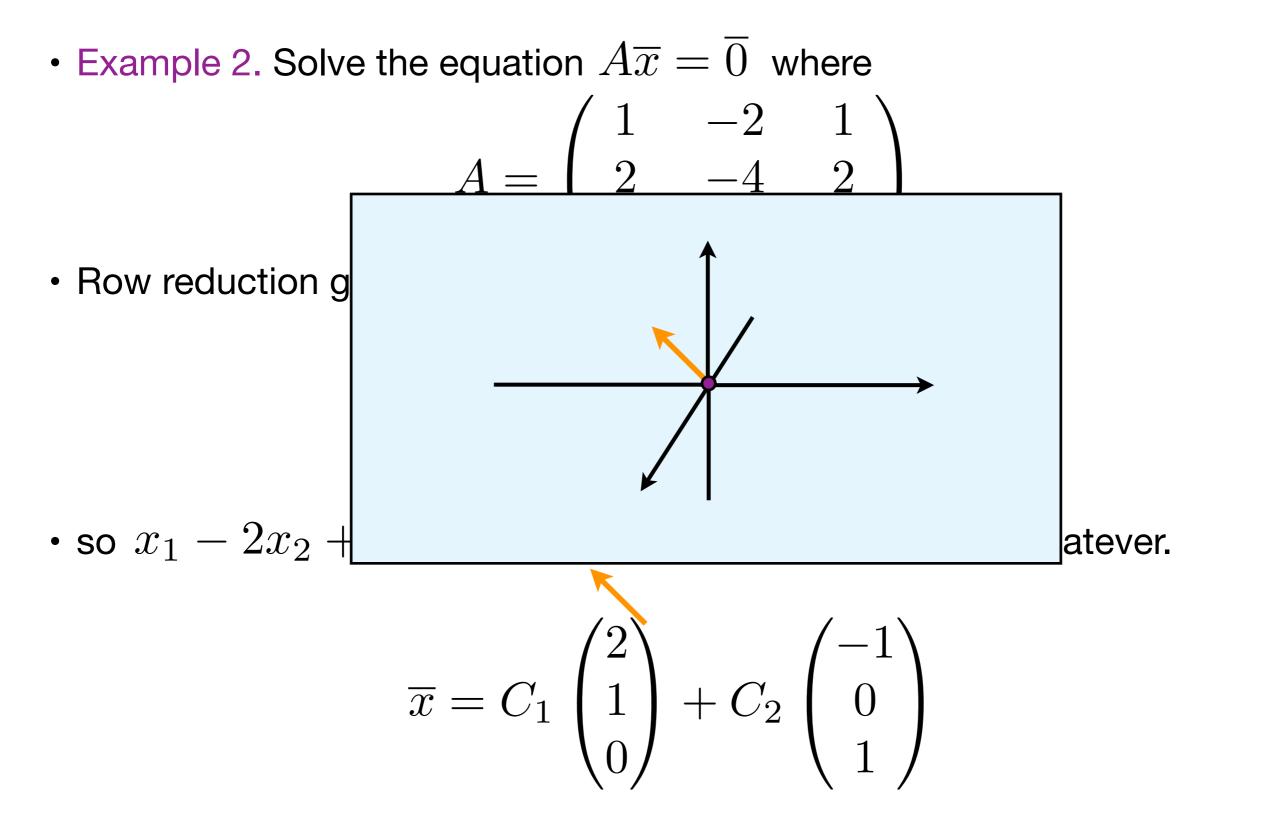
$$A \sim \begin{pmatrix} 1 & -2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

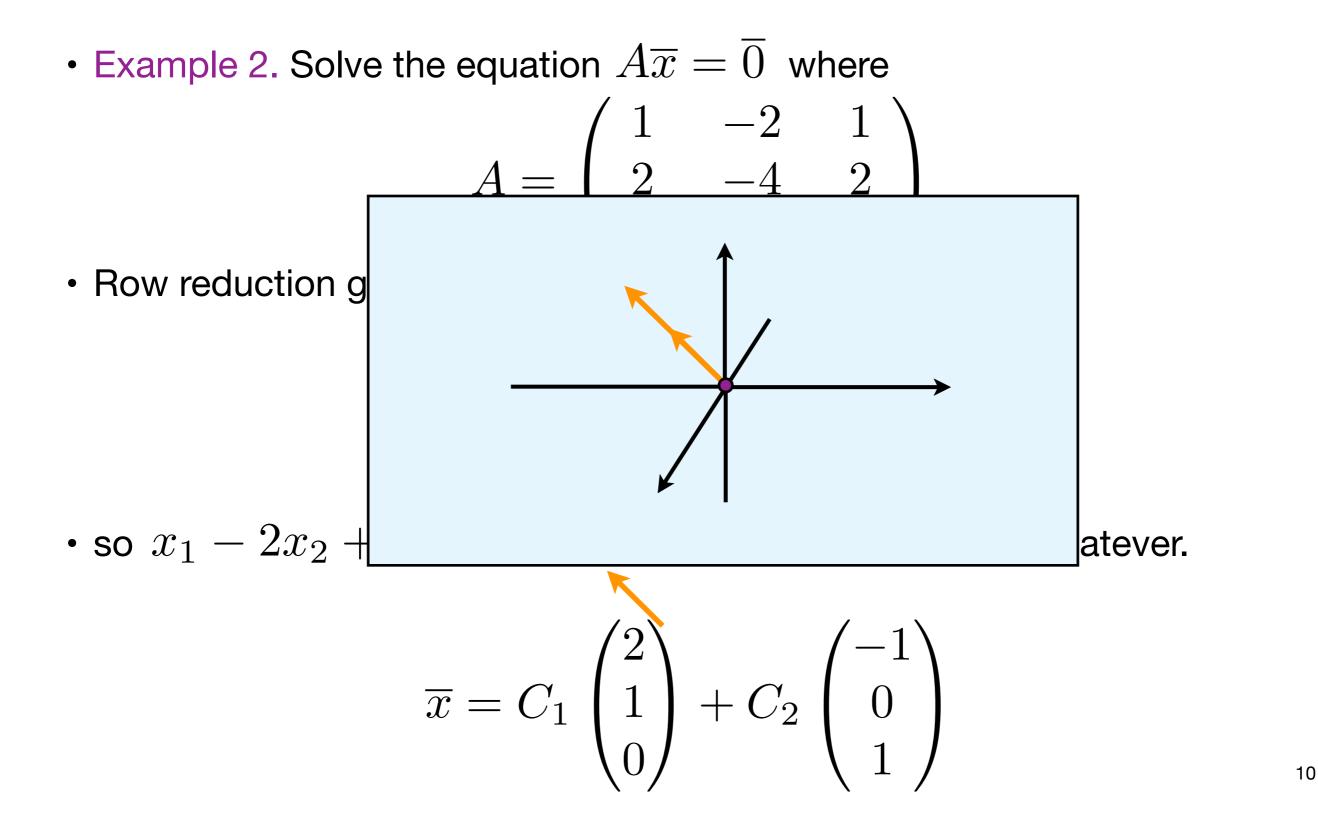
• so $x_1 - 2x_2 + x_3 = 0$ and both x_2 and x_3 can be whatever.

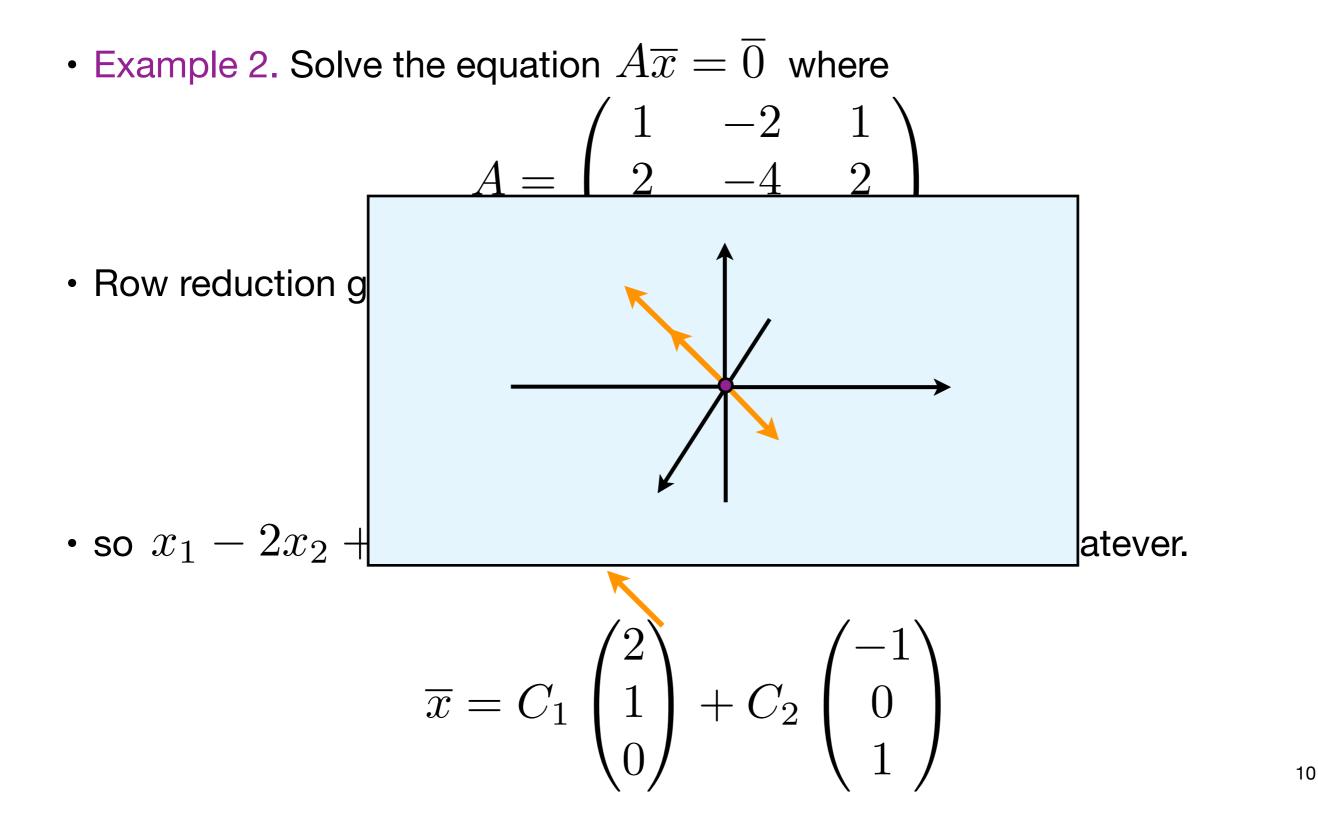
$$\overline{x} = C_1 \begin{pmatrix} 2\\1\\0 \end{pmatrix} + C_2 \begin{pmatrix} -1\\0\\1 \end{pmatrix}$$

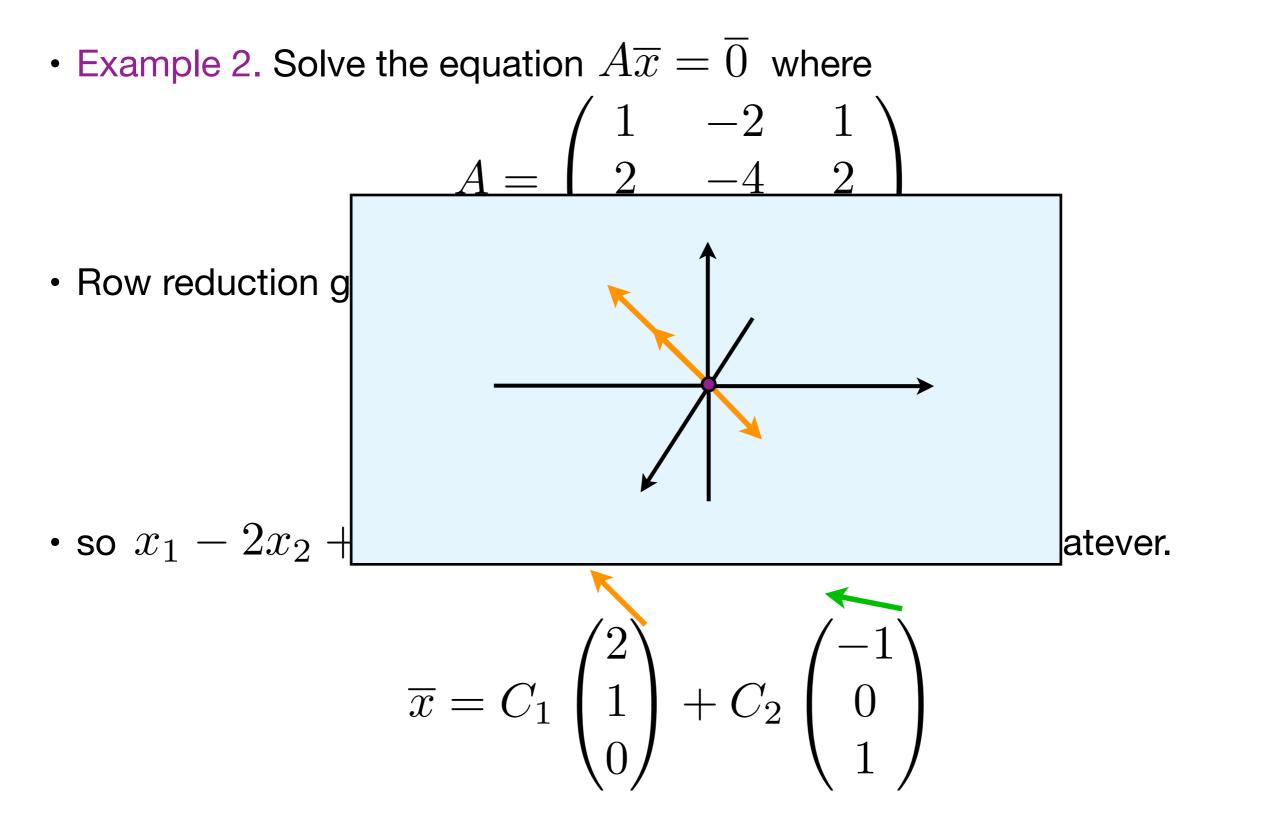


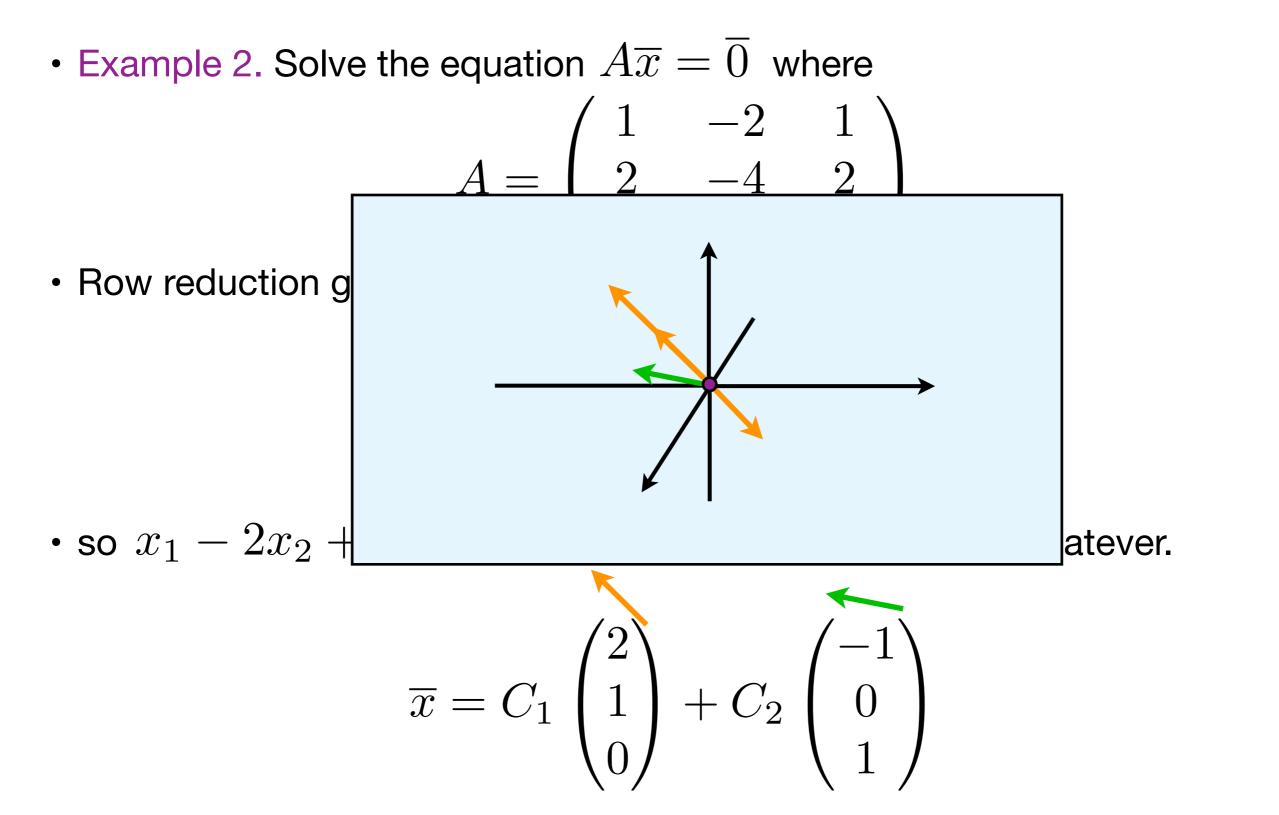


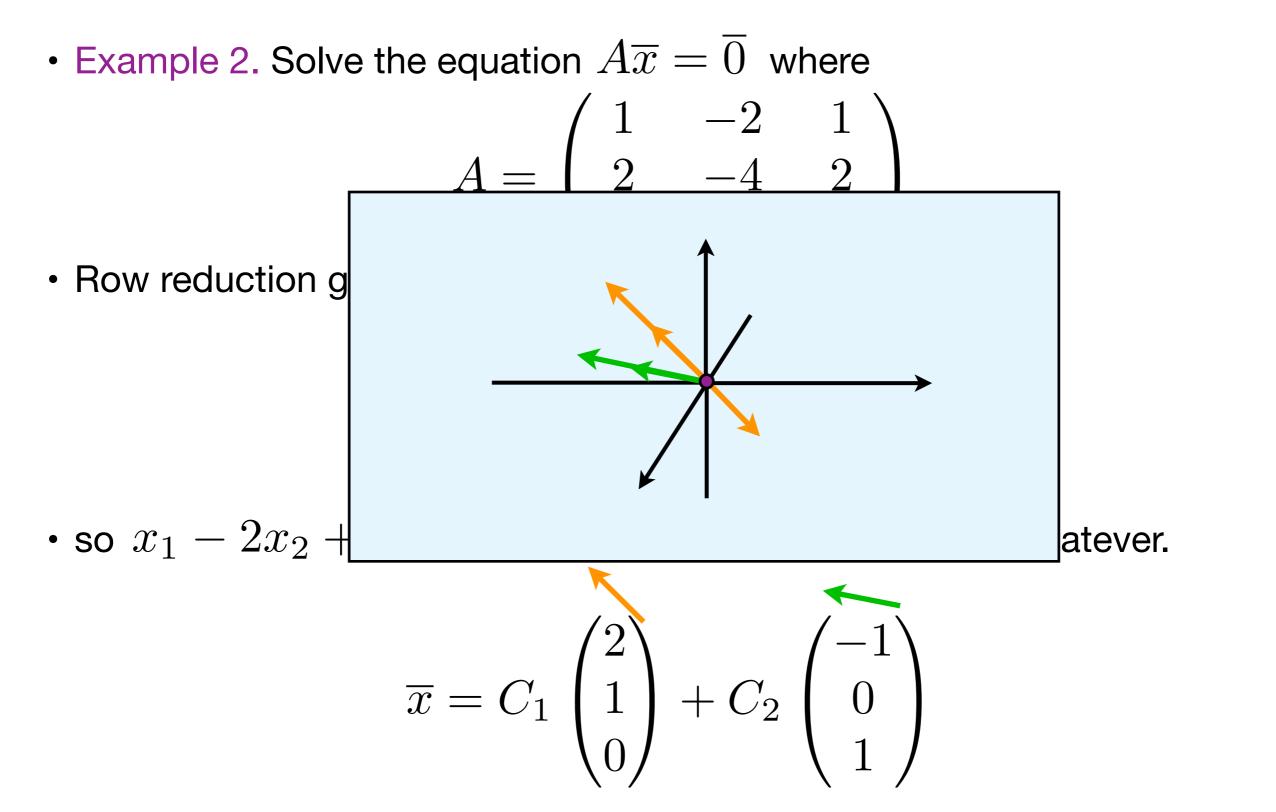


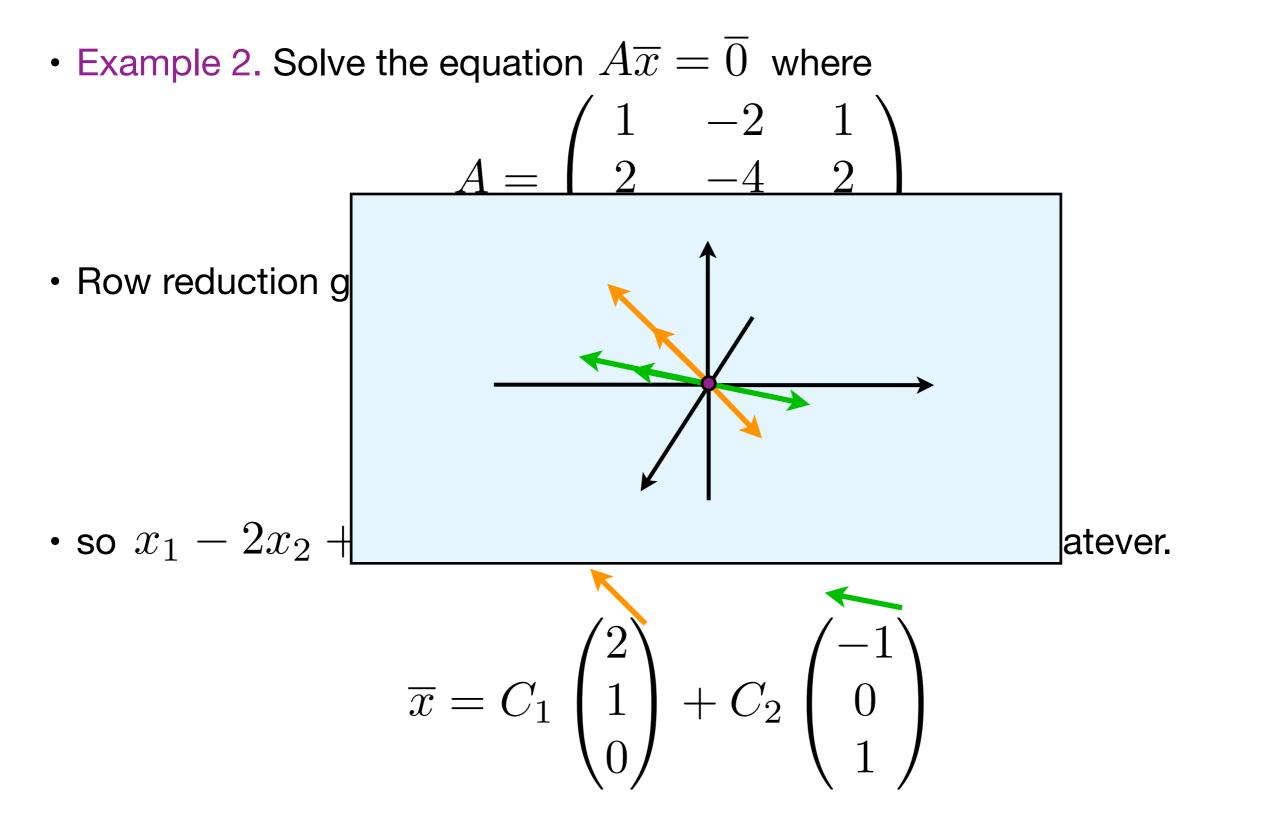




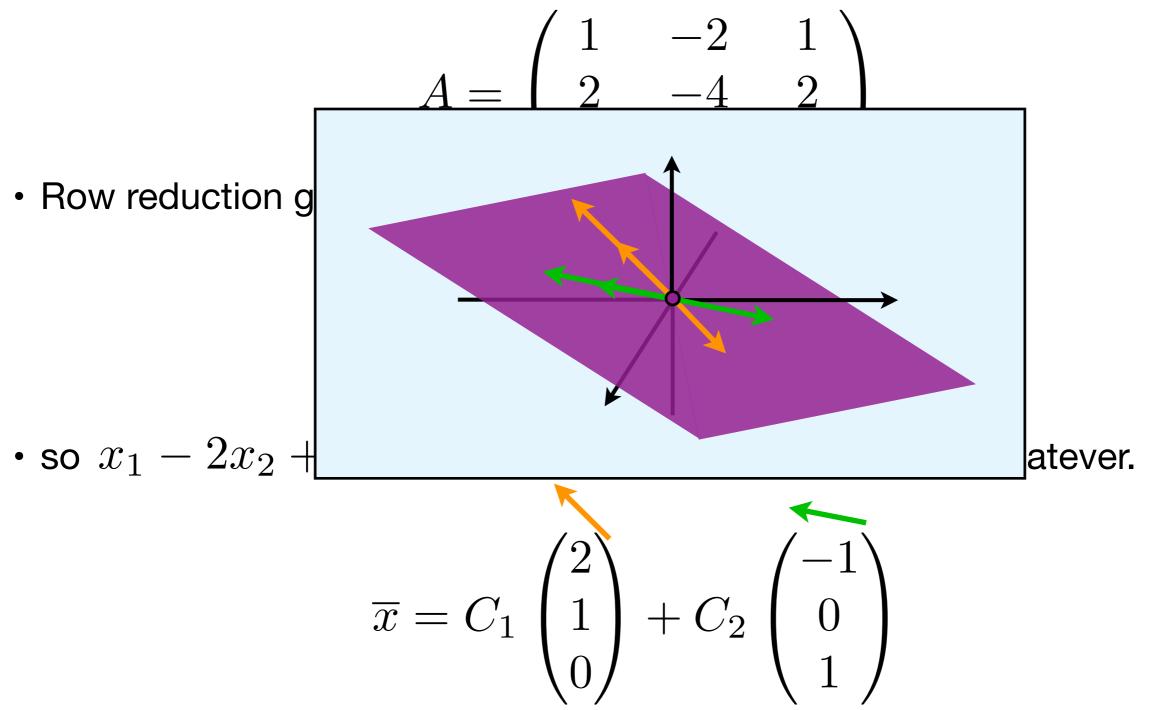












• Example 3. Solve the equation $A\overline{x} = \overline{b}$ where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix} \text{ and } \overline{b} = \begin{pmatrix} 2 \\ 0 \\ 2 \end{pmatrix}$$

• Example 3. Solve the equation $A\overline{x} = \overline{b}$ where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix} \text{ and } \overline{b} = \begin{pmatrix} 2 \\ 0 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & -1/3 & 2/3 \\ 0 & 1 & 5/3 & 2/3 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

• Example 3. Solve the equation $A\overline{x} = \overline{b}$ where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix} \text{ and } \overline{b} = \begin{pmatrix} 2 \\ 0 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & -1/3 & 2/3 \\ 0 & 1 & 5/3 & 2/3 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

• Example 3. Solve the equation $A\overline{x} = \overline{b}$ where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix} \text{ and } \overline{b} = \begin{pmatrix} 2 \\ 0 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & -1/3 & 2/3 \\ 0 & 1 & 5/3 & 2/3 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

• Example 3. Solve the equation $A\overline{x} = b$ where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix} \text{ and } \overline{b} = \begin{pmatrix} 2 \\ 0 \\ 2 \end{pmatrix}.$$

Row reduction gives

$$\begin{pmatrix} 1 & 0 & -1/3 & 2/3 \\ 0 & 1 & 5/3 & 2/3 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

• so $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$ and $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$ and x_3 can be whatever.

• Example 3. Solve the equation $A\overline{x} = \overline{b}$.

• so
$$x_1 - \frac{1}{3}x_3 = \frac{2}{3}$$
 and $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$ and x_3 can be whatever.

• Example 3. Solve the equation $A\overline{x} = \overline{b}$.

• so
$$x_1 - \frac{1}{3}x_3 = \frac{2}{3}$$
 and $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$ and x_3 can be whatever.
 $x_1 = \frac{1}{3}x_3 + \frac{2}{3}$

• Example 3. Solve the equation $A\overline{x} = \overline{b}$.

• so
$$x_1 - \frac{1}{3}x_3 = \frac{2}{3}$$
 and $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$ and x_3 can be whatever.
 $x_1 = \frac{1}{3}x_3 + \frac{2}{3}$ $x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$

- Example 3. Solve the equation $A\overline{x} = b$.
- so $x_1 \frac{1}{3}x_3 = \frac{2}{3}$ and $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$ and x_3 can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \qquad x_2 = -\frac{3}{3}x_3 + \frac{2}{3}$$

$$\overline{x} = \frac{C}{3} \begin{pmatrix} 1\\ -5\\ 3 \end{pmatrix} + \begin{pmatrix} 2/3\\ 2/3\\ 0 \end{pmatrix}$$

- Example 3. Solve the equation $A\overline{x} = b$.
- so $x_1 \frac{1}{3}x_3 = \frac{2}{3}$ and $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$ and x_3 can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \qquad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$$

$$\overline{x} = C' \begin{pmatrix} 1\\ -5\\ 3 \end{pmatrix} + \begin{pmatrix} 2/3\\ 2/3\\ 0 \end{pmatrix}$$

- Example 3. Solve the equation $A\overline{x} = b$.
- so $x_1 \frac{1}{3}x_3 = \frac{2}{3}$ and $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$ and x_3 can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \qquad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$$

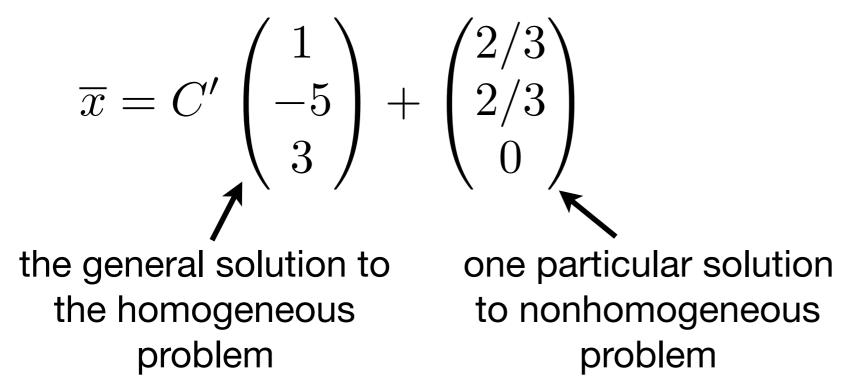
$$\overline{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$$

e general solution to

the general solution to the homogeneous problem

- Example 3. Solve the equation $A\overline{x} = b$.
- so $x_1 \frac{1}{3}x_3 = \frac{2}{3}$ and $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$ and x_3 can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \qquad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$$



- Example 3. Solve the equation $A\overline{x} = b$.
- so $x_1 \frac{1}{3}x_3 = \frac{2}{3}$ and $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$ and x_3 can be whatever. $x_1 = \frac{1}{3}x_3 + \frac{2}{3} \qquad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$ $\overline{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$ the general solution to one particular solution the homogeneous to nonhomogeneous problem problem

- Example 3. Solve the equation $A\overline{x} = b$.
- so $x_1 \frac{1}{3}x_3 = \frac{2}{3}$ and $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$ and x_3 can be whatever. $x_1 = \frac{1}{3}x_3 + \frac{2}{3} \qquad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$ $\overline{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$ the general solution to one particular solution the homogeneous to nonhomogeneous problem problem

- Example 3. Solve the equation $A\overline{x} = b$.
- so $x_1 \frac{1}{3}x_3 = \frac{2}{3}$ and $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$ and x_3 can be whatever. $x_1 = \frac{1}{3}x_3 + \frac{2}{3} \qquad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$ $\overline{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$ the general solution to one particular solution the homogeneous to nonhomogeneous problem problem

- Example 3. Solve the equation $A\overline{x} = b$.
- so $x_1 \frac{1}{3}x_3 = \frac{2}{3}$ and $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$ and x_3 can be whatever. $x_1 = \frac{1}{3}x_3 + \frac{2}{3}$ $x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$ $\overline{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$ the general solution to one particular solution the homogeneous to nonhomogeneous problem problem

- Example 3. Solve the equation $A\overline{x} = b$.
- so $x_1 \frac{1}{3}x_3 = \frac{2}{3}$ and $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$ and x_3 can be whatever. $x_1 = \frac{1}{3}x_3 + \frac{2}{3}$ $x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$ $\overline{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$ the general solution to one particular solution the homogeneous to nonhomogeneous problem problem

- Example 3. Solve the equation $A\overline{x} = b$.
- so $x_1 \frac{1}{3}x_3 = \frac{2}{3}$ and $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$ and x_3 can be whatever. $x_1 = \frac{1}{3}x_3 + \frac{2}{3}$ $x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$ $\overline{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$ the general solution to one particular solution the homogeneous to nonhomogeneous problem problem

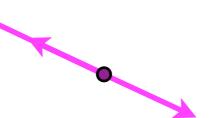
- Example 3. Solve the equation $A\overline{x} = b$.
- so $x_1 \frac{1}{3}x_3 = \frac{2}{3}$ and $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$ and x_3 can be whatever. $x_1 = \frac{1}{3}x_3 + \frac{2}{3}$ $x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$ $\overline{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$ the general solution to one particular solution the homogeneous to nonhomogeneous problem problem

Solutions to nonhomogeneous differential equations

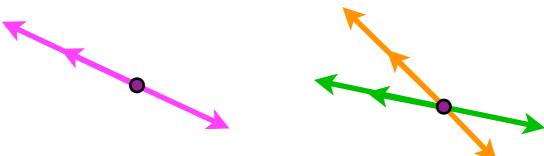
• To solve a nonhomogeneous differential equation:

- To solve a nonhomogeneous differential equation:
 - 1. Find the general solution to the associated homogeneous problem, $y_h(t)$.

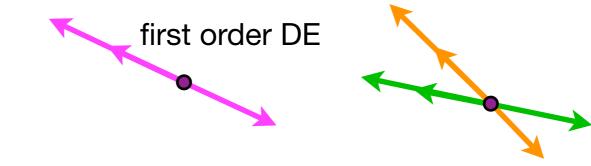
- To solve a nonhomogeneous differential equation:
 - 1. Find the general solution to the associated homogeneous problem, y_h(t).



- To solve a nonhomogeneous differential equation:
 - Find the general solution to the associated homogeneous problem, y_h(t).



- To solve a nonhomogeneous differential equation:
 - Find the general solution to the associated homogeneous problem, y_h(t).



- To solve a nonhomogeneous differential equation:
 - 1. Find the general solution to the associated homogeneous problem, y_h(t).



- To solve a nonhomogeneous differential equation:
 - Find the general solution to the associated homogeneous problem, y_h(t).

2. Find a particular solution to the nonhomogeneous problem, $y_p(t)$.

- To solve a nonhomogeneous differential equation:
 - Find the general solution to the associated homogeneous problem, y_h(t).
 first order DE

2. Find a particular solution to the nonhomogeneous problem, $y_p(t)$.



- To solve a nonhomogeneous differential equation:
 - Find the general solution to the associated homogeneous problem, y_h(t).

2. Find a particular solution to the nonhomogeneous problem, $y_p(t)$.

3. The general solution to the nonhomogeneous problem is their sum:

$$y = y_h + y_p = C_1 y_1 + C_2 y_2 + y_p$$

- To solve a nonhomogeneous differential equation:
 - Find the general solution to the associated homogeneous problem, y_h(t).

2. Find a particular solution to the nonhomogeneous problem, $y_p(t)$.

3. The general solution to the nonhomogeneous problem is their sum:

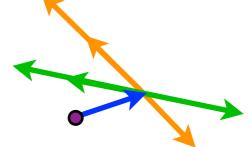
$$y = y_h + y_p = C_1 y_1 + C_2 y_2 + y_p$$

- To solve a nonhomogeneous differential equation:
 - Find the general solution to the associated homogeneous problem, y_h(t).

2. Find a particular solution to the nonhomogeneous problem, $y_p(t)$.

3. The general solution to the nonhomogeneous problem is their sum:

$$y = y_h + y_p = C_1 y_1 + C_2 y_2 + y_p$$



- To solve a nonhomogeneous differential equation:
 - Find the general solution to the associated homogeneous problem, y_h(t).

2. Find a particular solution to the nonhomogeneous problem, $y_p(t)$.

3. The general solution to the nonhomogeneous problem is their sum:

$$y = y_h + y_p = C_1 y_1 + C_2 y_2 + y_p$$

second order DE

• For step 2, try "Method of undetermined coefficients"...

• Example 4. Define the operator L[y] = y'' + 2y' - 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' - 3y = e^{2t}$.

- Example 4. Define the operator L[y] = y'' + 2y' 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' 3y = e^{2t}$.
 - Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$

- Example 4. Define the operator L[y] = y'' + 2y' 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' 3y = e^{2t}$.
 - Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$
$$y_h(t) = C_1 e^t + C_2 e^{-3t}$$

- Example 4. Define the operator L[y] = y'' + 2y' 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' 3y = e^{2t}$.
 - Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$
$$y_h(t) = C_1 e^t + C_2 e^{-3t}$$

- Example 4. Define the operator L[y] = y'' + 2y' 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' 3y = e^{2t}$.
 - Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$
$$y_h(t) = C_1 e^t + C_2 e^{-3t}$$

• Try
$$y_p(t) = Ae^{2t}$$
.

- Example 4. Define the operator L[y] = y'' + 2y' 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' 3y = e^{2t}$.
 - Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$
$$y_h(t) = C_1 e^t + C_2 e^{-3t}$$

• Try
$$y_p(t) = Ae^{2t}$$
.

•
$$L[y_p(t)] = L[Ae^{2t}] =$$

- Example 4. Define the operator L[y] = y'' + 2y' 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' 3y = e^{2t}$.
 - Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$
$$y_h(t) = C_1 e^t + C_2 e^{-3t}$$

• Try
$$y_p(t) = Ae^{2t}$$
.
• $L[y_p(t)] = L[Ae^{2t}] = \begin{cases} \text{(A) } 5e^{2t} & \text{(C) } 4e^{2t} \\ \text{(B) } 5Ae^{2t} & \text{(D) } 4Ae^{2t} \end{cases}$

- Example 4. Define the operator L[y] = y'' + 2y' 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' 3y = e^{2t}$.
 - Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$
$$y_h(t) = C_1 e^t + C_2 e^{-3t}$$

• Try
$$y_p(t) = Ae^{2t}$$
.
• $L[y_p(t)] = L[Ae^{2t}] = \begin{cases} \text{(A) } 5e^{2t} & \text{(C) } 4e^{2t} \\ \text{(B) } 5Ae^{2t} & \text{(D) } 4Ae^{2t} \end{cases}$

- Example 4. Define the operator L[y] = y'' + 2y' 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' 3y = e^{2t}$.
 - Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$
$$y_h(t) = C_1 e^t + C_2 e^{-3t}$$

• Step 2: What do you have to plug in to $L[\cdot]$ to get e^{2t} out?

• Try
$$y_p(t) = Ae^{2t}$$
.
• $L[y_p(t)] = L[Ae^{2t}] = \begin{cases} \text{(A) } 5e^{2t} & \text{(C) } 4e^{2t} \\ \text{(B) } 5Ae^{2t} & \text{(D) } 4Ae^{2t} \end{cases}$

• A is an undetermined coefficient (until you determine it).

• Example 4. Define the operator L[y] = y'' + 2y' - 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' - 3y = e^{2t}$.

- Example 4. Define the operator L[y] = y'' + 2y' 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' 3y = e^{2t}$.
 - Summarizing:

- Example 4. Define the operator L[y] = y'' + 2y' 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' 3y = e^{2t}$.
 - Summarizing:
 - We know that, for any C₁ and C₂,

$$L[C_1e^t + C_2e^{-3t}] = 0$$

- Example 4. Define the operator L[y] = y'' + 2y' 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' 3y = e^{2t}$.
 - Summarizing:
 - We know that, for any C₁ and C₂,

$$L[C_1e^t + C_2e^{-3t}] = 0$$

• We also know that

$$L[Ae^{2t}] = 5Ae^{2t}$$

- Example 4. Define the operator L[y] = y'' + 2y' 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' 3y = e^{2t}$.
 - Summarizing:
 - We know that, for any C₁ and C₂,

$$L[C_1e^t + C_2e^{-3t}] = 0$$

We also know that

$$L[Ae^{2t}] = 5Ae^{2t}$$

• Finally, by linearity, we know that

$$L[C_1e^t + C_2e^{-3t} + Ae^{2t}] = 0 + 5Ae^{2t}$$

- Example 4. Define the operator L[y] = y'' + 2y' 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' 3y = e^{2t}$.
 - Summarizing:
 - We know that, for any C₁ and C₂,

$$L[C_1e^t + C_2e^{-3t}] = 0$$

We also know that

$$L[Ae^{2t}] = 5Ae^{2t}$$

• Finally, by linearity, we know that

$$L[C_1e^t + C_2e^{-3t} + Ae^{2t}] = 0 + 5Ae^{2t}$$

So what's left to do to find our general solution? Pick A =?

- Example 4. Define the operator L[y] = y'' + 2y' 3y. Find the general solution to $L[y] = e^{2t}$. That is, $y'' + 2y' 3y = e^{2t}$.
 - Summarizing:
 - We know that, for any C₁ and C₂,

$$L[C_1e^t + C_2e^{-3t}] = 0$$

We also know that

$$L[Ae^{2t}] = 5Ae^{2t}$$

• Finally, by linearity, we know that

$$L[C_1e^t + C_2e^{-3t} + Ae^{2t}] = 0 + 5Ae^{2t}$$

• So what's left to do to find our general solution? Pick A = 1/5.

- Example 5. Find the general solution to the equation $y'' 4y = e^t$.
 - What is the solution to the associated homogeneous equation?

(A)
$$y_h(t) = C_1 e^{2t} + C_2 e^{-2t}$$

(B) $y_h(t) = C_1 \cos(2t) + C_2 \sin(2t)$
(C) $y_h(t) = C_1 e^{2t} + C_2 t e^{2t}$
(D) $y_h(t) = C_1 \cos(2t) + C_2 \sin(2t) + e^t$

- Example 5. Find the general solution to the equation $y'' 4y = e^t$.
 - What is the solution to the associated homogeneous equation?

$$A (A) y_h(t) = C_1 e^{2t} + C_2 e^{-2t}$$
(B) $y_h(t) = C_1 \cos(2t) + C_2 \sin(2t)$
(C) $y_h(t) = C_1 e^{2t} + C_2 t e^{2t}$
(D) $y_h(t) = C_1 \cos(2t) + C_2 \sin(2t) + e^t$

- Example 5. Find the general solution to the equation $y'' 4y = e^t$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = Ae^{2t}$$

(B)
$$y_p(t) = Ae^{-2t}$$

(C)
$$y_p(t) = Ae^t$$

(D)
$$y_p(t) = Ate^t$$

- Example 5. Find the general solution to the equation $y'' 4y = e^t$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = Ae^{2t}$$

(B)
$$y_p(t) = Ae^{-2t}$$

$$\bigstar(C) \quad y_p(t) = Ae^t$$

(D)
$$y_p(t) = Ate^t$$

- Example 5. Find the general solution to the equation $y'' 4y = e^t$.
 - What is the value of A that gives the particular solution (Ae^t) ?

(B)
$$A = 3$$

(C)
$$A = 1/3$$

(D) A = -1/3

- Example 5. Find the general solution to the equation $y'' 4y = e^t$.
 - What is the value of A that gives the particular solution (Ae^t) ?

(B)
$$A = 3$$

(C)
$$A = 1/3$$

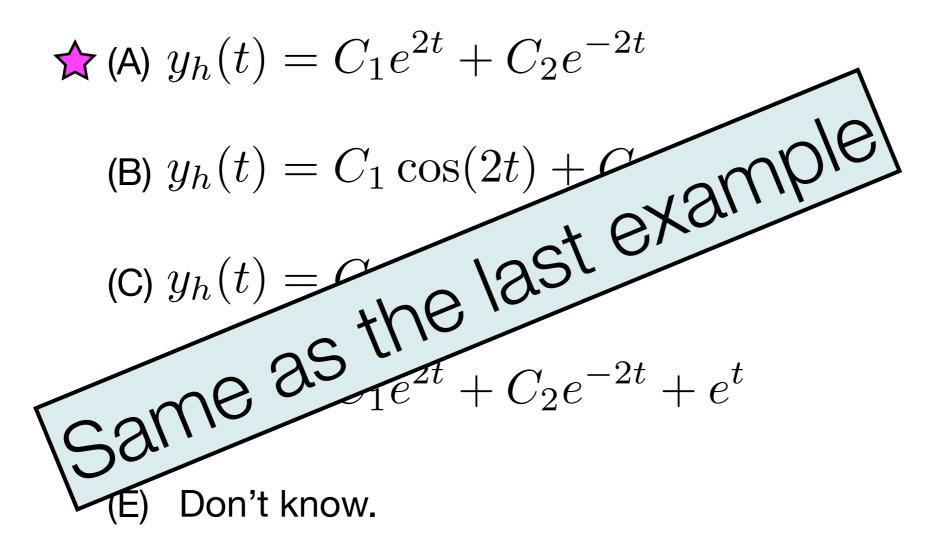
(D)
$$A = -1/3$$

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the solution to the associated homogeneous equation?

(A)
$$y_h(t) = C_1 e^{2t} + C_2 e^{-2t}$$

(B) $y_h(t) = C_1 \cos(2t) + C_2 \sin(2t)$
(C) $y_h(t) = C_1 e^{2t} + C_2 t e^{2t}$
(D) $y_h(t) = C_1 e^{2t} + C_2 e^{-2t} + e^t$

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the solution to the associated homogeneous equation?



- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = Ae^{2t}$$

(B)
$$y_p(t) = Ae^{-2t}$$

(C)
$$y_p(t) = Ate^{2t}$$

(D)
$$y_p(t) = Ae^t$$

(E) $y_p(t) = Ate^t$

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = Ae^{2t}$$
 $(Ae^{2t})'' - 4Ae^{2t} = 0 !$
(B) $y_p(t) = Ae^{-2t}$
(C) $y_p(t) = Ate^{2t}$
(D) $y_p(t) = Ae^t$
(E) $y_p(t) = Ate^t$

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = Ae^{2t}$$

(B)
$$y_p(t) = Ae^{-2t}$$

(C)
$$y_p(t) = Ate^{2t}$$

(D)
$$y_p(t) = Ae^t$$

(E) $y_p(t) = Ate^t$

$$(Ae^{2t})'' - 4Ae^{2t} = 0!$$

$$y' - y = e^t$$

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = Ae^{2t}$$

(B)
$$y_p(t) = Ae^{-2t}$$

(C)
$$y_p(t) = Ate^{2t}$$

(D)
$$y_p(t) = Ae^t$$

(E) $y_p(t) = Ate^t$

$$(Ae^{2t})'' - 4Ae^{2t} = 0 !$$

$$y' - y = e^t$$
$$e^{-t}y' - e^{-t}y = 1$$

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = Ae^{2t}$$

(B)
$$y_p(t) = Ae^{-2t}$$

(C)
$$y_p(t) = Ate^{2t}$$

(D)
$$y_p(t) = Ae^t$$

(E) $y_p(t) = Ate^t$

$$(Ae^{2t})'' - 4Ae^{2t} = 0!$$

$$y' - y = e^{t}$$
$$e^{-t}y' - e^{-t}y = 1$$
$$y = te^{t} + Ce^{t}$$

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = Ae^{2t}$$

(B)
$$y_p(t) = Ae^{-2t}$$

(C)
$$y_p(t) = Ate^{2t}$$

(D)
$$y_p(t) = Ae^t$$

(E) $y_p(t) = Ate^t$

$$(Ae^{2t})'' - 4Ae^{2t} = 0!$$

$$y' - y = e^{t}$$
$$e^{-t}y' - e^{-t}y = 1$$
$$y = te^{t} + Ce^{t}$$

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = Ae^{2t}$$

(B)
$$y_p(t) = Ae^{-2t}$$

$$\bigstar$$
 (C) $y_p(t) = Ate^{2t}$

(D)
$$y_p(t) = Ae^t$$

(E) $y_p(t) = Ate^t$

$$(Ae^{2t})'' - 4Ae^{2t} = 0!$$

$$y' - y = e^{t}$$
$$e^{-t}y' - e^{-t}y = 1$$
$$y = te^{t} + Ce^{t}$$

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = Ae^{2t}$$

(B)
$$y_p(t) = Ae^{-2t}$$

$$\bigstar$$
 (C) $y_p(t) = Ate^{2t}$

(D)
$$y_p(t) = Ae^t$$

(E) $y_p(t) = Ate^t$

$$(Ae^{2t})'' - 4Ae^{2t} = 0!$$

• Simpler example in which the RHS is a solution to the homogeneous problem.

$$y' - y = e^{t}$$
$$e^{-t}y' - e^{-t}y = 1$$
$$y = te^{t} + Ce^{t}$$

• General rule: when your guess at y_p makes LHS=0, try multiplying it by t. ₂₀

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the value of A that gives the particular solution (Ate^{2t}) ?

(B)
$$A = 4$$

(C)
$$A = -4$$

(D)
$$A = 1/4$$

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the value of A that gives the particular solution (Ate^{2t}) ?

(A)
$$A = 1$$

 $(Ate^{2t})' = Ae^{2t} + 2Ate^{2t}$
(B) $A = 4$
(C) $A = -4$
(D) $A = 1/4$
(E) $A = -1/4$

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the value of A that gives the particular solution (Ate^{2t}) ?

(A)
$$A = 1$$

 $(Ate^{2t})' = Ae^{2t} + 2Ate^{2t}$
(B) $A = 4$
 $(Ate^{2t})'' = 2Ae^{2t} + 2Ae^{2t} + 4Ate^{2t}$
(C) $A = -4$

(D) A = 1/4

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the value of A that gives the particular solution (Ate^{2t}) ?

(A)
$$A = 1$$

(Ate^{2t})' = $Ae^{2t} + 2Ate^{2t}$
(B) $A = 4$
(Ate^{2t})" = $2Ae^{2t} + 2Ae^{2t} + 4Ate^{2t}$
(C) $A = -4$
= $4Ae^{2t} + 4Ate^{2t}$

(D) A = 1/4

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the value of A that gives the particular solution (Ate^{2t}) ?

(A)
$$A = 1$$

(Ate^{2t})' = $Ae^{2t} + 2Ate^{2t}$
(B) $A = 4$
(Ate^{2t})'' = $2Ae^{2t} + 2Ae^{2t} + 4Ate^{2t}$
(C) $A = -4$
(Ate^{2t})'' - 4 (Ate^{2t}) =

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the value of A that gives the particular solution (Ate^{2t}) ?

(A)
$$A = 1$$

(Ate^{2t})' = $Ae^{2t} + 2Ate^{2t}$
(B) $A = 4$
(Ate^{2t})'' = $2Ae^{2t} + 2Ae^{2t} + 4Ate^{2t}$
(C) $A = -4$
(D) $A = 1/4$
(Ate^{2t})'' - 4 (Ate^{2t}) =

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the value of A that gives the particular solution (Ate^{2t}) ?

(A)
$$A = 1$$

(Ate^{2t})' = $Ae^{2t} + 2Ate^{2t}$
(B) $A = 4$
(Ate^{2t})'' = $2Ae^{2t} + 2Ae^{2t} + 4Ate^{2t}$
(C) $A = -4$
(D) $A = 1/4$
(Ate^{2t})'' - 4 (Ate^{2t}) = $4Ae^{2t}$

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the value of A that gives the particular solution (Ate^{2t}) ?

(A)
$$A = 1$$

 $(Ate^{2t})' = Ae^{2t} + 2Ate^{2t}$
(B) $A = 4$
 $(Ate^{2t})'' = 2Ae^{2t} + 2Ae^{2t} + 4Ate^{2t}$
(C) $A = -4$
 $(Ate^{2t})'' - 4(Ate^{2t}) = 4Ae^{2t}$
(D) $A = 1/4$
 $(Ate^{2t})'' - 4(Ate^{2t}) = 4Ae^{2t}$
(E) $A = -1/4$
Need: $= e^{2t}$

- Example 6. Find the general solution to the equation $y'' 4y = e^{2t}$.
 - What is the value of A that gives the particular solution (Ate^{2t}) ?

(A)
$$A = 1$$

(Ate^{2t})' = $Ae^{2t} + 2Ate^{2t}$
(B) $A = 4$
(Ate^{2t})" = $2Ae^{2t} + 2Ae^{2t} + 4Ate^{2t}$
(C) $A = -4$
(D) $A = 1/4$
(Ate^{2t})" - 4 (Ate^{2t}) = $4Ae^{2t}$
(E) $A = -1/4$
Need: $= e^{2t}$

- Example 7. Find the general solution to $y'' 4y = \cos(2t)$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = A\cos(2t)$$

(B)
$$y_p(t) = A\sin(2t)$$

(C)
$$y_p(t) = A\cos(2t) + B\sin(2t)$$

(D)
$$y_p(t) = t(A\cos(2t) + B\sin(2t))$$

(E)
$$y_p(t) = e^{2t} (A\cos(2t) + B\sin(2t))$$

- Example 7. Find the general solution to $y'' 4y = \cos(2t)$.
 - What is the form of the particular solution?

- Example 7. Find the general solution to $y'' 4y = \cos(2t)$.
 - What is the form of the particular solution?

$$\begin{aligned} &\bigstar (A) \quad y_p(t) = A\cos(2t) \\ &(B) \quad y_p(t) = A\sin(2t) \\ &\bigstar (C) \quad y_p(t) = A\cos(2t) + B\sin(2t) \\ &(D) \quad y_p(t) = t(A\cos(2t) + B\sin(2t)) \\ &(E) \quad y_p(t) = e^{2t}(A\cos(2t) + B\sin(2t)) \end{aligned}$$

Challenge: What small change to the DE makes (D) correct?

- Example 7. Find the general solution to $y'' + y' 4y = \cos(2t)$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = A\cos(2t)$$

(B)
$$y_p(t) = A\sin(2t)$$

(C)
$$y_p(t) = A\cos(2t) + B\sin(2t)$$

(D)
$$y_p(t) = t(A\cos(2t) + B\sin(2t))$$

(E)
$$y_p(t) = e^{2t} (A\cos(2t) + B\sin(2t))$$

- Example 7. Find the general solution to $y'' + y' 4y = \cos(2t)$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = A\cos(2t)$$

(B)
$$y_p(t) = A\sin(2t)$$

$$rightarrow (C) \quad y_p(t) = A\cos(2t) + B\sin(2t)$$

(D)
$$y_p(t) = t(A\cos(2t) + B\sin(2t))$$

(E)
$$y_p(t) = e^{2t} (A\cos(2t) + B\sin(2t))$$

- Example 8. Find the general solution to $y'' 4y = t^3$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = At^3$$

(B)
$$y_p(t) = At^3 + Bt^2 + Ct$$

(C)
$$y_p(t) = At^3 + Bt^2 + Ct + D$$

(D)
$$y_p(t) = At^3 + Be^{2t} + Ce^{-2t}$$

(E) Don't know.

- Example 8. Find the general solution to $y'' 4y = t^3$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = At^3$$

(B)
$$y_p(t) = At^3 + Bt^2 + Ct$$

☆ (C)
$$y_p(t) = At^3 + Bt^2 + Ct + D$$

(D)
$$y_p(t) = At^3 + Be^{2t} + Ce^{-2t}$$

(E) Don't know.

- Example 8. Find the general solution to $y'' 4y = t^3$.
 - What is the form of the particular solution?

(A)
$$y_p(t) = At^3$$

(B)
$$y_p(t) = At^3 + Bt^2 + Ct$$

$$rightarrow (C) \quad y_p(t) = At^3 + Bt^2 + Ct + D$$

(D)
$$y_p(t) = At^3 + Be^{2t} + Ce^{-2t}$$

waste of time including
solution to homogeneous eq.

• When RHS is sum of terms:

$$y'' - 4y = \cos(2t) + t^3$$

 $y_p(t) = A\cos(2t) + B\sin(2t) + Ct^3 + Dt^2 + Et + F$

When RHS is sum of terms:

$$y'' - 4y = \cos(2t) + t^3$$

 $y_p(t) = A\cos(2t) + B\sin(2t) + Ct^3 + Dt^2 + Et + F$

or

$$y_{p_1}(t) = A\cos(2t) + B\sin(2t)$$

 $y_{p_2}(t) = Ct^3 + Dt^2 + Et + F$
 $y_p(t) = y_{p_1}(t) + y_{p_2}(t)$