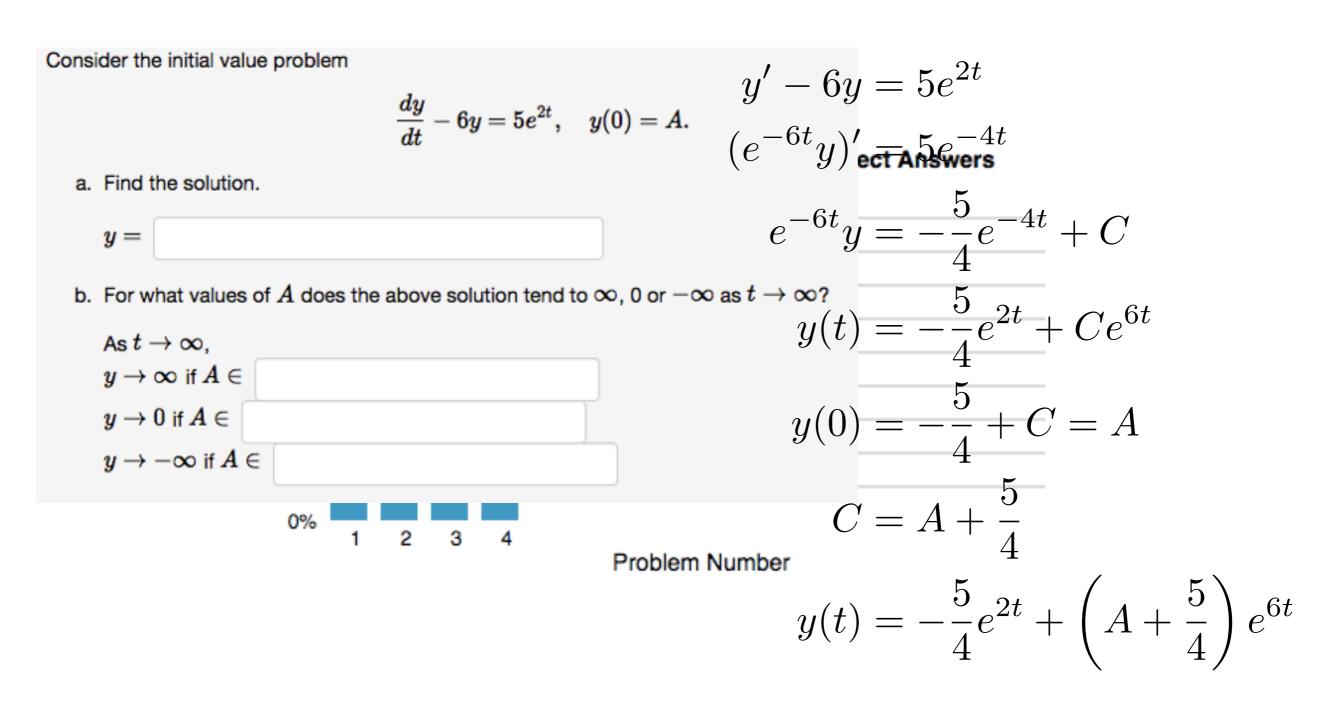
# Today

- Comment on pre-lecture problems
- Finish up with integrating factors
- The structure of solutions
- Separable equations

## Pre-lecture assignment comments



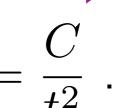
Desmos demo: <a href="https://www.desmos.com/calculator/ne9u9c2q3b">https://www.desmos.com/calculator/ne9u9c2q3b</a>

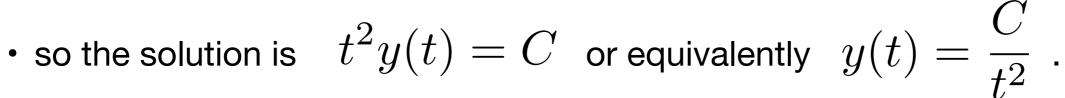
• Given that 
$$\ \frac{d}{dt}\left(t^2y(t)\right) = \ t^2\frac{dy}{dt} + 2ty$$

• if you're given the equation 
$$t^2 \frac{dy}{dt} + 2ty = 0$$

• you can rewrite is as  $\frac{d}{dt}\left(t^2y(t)\right)=0$ 

arbitrary constant that appeared at an integration step





• Solve the equation  $t^2 \frac{dy}{dt} + 2ty(t) = \sin(t)$  (not brute force checking).

(A) 
$$y(t) = -\cos(t) + C$$

(B) 
$$y(t) = \frac{C - \cos(t)}{t^2}$$

(C) 
$$y(t) = \sin(t) + C$$

(D) 
$$y(t) = -\frac{1}{t^2}\cos(t)$$

(E) Don't know.

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$$y(t) = -\cos(t) + C$$

$$(B) y(t) = \frac{C - \cos(t)}{t^2}$$

(C)  $y(t) = \sin(t) + C$ 

general solution (although that's not obvious)

(D) 
$$y(t) = -\frac{1}{t^2}\cos(t)$$

a particular solution

(E) Don't know.

## Initial conditions (IC) and initial value problems (IVP)

An initial condition is an added constraint on a solution.

• e.g. Solve 
$$t^2 \frac{dy}{dt} + 2ty(t) = \sin(t)$$
 subject to the IC  $y(\pi) = 0$  .

(A) 
$$y(t) = -\frac{C + \cos(\pi)}{\pi^2}$$

(B) 
$$y(t) = -\frac{1 - \cos(t)}{t^2}$$

(C) 
$$y(t) = \frac{1 + \cos(t)}{t^2}$$

(D) 
$$y(t) = -\frac{1 + \cos(t)}{t^2}$$

An Initial Value Problem (IVP) is a ODE together with an IC.

(E) Don't know.

 What function should we multiply through by to make the LHS a perfect product rule?

$$t\frac{dy}{dt} + 2y(t) = 1 \qquad \to f(t) = t$$

$$t^2 \frac{dy}{dt} + 4ty(t) = \frac{1}{t} \qquad \to f(t) = t^2$$

$$\frac{dy}{dt} + y(t) = 0 \qquad \to f(t) = e^t$$

$$\frac{dy}{dt} + \cos(t)y(t) = 0 \qquad \to f(t) = e^{\sin(t)}$$

$$\frac{dy}{dt} + g'(t)y(t) = 0 \qquad \to f(t) = e^{g(t)}$$

## Technical definition of integrating factor

For the general first order linear ODE

$$a(t)y' + b(t)y = g(t)$$

Divide through by a(t) and define p(t) = b(t) / a(t) and q(t) = g(t) / a(t) :

$$y' + p(t)y = q(t)$$

• The function that, when multiplied through, make the LHS a perfect product rule is called the integrating factor.

General case - all first order linear ODEs can be written in the form

$$\frac{dy}{dt} + p(t)y = q(t)$$

- The appropriate integrating factor is  $e^{\int p(t)dt}$  .
- The equation can be rewritten  $\frac{d}{dt}\left(e^{\int p(t)dt}y\right)=e^{\int p(t)dt}q(t)$  which is solvable provided you can find the antiderivative of the right hand side.

$$e^{\int p(t)dt}y(t) = \int e^{\int p(t)dt}q(t)dt + C$$

$$y(t) = e^{-\int p(t)dt} \int e^{\int p(t)dt} q(t)dt + Ce^{-\int p(t)dt}$$

#### The structure of solutions

When the equation is of the form (called homogeneous)

$$\frac{dy}{dt} + p(t)y = 0$$

the solution is

$$y(t) = C\mu(t)^{-1}$$

where

$$\mu(t) = \exp\left(\int p(t)dt\right)$$

is the integrating factor.

#### The structure of solutions

When the equation is of the form (called nonhomogeneous)

$$\frac{dy}{dt} + p(t)y = q(t)$$

- the solution is  $y(t) = k(t) + C\mu(t)^{-1}$
- where k(t), as given earlier, involves no arbitrary constants.
- Think about this expression as  $y(t) = y_p(t) + y_h(t)$
- Directly analogous to solving the vector equations  $A\overline{x}=0$  and  $A\overline{x}=\overline{b}$  .

#### Examples

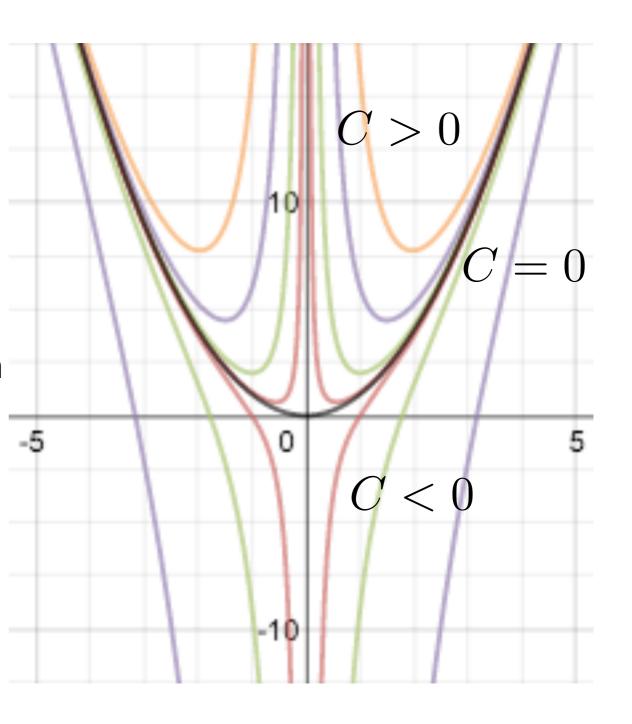
Find the general solution to

$$t\frac{dy}{dt} + 2y = 4t^2$$

- and plot a few of the integral curves.
- Integral curve the graph of a solution to an ODE.

$$y(t) = t^2 + C\frac{1}{t^2}$$

 Steps: divide through by t, calculate I(t), take antiderivatives, solve for y. Or shortcut.



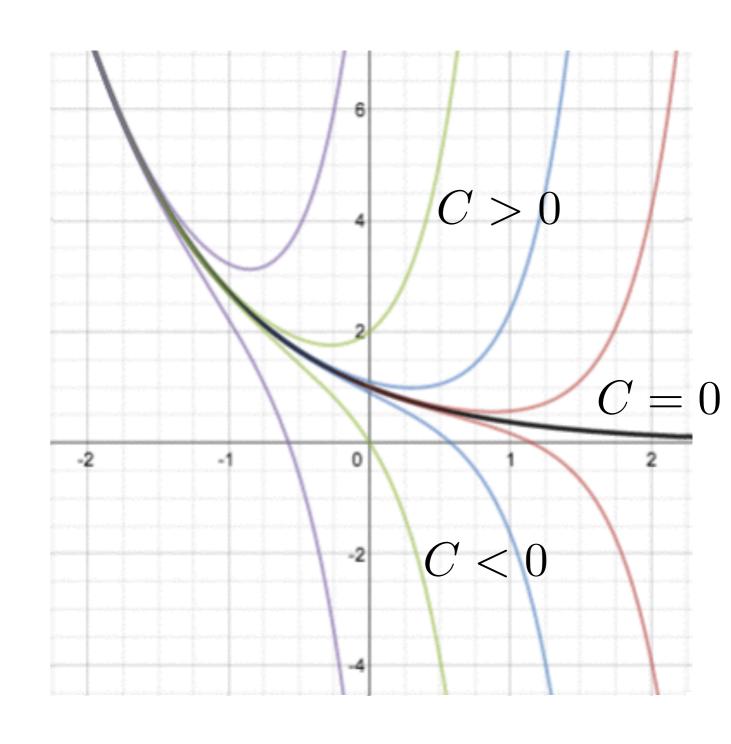
# Examples

Find the general solution to

$$\frac{dy}{dt} - 3y = -4e^{-t}$$

 and plot a few of the integral curves.

$$y(t) = e^{-t} + Ce^{3t}$$



# Limits at infinity

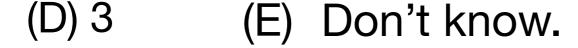
If y(t) is a particular solution to

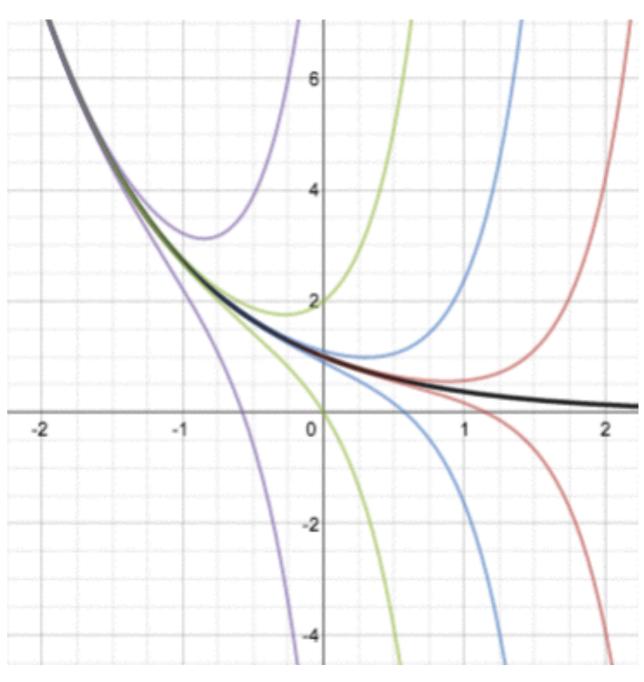
$$\frac{dy}{dt} - 3y = -4e^{-t}$$

 depending on C, how many different results are possible for

$$\lim_{t\to\infty}y(t) ?$$

- (A) 0
- (B) 1
- (C) 2





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