### Today

- General solution for complex eigenvalues case.
- Shapes of solutions for complex eigenvalues case.

#### Calculating eigenvalues - trace/det shortcut

For the general matrix

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

· find the characteristic equation and solve it to find the eigenvalues.

(A) 
$$\lambda^2 + (ad - bc)\lambda + a + d = 0$$

(B) 
$$\lambda^2 + (b+c)\lambda + ac - bd = 0$$

(C) 
$$\lambda^2 - (a+d)\lambda + ad - bc = 0$$

(D) 
$$\lambda^2 + (a - d)\lambda + ad + bc = 0$$

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$$\lambda^2$$
 
$$\lambda^2 - \operatorname{tr}(A)\lambda + \det(A) = 0$$
 (B)  $\lambda^2 + (\upsilon + c)\lambda + ac - \upsilon a = 0$ 

$$(C) \lambda^2 - (a+d)\lambda + ad - bc = 0$$

(D) 
$$\lambda^2 + (a - d)\lambda + ad + bc = 0$$

- Find the general solution to  $\mathbf{x}' = \begin{pmatrix} 1 & 1 \\ -4 & 1 \end{pmatrix} \mathbf{x}$  .
  - The eigenvalues are

(A) 
$$\lambda = 1 \pm 2i$$

(B) 
$$\lambda = -1, 3$$

(C) 
$$\lambda = 2 \pm 4i$$

(D) 
$$\lambda = -2, 6$$

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• The eigenvectors are . . .

$$A - \lambda_1 I = \begin{pmatrix} 1 - (1+2i) & 1 \\ -4 & 1 - (1+2i) \end{pmatrix}$$
$$= \begin{pmatrix} -2i & 1 \\ -4 & -2i \end{pmatrix} \times \frac{1}{2}i$$
$$\sim \begin{pmatrix} -2i & 1 \\ -2i & 1 \end{pmatrix}$$
$$\mathbf{v_1} = \begin{pmatrix} 1 \\ 2i \end{pmatrix}$$

$$\mathbf{v_2} = \begin{pmatrix} 1 \\ -2i \end{pmatrix}$$

We could just write down a (complex valued) general solution:

$$\mathbf{x}(\mathbf{t}) = C_1 e^{(1+2i)t} \begin{pmatrix} 1\\2i \end{pmatrix} + C_2 e^{(1-2i)t} \begin{pmatrix} 1\\-2i \end{pmatrix}$$

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• Find e-values,  $\lambda=\alpha\pm\beta i$  , and e-vectors,  $\mathbf{v}=\begin{pmatrix}a_1\\a_2\end{pmatrix}\pm i\begin{pmatrix}b_1\\b_2\end{pmatrix}$ .

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• Suppose you find eigenvalue  $\lambda=2\pi i$  and eigenvector  $\mathbf{v}=\begin{pmatrix}1\\i\end{pmatrix}$  . Which of the following is a solution to the original equation?

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$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

(B) 
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t)$$

(C) 
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$$(\mathbf{C}) \quad \mathbf{x}(\mathbf{t}) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t)$$

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= \begin{pmatrix} \cos(2\pi t) + i\sin(2\pi t) \\ -\sin(2\pi t) + i\cos(2\pi t) \end{pmatrix} \\
= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t) \\
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= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t) \\
+i \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t)$$

• Suppose you find eigenvalue  $\lambda=2\pi i$  and eigenvector  $\mathbf{v}=\begin{pmatrix}1\\i\end{pmatrix}$ . Which of the following is a solution to the original equation?

$$\overline{\mathbf{x}}(\mathbf{t}) = e^{2\pi i t} \begin{pmatrix} 1 \\ i \end{pmatrix}$$
$$= (\cos(2\pi t) + i\sin(2\pi t)) \begin{pmatrix} 1 \\ i \end{pmatrix}$$

 Sum and difference trick lets us take the Real and Imaginary parts as two indep. solutions

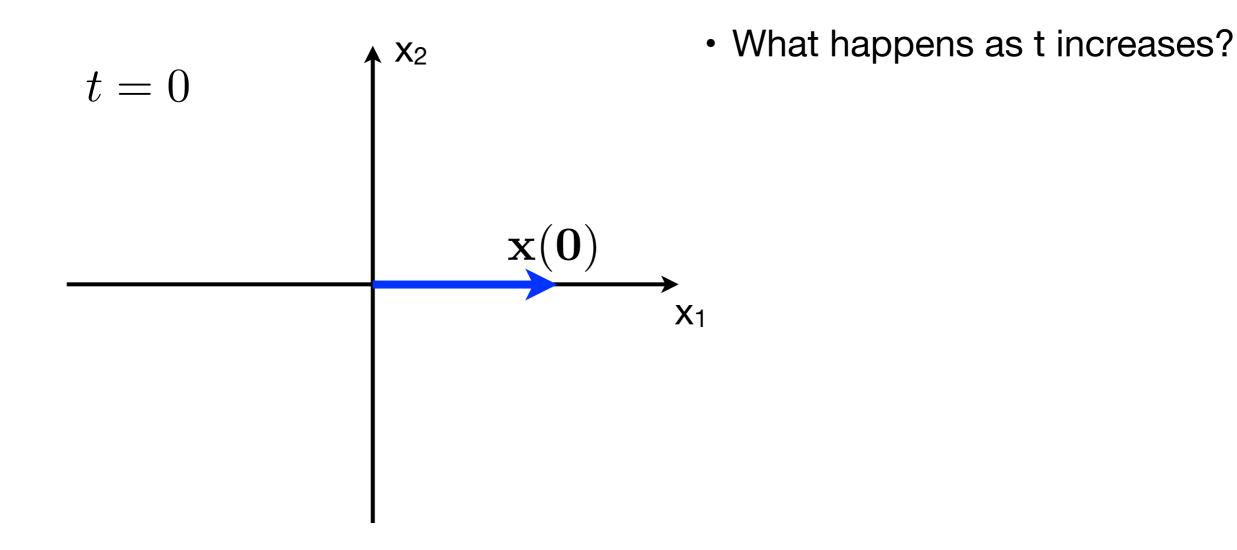
$$= \begin{pmatrix} \cos(2\pi t) + i\sin(2\pi t) \\ -\sin(2\pi t) + i\cos(2\pi t) \end{pmatrix}$$
$$= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$
$$+i \begin{bmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) \end{bmatrix}$$

• But what about  $\lambda_2 = -2\pi i$  and  $\mathbf{v_2} = \begin{pmatrix} 1 \\ -i \end{pmatrix}$ ?  $\overline{\mathbf{x}}(\mathbf{t}) = e^{-2\pi i t} \begin{pmatrix} 1 \\ -i \end{pmatrix}$  $= (\cos(-2\pi t) + i\sin(-2\pi t)) \begin{pmatrix} 1\\ -i \end{pmatrix}$  $= \begin{pmatrix} \cos(2\pi t) - i\sin(2\pi t) \\ -\sin(2\pi t) - i\cos(2\pi t) \end{pmatrix}$  $= \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$  $-i \left| \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) \right|$ 

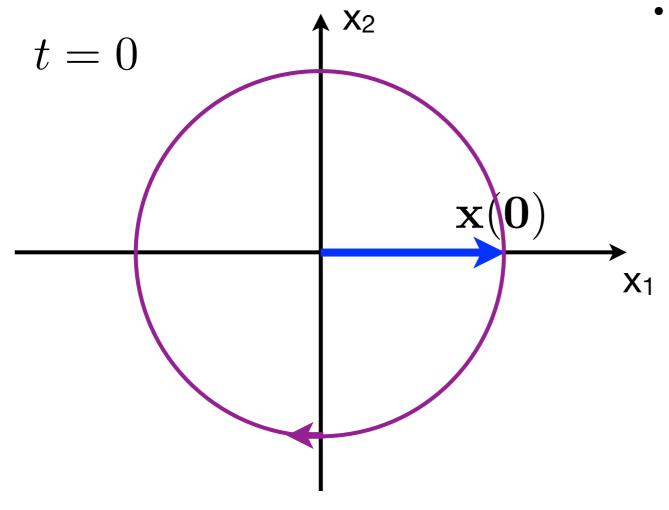
• But what about 
$$\lambda_2=-2\pi i$$
 and  $\mathbf{v_2}=\begin{pmatrix}1\\-i\end{pmatrix}$ ? 
$$\overline{\mathbf{x}}(\mathbf{t})=e^{-2\pi it}\begin{pmatrix}1\\-i\end{pmatrix}\\=\left(\cos(-2\pi t)+i\sin(-2\pi t)\right)\begin{pmatrix}1\\-i\end{pmatrix}\\=\left(\frac{\cos(2\pi t)-i\sin(2\pi t)}{-\sin(2\pi t)-i\cos(2\pi t)}\right)$$
 
$$=\begin{pmatrix}1\\0\end{pmatrix}\cos(2\pi t)-\begin{pmatrix}0\\1\\\sin(2\pi t)\end{pmatrix}$$
 
$$=\begin{pmatrix}1\\0\end{pmatrix}\cos(2\pi t)+\begin{pmatrix}1\\0\\1\end{pmatrix}\sin(2\pi t)$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



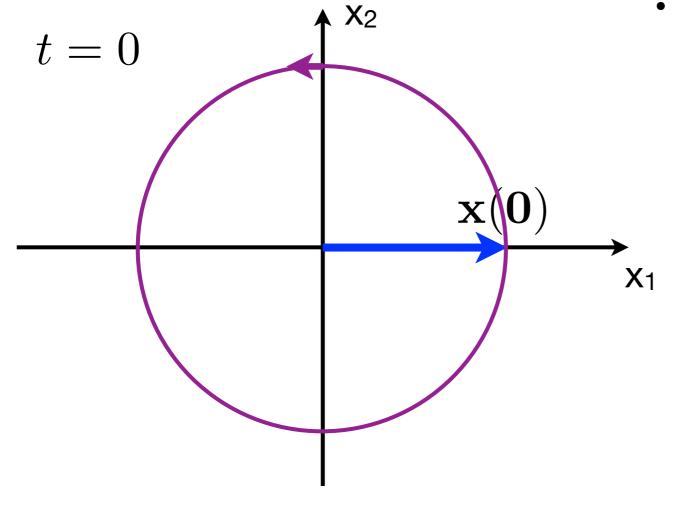
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



What happens as t increases?

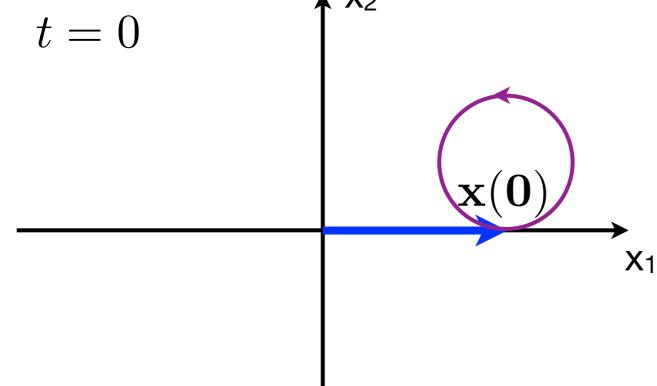
(A) The vector rotates clockwise.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



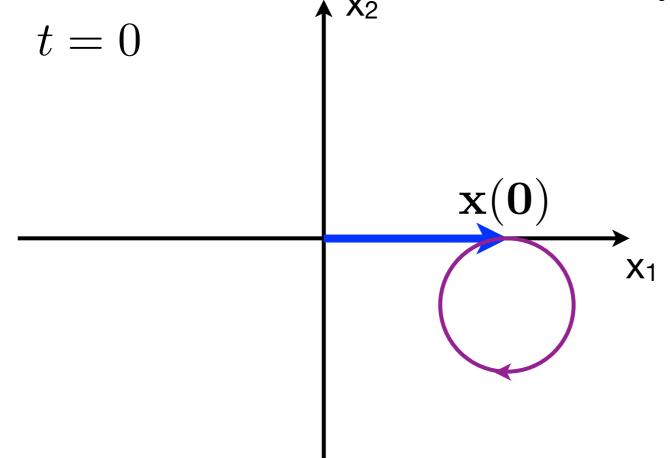
- What happens as t increases?
  - (A) The vector rotates clockwise.
  - (B) The vector rotates counterclockwise.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



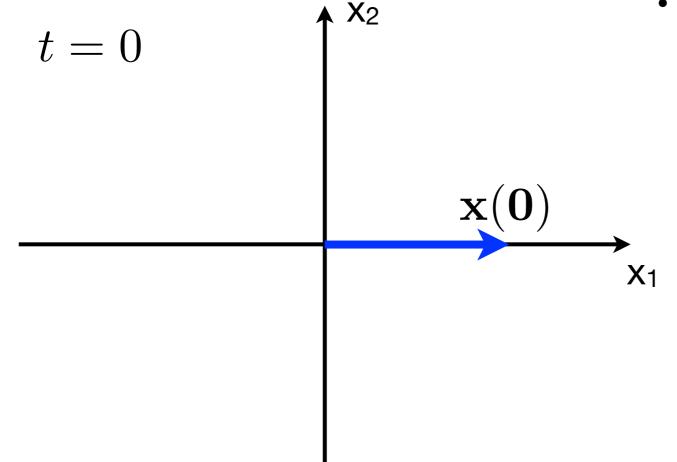
- What happens as t increases?
  - (A) The vector rotates clockwise.
  - (B) The vector rotates counterclockwise.
  - (C) The tip of the vector maps out a circle in the first quadrant.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



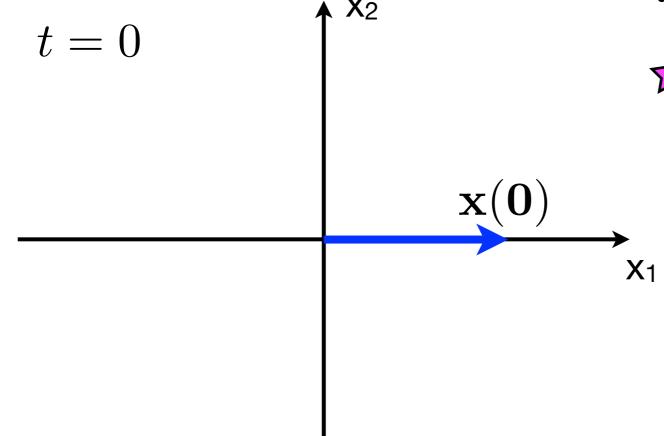
- What happens as t increases?
  - (A) The vector rotates clockwise.
  - (B) The vector rotates counterclockwise.
  - (C) The tip of the vector maps out a circle in the first quadrant.
  - (D) The tip of the vector maps out a circle in the fourth quadrant.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



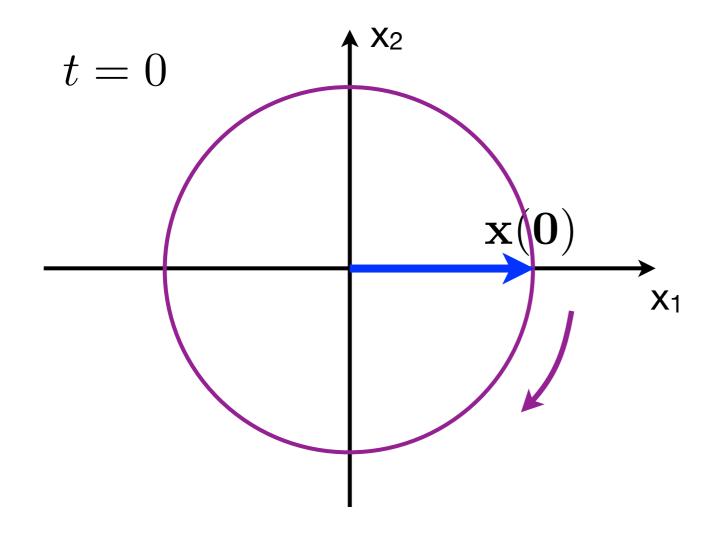
- What happens as t increases?
  - (A) The vector rotates clockwise.
  - (B) The vector rotates counterclockwise.
  - (C) The tip of the vector maps out a circle in the first quadrant.
  - (D) The tip of the vector maps out a circle in the fourth quadrant.
  - (E) Explain please.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

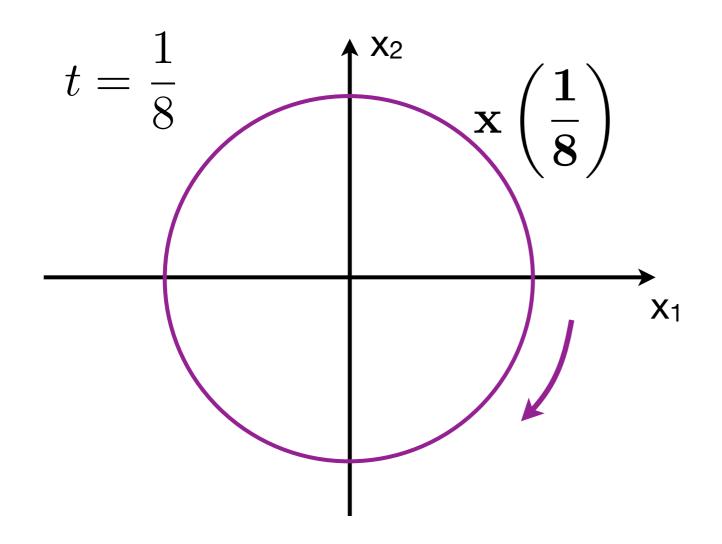


- What happens as t increases?
- (A) The vector rotates clockwise.
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  - (D) The tip of the vector maps out a circle in the fourth quadrant.
  - (E) Explain please.

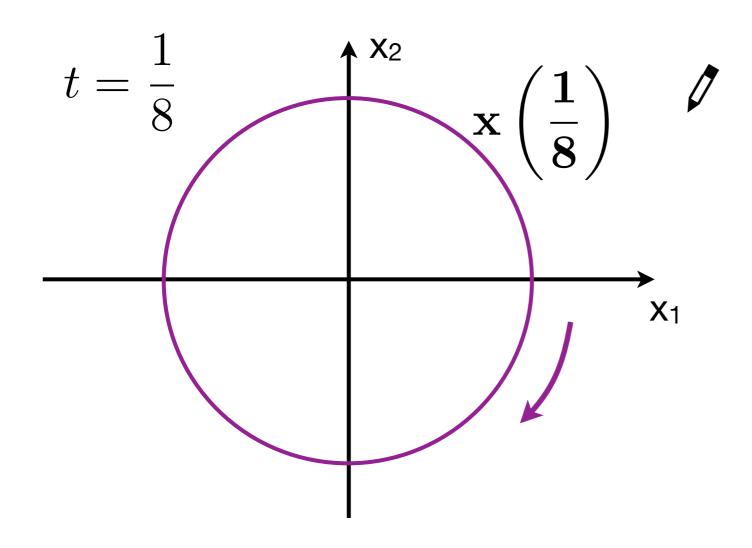
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



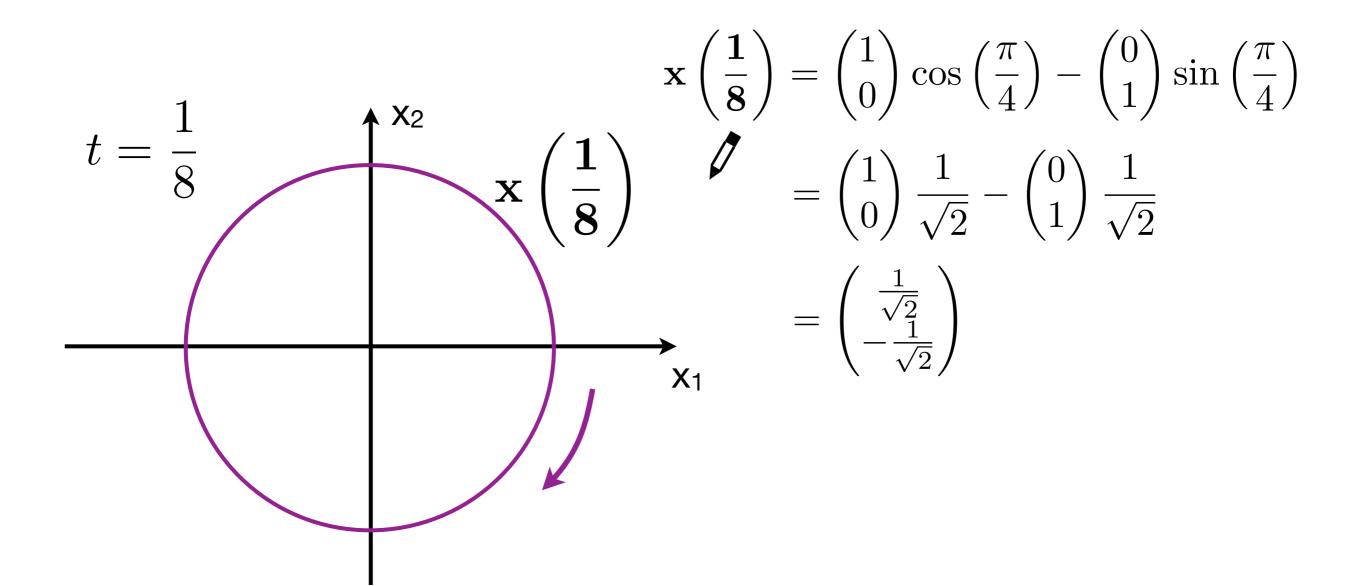
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



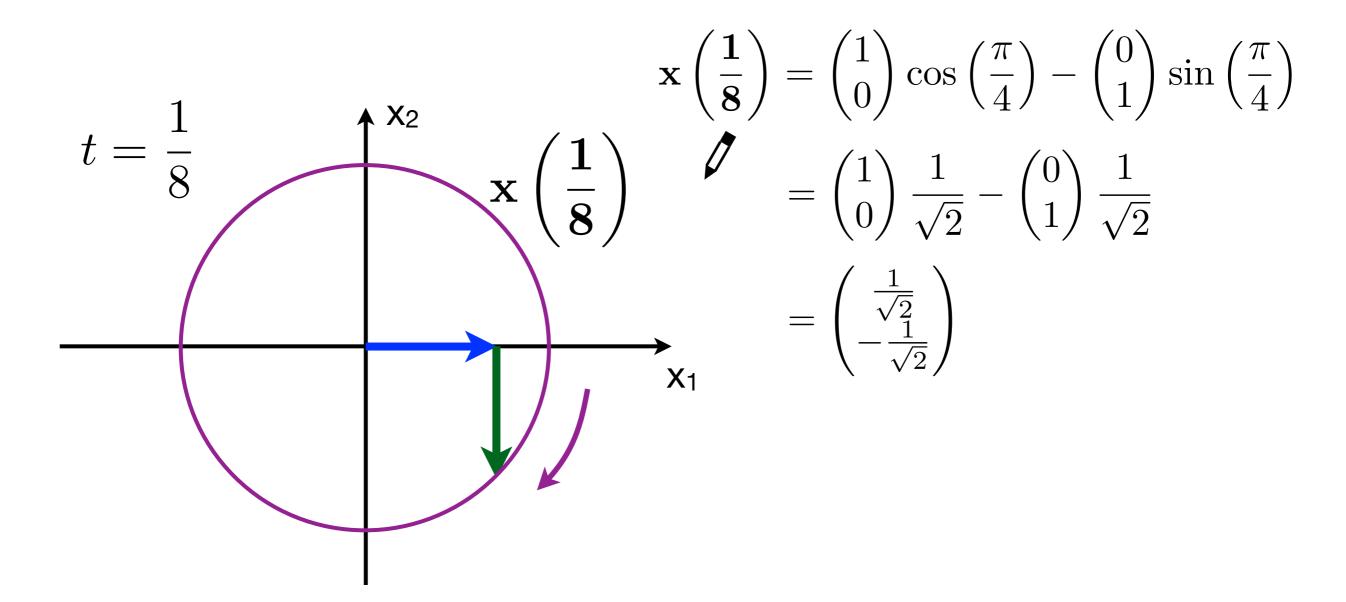
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



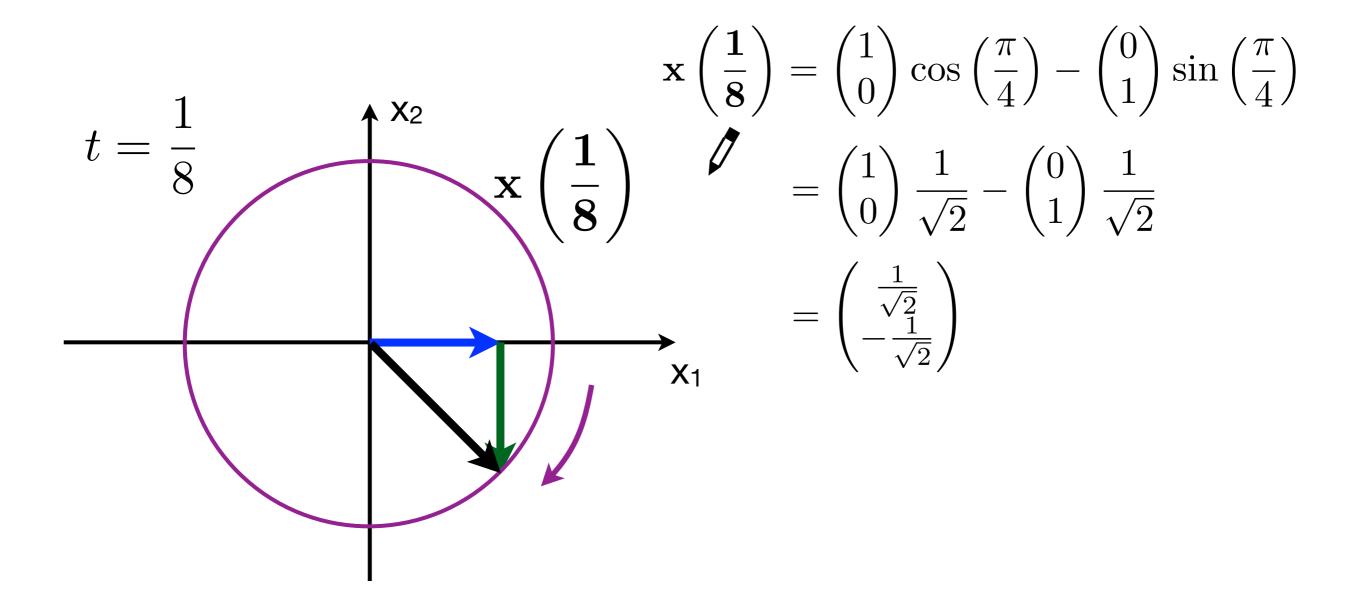
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



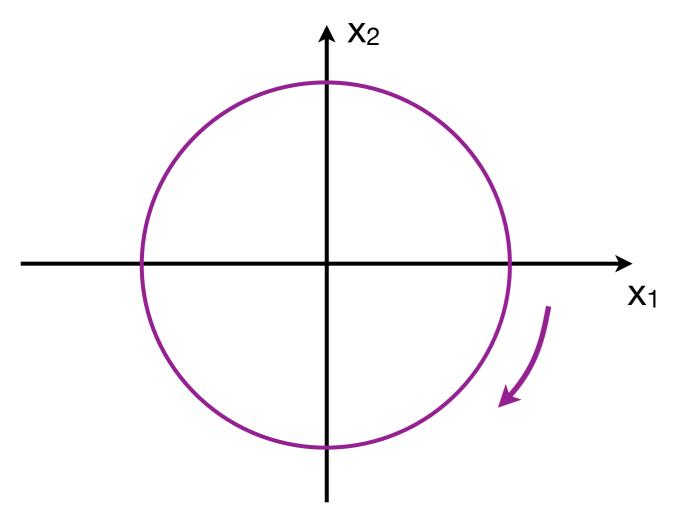
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



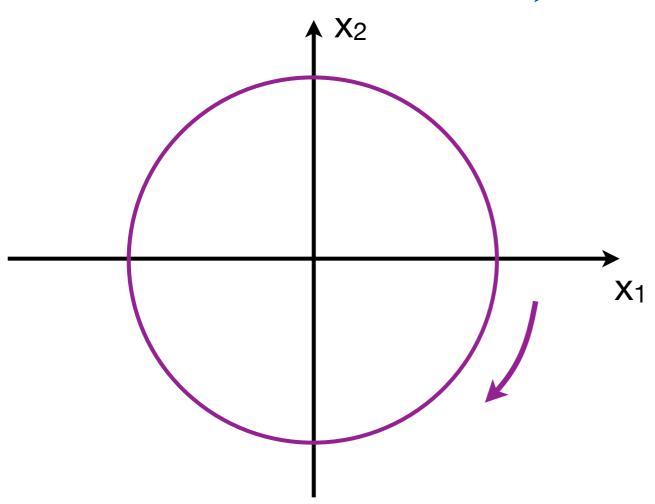
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

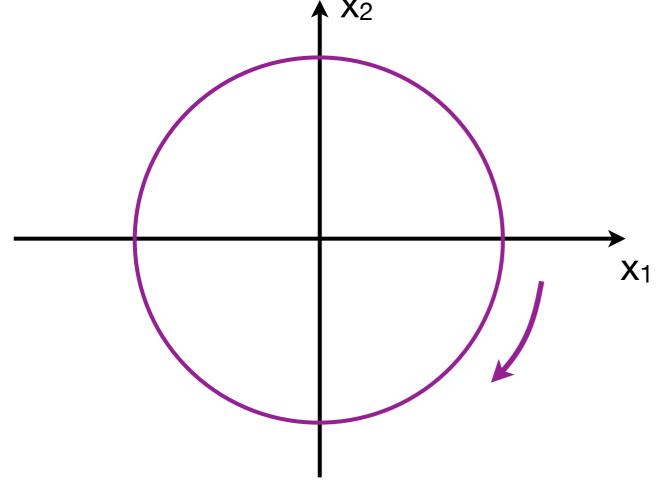


$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$



$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{0}) = \mathbf{x}(\mathbf{0}) = \mathbf{x}(\mathbf{0})$$



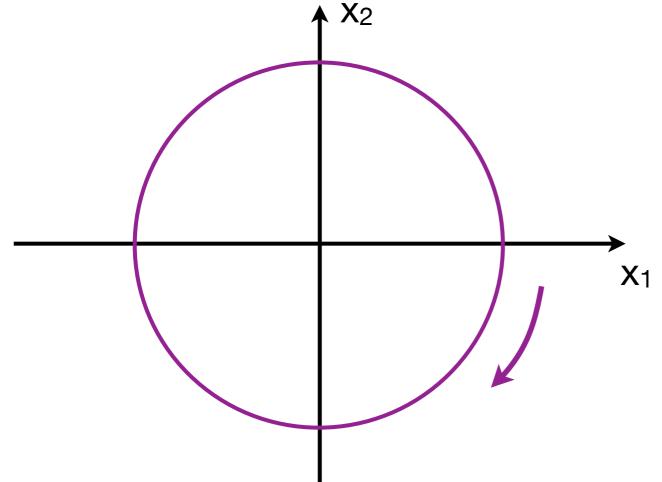
$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{0}) = \longrightarrow \mathbf{x}(\mathbf{0})$$

 $X_1$ 

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{0}) = \longrightarrow - = -$$



$$\mathbf{x}(\mathbf{0}) = \longrightarrow - - = \longrightarrow$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{0}) = \longrightarrow - = \longrightarrow$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{0}) = \longrightarrow - \longrightarrow = \longrightarrow$$

$$\mathbf{x} \begin{pmatrix} \frac{1}{4} \end{pmatrix} = \longrightarrow$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{0}) = \longrightarrow - \longrightarrow = \longrightarrow$$

$$\mathbf{x} \begin{pmatrix} \frac{1}{4} \end{pmatrix} = - \longrightarrow = \longrightarrow$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{0}) = \longrightarrow - \longrightarrow = \longrightarrow$$

$$\mathbf{x} \begin{pmatrix} \frac{1}{4} \end{pmatrix} = - \longrightarrow = \longrightarrow$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{0}) = \longrightarrow - \longrightarrow - \longrightarrow \times \begin{pmatrix} \frac{1}{4} \\ \frac{1}{4} \end{pmatrix} = - \longrightarrow - \longrightarrow \times \begin{pmatrix} \frac{1}{4} \\ \frac{1}{2} \end{pmatrix} = - \longrightarrow \times \begin{pmatrix} \frac{1}{4} \\ \frac{1}{2} \end{pmatrix} = - \longrightarrow \times \begin{pmatrix} \frac{1}{4} \\ \frac{1}{2} \end{pmatrix} = - \longrightarrow \times \begin{pmatrix} \frac{1}{4} \\ \frac{1}{2} \end{pmatrix} = - \longrightarrow \times \begin{pmatrix} \frac{1}{4} \\ \frac{1}{2} \end{pmatrix} = - \longrightarrow \times \begin{pmatrix} \frac{1}{4} \\ \frac{1}{2} \end{pmatrix} = - \longrightarrow \times \begin{pmatrix} \frac{1}{4} \\ \frac{1}{2} \end{pmatrix} = - \longrightarrow \times \begin{pmatrix} \frac{1}{4} \\ \frac{1}{2} \end{pmatrix} = - \longrightarrow \times \begin{pmatrix} \frac{1}{4} \\ \frac{1}{2} \end{pmatrix} = - \longrightarrow \times \begin{pmatrix} \frac{1}{4} \\ \frac{1}{2} \end{pmatrix} = - 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$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{0}) = \longrightarrow - \cdot = \longrightarrow$$

$$\mathbf{x} \begin{pmatrix} \frac{1}{4} \end{pmatrix} = \cdot - \uparrow = \downarrow$$

$$\mathbf{x} \begin{pmatrix} \frac{1}{4} \end{pmatrix} = - \cdot - \cdot$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{0}) = \longrightarrow - \cdot = \longrightarrow$$

$$\mathbf{x} \begin{pmatrix} \frac{1}{4} \end{pmatrix} = \cdot - \uparrow = \downarrow$$

$$\mathbf{x} \begin{pmatrix} \frac{1}{4} \end{pmatrix} = - \cdot = \checkmark$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{0}) = \longrightarrow - \cdot = \longrightarrow$$

$$\mathbf{x} \begin{pmatrix} \frac{1}{4} \end{pmatrix} = \cdot - \uparrow = \downarrow$$

$$\mathbf{x} \begin{pmatrix} \frac{1}{4} \end{pmatrix} = - \cdot = \checkmark$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{0}) = \rightarrow - \cdot = \rightarrow$$

$$\mathbf{x}\left(\frac{1}{4}\right) = \cdot - \uparrow = \downarrow$$

$$\mathbf{x}\left(\frac{1}{2}\right) = \leftarrow - \cdot = \leftarrow$$

$$\mathbf{x}\left(\frac{3}{4}\right) = \cdot - \downarrow = \uparrow$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(\mathbf{0}) = \rightarrow - \cdot = \rightarrow$$

$$\mathbf{x}\left(\frac{1}{4}\right) = \cdot - \uparrow = \downarrow$$

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$$\mathbf{x}\left(\frac{3}{4}\right) = \cdot - \downarrow = \uparrow$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1\\0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0\\1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(0) = \longrightarrow - \longrightarrow = \longrightarrow$$

$$\mathbf{x} \begin{pmatrix} \frac{1}{4} \end{pmatrix} = \longrightarrow - \longrightarrow = \longrightarrow$$

$$\mathbf{x} \begin{pmatrix} \frac{1}{4} \end{pmatrix} = \longrightarrow - \longrightarrow = \longrightarrow$$

$$\mathbf{x} \begin{pmatrix} \frac{3}{4} \end{pmatrix} = \longrightarrow - \longrightarrow = \longrightarrow$$

$$\mathbf{x}(1) = \bigcirc$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1\\0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0\\1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(0) = \longrightarrow - \longrightarrow = \longrightarrow$$

$$\mathbf{x} \begin{pmatrix} \frac{1}{4} \end{pmatrix} = \longrightarrow - \longrightarrow = \longrightarrow$$

$$\mathbf{x} \begin{pmatrix} \frac{1}{4} \end{pmatrix} = \longrightarrow - \longrightarrow = \longrightarrow$$

$$\mathbf{x} \begin{pmatrix} \frac{3}{4} \end{pmatrix} = \longrightarrow - \longrightarrow = \longrightarrow$$

$$\mathbf{x}(1) = \longrightarrow - \longrightarrow$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1\\0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0\\1 \end{pmatrix} \sin(2\pi t)$$

$$\mathbf{x}(0) = \longrightarrow - \cdot = \longrightarrow$$

$$\mathbf{x} \left(\frac{1}{4}\right) = \cdot - \uparrow = \downarrow$$

$$\mathbf{x} \left(\frac{1}{2}\right) = \longleftarrow - \cdot = \longrightarrow$$

$$\mathbf{x} \left(\frac{3}{4}\right) = \cdot - \downarrow = \uparrow$$

$$\mathbf{x}(1) = \longrightarrow - \cdot = \longrightarrow$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1\\0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0\\1 \end{pmatrix} \sin(2\pi t)$$

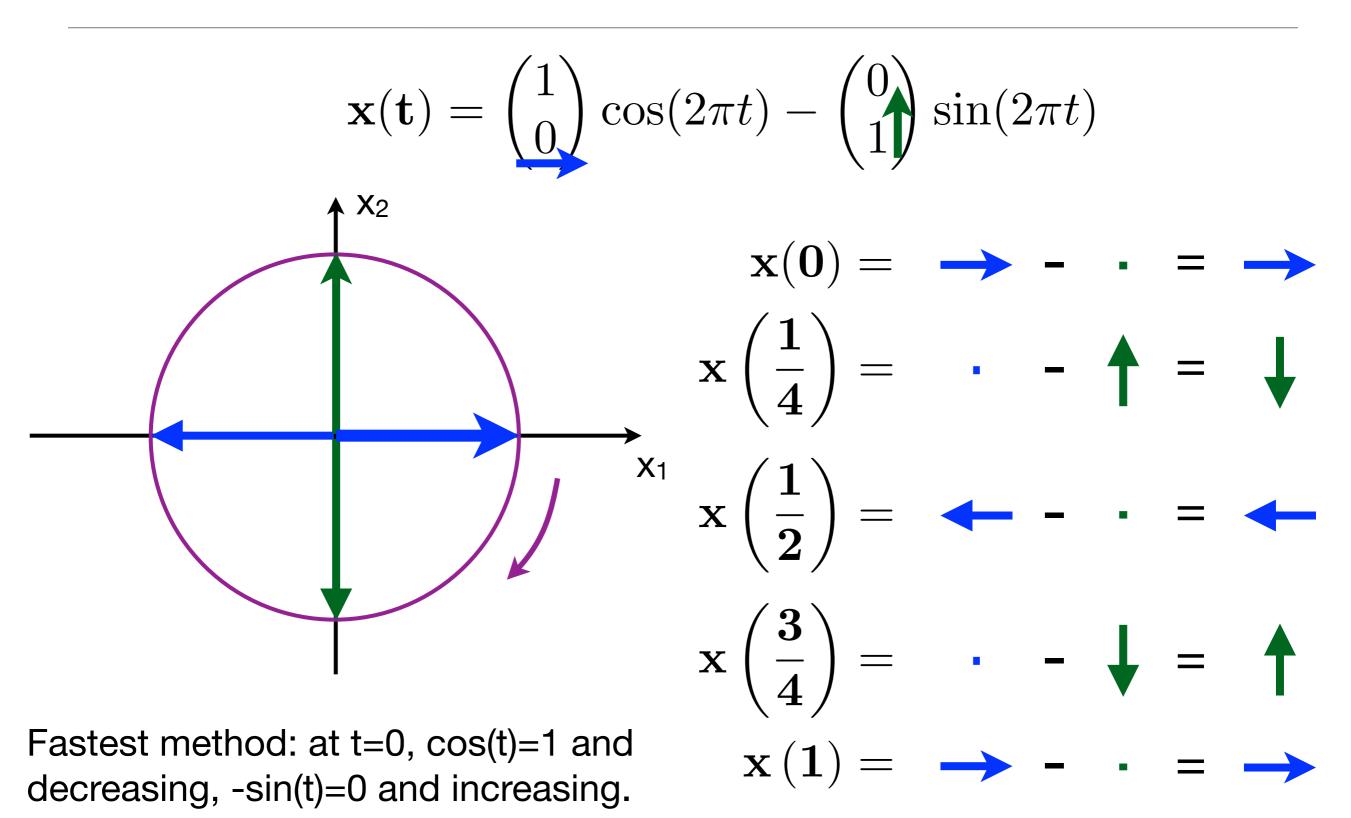
$$\mathbf{x}(0) = \longrightarrow - \cdot = \longrightarrow$$

$$\mathbf{x} \left(\frac{1}{4}\right) = \cdot - \uparrow = \downarrow$$

$$\mathbf{x} \left(\frac{1}{2}\right) = \longleftarrow - \cdot = \longrightarrow$$

$$\mathbf{x} \left(\frac{3}{4}\right) = \cdot - \downarrow = \uparrow$$

$$\mathbf{x}(1) = \longrightarrow - \cdot = \longrightarrow$$



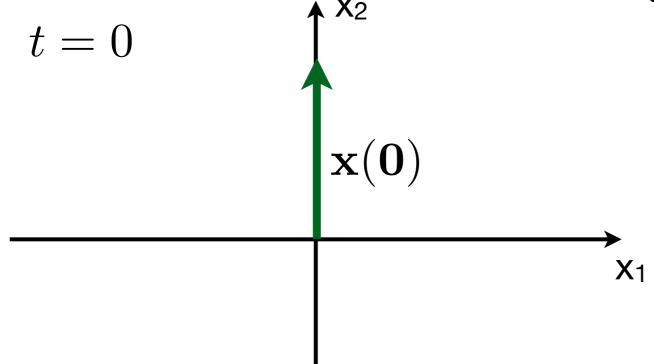
Same equation, initial condition chosen so that C₁=0 and C₂=1.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t)$$

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[ C_1 \left( \mathbf{a} \cos(\beta t) - \mathbf{b} \sin(\beta t) \right) + C_2 \left( \mathbf{a} \sin(\beta t) + \mathbf{b} \cos(\beta t) \right) \right]$$

Same equation, initial condition chosen so that C₁=0 and C₂=1.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t)$$



- What happens as t increases?
  - (A) The vector rotates clockwise.
  - (B) The vector rotates counterclockwise.
  - (C) The tip of the vector maps out a circle in the first quadrant.
  - (D) The tip of the vector maps out a circle in the second quadrant.
  - (E) Explain please.

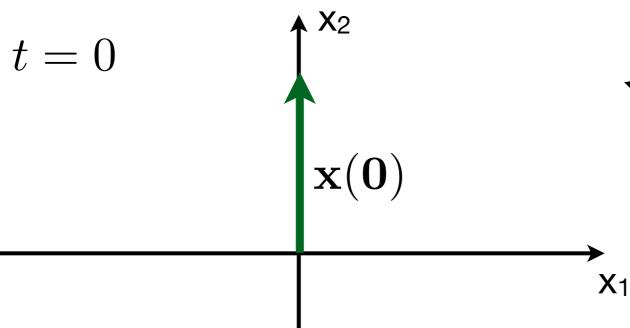
• Same equation, initial condition chosen so that C₁=0 and C₂=1.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t) + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t)$$
 • What happens as t increases?

- (A) The vector rotates clockwise.
  - (B) The vector rotates counterclockwise.
  - (C) The tip of the vector maps out a circle in the first quadrant.
  - (D) The tip of the vector maps out a circle in the second quadrant.
  - (E) Explain please.

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"Same" solution as before, just

 $\pi/2$  delayed.

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  - (E) Explain please.

Looking at the general solution again...

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[ C_1 \left( \mathbf{a} \cos(\beta t) - \mathbf{b} \sin(\beta t) \right) + C_2 \left( \mathbf{a} \sin(\beta t) + \mathbf{b} \cos(\beta t) \right) \right]$$

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• Both parts rotate in the exact same way but the C<sub>2</sub> part is delayed by a quarter phase.

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- If an initial condition lies neither parallel to vector **a** nor to vector **b**, C<sub>1</sub> and C2 allow for intermediate phases to be achieved.

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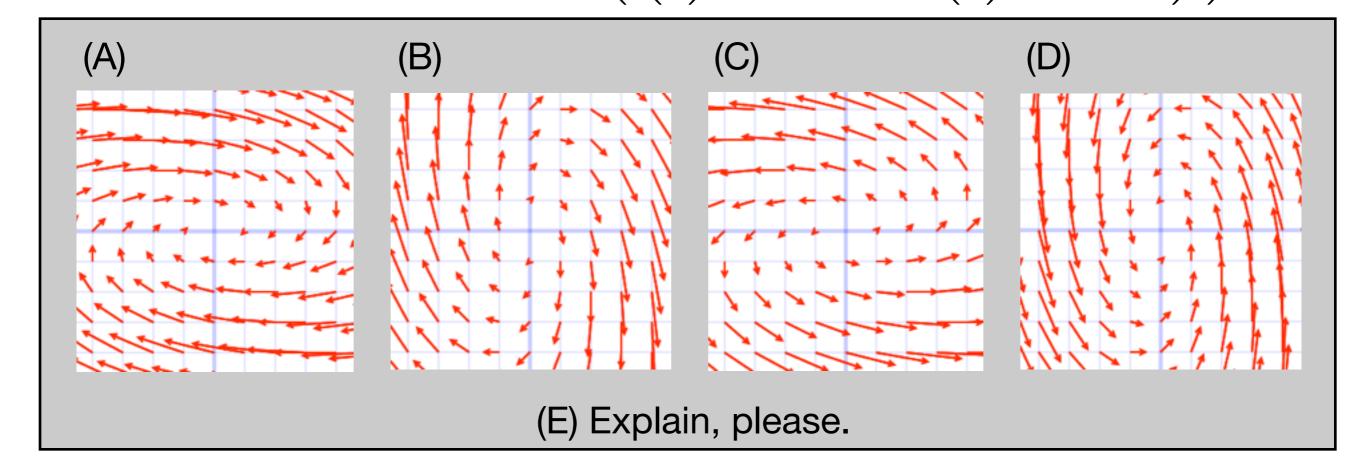
- Both parts rotate in the exact same way but the C<sub>2</sub> part is delayed by a quarter phase.
- If an initial condition lies neither parallel to vector **a** nor to vector **b**, C<sub>1</sub> and C2 allow for intermediate phases to be achieved.
- x(t) can be rewritten (using trig identities) as

$$\mathbf{x}(\mathbf{t}) = Me^{\alpha t} \left( \mathbf{a} \cos(\beta t - \phi) - \mathbf{b} \sin(\beta t - \phi) \right)$$

where M and  $\phi$  are constants to replace  $C_1$  and  $C_2$ .

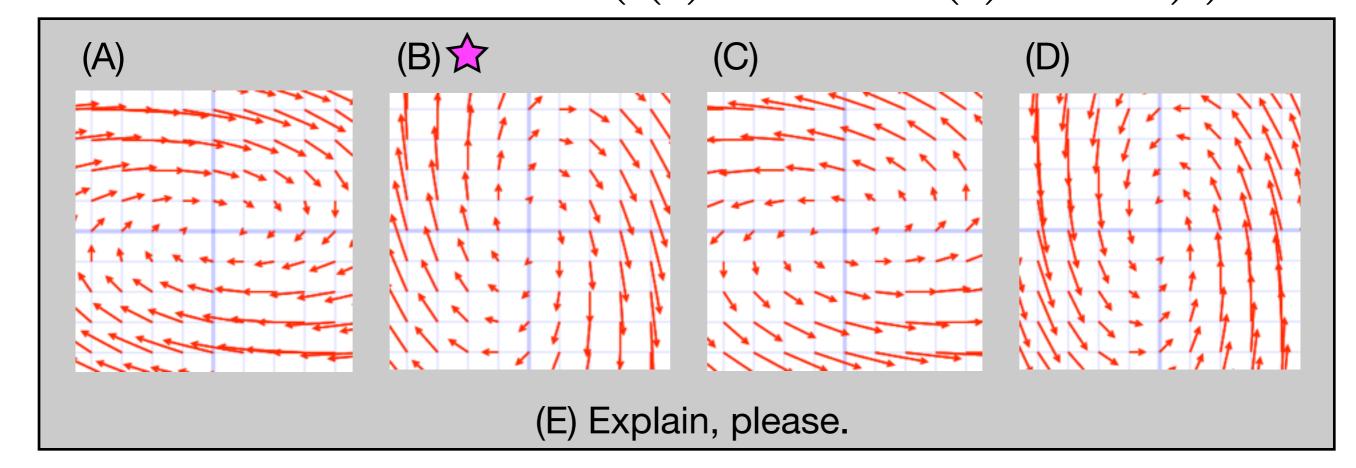
Back to our earlier example where we found the general solution

$$\mathbf{x}(\mathbf{t}) = e^{t} \left( C_{1} \left( \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2t) - \begin{pmatrix} 0 \\ 2 \end{pmatrix} \sin(2t) \right) + C_{2} \left( \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2t) + \begin{pmatrix} 0 \\ 2 \end{pmatrix} \cos(2t) \right) \right)$$



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Back to our earlier example where we found the general solution

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