

Today

- Reminder - midterm next week! Chapter 1.1-1.3, 2.1-2.4, 3 (not 3.6)
- Finish up undetermined coefficients
- Physics applications - mass springs
- Undamped, over/under/critically damped oscillations

Method of undetermined coefficients (3.5)

- **Example 6.** Find the general solution to $y'' - 4y = t^3$.

- What is the form of the particular solution?

(A) $y_p(t) = At^3$

(B) $y_p(t) = At^3 + Bt^2 + Ct$

★ (C) $y_p(t) = At^3 + Bt^2 + Ct + D$

(D) $y_p(t) = At^3 + Bt^2 + Ct + D + Ee^{2t} + Fe^{-2t}$

(E) Don't know / still thinking.

Method of undetermined coefficients (3.5)

- **Example 6.** Find the general solution to $y'' + 2y' = e^{2t} + t^3$.

- What is the form of the particular solution?

(A) $y_p(t) = Ae^{2t} + Bt^3 + Ct^2 + Dt$

(B) $y_p(t) = Ae^{2t} + Bt^3 + Ct^2 + Dt + E$

★ (C) $y_p(t) = Ae^{2t} + (Bt^4 + Ct^3 + Dt^2 + Et)$
 $y_p(t) = Ae^{2t} + t(Bt^3 + Ct^2 + Dt + E)$

(D) $y_p(t) = Ae^{2t} + Be^{-2t} + Ct^3 + Dt^2 + Et + F$

(E) Don't know / still thinking.

For each wrong answer, for what DE is it the correct form?

Method of undetermined coefficients (3.5)

- **Example 6.** Find the general solution to $y'' - 4y = t^3 e^{2t}$.
 - What is the form of the particular solution?
 - (A) $y_p(t) = (At^3 + Bt^2 + Ct + D)e^{2t}$
 - (B) $y_p(t) = (At^3 + Bt^2 + Ct)e^{2t}$
 - (C) $y_p(t) = (At^3 + Bt^2 + Ct)e^{2t} + (Dt^3 + Et^2 + Ft)e^{-2t}$
 - ★ (D) $y_p(t) = (At^4 + Bt^3 + Ct^2 + Dt)e^{2t}$
 $y_p(t) = t(At^3 + Bt^2 + Ct + D)e^{2t}$
 - (E) Don't know / still thinking.

Method of undetermined coefficients (3.5)

$$y'' + 3y' - 10y = x^2 e^{-5x}$$

$$y_p(x) = Ax^2 e^{-5x}$$

$$y_p'(x) = 2Ax e^{-5x} - 5Ax^2 e^{-5x}$$

$$y_p''(x) = 2Ae^{-5x} - 10Ax e^{-5x} - 10Ax e^{-5x} + 25Ax^2 e^{-5x}$$

$$-10y_p(x) = \phantom{2Ae^{-5x} - 10Ax e^{-5x} - 10Ax e^{-5x} + 25Ax^2 e^{-5x}} - 10Ax^2 e^{-5x}$$

$$3y_p'(x) = \phantom{2Ae^{-5x} - 10Ax e^{-5x} - 10Ax e^{-5x} + 25Ax^2 e^{-5x}} 6Ax e^{-5x} - 15Ax^2 e^{-5x}$$

$$y_p''(x) = 2Ae^{-5x} - 20Ax e^{-5x} + 25Ax^2 e^{-5x}$$

$$2Ae^{-5x} - 14Ax e^{-5x} + 0 = x^2 e^{-5x}$$

Can't find A that works!

Need 3 unknowns to match all 3 terms.

Method of undetermined coefficients (3.5)

$$y'' + 3y' - 10y = x^2 e^{-5x}$$

$$y_p(x) = Ax^2 e^{-5x} + Bx e^{-5x} + C e^{-5x}$$

$$y'_p(x) \text{ involves } x^2, x, 1$$

$$y''_p(x) \text{ involves } x^2, x, 1$$

But e^{-5x} gets killed by the operator so C disappears - only 2 unknowns for matching.

Need 3 unknowns but not including e^{-5x} .

$$\begin{aligned} y_p(x) &= Ax^3 e^{-5x} + Bx^2 e^{-5x} + Cx e^{-5x} \\ &= x(Ax^2 e^{-5x} + Bx e^{-5x} + C e^{-5x}) \end{aligned}$$

Method of undetermined coefficients (3.5)

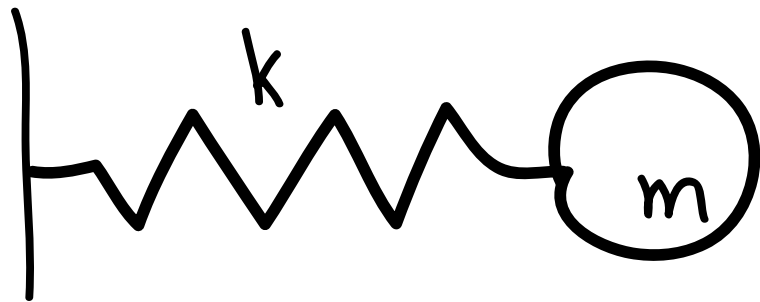
- Summary - finding a particular solution to $L[y] = g(t)$.
 - Include all functions that are part of the $g(t)$ family (e.g. \cos **and** \sin)
 - If part of the $g(t)$ family is a solution to the homogeneous (h-)problem, use $t \times (g(t) \text{ family})$.
 - If $t \times (\text{part of the } g(t) \text{ family})$, is a solution to the h-problem, use $t^2 \times (g(t) \text{ family})$. etc.
 - For sums, group terms into families and include a term for each.
 - For products of families, use the above rules and multiply them.
 - If your guess includes a solution to the h-problem, you may as well remove it as it won't survive $L[]$ so you won't be able to determine its undetermined coefficient.

Method of undetermined coefficients (3.5)

- Do lots of these problems and the trends will become clear.
- Two crucial facts to remember
 - If you try a form and you can make $\text{LHS}=\text{RHS}$ with some choice for the coefficients then you're done.
 - If you can't, your guess is most likely missing a term(s).

Applications - vibrations (3.7)

Mass-spring systems



$$E = \frac{1}{2} k (x - x_0)^2$$

$$F = - \frac{dE}{dx} = -k(x - x_0)$$

$$ma = F$$

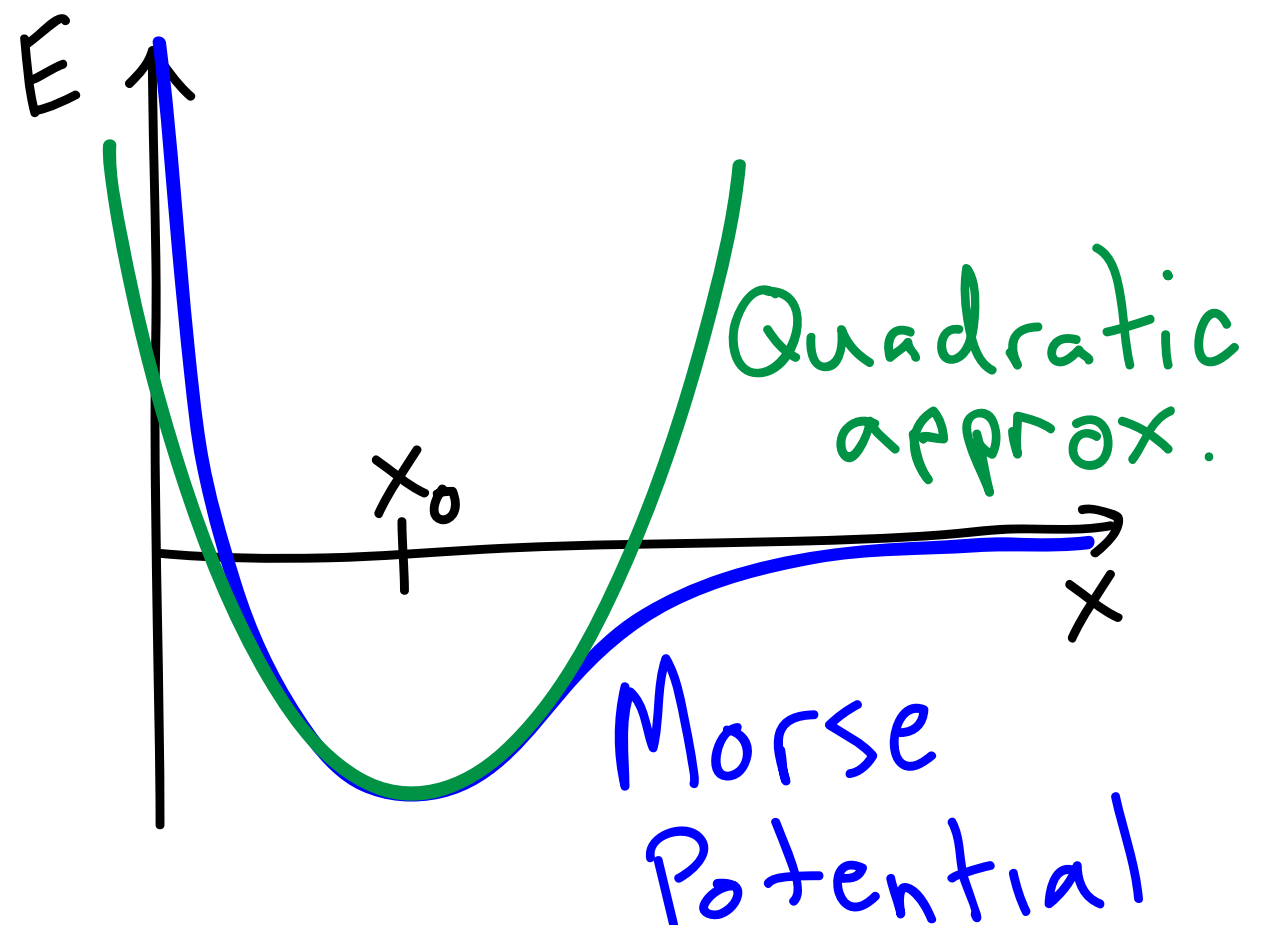
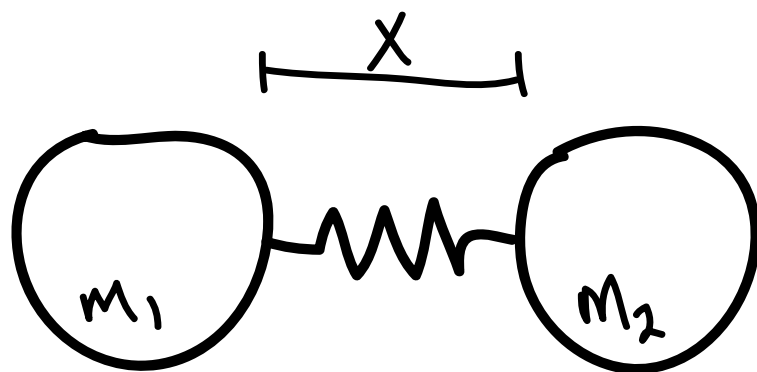
$$ma = -k(x - x_0)$$

$$m x'' = -k(x - x_0)$$

$$m x'' + kx = kx_0$$

Applications - vibrations (3.7)

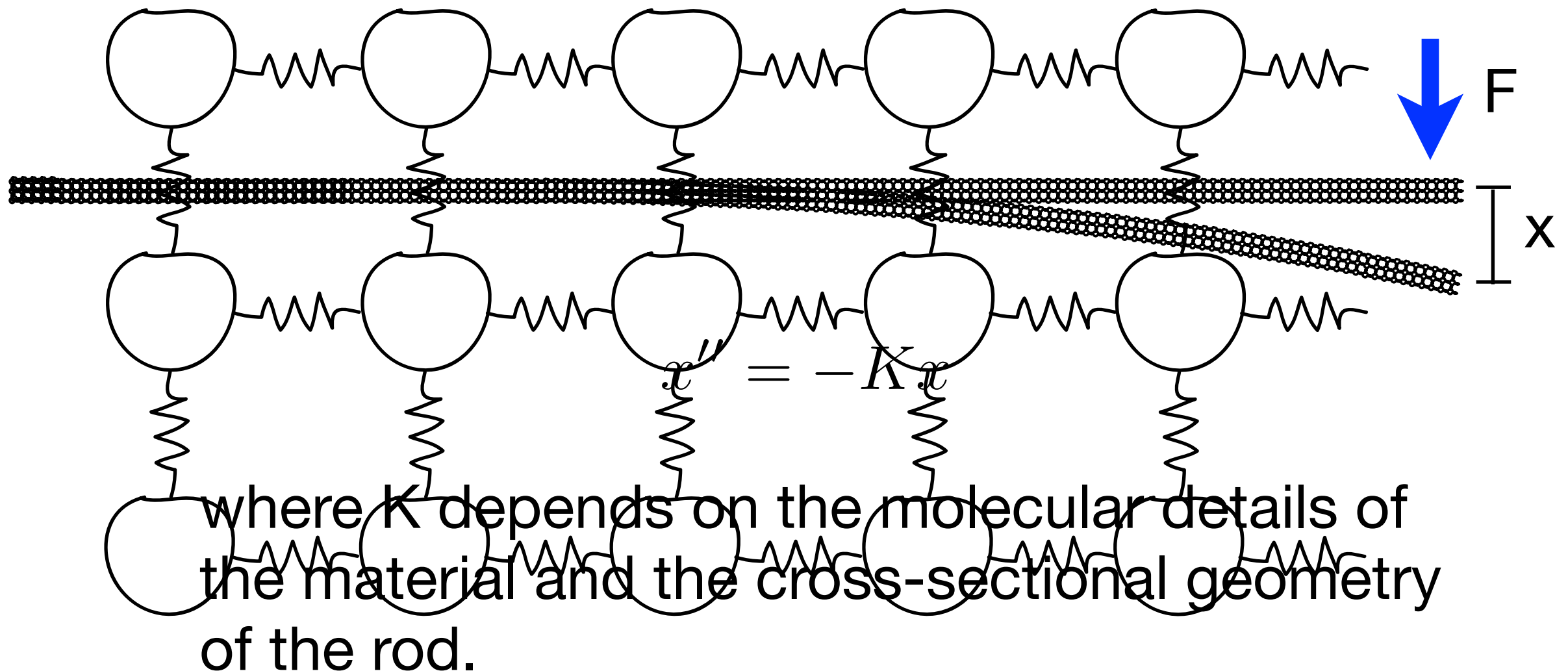
Molecular bonds



Applications - vibrations (3.7)

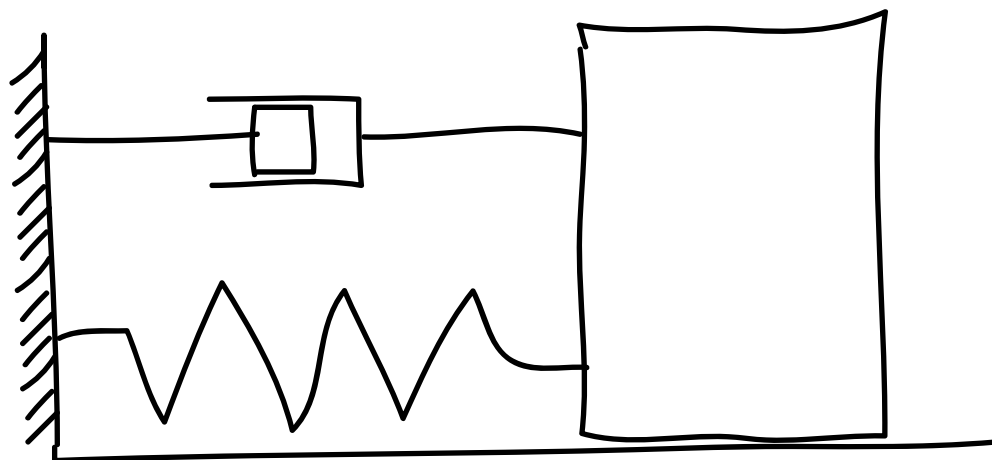
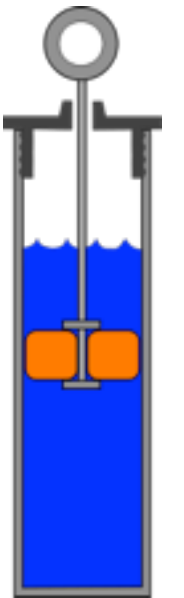
Solid mechanics

e.g. tuning fork, bridges, buildings



Applications - vibrations (3.7)

- So far, no x' term so no exponential decay in the solutions.
- Dashpot - mechanical element that adds friction.
 - sometimes an abstraction that accounts for energy loss.



Kelvin-Voigt model



shock absorber

$$ma = -k(x - x_0) - \gamma v$$

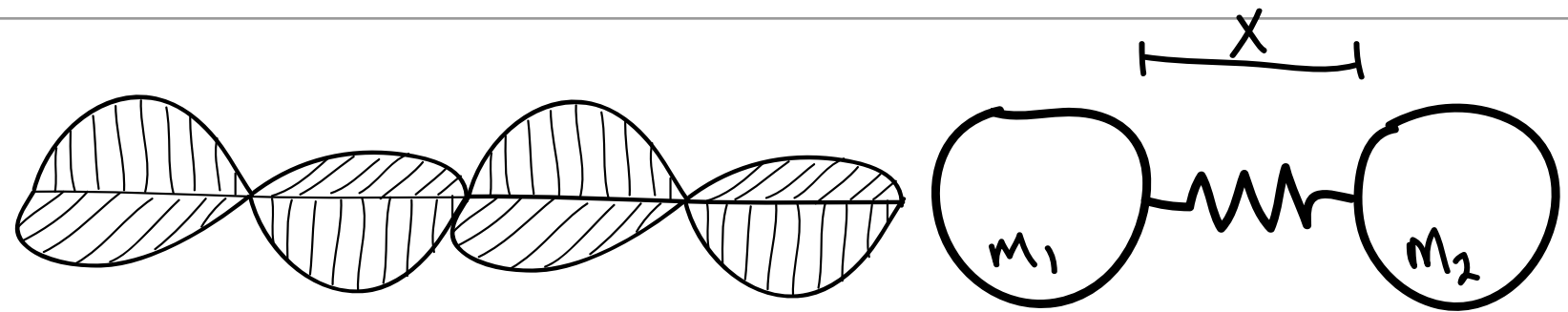
$$m\ddot{x} = -k(x - x_0) - \gamma \dot{x}$$

$$m\ddot{x} + \gamma \dot{x} + kx = kx_0$$

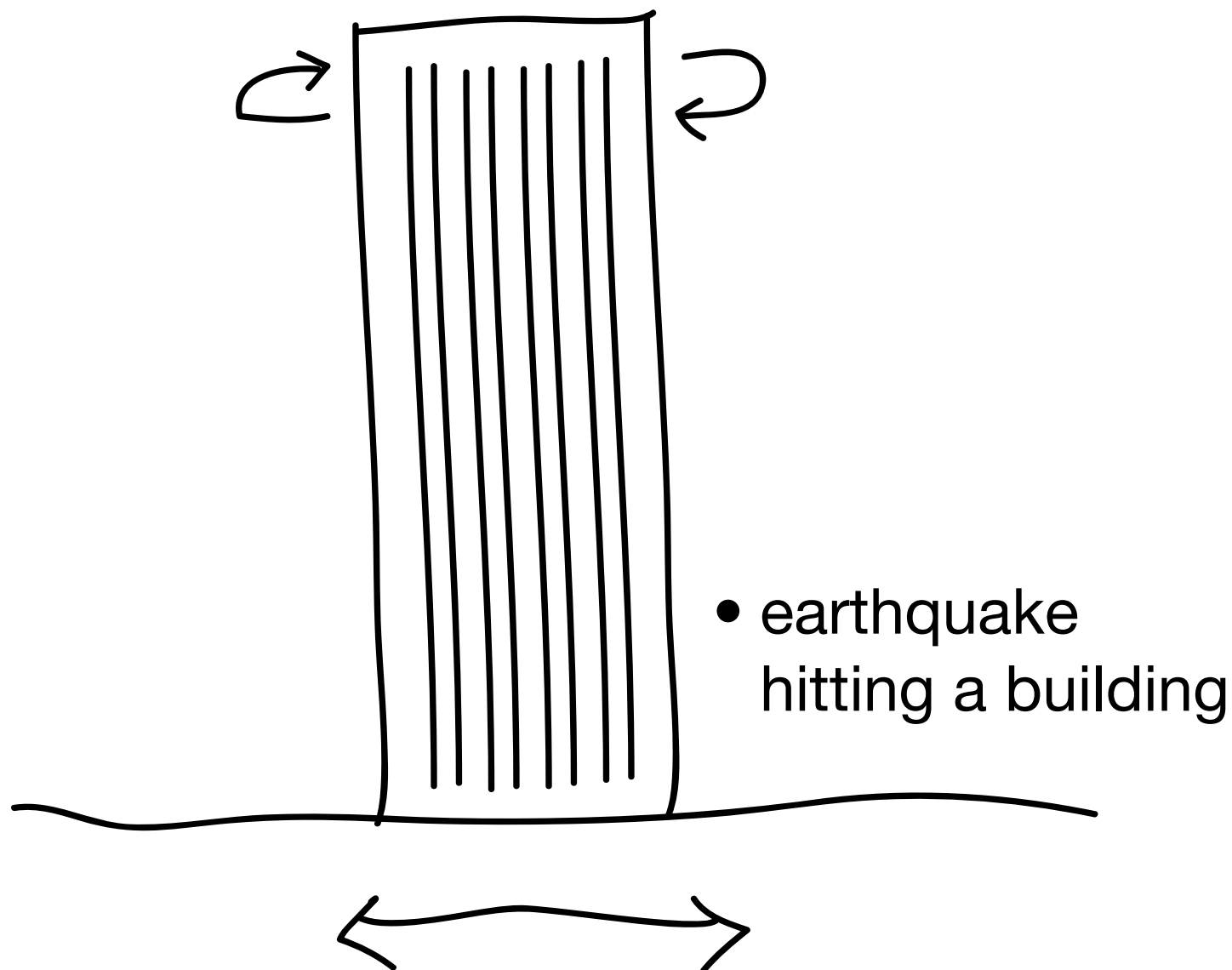
$$y = x - x_0$$

$$m\ddot{y} + \gamma \dot{y} + ky = 0$$

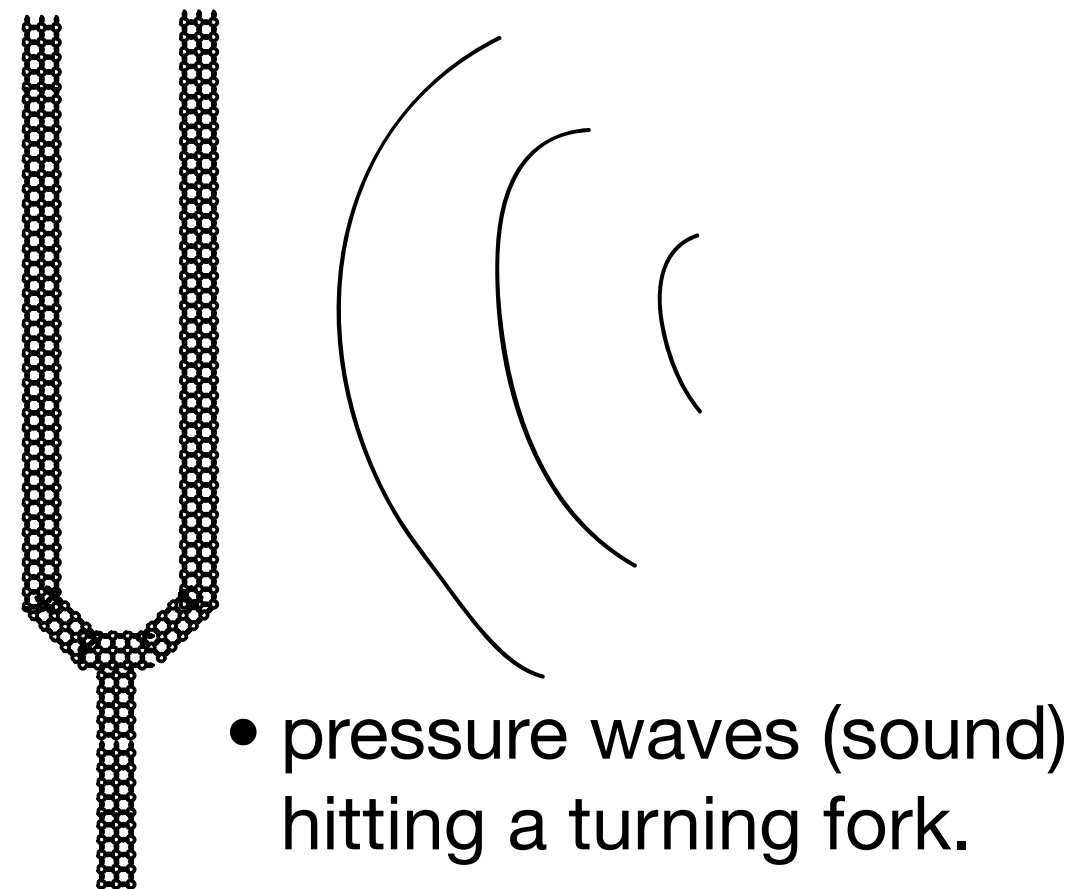
Applications - forced vibrations (3.8)



- light hitting a molecular bond



- earthquake hitting a building



- pressure waves (sound) hitting a tuning fork.

Applications - vibrations (3.7)

- Undamped mass spring

$$mx'' + kx = 0$$

$$mr^2 + k = 0$$

$$r = \pm \sqrt{\frac{k}{m}}i$$

$$x(t) = C_1 \cos(\omega_0 t) + C_2 \sin(\omega_0 t)$$

$$\omega_0 = \sqrt{\frac{k}{m}}$$

- frequency
 - increases with stiffness
 - decreases with mass

Applications - vibrations (3.7)

Trig identity reminders

$$\sin(A + B) = \sin(A) \cos(B) + \cos(A) \sin(B)$$

$$\cos(A + B) = \cos(A) \cos(B) - \sin(A) \sin(B)$$

$$2 \cos(3t + \pi/3) =$$

(A) $2 \sin(\pi/3) \cos(3t) - 2 \sin(\pi/3) \cos(3t)$

(B) $2 \sin(\pi/3) \cos(3t) + 2 \sin(\pi/3) \cos(3t)$

(C) $2 \cos(\pi/3) \cos(3t) - 2 \sin(\pi/3) \sin(3t)$

(D) $2 \cos(\pi/3) \cos(3t) + 2 \sin(\pi/3) \sin(3t) - \sqrt{3} \sin(3t)$

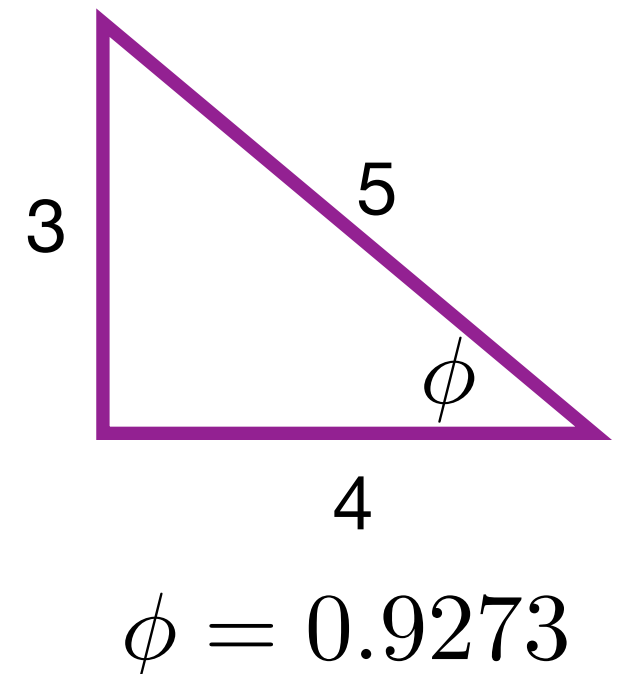
(E) Don't know / still thinking.

Applications - vibrations (3.7)

- Converting from sum-of-sin-cos to a single cos expression:

- Example:

$$\begin{aligned} & 4 \cos(2t) + 3 \sin(2t) \\ &= 5 \left(\frac{4}{5} \cos(2t) + \frac{3}{5} \sin(2t) \right) \\ &= 5(\cos(\phi) \cos(2t) + \sin(\phi) \sin(2t)) \\ &= 5 \cos(2t - \phi) \end{aligned}$$



$$\cos(A - B) = \overset{\cancel{4}}{\cos(A)} \overset{\cancel{3}}{\cos(B)} + \sin(A) \sin(B)$$

(cos(A), sin(A)) must lie on the unit circle. i.e. $\cos^2(A) + \sin^2(A) = 1$.

Applications - vibrations (3.7)

- Converting from sum-of-sin-cos to a single cos expression:

$$y(t) = C_1 \cos(\omega_0 t) + C_2 \sin(\omega_0 t)$$

- Step 1 - Factor out $A = \sqrt{C_1^2 + C_2^2}$.

- Step 2 - Find the angle ϕ for which $\cos(\phi) = \frac{C_1}{\sqrt{C_1^2 + C_2^2}}$
and $\sin(\phi) = \frac{C_2}{\sqrt{C_1^2 + C_2^2}}$.

- Step 3 - Rewrite the solution as $y(t) = A \cos(\omega_0 t - \phi)$.

Applications - vibrations (3.7)

- Damped mass-spring

$$mx'' + \gamma x' + kx = 0 \quad m, \gamma, k > 0$$

$$\Rightarrow mr^2 + \gamma r + k = 0$$

$$r_{1,2} = -\frac{\gamma}{2m} \pm \frac{\sqrt{\gamma^2 - 4km}}{2m} = \frac{\gamma}{2m} \left(-1 \pm \sqrt{1 - \frac{4km}{\gamma^2}} \right)$$

negative or complex

smaller than 1 or complex

We have the usual
three cases...

Applications - vibrations (3.7)

- Damped oscillations

$$r_{1,2} = \frac{\gamma}{2m} \left(-1 \pm \sqrt{1 - \frac{4km}{\gamma^2}} \right)$$

(i) $\frac{4km}{\gamma^2} < 1 \Rightarrow r_1, r_2 < 0$, exponential decay only
(over damped - γ large)

(ii) $\frac{4km}{\gamma^2} = 1 \Rightarrow r_1=r_2$, exp and t^* exp decay
(critically damped)

(iii) $\frac{4km}{\gamma^2} > 1 \Rightarrow r = \alpha \pm \beta i$

$\alpha = -\frac{\gamma}{2m} < 0 \Rightarrow$ decaying oscillations
(under damped - γ small)
 $x(t) = e^{\alpha t} (C_1 \cos(\beta t) + C_2 \sin(\beta t))$

$$\beta = \sqrt{\frac{4km}{\gamma^2} - 1}$$

← called pseudo-frequency

For graphs, see:

<https://www.desmos.com/calculator/psy5r8hpln>