

Today

- Summary of 2×2 systems all in one picture
- Non-homogeneous systems of ODEs
- Non-homogeneous two-tank example
- Intro to Laplace transforms

Summary - homogeneous 2x2 systems

- To find eigenvalues of A :

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Summary - homogeneous 2x2 systems

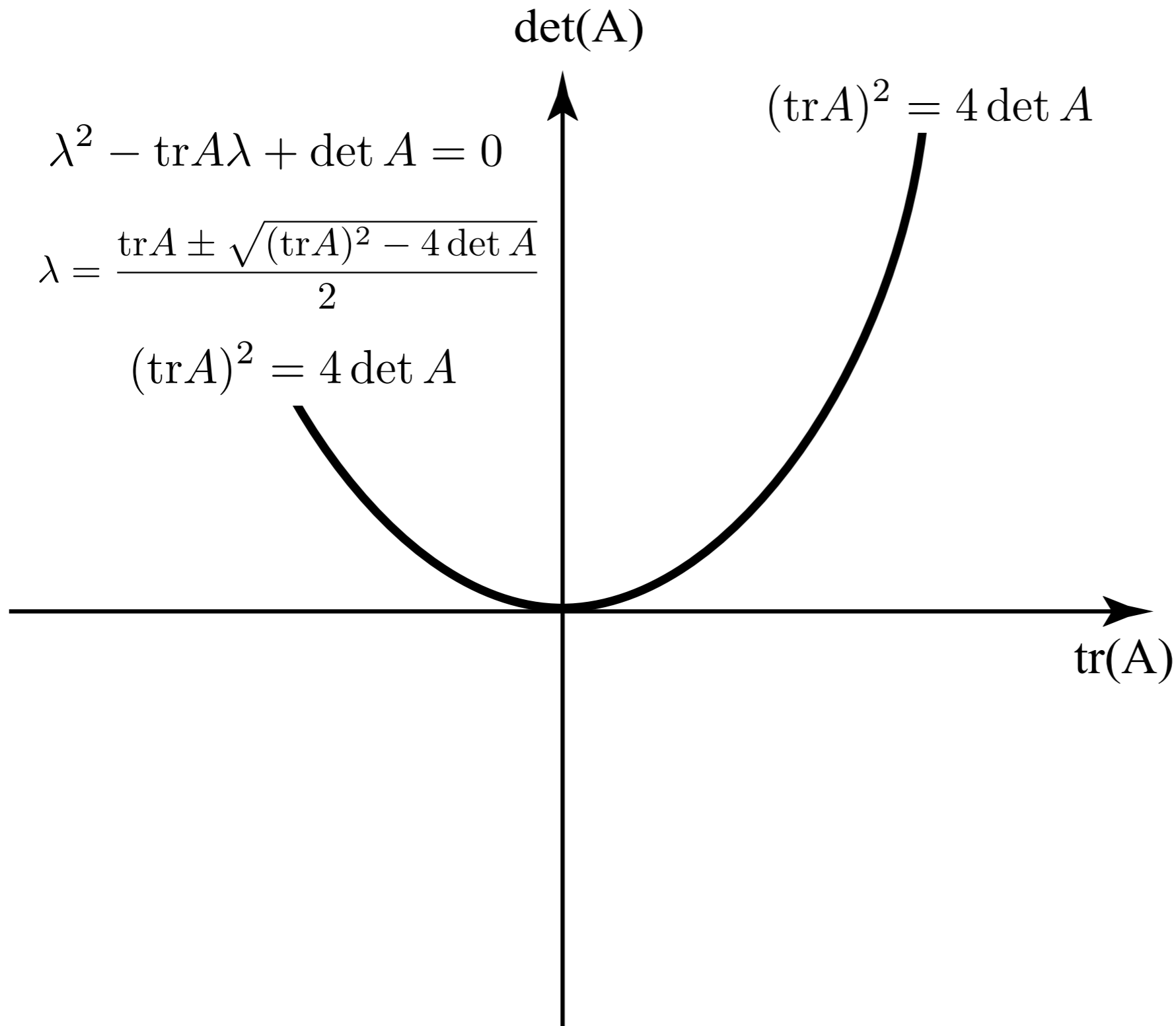
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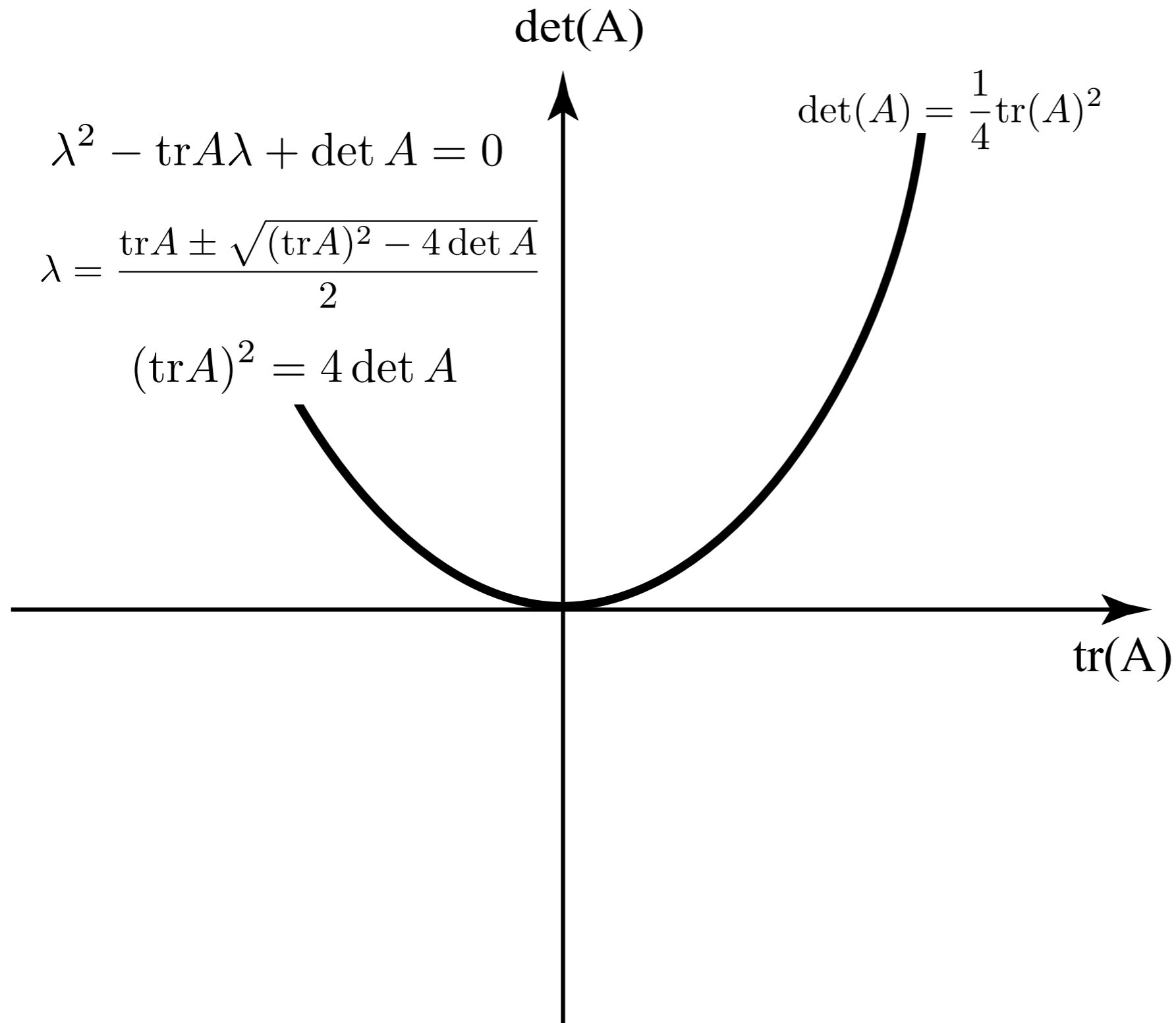
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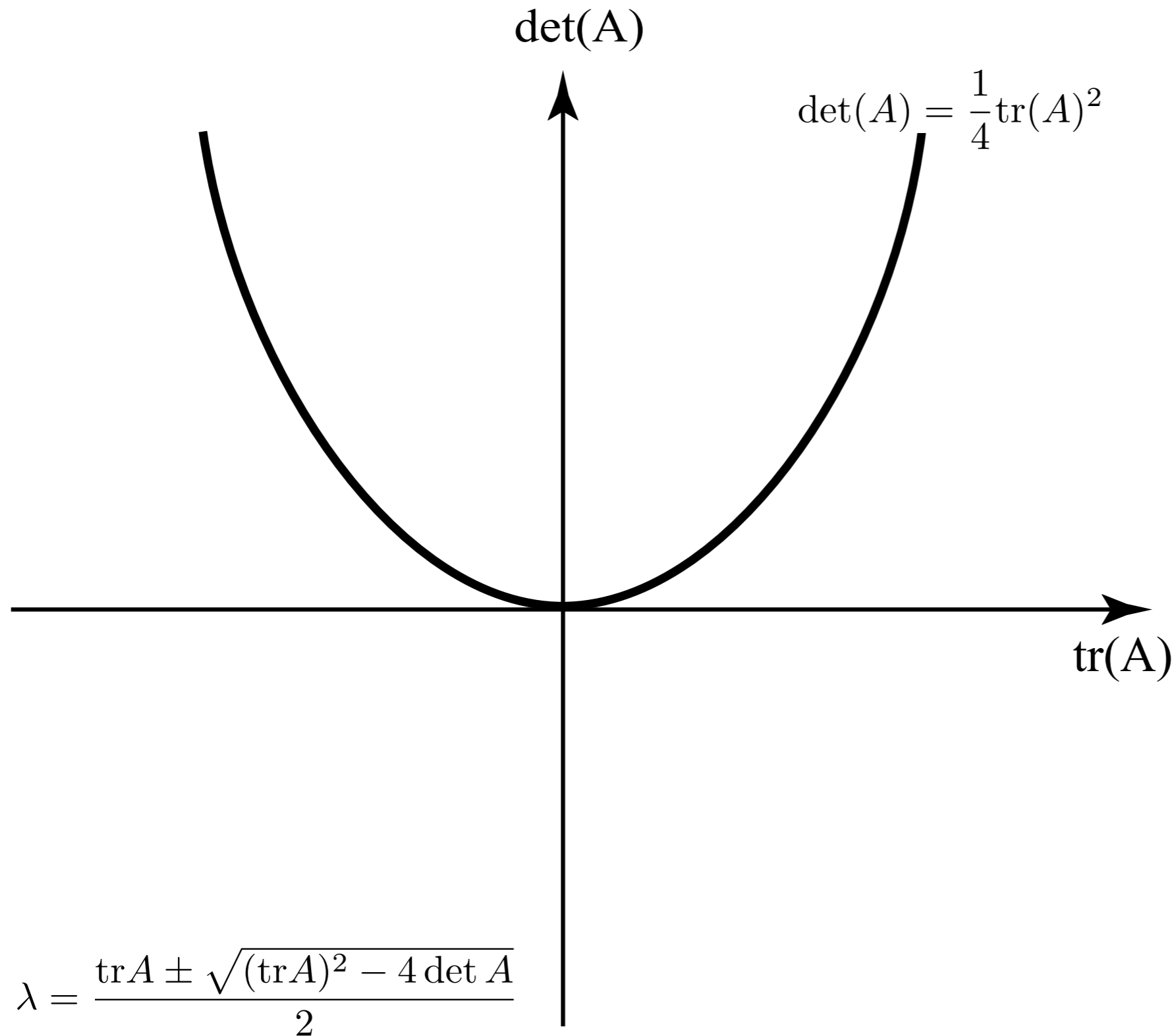
Summary - homogeneous 2x2 systems



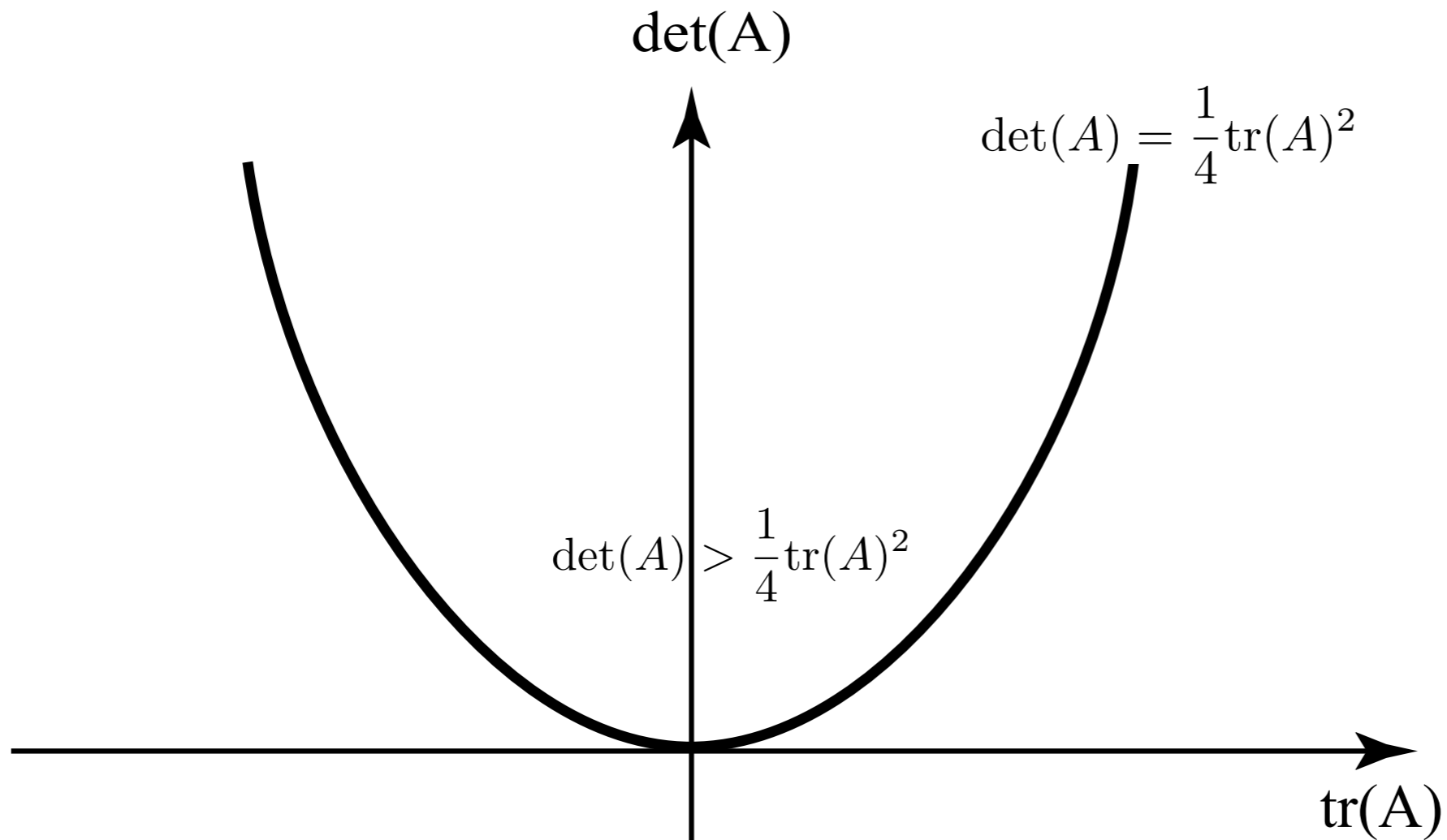
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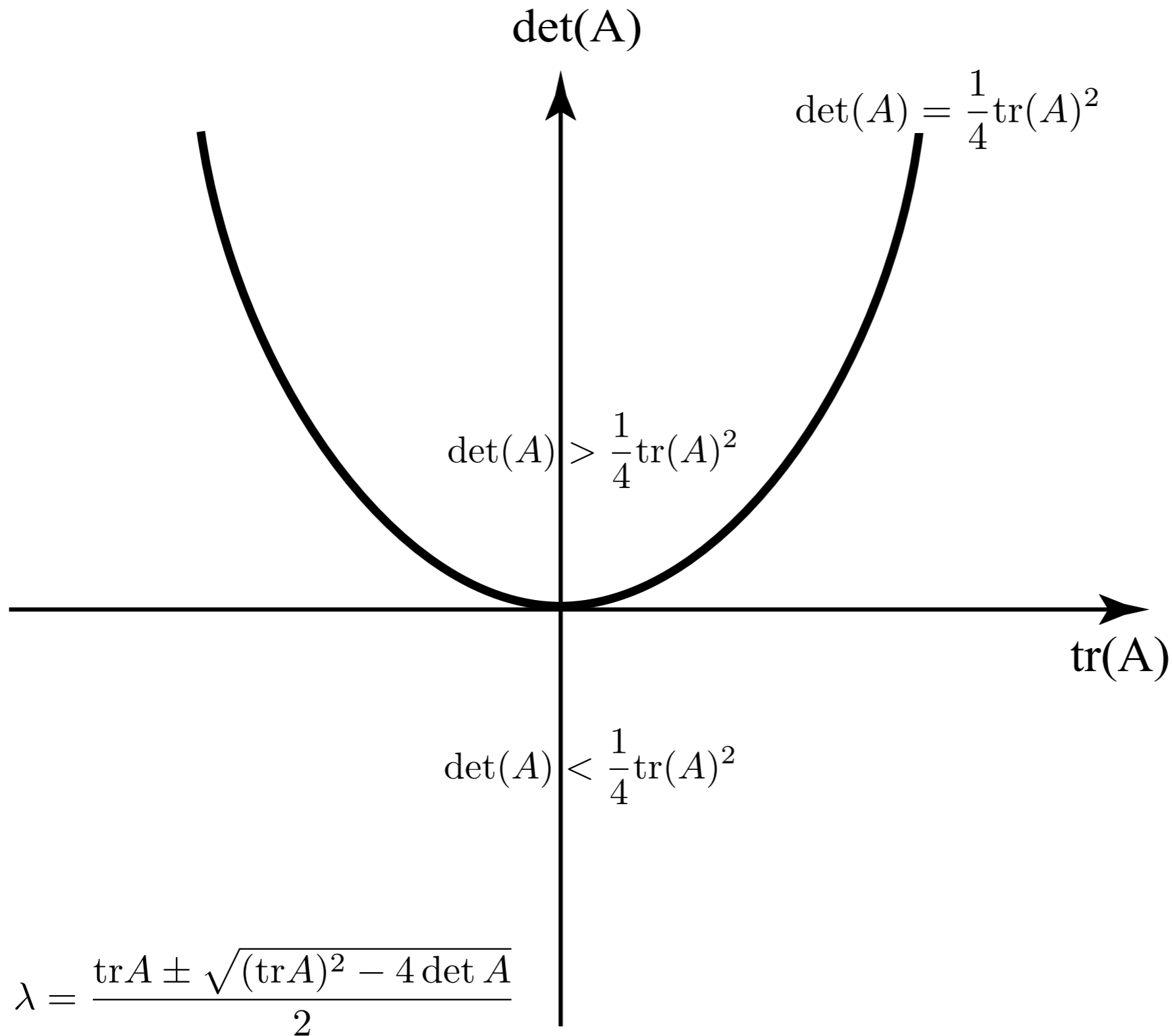


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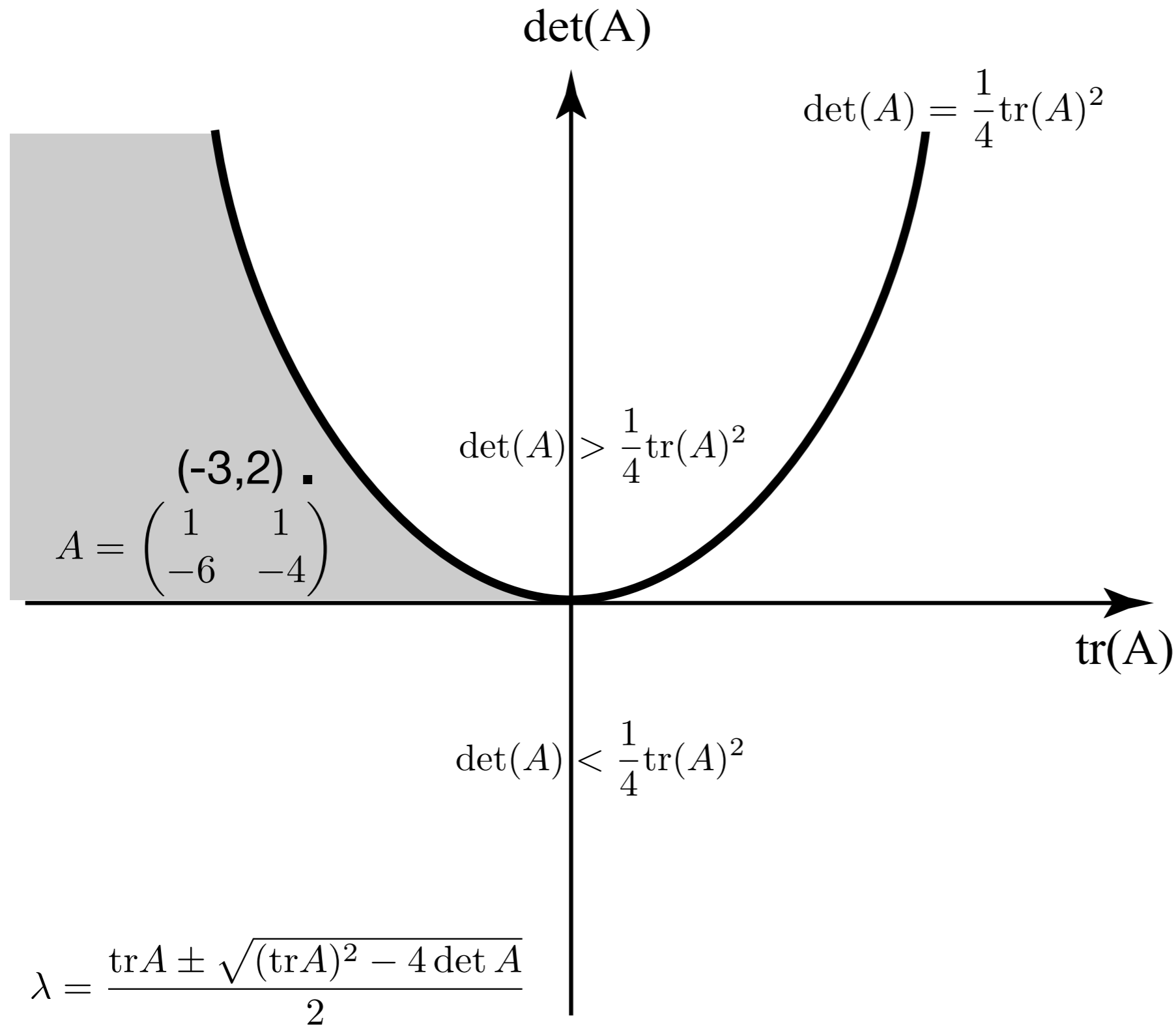


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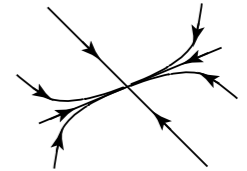


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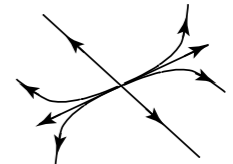


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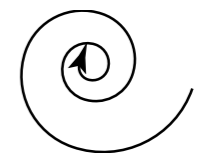
(A) stable node



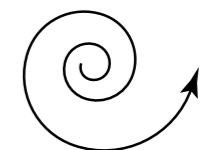
(B) unstable node



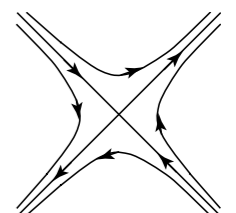
(C) stable spiral



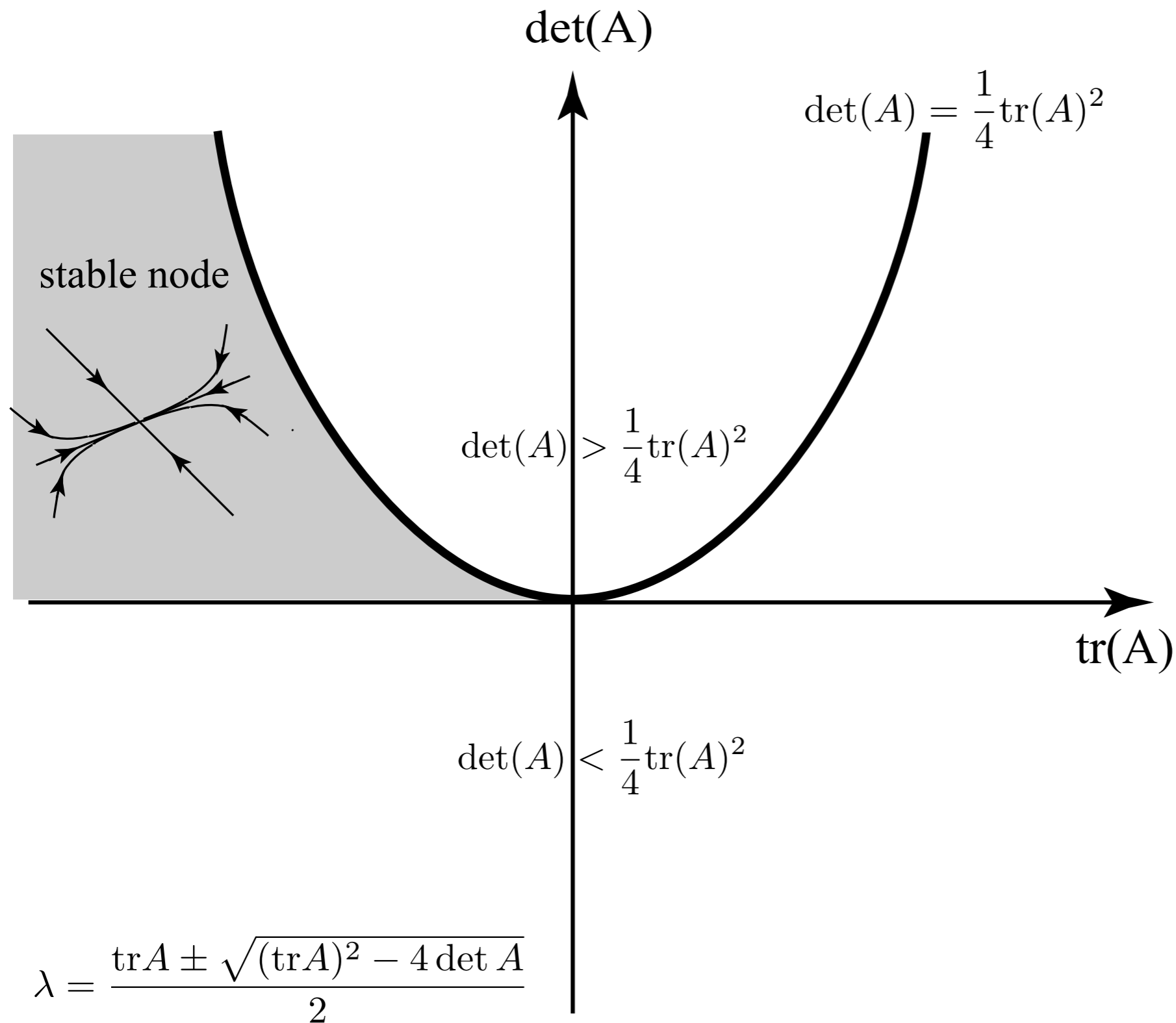
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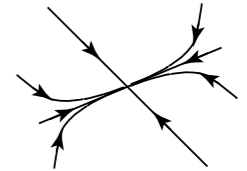


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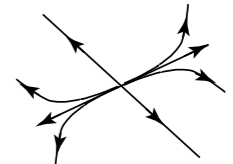


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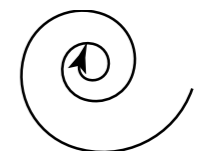
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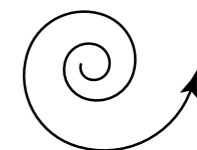
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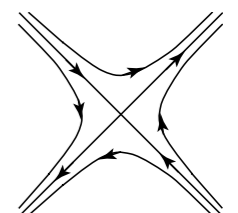
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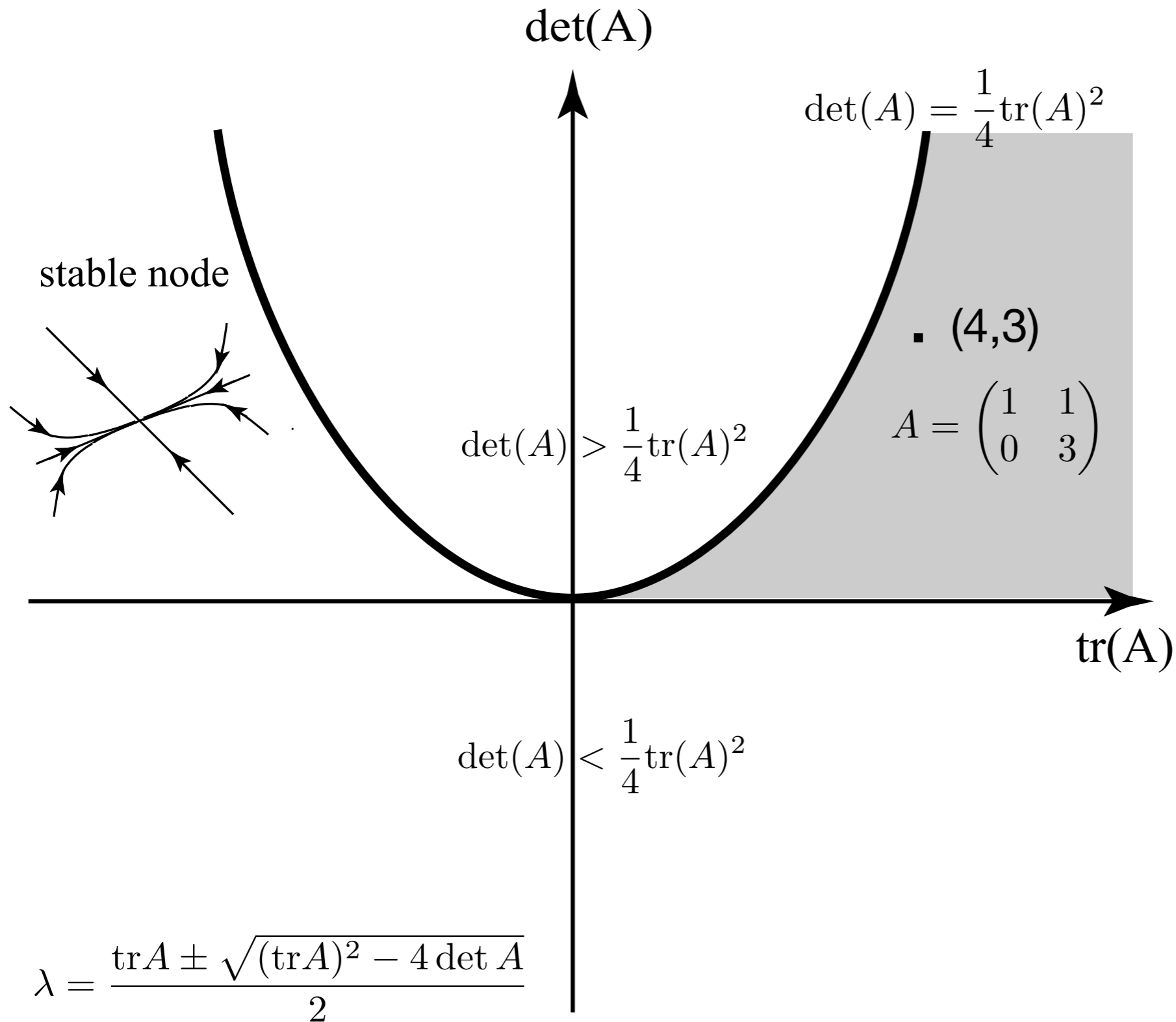
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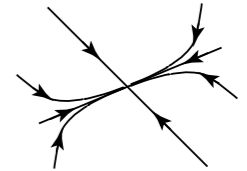


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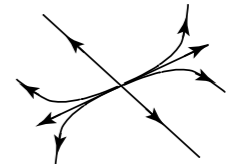


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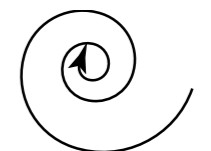
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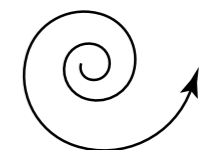
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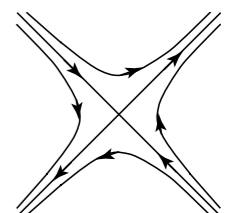
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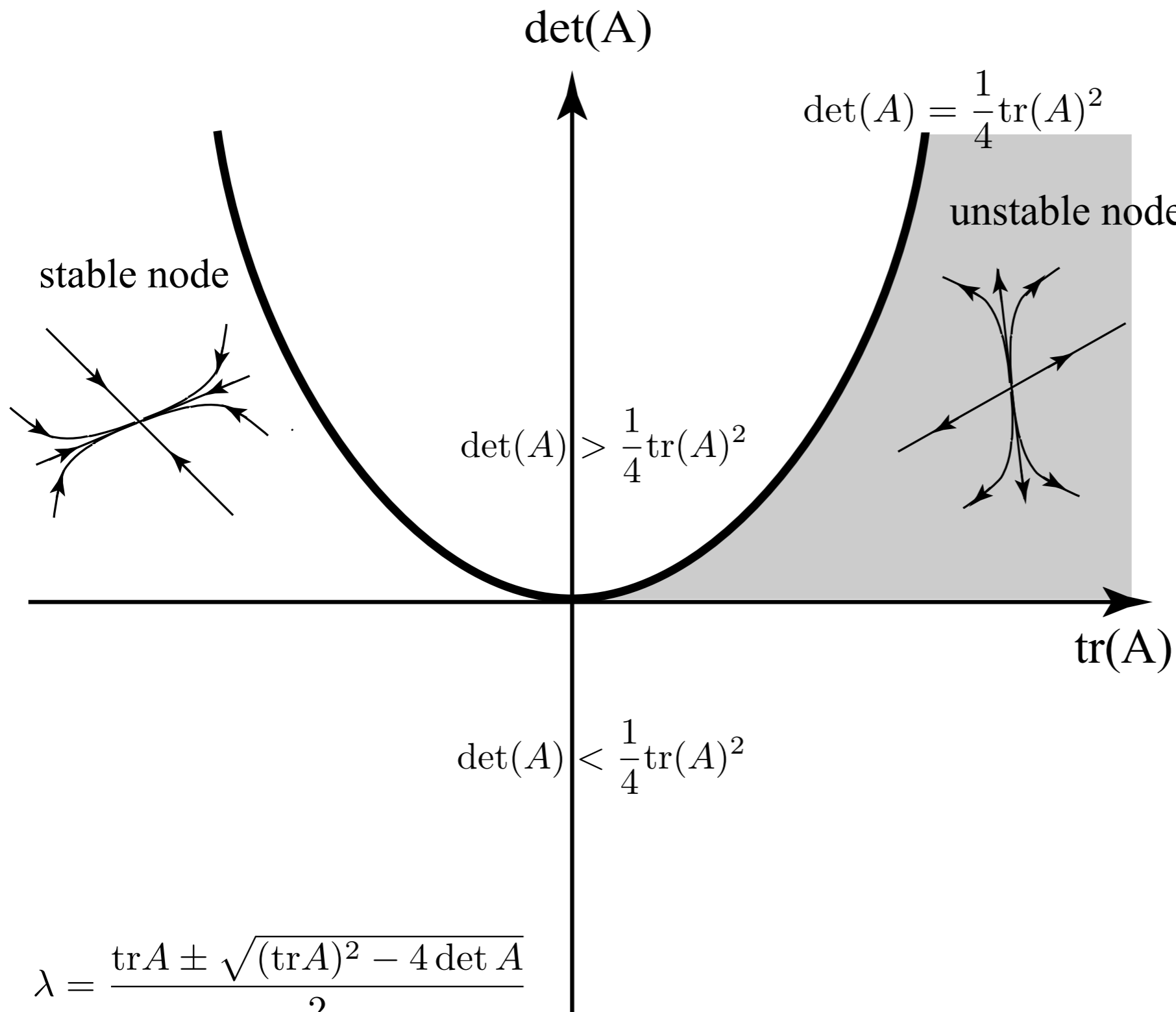
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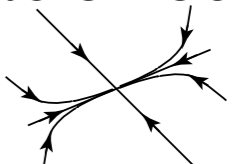
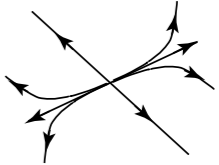
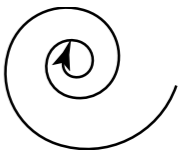
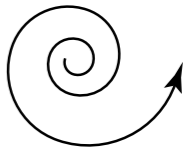
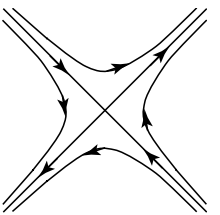
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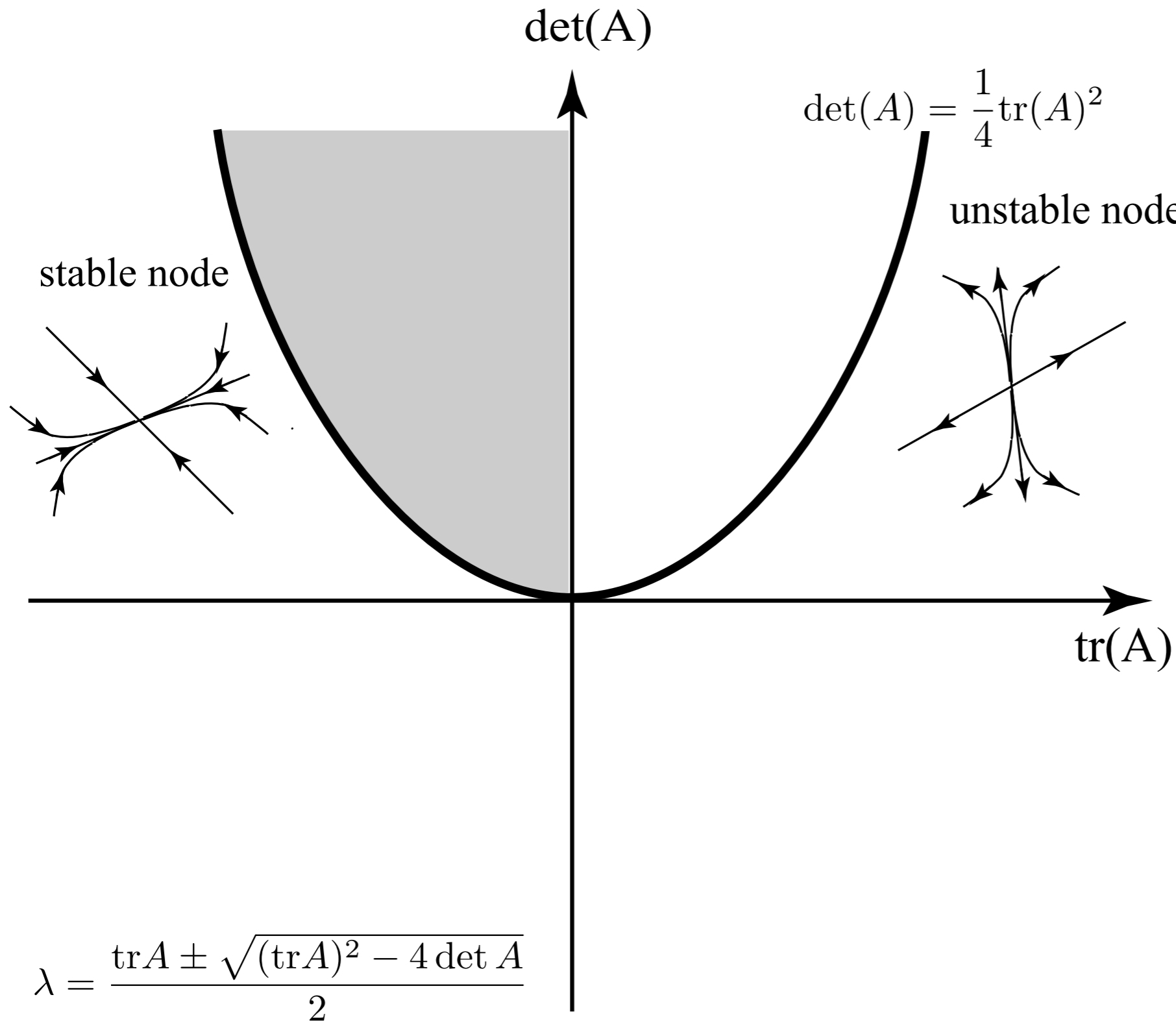


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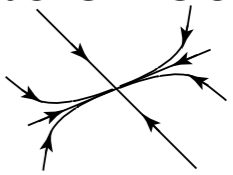
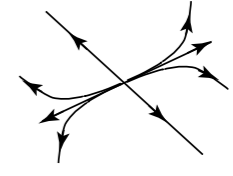
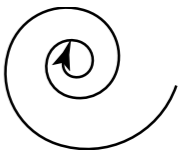
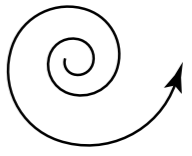
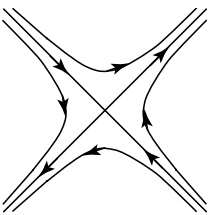
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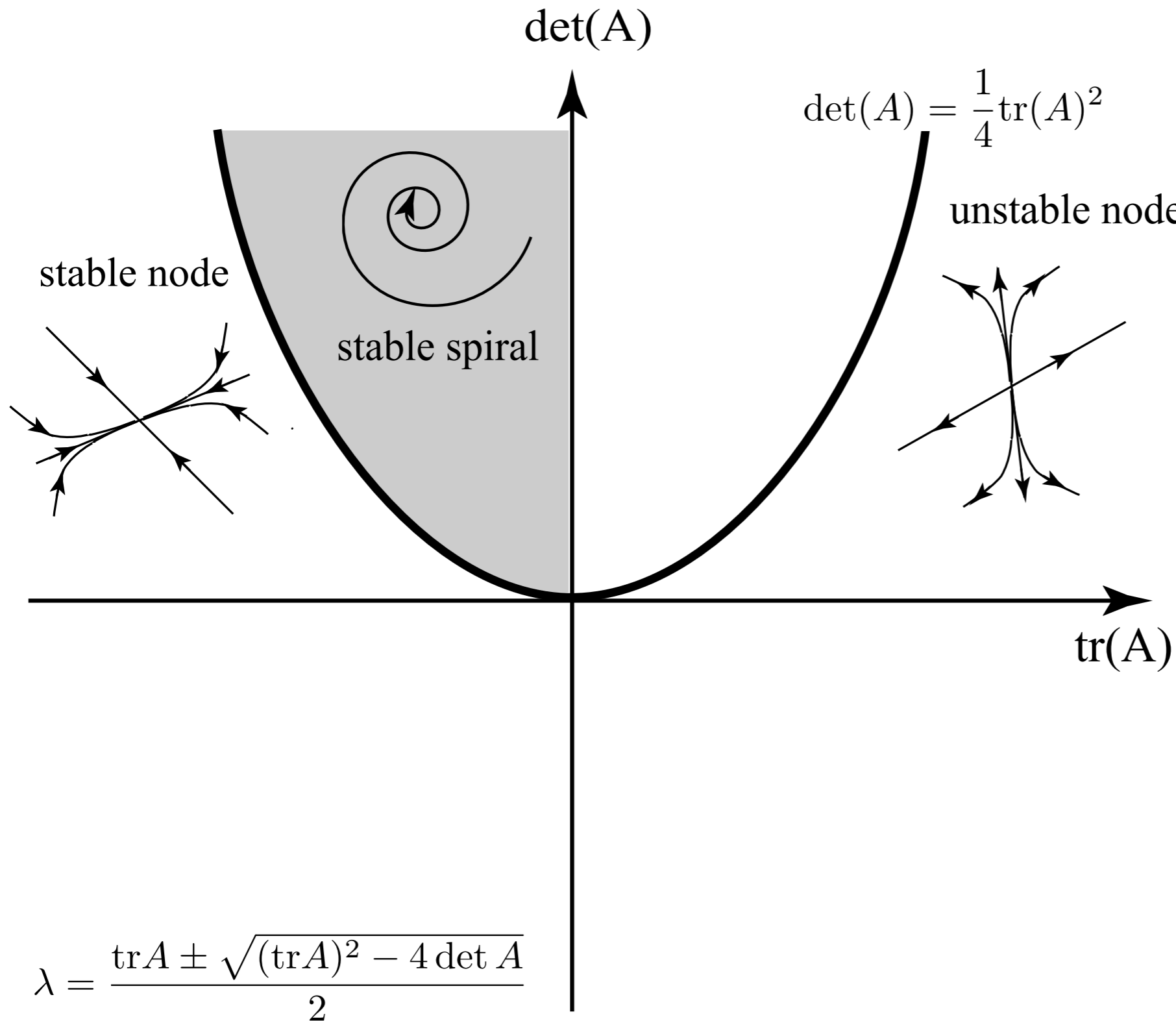
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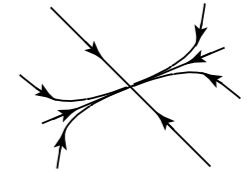
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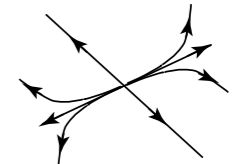


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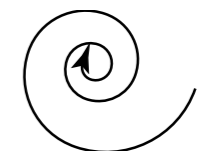
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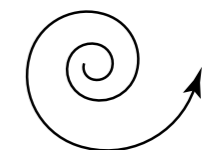
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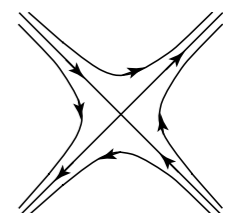
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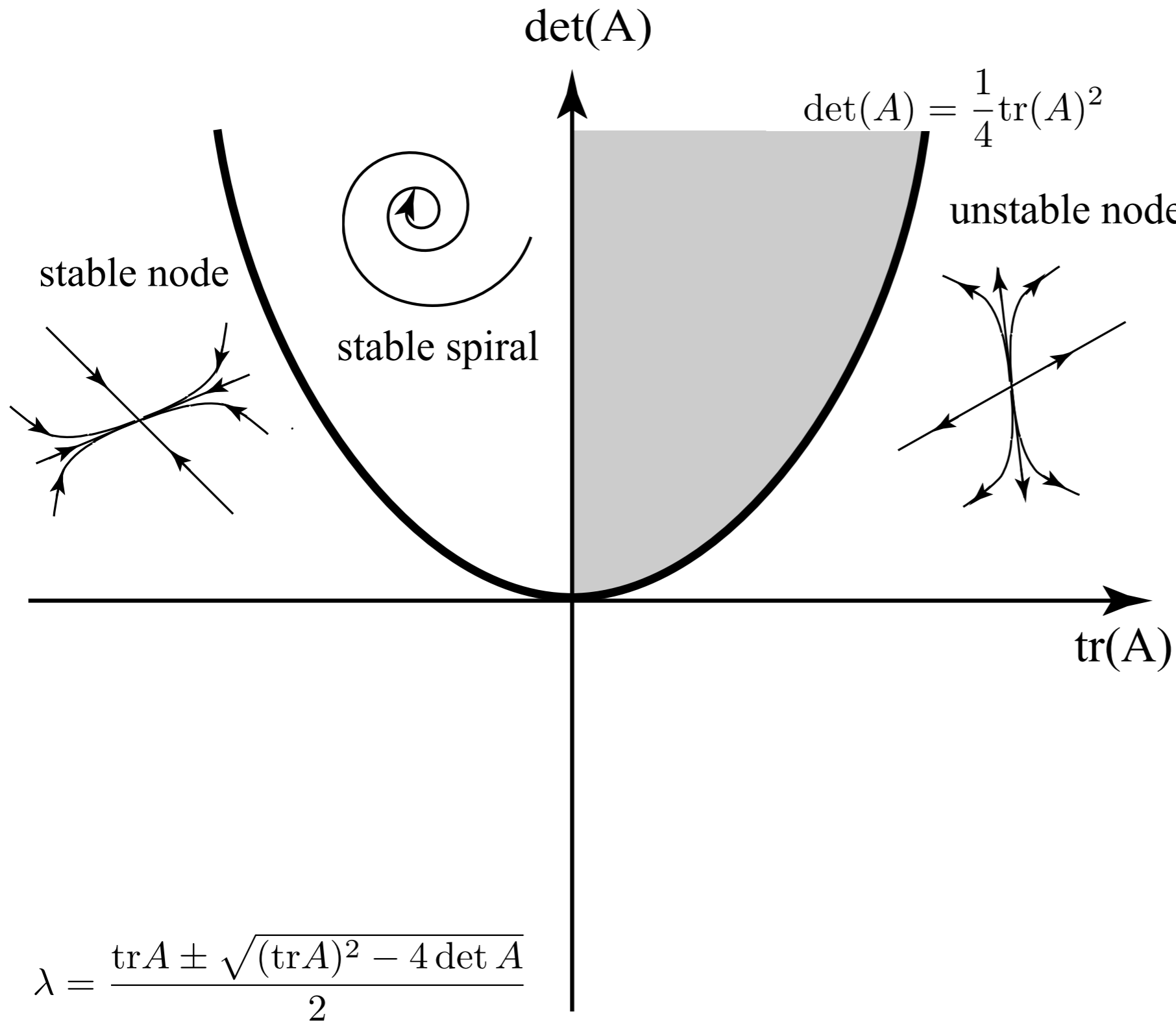
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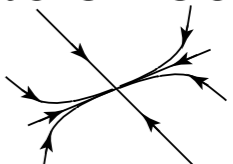
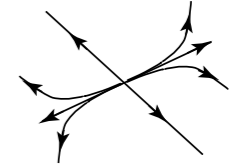
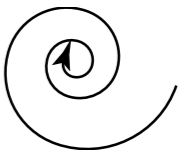
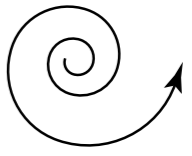
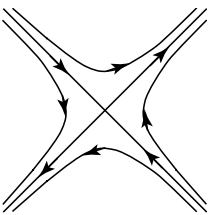
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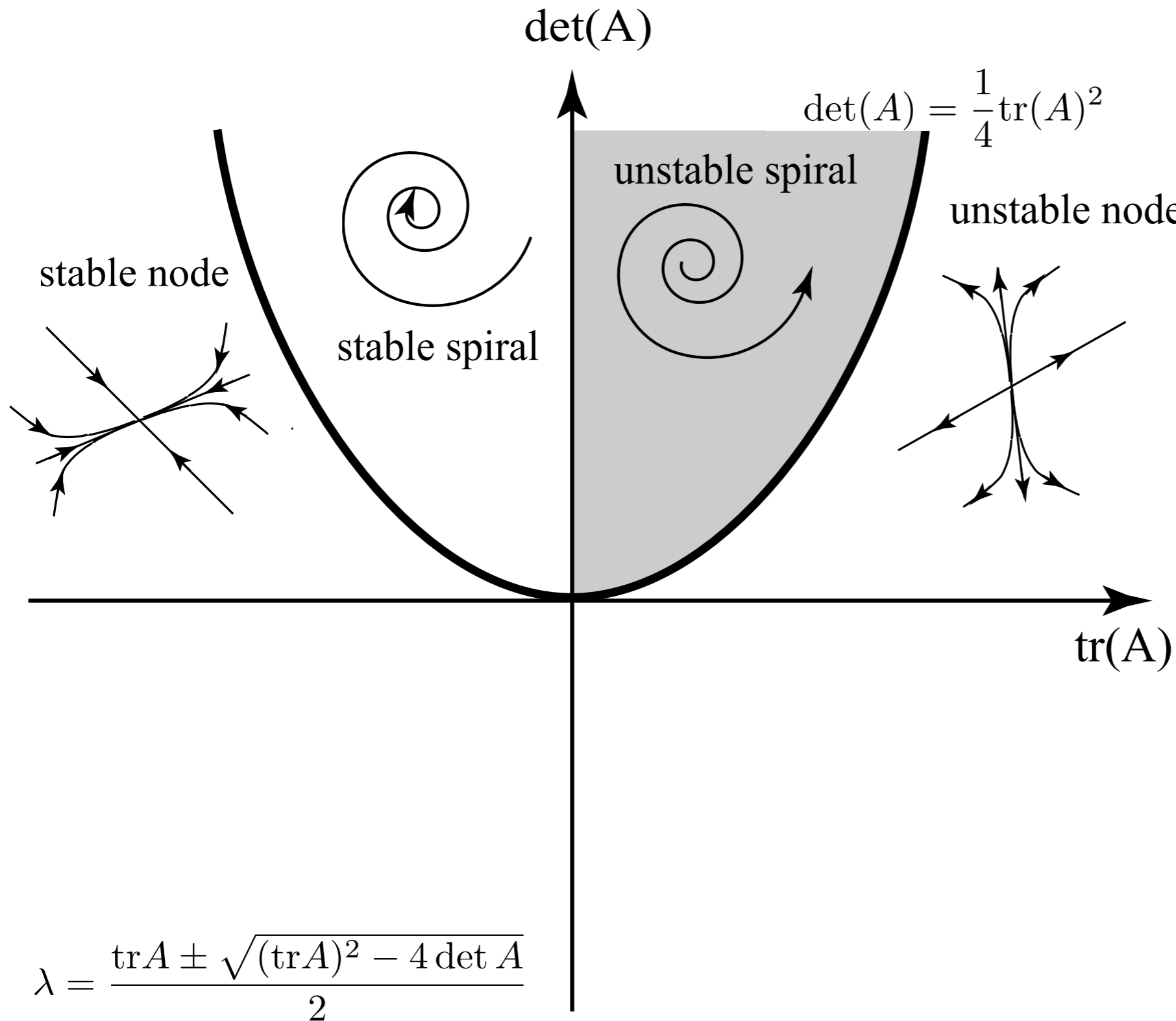
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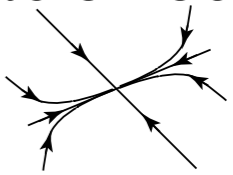
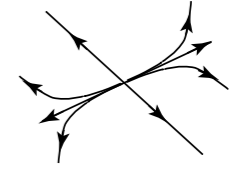
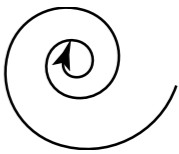
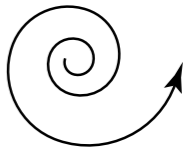
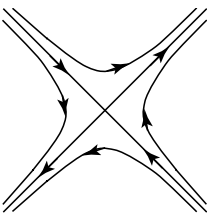
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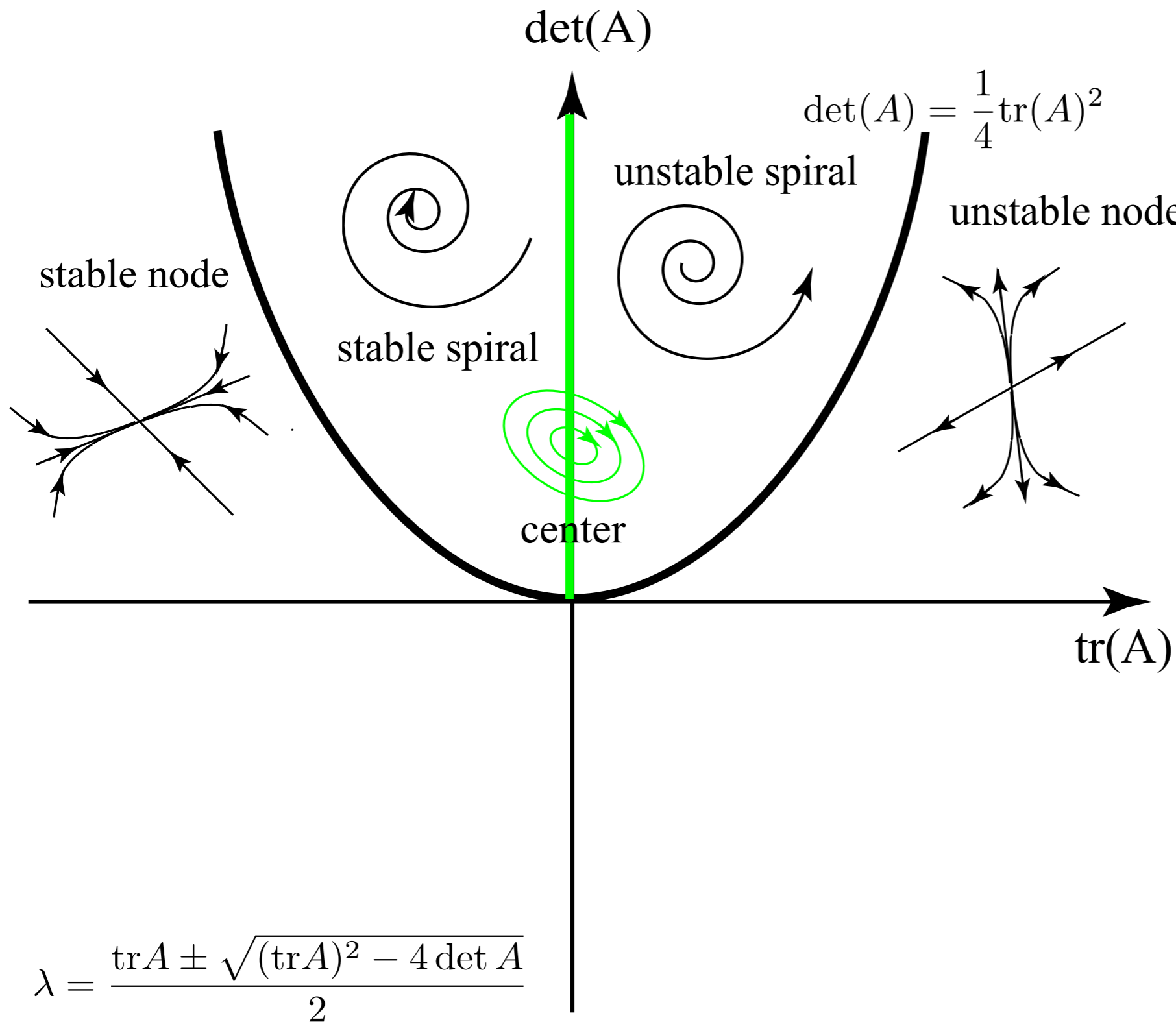
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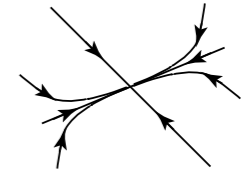
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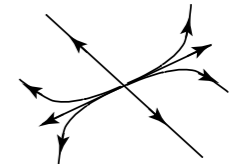


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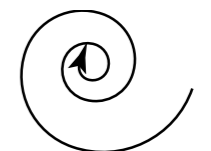
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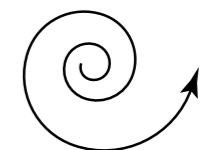
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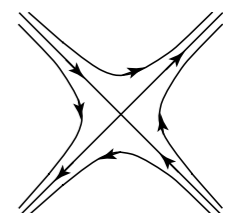
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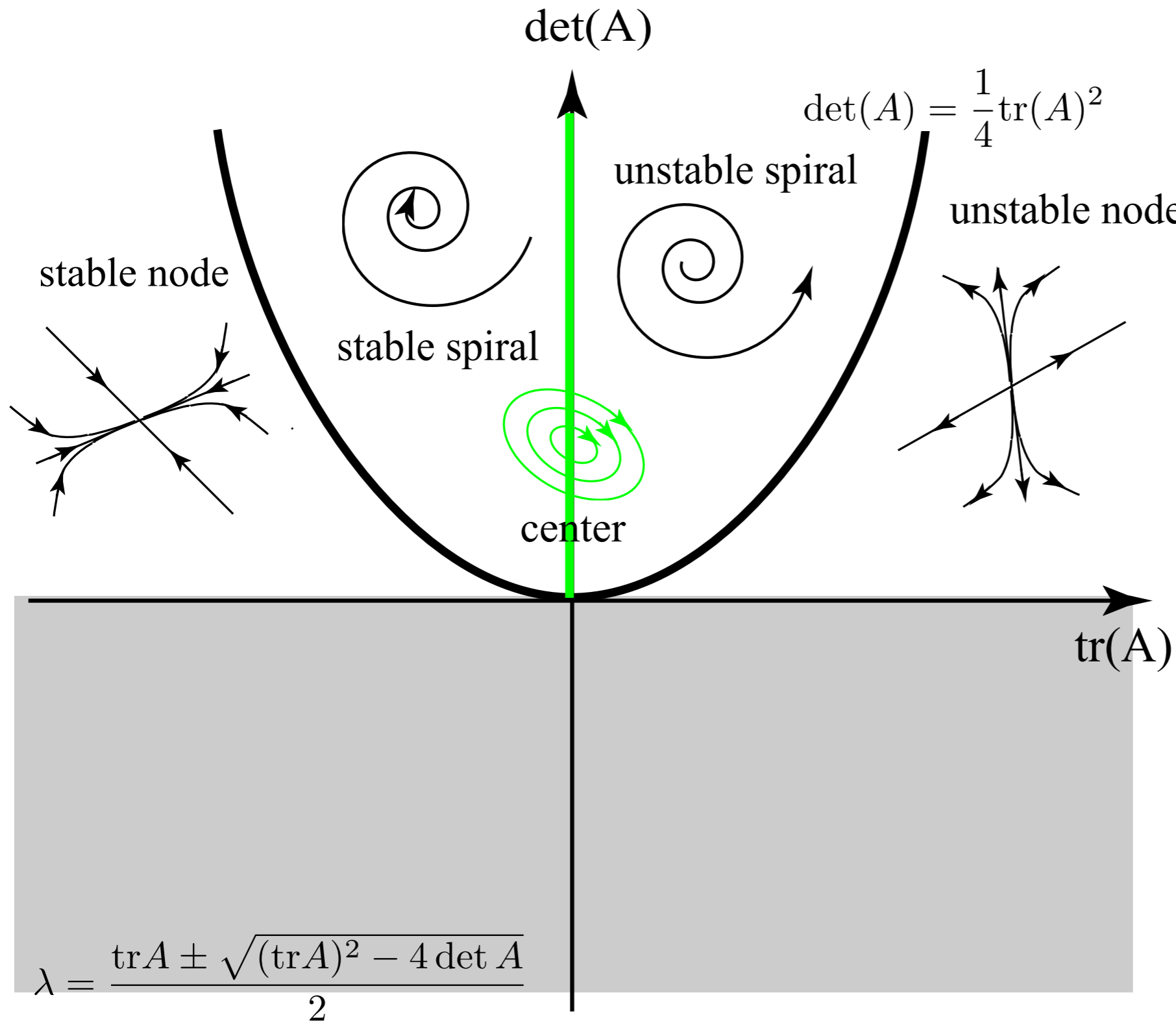
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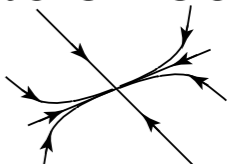
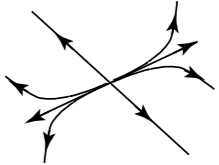
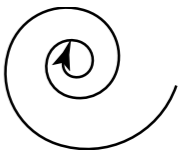
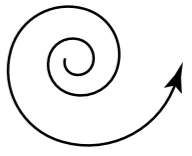
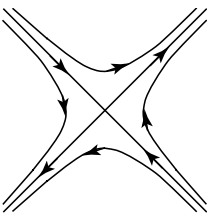
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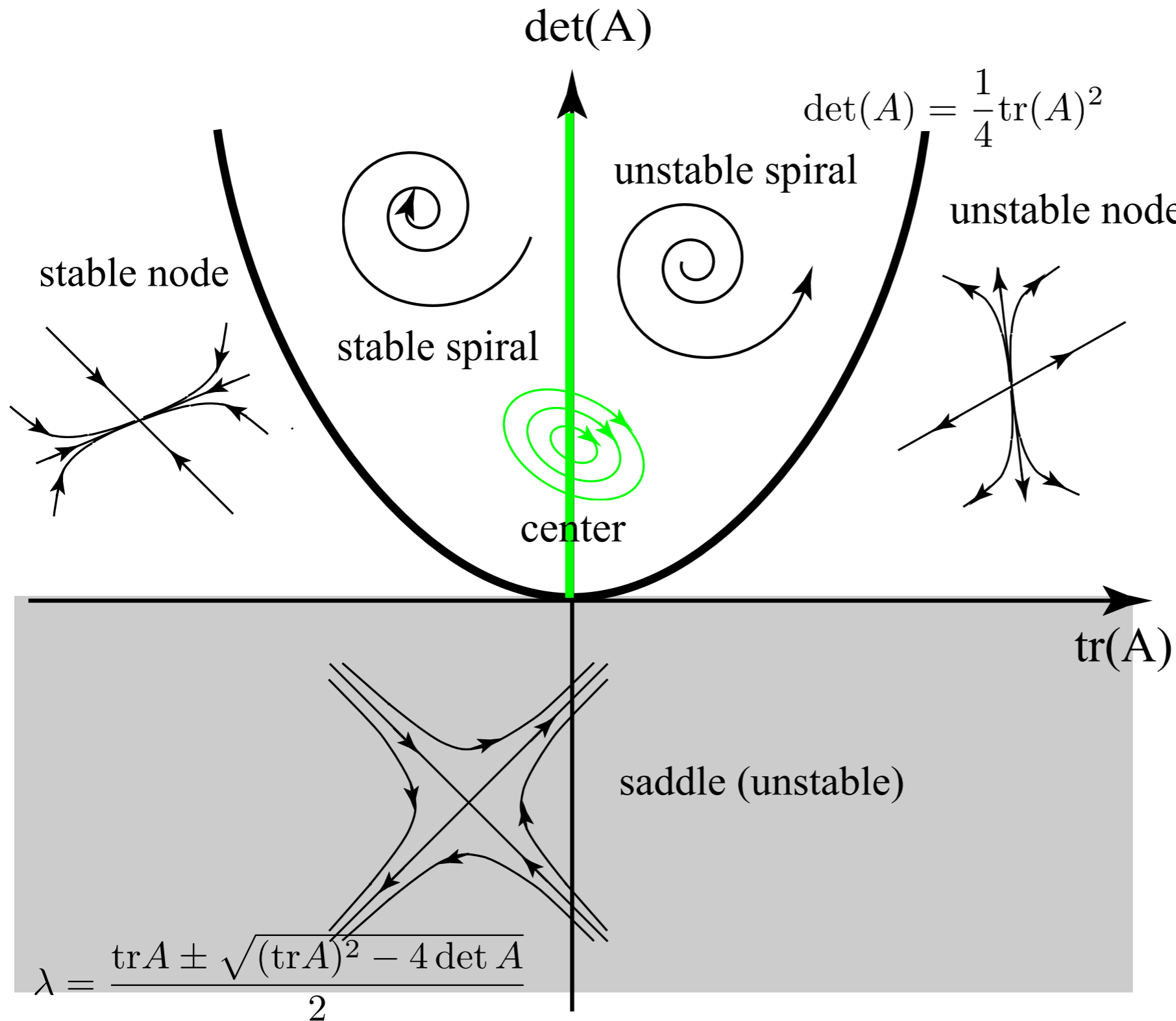
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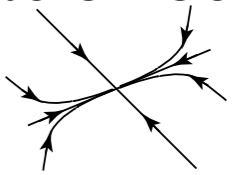
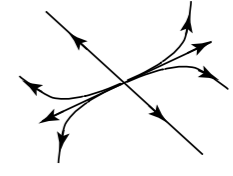
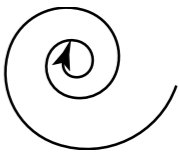
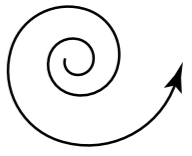
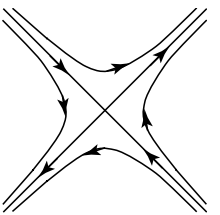
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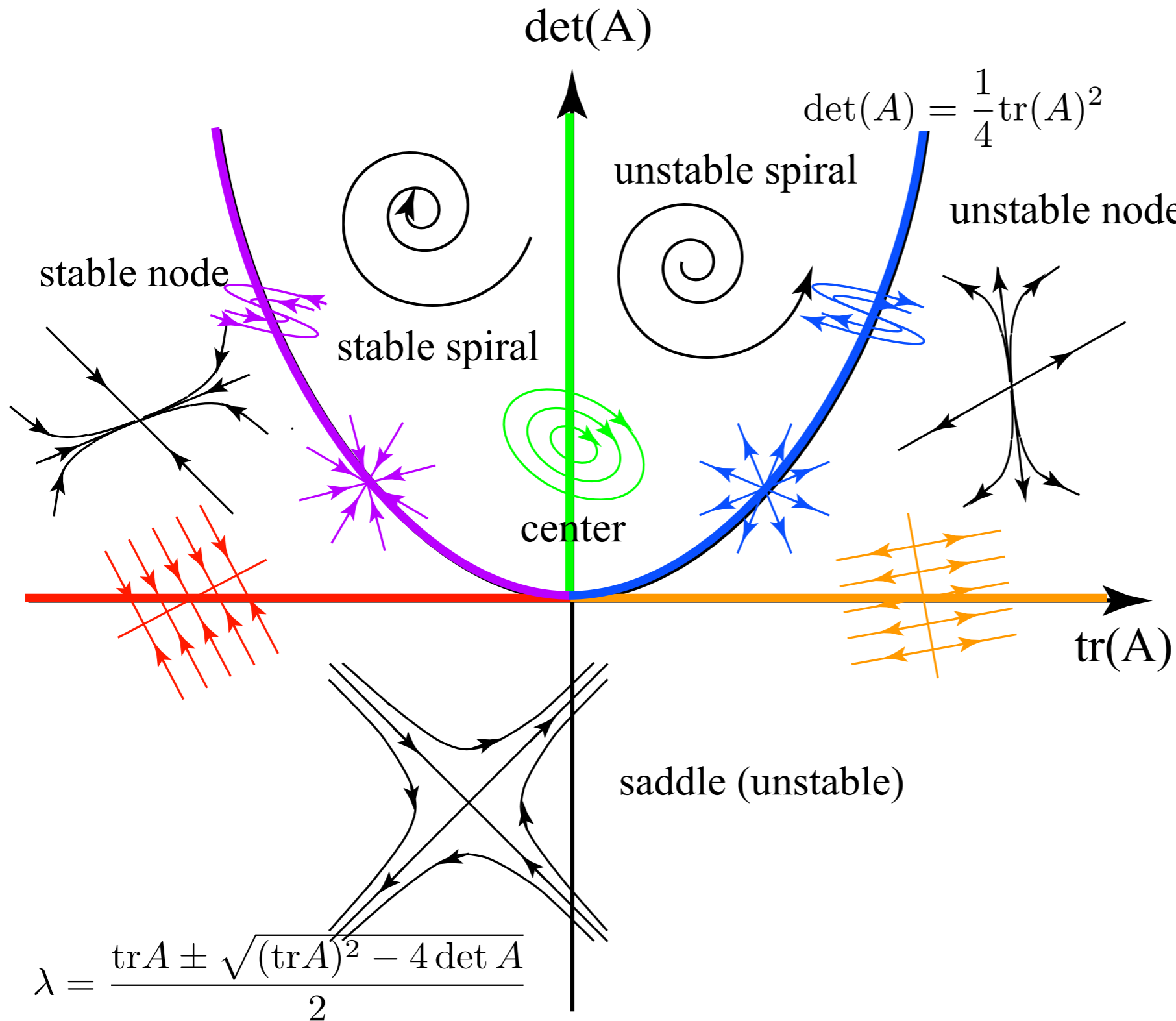
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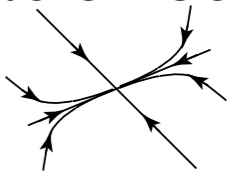
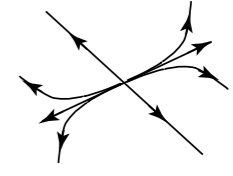
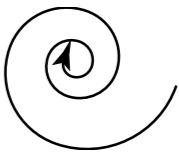
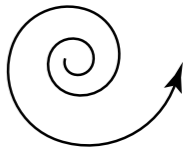
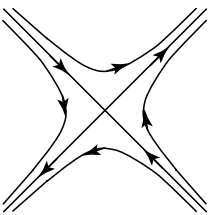
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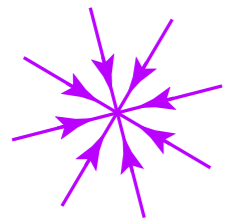


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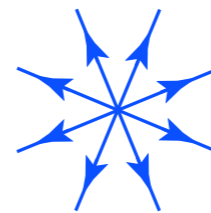
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- (E) saddle 

Summary - homogeneous 2x2 systems

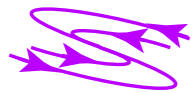
Repeated evalue cases:



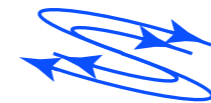
$\lambda < 0$, two indep. evector.



$\lambda > 0$, two indep. evector.

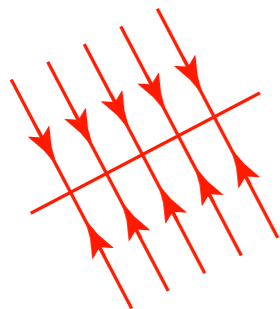


$\lambda < 0$, only one evector.

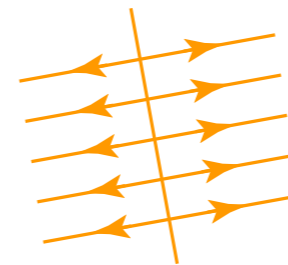


$\lambda > 0$, only one evector.

One zero evalue (singular matrix):



$\lambda_1 = 0$, $\lambda_2 < 0$,



$\lambda_1 = 0$, $\lambda_2 > 0$,

Nonhomogeneous system of DEs

- How do you solve the equation

$$\mathbf{x}'(\mathbf{t}) = A\mathbf{x}(\mathbf{t}) + \mathbf{b} \ ?$$

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$$L[\mathbf{x}] = \mathbf{x}'(\mathbf{t}) - A\mathbf{x}(\mathbf{t})$$

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- then Method of Undetermined Coefficients...

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what form should we guess for $x_p(t)$ (in the sense of MUC)?

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- (d) $\mathbf{x}_p = t^2\mathbf{v} + t\mathbf{u} + \mathbf{w}$

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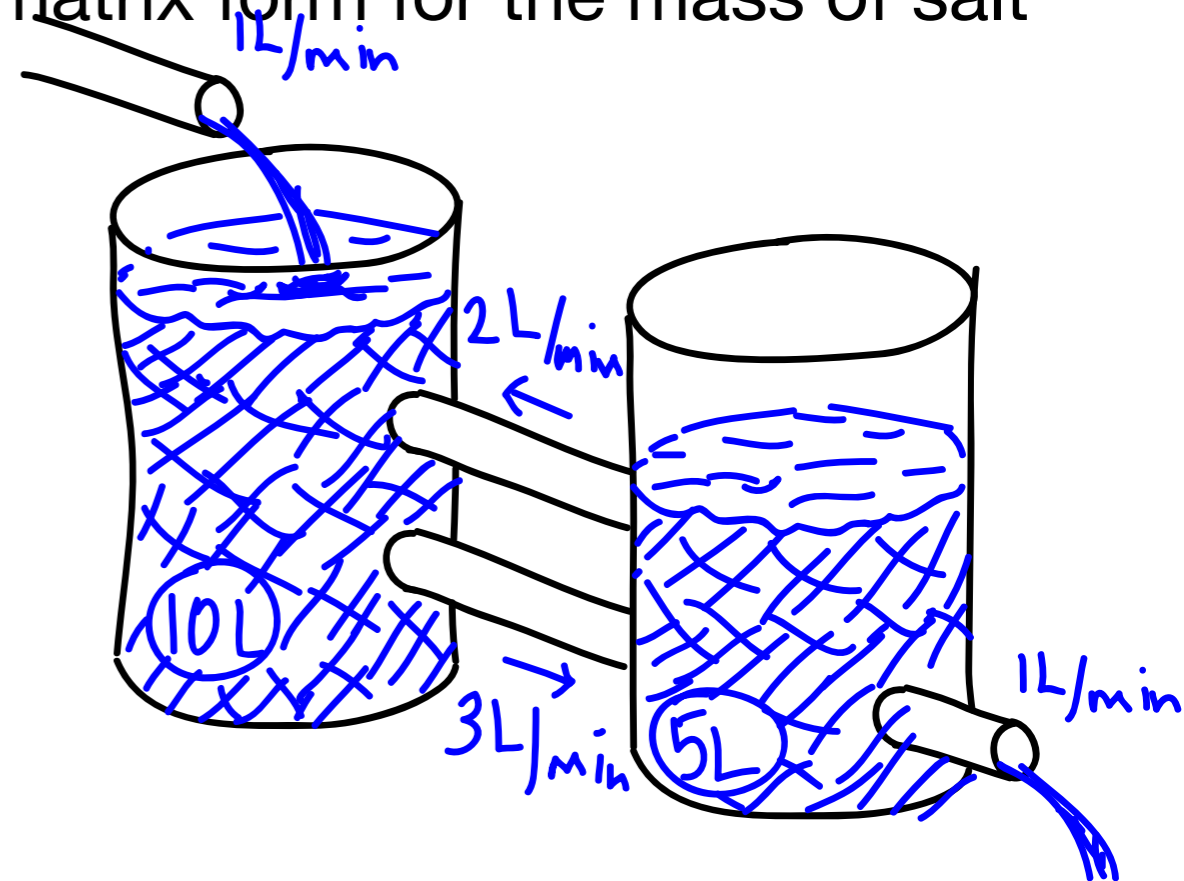
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Nonhomogeneous system of DEs - example

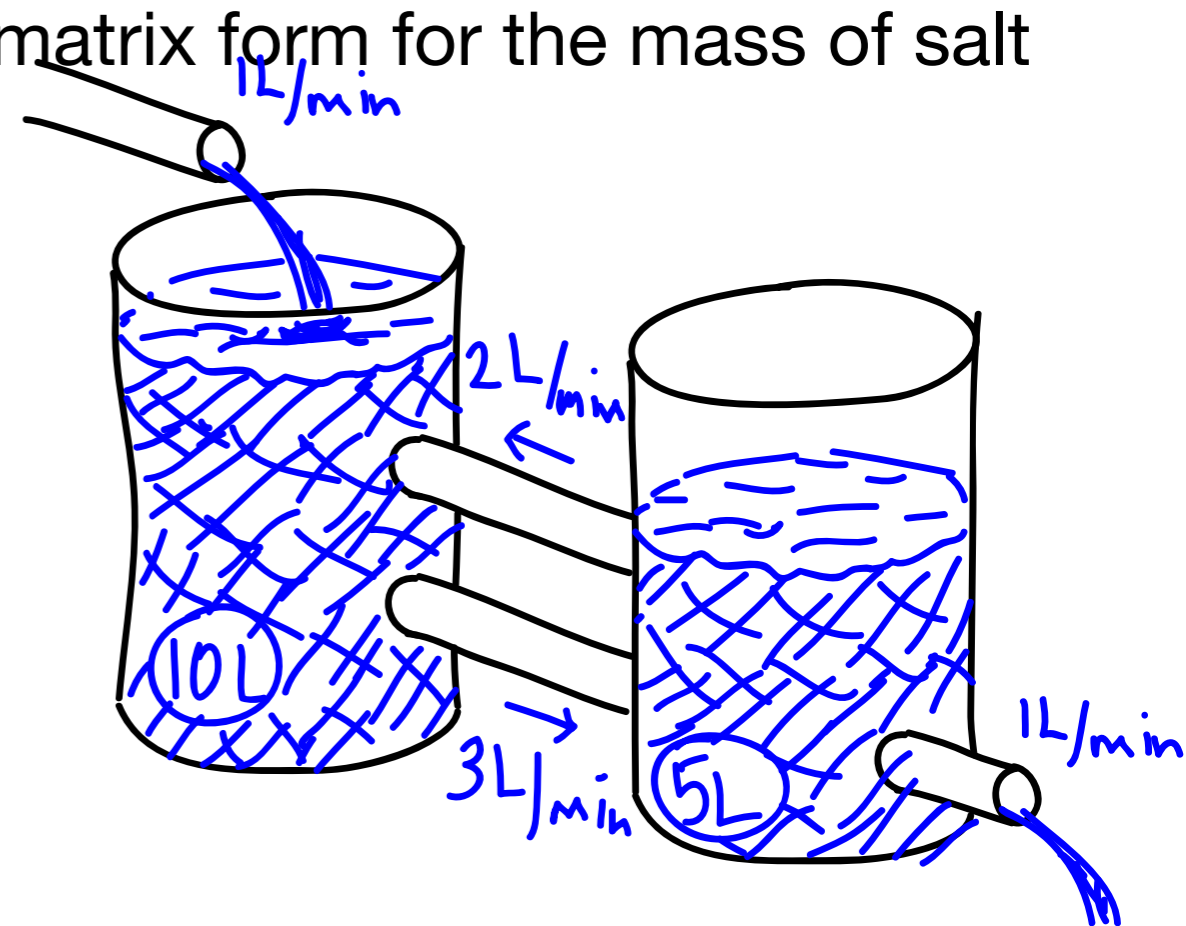
- Salt water flows into a tank holding 10 L of water at a rate of 1 L/min with a concentration of 200 g/L. The well-mixed solution flows from that tank into a tank holding 5 L through a pipe at 3 L/min. Another pipe takes the solution in the second tank back into the first at a rate of 2 L/min. Finally, solution drains out of the second tank at a rate of 1 L/min.
- Write down a system of equations in matrix form for the mass of salt in each tank.



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$$\begin{pmatrix} m_1 \\ m_2 \end{pmatrix}' = \begin{pmatrix} -\frac{3}{10} & \frac{2}{5} \\ \frac{3}{10} & -\frac{3}{5} \end{pmatrix} \begin{pmatrix} m_1 \\ m_2 \end{pmatrix} + \begin{pmatrix} 200 \\ 0 \end{pmatrix}$$



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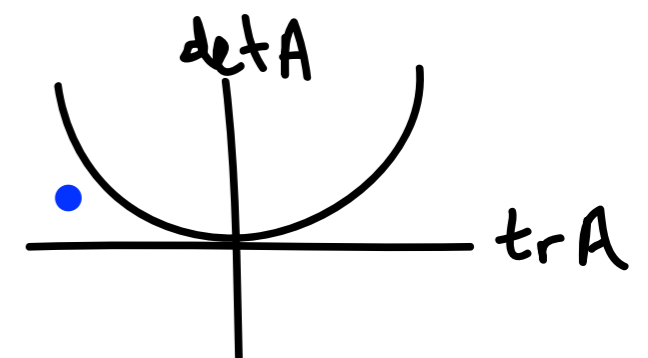


$$\text{tr} A = -\frac{9}{10}$$

$$(\text{tr} A)^2 = \frac{81}{100}$$

$$\det A = \frac{9}{50} - \frac{6}{50} = \frac{3}{50}$$

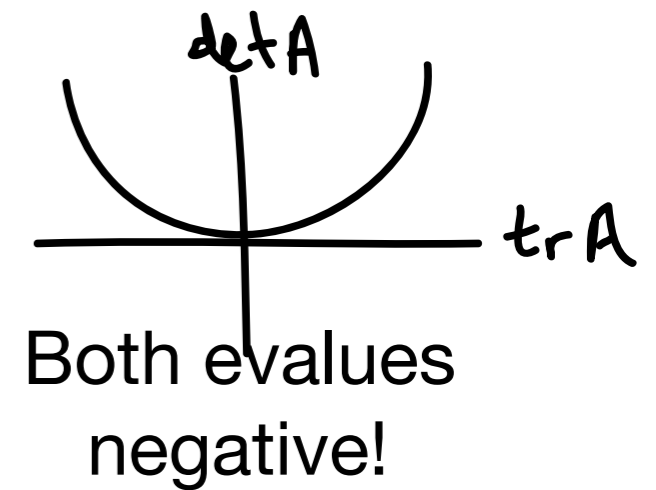
$$4 \det A = \frac{12}{50}$$



Both values
negative!

Nonhomogeneous case - example

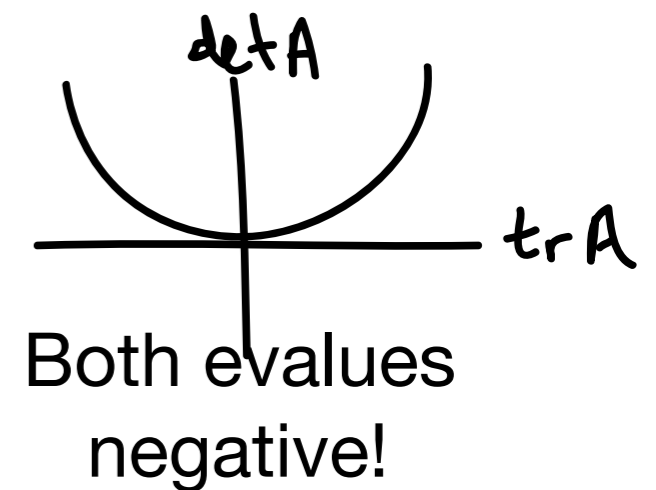
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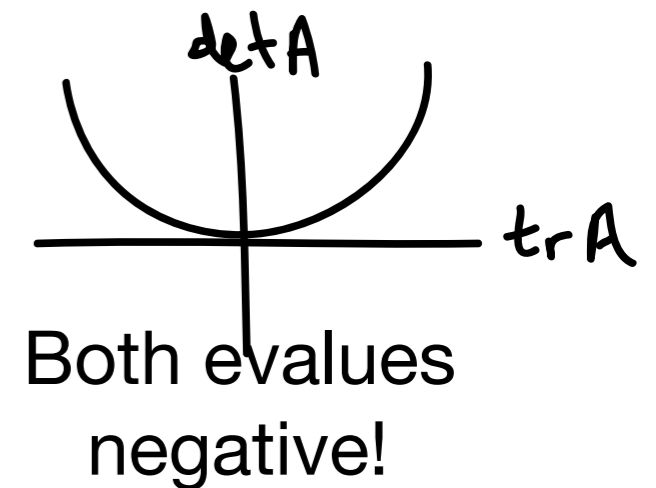
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$$\mathbf{m}_h(t) = C_1 e^{\lambda_1 t} \mathbf{v}_1 + C_2 e^{\lambda_2 t} \mathbf{v}_2 \quad \left(\lambda_{1,2} = -\frac{9}{20} \pm \frac{\sqrt{57}}{20} \right)$$



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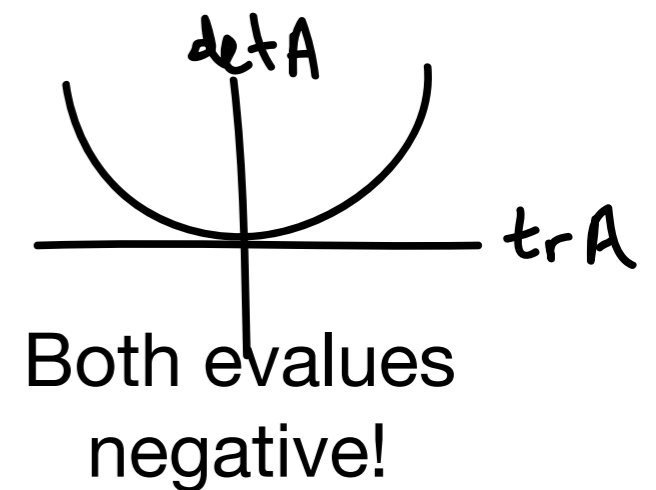
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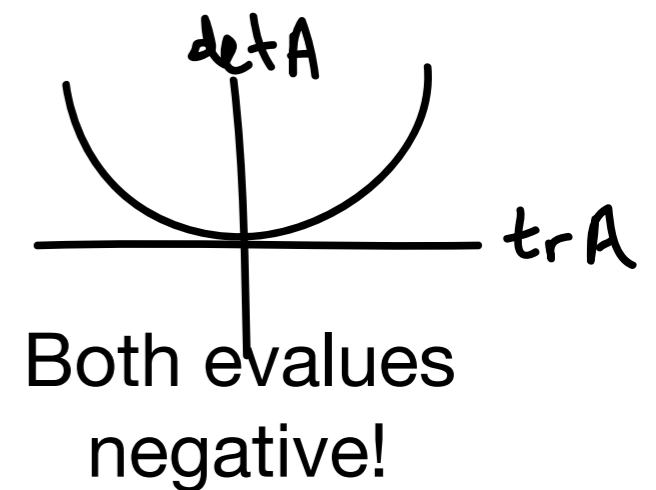
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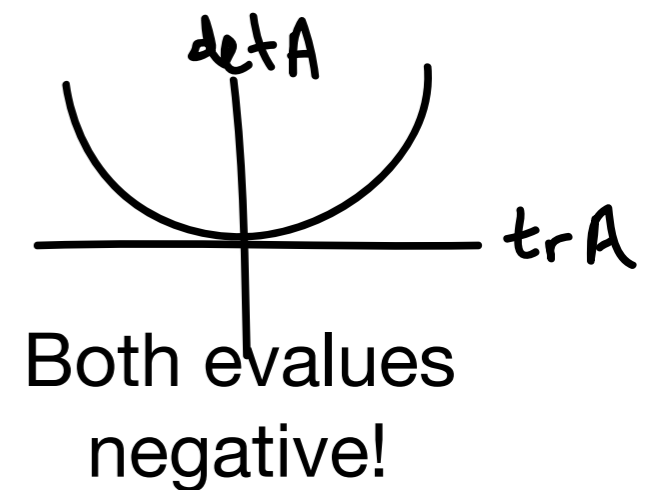
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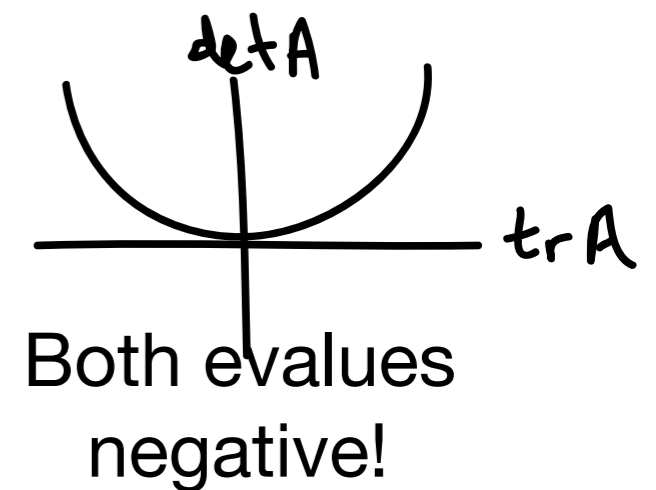


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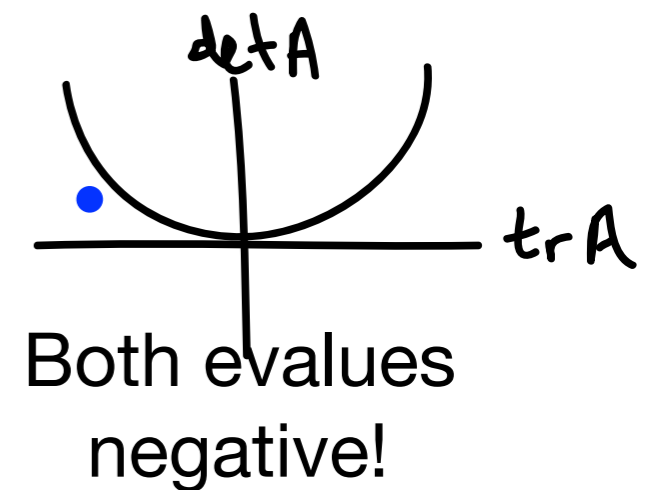
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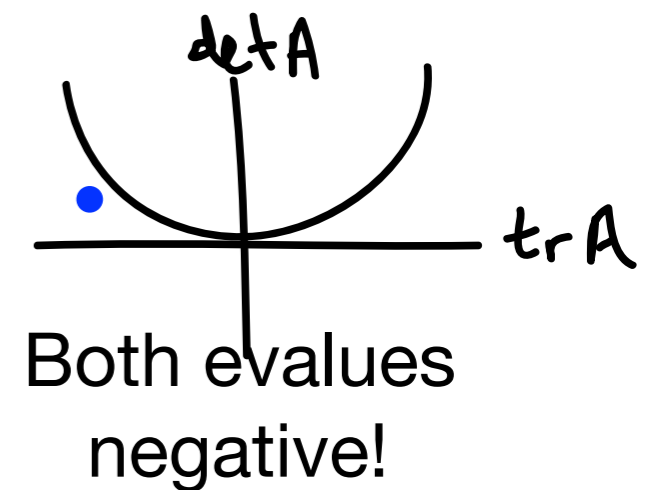
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Nonhomogeneous case - example

$$\begin{pmatrix} m_1 \\ m_2 \end{pmatrix}' = \begin{pmatrix} -\frac{3}{10} & \frac{2}{5} \\ \frac{3}{10} & -\frac{3}{5} \end{pmatrix} \begin{pmatrix} m_1 \\ m_2 \end{pmatrix} + \begin{pmatrix} 200 \\ 0 \end{pmatrix}$$



$$\mathbf{m}_h(t) = C_1 e^{\lambda_1 t} \mathbf{v}_1 + C_2 e^{\lambda_2 t} \mathbf{v}_2 \quad \left(\lambda_{1,2} = -\frac{9}{20} \pm \frac{\sqrt{57}}{20} \right)$$

$$\mathbf{m}_p(t) = \mathbf{w} = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}$$

$$\mathbf{0} = A\mathbf{w} + \begin{pmatrix} 200 \\ 0 \end{pmatrix} \rightarrow A\mathbf{w} = -\begin{pmatrix} 200 \\ 0 \end{pmatrix} \rightarrow \mathbf{w} = \begin{pmatrix} 2000 \\ 1000 \end{pmatrix}$$

$$\mathbf{m}(t) = C_1 e^{\lambda_1 t} \mathbf{v}_1 + C_2 e^{\lambda_2 t} \mathbf{v}_2 + \begin{pmatrix} 2000 \\ 1000 \end{pmatrix}$$

Nonhomogeneous case - example

- A “Method of undetermined coefficients” similar to what we saw for second order equations can be used for systems.
- For this course, I’ll only test you on constant nonhomogeneous terms (like the previous example).