Today

- General solution for complex eigenvalues case.
- Shapes of solutions for complex eigenvalues case.

Calculating eigenvalues - trace/det shortcut

• For the general matrix

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

• find the characteristic equation and solve it to find the eigenvalues.

(A)
$$\lambda^2$$

(B) $\lambda^2 + (o + c)\lambda + \det(A) = 0$
(C) $\lambda^2 - (a + d)\lambda + ad - bc = 0$
(D) $\lambda^2 + (a - d)\lambda + ad + bc = 0$
(E) I don't know how to find eigenvalues.

- Find the general solution to $\mathbf{x}' = \begin{pmatrix} 1 & 1 \\ -4 & 1 \end{pmatrix} \mathbf{x}$.
 - The eigenvalues are

 \mathbf{A} (A) $\lambda = 1 \pm 2i$

• The eigenvectors are . . .

$$A - \lambda_1 I = \begin{pmatrix} 1 - (1+2i) & 1 \\ -4 & 1 - (1+2i) \end{pmatrix}$$

(B)
$$\lambda = -1, 3$$

(C) $\lambda = 2 \pm 4i$
(D) $\lambda = -2, 6$

$$= \begin{pmatrix} -2i & 1\\ -4 & -2i \end{pmatrix} \times \frac{1}{2}i$$

$$\sim \begin{pmatrix} -2i & 1\\ -2i & 1 \end{pmatrix}$$
 $\mathbf{v_1} = \begin{pmatrix} 1\\ 2i \end{pmatrix}$

(E) I don't know how to find eigenvalues.

$$\mathbf{v_2} = \begin{pmatrix} 1\\ -2i \end{pmatrix}$$

• We could just write down a (complex valued) general solution:

$$\mathbf{x}(\mathbf{t}) = C_1 e^{(1+2i)t} \begin{pmatrix} 1\\2i \end{pmatrix} + C_2 e^{(1-2i)t} \begin{pmatrix} 1\\-2i \end{pmatrix}$$

• But we want real valued solutions.

$$\mathbf{x}' = \begin{pmatrix} 1 & 1 \\ -4 & 1 \end{pmatrix} \mathbf{x} \qquad \Rightarrow \qquad \begin{aligned} x_1' &= x_1 + x_2 \\ x_2' &= -4x_1 + x_2 \\ x_1'' &= x_1' + x_2' \\ x_1'' &= x_1' - 4x_1 + x_2 \\ x_1'' &= x_1' - 4x_1 + x_1' - x_1 \end{aligned} \qquad \begin{aligned} r^2 - 2r + 5 &= \\ r &= 1 \pm 2i \\ x_1'' - 2x_1' + 5x_1 &= 0 \end{aligned}$$

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• But we want real valued solutions.

$$\mathbf{x}' = \begin{pmatrix} 1 & 1\\-4 & 1 \end{pmatrix} \mathbf{x} \implies \begin{aligned} x'_1 = x_1 + x_2 \\ x'_2 = -4x_1 + x_2 \end{aligned} \begin{pmatrix} 1\\2i \end{pmatrix} = \begin{pmatrix} 1\\0 \end{pmatrix} + \begin{pmatrix} 0\\2 \end{pmatrix}$$

$$x_1(t) = e^t (C_1 \cos(2t) + C_2 \sin(2t)) \\ x_2(t) = e^t (-2C_1 \sin(2t) + 2C_2 \cos(2t)) \\ \mathbf{x}(\mathbf{t}) = e^t \left(C_1 \left(\begin{pmatrix} 1\\0 \end{pmatrix} \cos(2t) - \begin{pmatrix} 0\\2 \end{pmatrix} \sin(2t) \right) \\ + C_2 \left(\begin{pmatrix} 1\\0 \end{pmatrix} \sin(2t) + \begin{pmatrix} 0\\2 \end{pmatrix} \cos(2t) \right) \right)$$

 Alternatively, multiply out the complex solution and extract real and imaginary parts:

$$\mathbf{x}(\mathbf{t}) = C_1 e^{(1+2i)t} \begin{pmatrix} 1\\2i \end{pmatrix} + C_2 e^{(1-2i)t} \begin{pmatrix} 1\\-2i \end{pmatrix}$$

• Simple case: $C_1 = 1, \ C_2 = 0$
 $\mathbf{i} \quad \mathbf{x}(\mathbf{t}) = e^{(1+2i)t} \begin{pmatrix} 1\\2i \end{pmatrix}$
 $= e^t (\cos(2t) + i\sin(2t)) \left(\begin{pmatrix} 1\\0 \end{pmatrix} + \begin{pmatrix} 0\\2 \end{pmatrix} i \right)$
 $= e^t \left[\begin{pmatrix} 1\\0 \end{pmatrix} \cos(2t) - \begin{pmatrix} 0\\2 \end{pmatrix} \sin(2t) \right]$
 $+ e^t \left[\begin{pmatrix} 1\\0 \end{pmatrix} \sin(2t) + \begin{pmatrix} 0\\2 \end{pmatrix} \cos(2t) \right] i$

Complex eigenvalues (7.6) - general case

- Find e-values, $\lambda = \alpha \pm \beta i$, and e-vectors, $\mathbf{v} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \pm i \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$. = **a**+ **b**
- Write down solution (or use method on previous slide for formula-free):

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[C_1 \left(\begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \cos(\beta t) - \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \sin(\beta t) \right) + C_2 \left(\begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \sin(\beta t) + \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \cos(\beta t) \right) \right]$$

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[C_1 \left(\mathbf{a} \cos(\beta t) - \mathbf{b} \sin(\beta t) \right) + C_2 \left(\mathbf{a} \sin(\beta t) + \mathbf{b} \cos(\beta t) \right) \right]$$

• Suppose you find eigenvalue $\lambda = 2\pi i$ and eigenvector $\mathbf{v} = \begin{pmatrix} 1 \\ i \end{pmatrix}$. Which of the following is a solution to the original equation?

$$\bigstar (A) \quad \mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

$$(B) \quad \mathbf{x}(\mathbf{t}) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t)$$

$$\bigstar (C) \quad \mathbf{x}(\mathbf{t}) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sin(2\pi t)$$

$$(D) \quad \mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sin(2\pi t)$$

• Suppose you find eigenvalue $\lambda = 2\pi i$ and eigenvector $\mathbf{v} = \begin{pmatrix} 1 \\ i \end{pmatrix}$. Which of the following is a solution to the original equation?

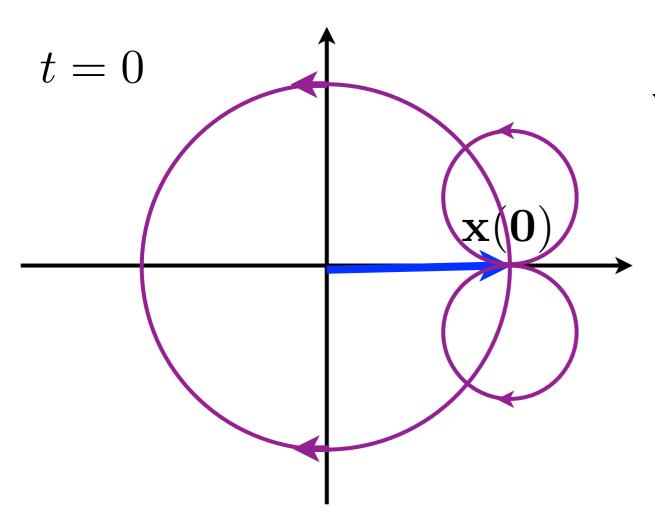
$$\begin{aligned} \bar{\mathbf{x}}(\mathbf{t}) &= e^{2\pi i t} \begin{pmatrix} 1\\ i \end{pmatrix} \\ &= \left(\cos(2\pi t) + i\sin(2\pi t)\right) \begin{pmatrix} 1\\ i \end{pmatrix} \\ &= \left(\frac{\cos(2\pi t) + i\sin(2\pi t)}{-\sin(2\pi t) + i\cos(2\pi t)} \right) \\ \text{nce} &= \left(\frac{1}{0} \cos(2\pi t) - \begin{pmatrix} 0\\ 1 \end{pmatrix} \sin(2\pi t) \\ &+ i \left[\begin{pmatrix} 0\\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1\\ 0 \end{pmatrix} \sin(2\pi t) \right] \end{aligned}$$

 Sum and difference trick lets us take the Real and Imaginary parts as two indep. solutions

• But what about $\lambda_2 = -2\pi i$ and $\mathbf{v_2} = \begin{pmatrix} 1 \\ -i \end{pmatrix}$?

$$\begin{aligned} \overline{\mathbf{x}}(\mathbf{t}) &= e^{-2\pi i t} \begin{pmatrix} 1\\ -i \end{pmatrix} \\ &= \left(\cos(-2\pi t) + i \sin(-2\pi t) \right) \begin{pmatrix} 1\\ -i \end{pmatrix} \\ &= \begin{pmatrix} \cos(2\pi t) - i \sin(2\pi t) \\ -\sin(2\pi t) - i \cos(2\pi t) \end{pmatrix} \\ &= \begin{bmatrix} 1\\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0\\ 1 \end{pmatrix} \sin(2\pi t) \\ &-i \begin{bmatrix} 0\\ 1 \end{pmatrix} \cos(2\pi t) + \begin{pmatrix} 1\\ 0 \end{pmatrix} \sin(2\pi t) \end{bmatrix} \end{aligned}$$

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1\\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0\\ 1 \end{pmatrix} \sin(2\pi t)$$



- What happens as t increases?
- \bigstar (A) The vector rotates clockwise.
 - (B) The vector rotates counterclockwise.
 - (C) The tip of the vector maps out a circle in the first quadrant.
 - (D) The tip of the vector maps out a circle in the fourth quadrant.

(E) Explain please.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1\\ 0 \end{pmatrix} \cos(2\pi t) - \begin{pmatrix} 0\\ 1 \end{pmatrix} \sin(2\pi t)$$
$$\mathbf{x}\left(\frac{1}{8}\right) = \begin{pmatrix} 1\\ 0 \end{pmatrix} \cos\left(\frac{\pi}{4}\right) - \begin{pmatrix} 0\\ 1 \end{pmatrix} \sin\left(\frac{\pi}{4}\right)$$
$$\mathbf{t} = \begin{pmatrix} 1\\ 0 \end{pmatrix} \frac{1}{\sqrt{2}} - \begin{pmatrix} 0\\ 1 \end{pmatrix} \frac{1}{\sqrt{2}}$$
$$= \begin{pmatrix} \frac{1}{\sqrt{2}}\\ -\frac{1}{\sqrt{2}} \end{pmatrix}$$

 $\mathbf{X}(\mathbf{0})$

• Same equation, initial condition chosen so that $C_1=0$ and $C_2=1$.

$$\mathbf{x}(\mathbf{t}) = \begin{pmatrix} 1\\ 0 \end{pmatrix} \sin(2\pi t) + \begin{pmatrix} 0\\ 1 \end{pmatrix} \cos(2\pi t)$$

• What happens as t increases?

 \bigstar (A) The vector rotates clockwise.

- (B) The vector rotates counterclockwise.
- (C) The tip of the vector maps out a circle in the first quadrant.
- "Same" solution as before, $\mu \approx \cos(\beta t) = \cos(\beta t)$ become under a cos (βt) a characteria second quadrant. $\pi/2$ delayed.

 $-C_2$ (Easiplaint)leaso. $\cos(\beta t))]$

t = 0

Complex eigenvalues (7.6) - general case

• Looking at the general solution again...

$$\mathbf{x}(\mathbf{t}) = e^{\alpha t} \left[C_1 \left(\mathbf{a} \cos(\beta t) - \mathbf{b} \sin(\beta t) \right) + C_2 \left(\mathbf{a} \sin(\beta t) + \mathbf{b} \cos(\beta t) \right) \right]$$

- Both parts rotate in the exact same way but the C₂ part is delayed by a quarter phase.
- If an initial condition lies neither parallel to vector a nor to vector b, C₁ and C2 allow for intermediate phases to be achieved.
- x(t) can be rewritten (using trig identities) as

$$\mathbf{x}(\mathbf{t}) = M e^{\alpha t} \left(\mathbf{a} \cos(\beta t - \phi) - \mathbf{b} \sin(\beta t - \phi) \right)$$

where M and ϕ are constants to replace C₁ and C₂.

• Back to our earlier example where we found the general solution

$$\mathbf{x}(\mathbf{t}) = e^t \left(C_1 \left(\begin{pmatrix} 1\\0 \end{pmatrix} \cos(2t) - \begin{pmatrix} 0\\2 \end{pmatrix} \sin(2t) \right) + C_2 \left(\begin{pmatrix} 1\\0 \end{pmatrix} \sin(2t) + \begin{pmatrix} 0\\2 \end{pmatrix} \cos(2t) \right) \right)$$

