

# Today

---

- The geometry of homogeneous and nonhomogeneous matrix equations
- Solving nonhomogeneous equations
  - Method of undetermined coefficients

## Second order, linear, constant coeff, **non**homogeneous (3.5)

---

- Our next goal is to figure out how to find solutions to nonhomogeneous equations like this one:

$$y'' - 6y' + 8y = \sin(2t)$$

- But first, a bit more on the connections between matrix algebra and differential equations . . .

# Some connections to linear (matrix) algebra

---

- An  $m \times n$  matrix is a gizmo that takes an  $n$ -vector and returns an  $m$ -vector:

$$\bar{y} = A\bar{x}$$

# Some connections to linear (matrix) algebra

---

- An  $m \times n$  matrix is a gizmo that takes an  $n$ -vector and returns an  $m$ -vector:

$$\bar{y} = A\bar{x}$$

- It is called a **linear operator** because it has the following properties:

$$A(c\bar{x}) = cA\bar{x}$$

$$A(\bar{x} + \bar{y}) = A\bar{x} + A\bar{y}$$

# Some connections to linear (matrix) algebra

---

- An  $m \times n$  matrix is a gizmo that takes an  $n$ -vector and returns an  $m$ -vector:

$$\bar{y} = A\bar{x}$$

- It is called a **linear operator** because it has the following properties:

$$A(c\bar{x}) = cA\bar{x}$$

$$A(\bar{x} + \bar{y}) = A\bar{x} + A\bar{y}$$

- Not all operators work on vectors. Derivative operators take a function and return a new function. For example,

$$z = L[y] = \frac{d^2 y}{dt^2} - 2\frac{dy}{dt} + y$$

# Some connections to linear (matrix) algebra

---

- An  $m \times n$  matrix is a gizmo that takes an  $n$ -vector and returns an  $m$ -vector:

$$\bar{y} = A\bar{x}$$

- It is called a **linear operator** because it has the following properties:

$$A(c\bar{x}) = cA\bar{x}$$

$$A(\bar{x} + \bar{y}) = A\bar{x} + A\bar{y}$$

- Not all operators work on vectors. Derivative operators take a function and return a new function. For example,

$$z = L[y] = \frac{d^2 y}{dt^2} - 2\frac{dy}{dt} + y$$

- This one is linear because

$$L[cy] = cL[y]$$

$$L[y + z] = L[y] + L[z]$$

Note:  $y, z$  are functions of  $t$  and  $c$  is a constant.

# Some connections to linear (matrix) algebra

---

- A homogeneous matrix equation has the form

$$A\bar{x} = \bar{0}$$

# Some connections to linear (matrix) algebra

---

- A homogeneous matrix equation has the form

$$A\bar{x} = \bar{0}$$

- A non-homogeneous matrix equation has the form

$$A\bar{x} = \bar{b}$$



# Some connections to linear (matrix) algebra

---

- A homogeneous matrix equation has the form

$$A\bar{x} = \bar{0}$$

- A non-homogeneous matrix equation has the form

$$A\bar{x} = \bar{b}$$

- A homogeneous differential equation has the form

$$L[y] = 0$$

# Some connections to linear (matrix) algebra

---

- A homogeneous matrix equation has the form

$$A\bar{x} = \bar{0}$$

- A non-homogeneous matrix equation has the form

$$A\bar{x} = \bar{b}$$

- A homogeneous differential equation has the form

$$L[y] = 0$$

- A non-homogeneous differential equation has the form

$$L[y] = g(t)$$

# Solutions to homogeneous matrix equations

---

- The matrix equation  $A\bar{x} = \bar{0}$  could have (depending on A)
  - (A) no solutions.
  - (B) exactly one solution.
  - (C) a one-parameter family of solutions.
  - (D) an n-parameter family of solutions.

Choose the answer that is **incorrect**.

# Solutions to homogeneous matrix equations

---

- The matrix equation  $A\bar{x} = \bar{0}$  could have (depending on A)

★ (A) no solutions.

(B) exactly one solution.

(C) a one-parameter family of solutions.

(D) an n-parameter family of solutions.

Choose the answer that is **incorrect**.

# Solutions to homogeneous matrix equations

---

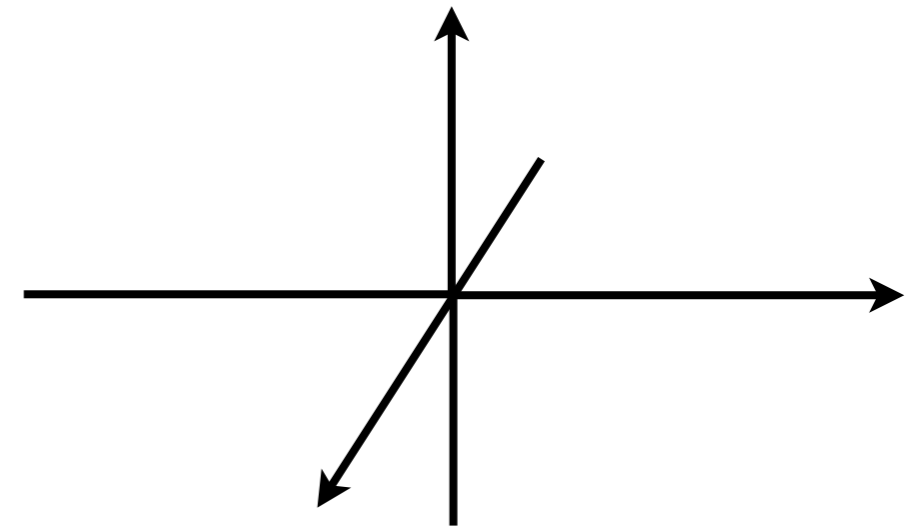
- The matrix equation  $A\bar{x} = \bar{0}$  could have (depending on A)

★ (A) no solutions.

(B) exactly one solution.

(C) a one-parameter family of solutions.

(D) an n-parameter family of solutions.



Possibilities:

Choose the answer that is **incorrect**.

# Solutions to homogeneous matrix equations

---

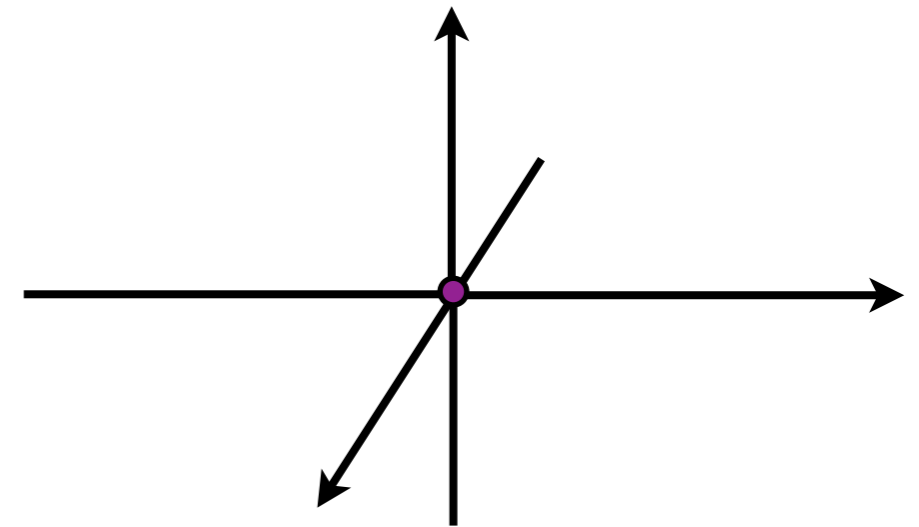
- The matrix equation  $A\bar{x} = \bar{0}$  could have (depending on  $A$ )

★ (A) no solutions.

→ (B) exactly one solution.

(C) a one-parameter family of solutions.

(D) an n-parameter family of solutions.



Possibilities:

$$\bar{x} = \bar{0}$$

Choose the answer that is **incorrect**.

# Solutions to homogeneous matrix equations

---

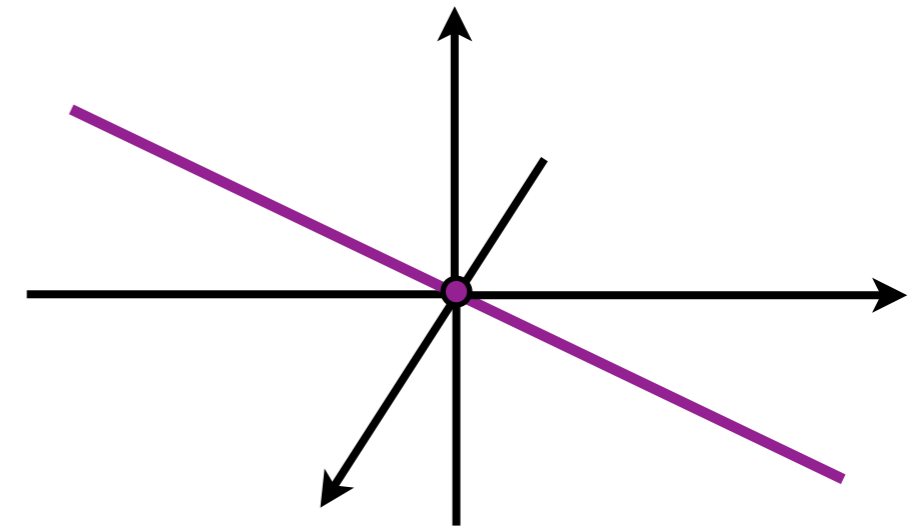
- The matrix equation  $A\bar{x} = \bar{0}$  could have (depending on A)

★ (A) no solutions.

(B) exactly one solution.

➔ (C) a one-parameter family of solutions.

(D) an n-parameter family of solutions.



Possibilities:

$$\bar{x} = C \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

Choose the answer that is **incorrect**.

# Solutions to homogeneous matrix equations

---

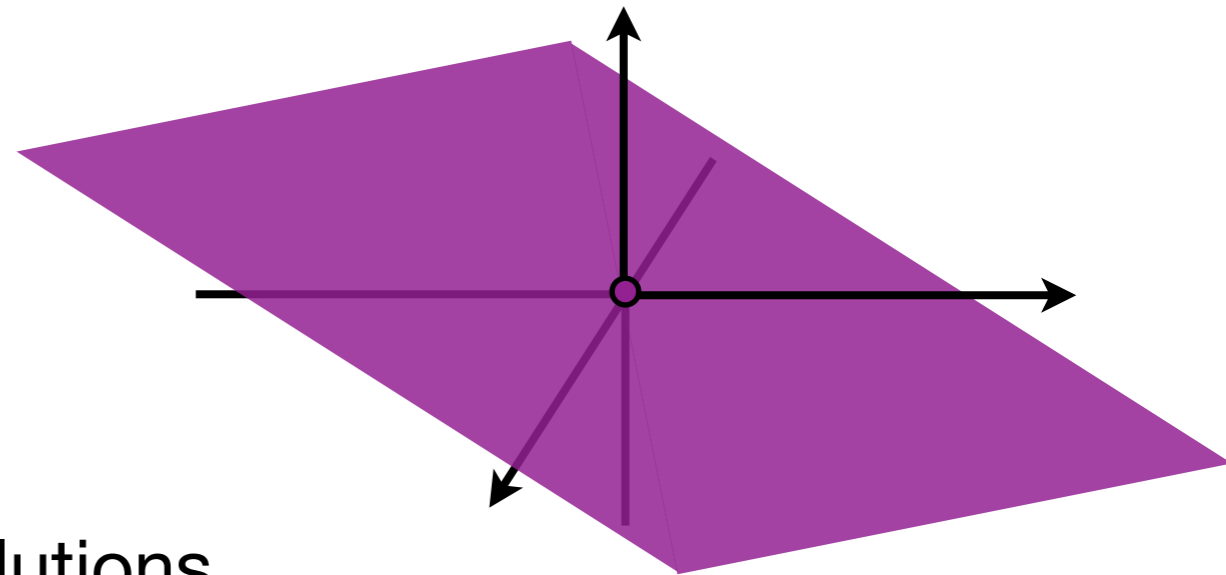
- The matrix equation  $A\bar{x} = \bar{0}$  could have (depending on A)

★ (A) no solutions.

(B) exactly one solution.

(C) a one-parameter family of solutions.

➔ (D) an n-parameter family of solutions.



Possibilities:

$$\bar{x} = C_1 \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} + C_2 \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix}$$

Choose the answer that is **incorrect**.



# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix}$$

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix}$$

Each equation describes a plane.

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix}$$

Each equation describes a plane.

- Row reduction gives

$$A \sim \begin{pmatrix} 1 & 0 & -1/3 \\ 0 & 1 & 5/3 \\ 0 & 0 & 0 \end{pmatrix}$$

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix}$$

Each equation describes a plane.

- Row reduction gives

$$A \sim \begin{pmatrix} 1 & 0 & -1/3 \\ 0 & 1 & 5/3 \\ 0 & 0 & 0 \end{pmatrix}$$

In this case, only two of them really matter.

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix}$$

Each equation describes a plane.

- Row reduction gives

$$A \sim \begin{pmatrix} 1 & 0 & -1/3 \\ 0 & 1 & 5/3 \\ 0 & 0 & 0 \end{pmatrix}$$

In this case, only two of them really matter.

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever (because it doesn't have a leading one).

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$ .

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever.

- Thus, the solution can be written as

.

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$ .

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3$$

- Thus, the solution can be written as

.

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$ .

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3$$

$$x_2 = -\frac{5}{3}x_3$$

- Thus, the solution can be written as .



# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$ .

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3$$

$$x_2 = -\frac{5}{3}x_3$$

$$x_3 = C$$

- Thus, the solution can be written as

.

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$ .

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3 \qquad x_1 = \frac{1}{3}C$$

$$x_2 = -\frac{5}{3}x_3$$

$$x_3 = C$$

- Thus, the solution can be written as

.

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$ .

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3$$

$$x_1 = \frac{1}{3}C$$

$$x_2 = -\frac{5}{3}x_3$$

$$x_2 = -\frac{5}{3}C$$

$$x_3 = C$$

- Thus, the solution can be written as

.

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$ .

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3$$

$$x_1 = \frac{1}{3}C$$

$$x_2 = -\frac{5}{3}x_3$$

$$x_2 = -\frac{5}{3}C$$

$$x_3 = C$$

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$ .

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3$$

$$x_1 = \frac{1}{3}C$$

$$x_2 = -\frac{5}{3}x_3$$

$$x_2 = -\frac{5}{3}C$$

$$x_3 = C$$

- Thus, the solution can be written as  $\bar{x} = \frac{C}{3} \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix}$ .

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$ .

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3$$

$$x_1 = \frac{1}{3}C$$

$$x_2 = -\frac{5}{3}x_3$$

$$x_2 = -\frac{5}{3}C$$

$$x_3 = C$$

- Thus, the solution can be written as  $\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix}$ .

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$ .

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever.

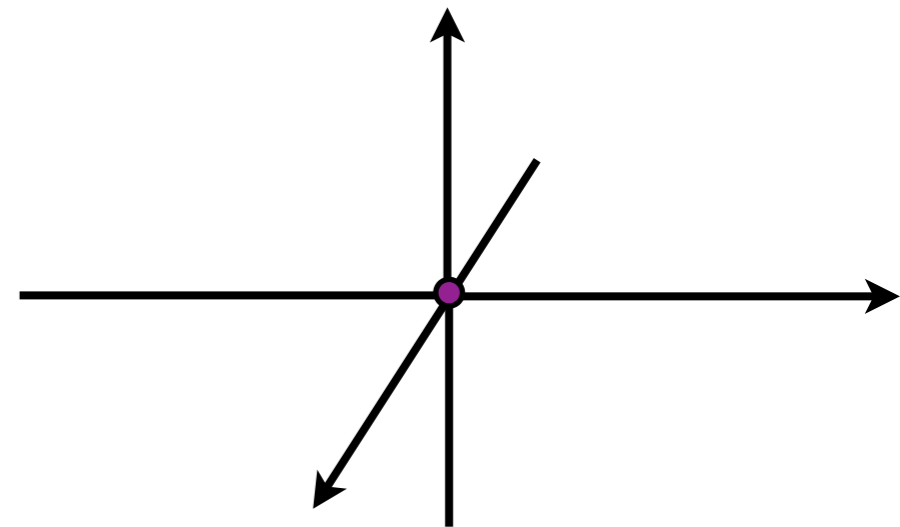
$$x_1 = \frac{1}{3}x_3$$

$$x_1 = \frac{1}{3}C$$

$$x_2 = -\frac{5}{3}x_3$$

$$x_2 = -\frac{5}{3}C$$

$$x_3 = C$$



- Thus, the solution can be written as  $\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix}$ .

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$ .

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever.

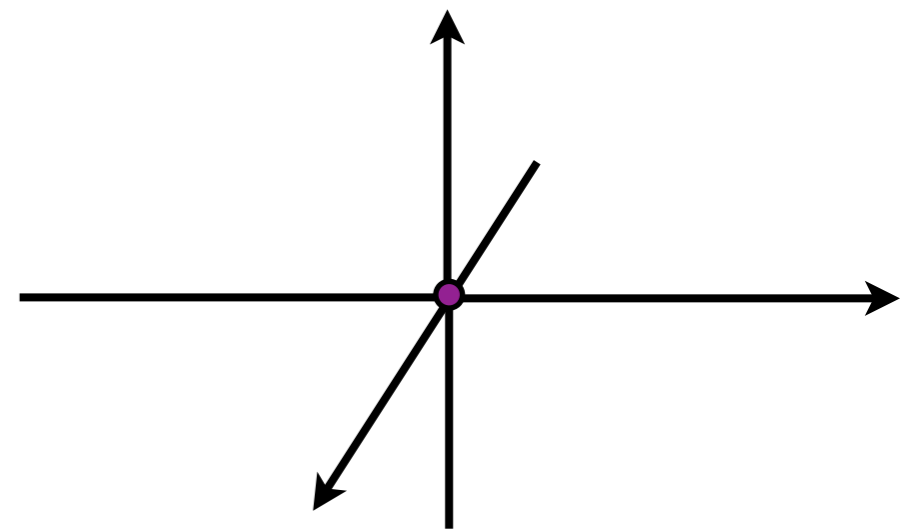
$$x_1 = \frac{1}{3}x_3$$

$$x_1 = \frac{1}{3}C$$

$$x_2 = -\frac{5}{3}x_3$$

$$x_2 = -\frac{5}{3}C$$

$$x_3 = C$$



- Thus, the solution can be written as  $\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix}$ .



# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$ .

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever.

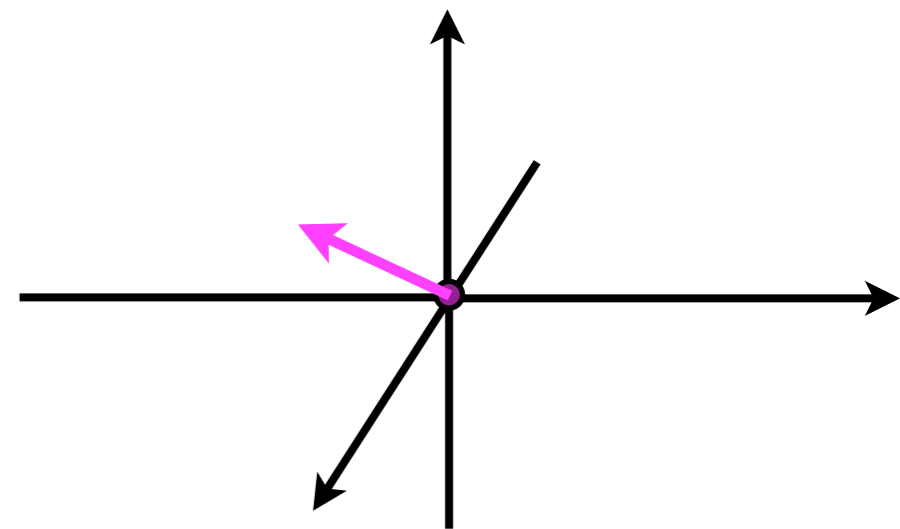
$$x_1 = \frac{1}{3}x_3$$

$$x_1 = \frac{1}{3}C$$

$$x_2 = -\frac{5}{3}x_3$$

$$x_2 = -\frac{5}{3}C$$

$$x_3 = C$$



- Thus, the solution can be written as  $\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix}$ .

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$ .

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever.

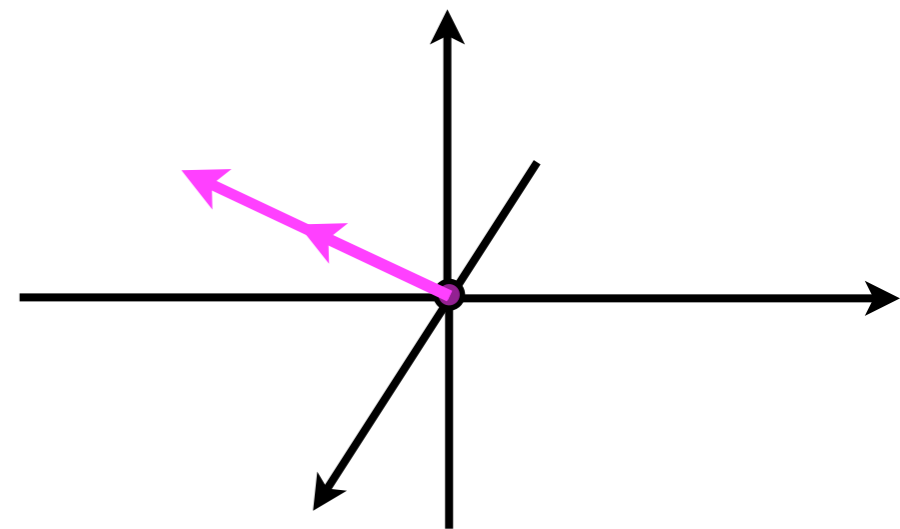
$$x_1 = \frac{1}{3}x_3$$

$$x_1 = \frac{1}{3}C$$

$$x_2 = -\frac{5}{3}x_3$$

$$x_2 = -\frac{5}{3}C$$

$$x_3 = C$$



- Thus, the solution can be written as  $\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix}$ .

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$ .

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever.

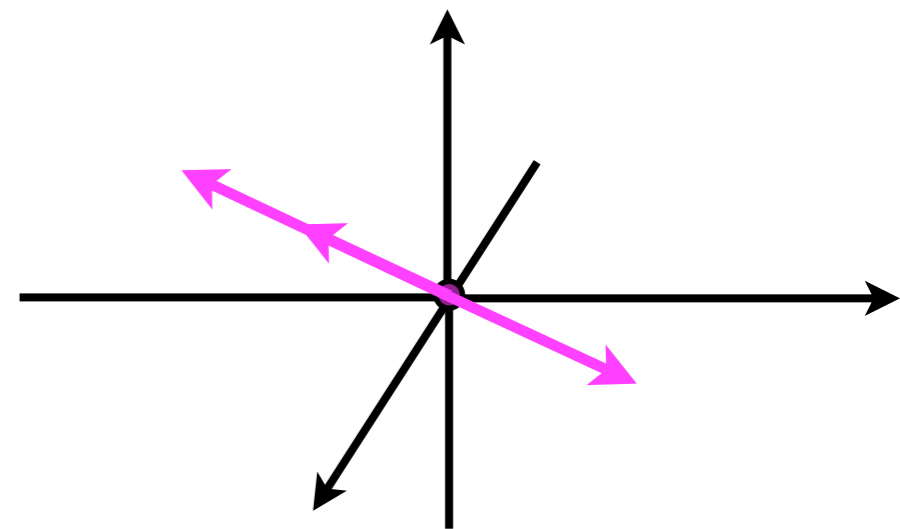
$$x_1 = \frac{1}{3}x_3$$

$$x_1 = \frac{1}{3}C$$

$$x_2 = -\frac{5}{3}x_3$$

$$x_2 = -\frac{5}{3}C$$

$$x_3 = C$$



- Thus, the solution can be written as  $\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix}$ .

# Solutions to homogeneous matrix equations

---

- **Example 1.** Solve the equation  $A\bar{x} = \bar{0}$ .

- so  $x_1 - \frac{1}{3}x_3 = 0$  and  $x_2 + \frac{5}{3}x_3 = 0$  and  $x_3$  can be whatever.

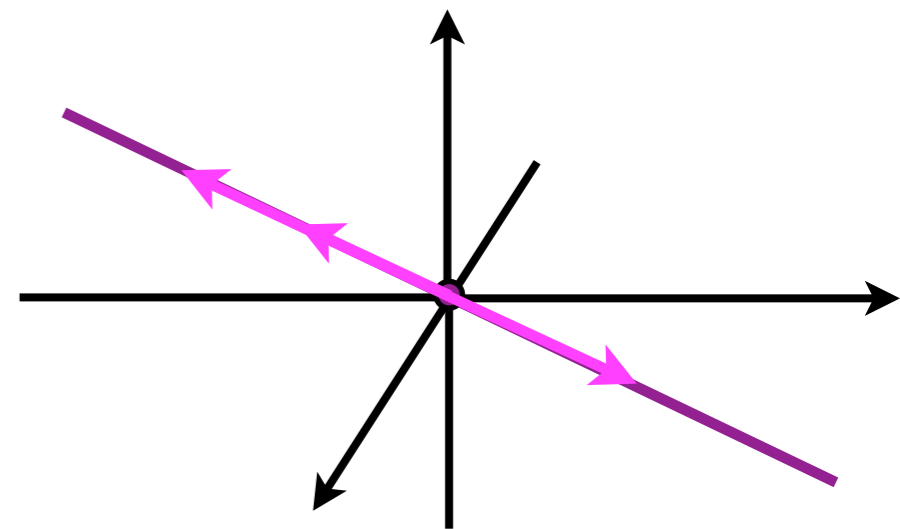
$$x_1 = \frac{1}{3}x_3$$

$$x_1 = \frac{1}{3}C$$

$$x_2 = -\frac{5}{3}x_3$$

$$x_2 = -\frac{5}{3}C$$

$$x_3 = C$$



- Thus, the solution can be written as  $\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix}$ .

# Solutions to homogeneous matrix equations

---

- **Example 2.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \\ -1 & 2 & -1 \end{pmatrix}$$

# Solutions to homogeneous matrix equations

---

- **Example 2.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \\ -1 & 2 & -1 \end{pmatrix}$$

# Solutions to homogeneous matrix equations

---

- **Example 2.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \\ -1 & 2 & -1 \end{pmatrix}$$

- Row reduction gives

$$A \sim \begin{pmatrix} 1 & -2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

# Solutions to homogeneous matrix equations

---

- **Example 2.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \\ -1 & 2 & -1 \end{pmatrix}$$

- Row reduction gives

$$A \sim \begin{pmatrix} 1 & -2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

- so  $x_1 - 2x_2 + x_3 = 0$  and both  $x_2$  and  $x_3$  can be whatever.



# Solutions to homogeneous matrix equations

---

- **Example 2.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \\ -1 & 2 & -1 \end{pmatrix}$$

- Row reduction gives

$$A \sim \begin{pmatrix} 1 & -2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

- so  $x_1 - 2x_2 + x_3 = 0$  and both  $x_2$  and  $x_3$  can be whatever.

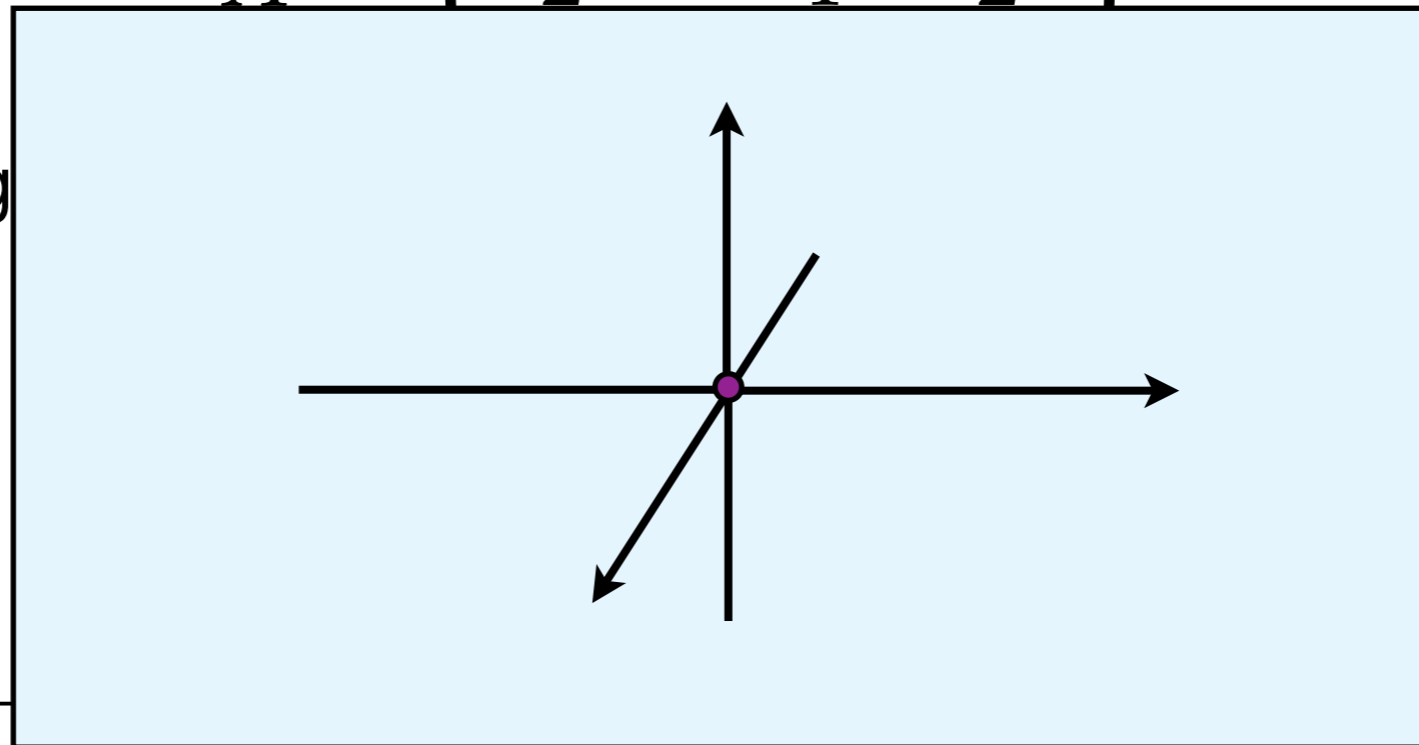
$$\bar{x} = C_1 \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + C_2 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

# Solutions to homogeneous matrix equations

- **Example 2.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \end{pmatrix}$$

- Row reduction gives



- so  $x_1 = 2x_2 +$  whatever.

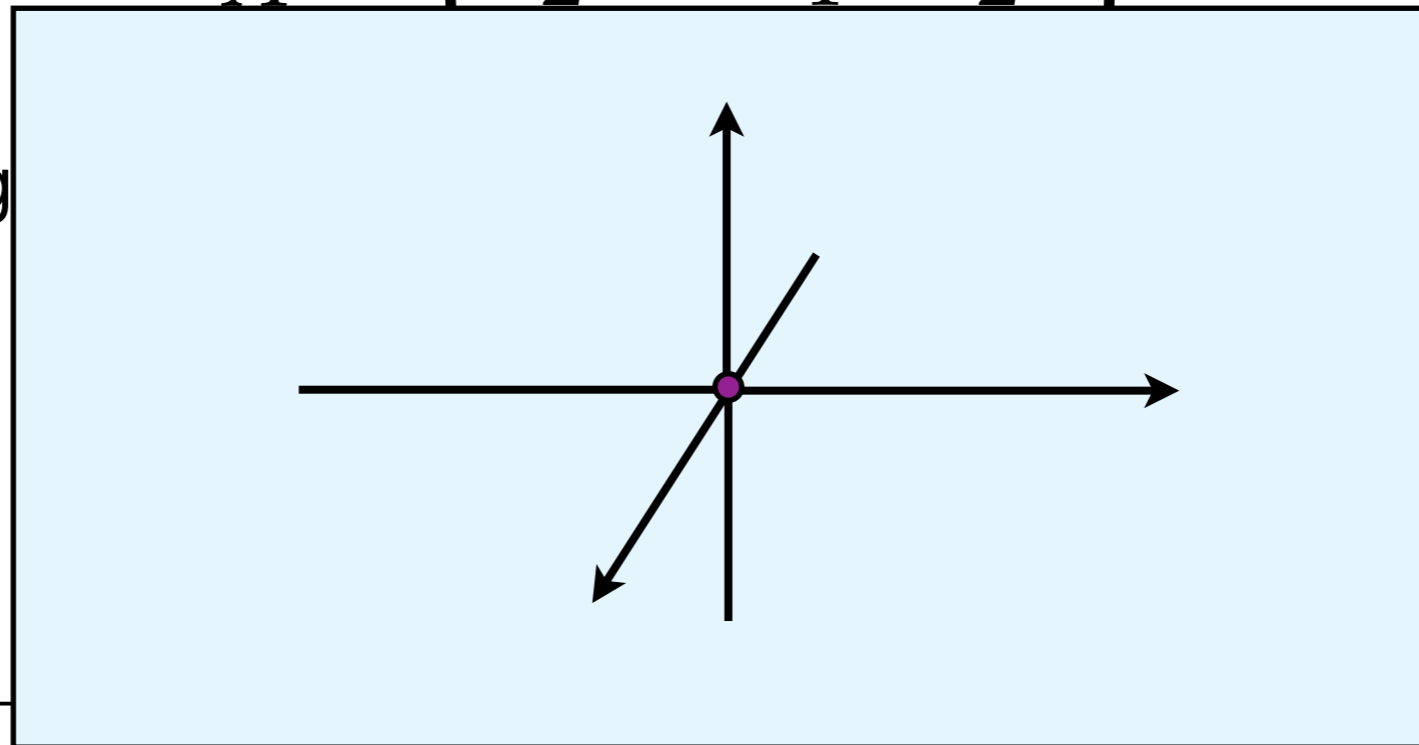
$$\bar{x} = C_1 \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + C_2 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

# Solutions to homogeneous matrix equations

- **Example 2.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \end{pmatrix}$$

- Row reduction gives



- so  $x_1 - 2x_2 + 0x_3 = 0$  and  $2x_1 - 4x_2 + 2x_3 = 0$  for whatever.

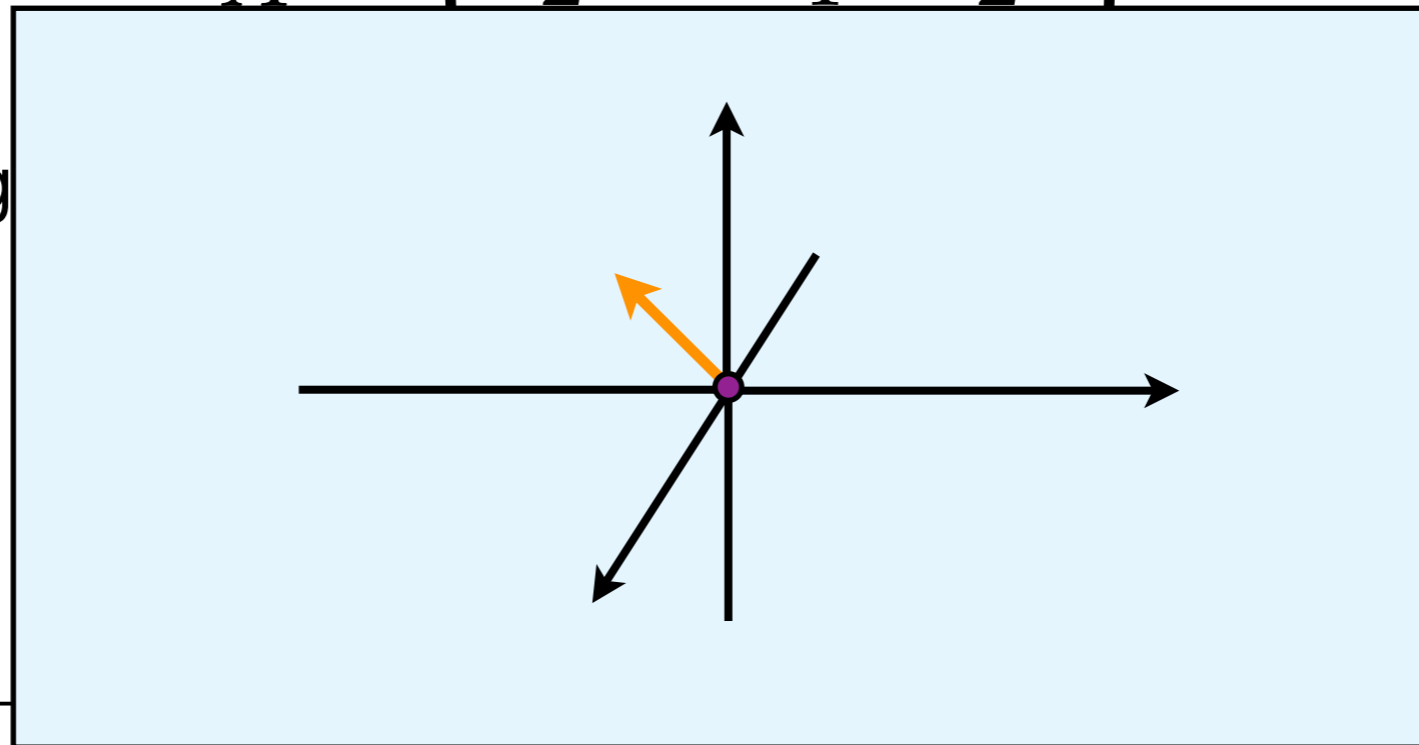
$$\bar{x} = C_1 \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + C_2 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

# Solutions to homogeneous matrix equations

- **Example 2.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \end{pmatrix}$$

- Row reduction gives



- so  $x_1 - 2x_2 +$  whatever.

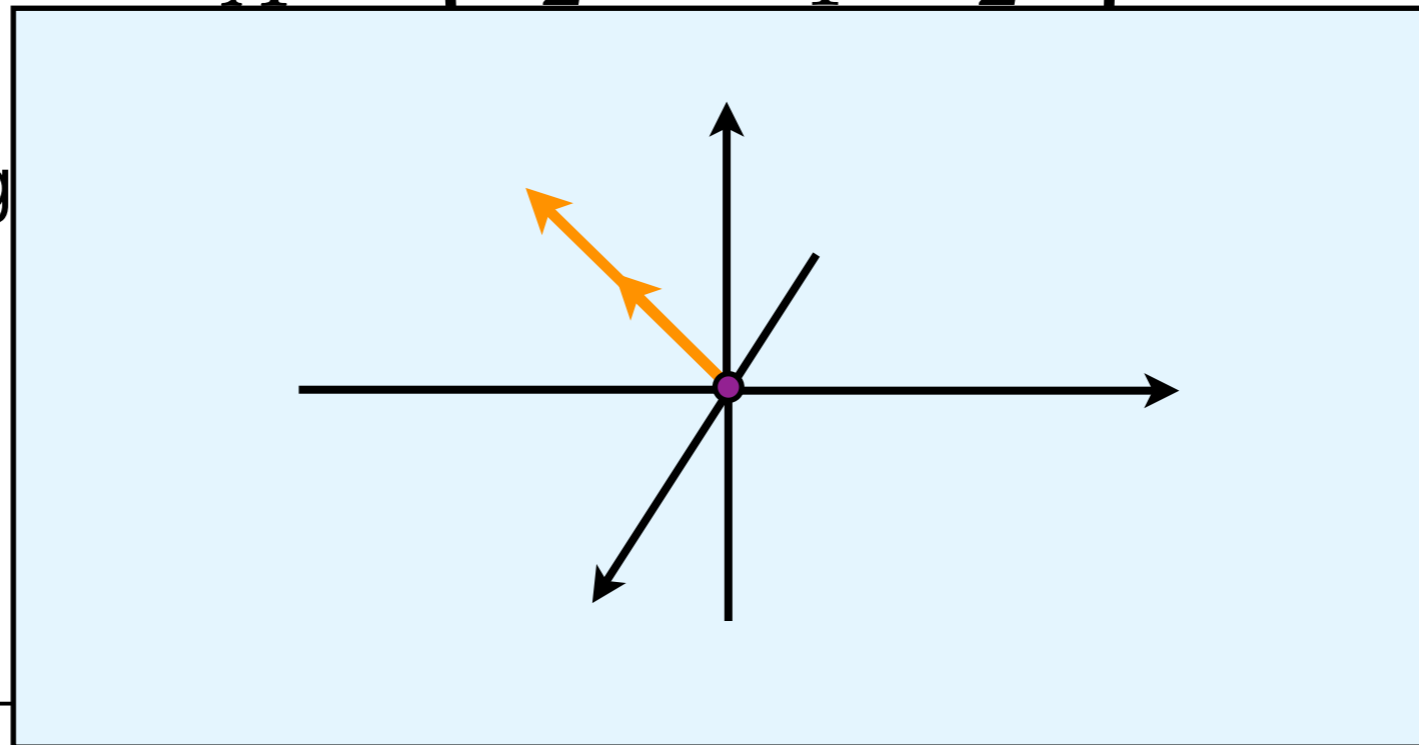
$$\bar{x} = C_1 \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + C_2 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

# Solutions to homogeneous matrix equations

- **Example 2.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \end{pmatrix}$$

- Row reduction gives



- so  $x_1 - 2x_2 +$  whatever.

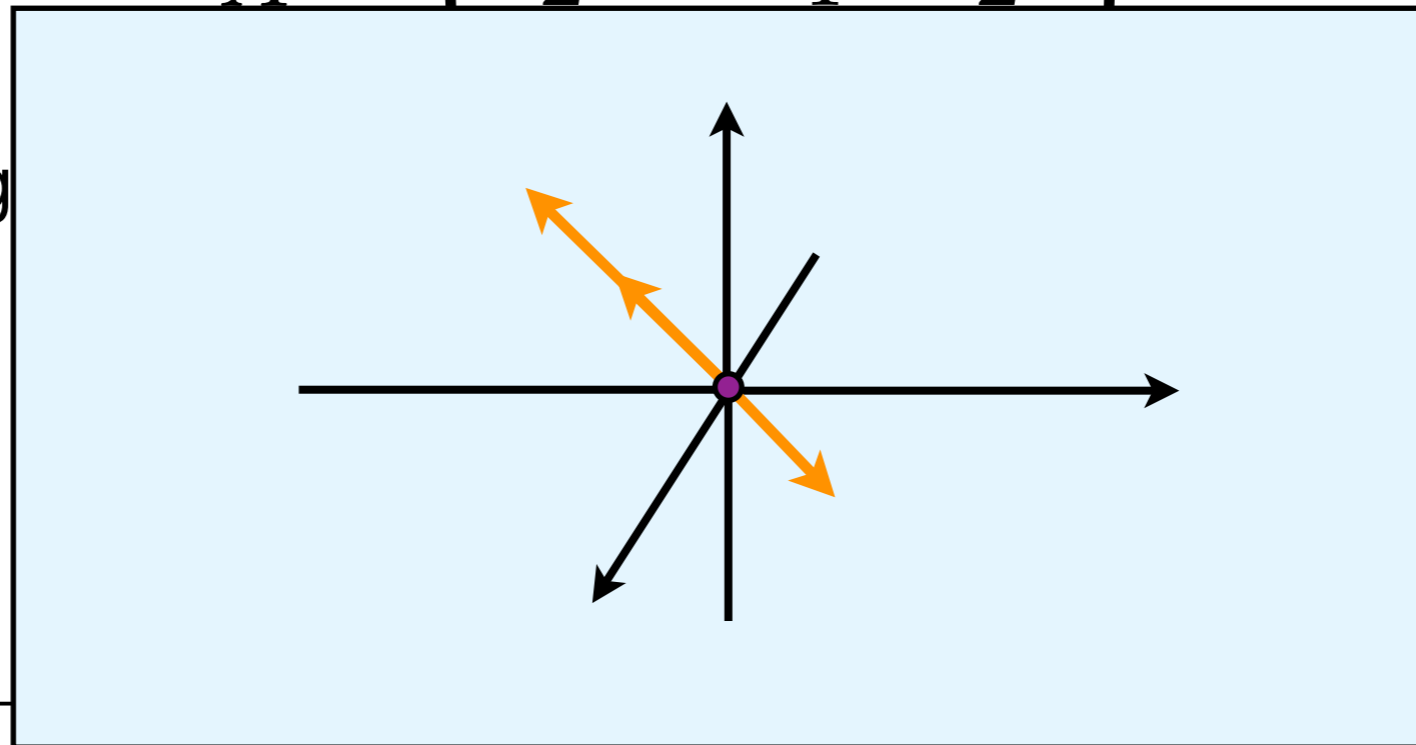
$$\bar{x} = C_1 \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + C_2 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

# Solutions to homogeneous matrix equations

- **Example 2.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \end{pmatrix}$$

- Row reduction gives



- so  $x_1 - 2x_2 + 0x_3 = 0$  for whatever.

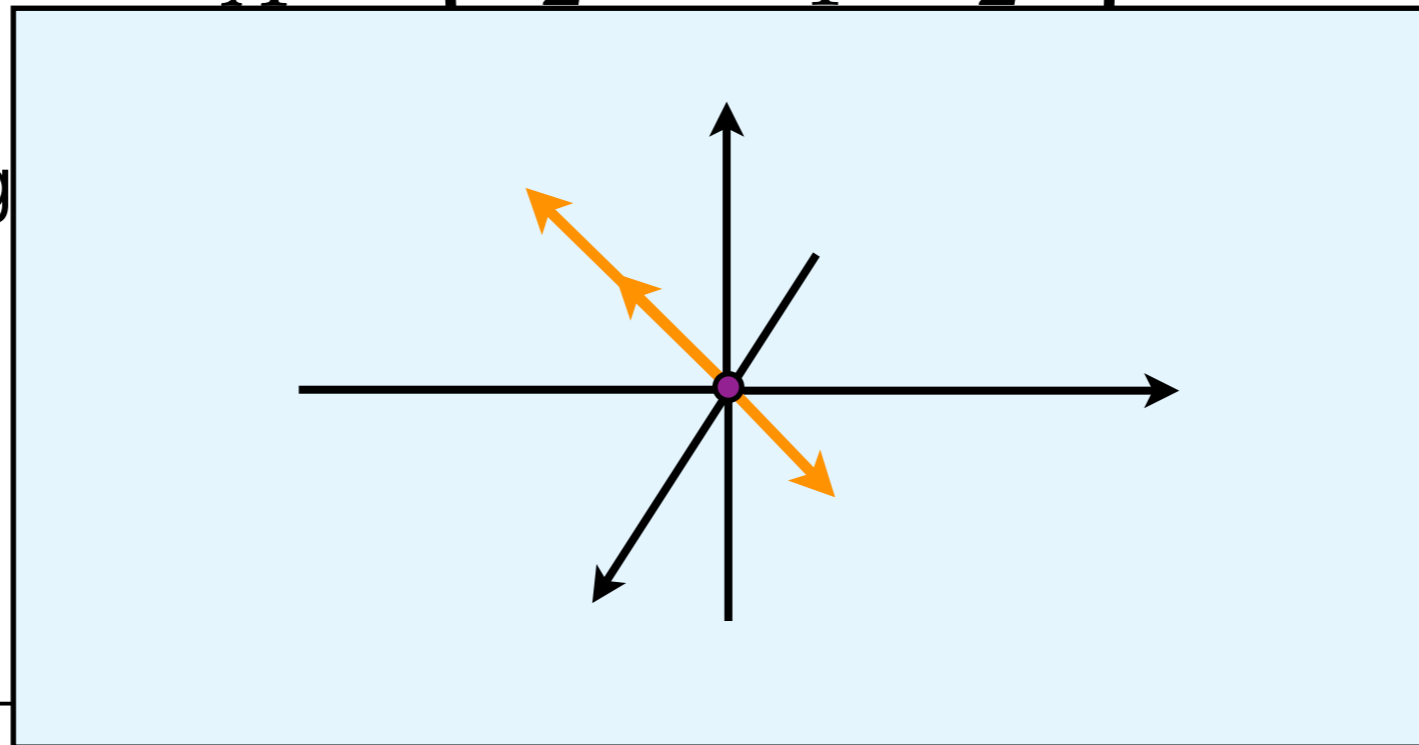
$$\bar{x} = C_1 \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + C_2 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

# Solutions to homogeneous matrix equations

- **Example 2.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \end{pmatrix}$$

- Row reduction gives



- so  $x_1 - 2x_2 + x_3 = 0$  whatever.

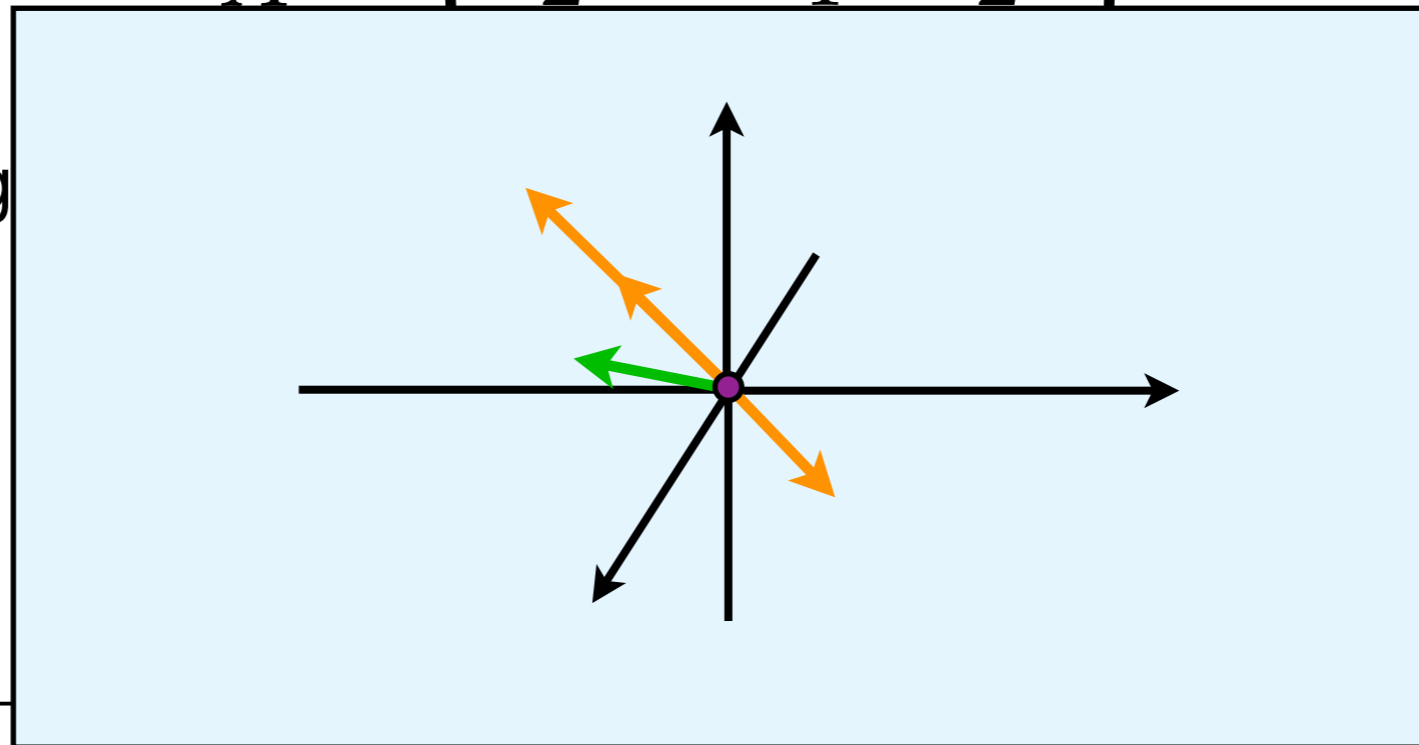
$$\bar{x} = C_1 \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + C_2 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

# Solutions to homogeneous matrix equations

- **Example 2.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \end{pmatrix}$$

- Row reduction gives



- so  $x_1 - 2x_2 + x_3 = 0$  whatever.

$$\bar{x} = C_1 \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + C_2 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

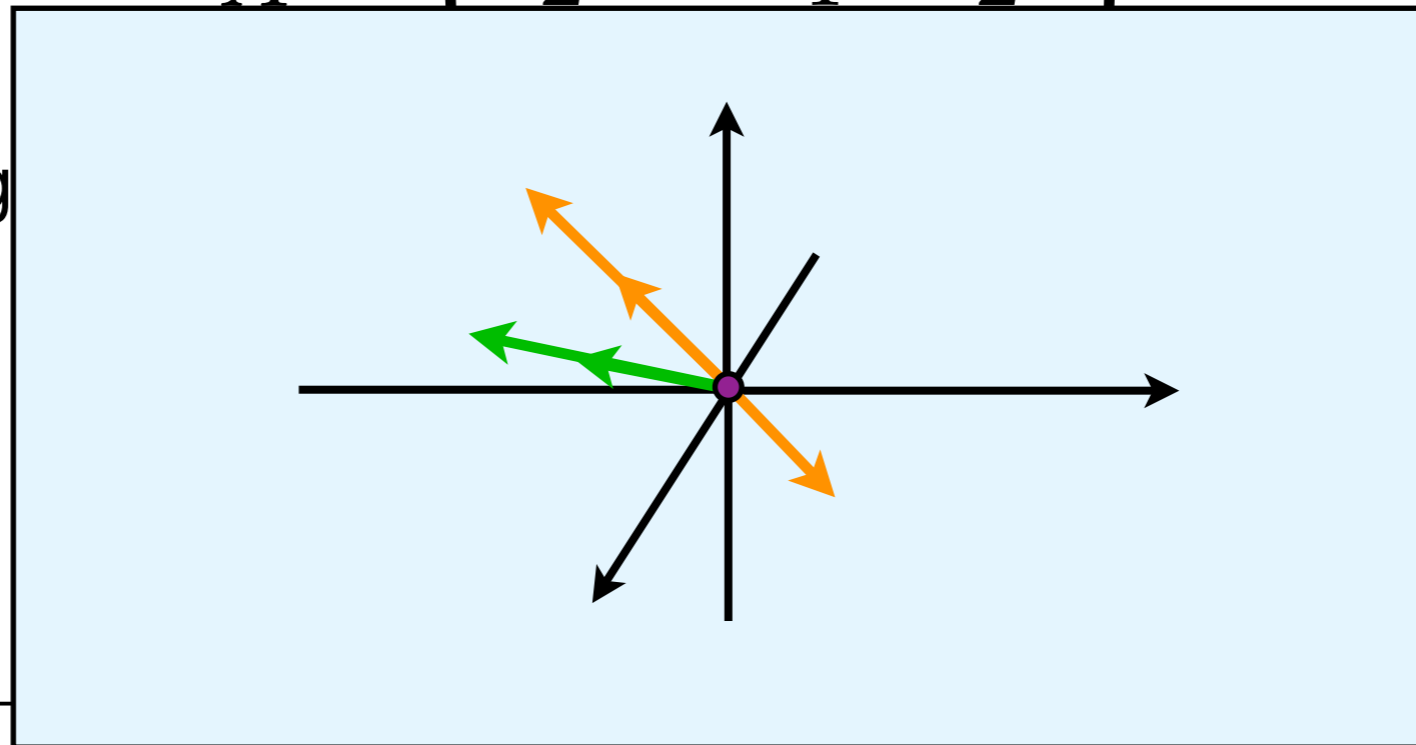


# Solutions to homogeneous matrix equations

- **Example 2.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \end{pmatrix}$$

- Row reduction gives



- so  $x_1 - 2x_2 + x_3 = 0$  whatever.

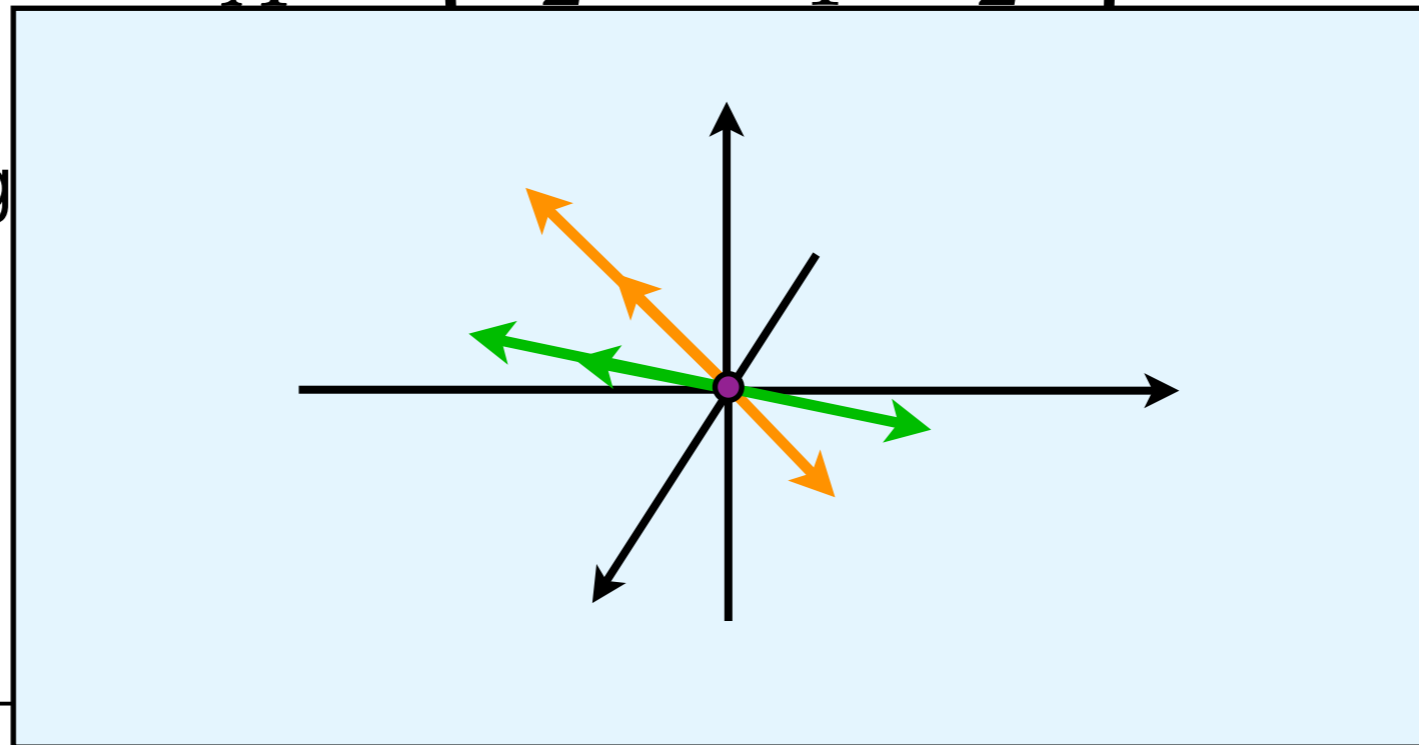
$$\bar{x} = C_1 \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + C_2 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

# Solutions to homogeneous matrix equations

- **Example 2.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \end{pmatrix}$$

- Row reduction gives



- so  $x_1 - 2x_2 + x_3 = 0$  whatever.

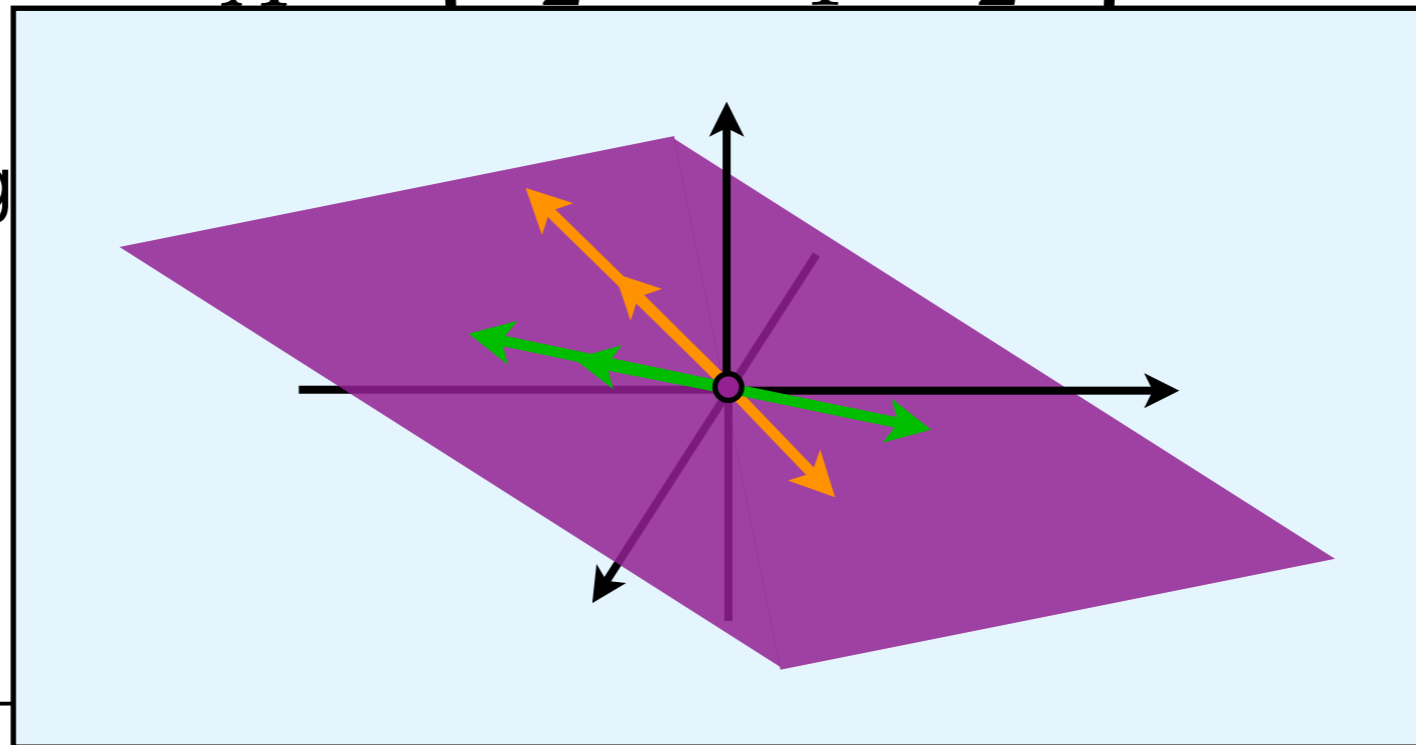
$$\bar{x} = C_1 \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + C_2 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

# Solutions to homogeneous matrix equations

- **Example 2.** Solve the equation  $A\bar{x} = \bar{0}$  where

$$A = \begin{pmatrix} 1 & -2 & 1 \\ 2 & -4 & 2 \end{pmatrix}$$

- Row reduction gives



- so  $x_1 - 2x_2 +$

whatever.

$$\bar{x} = C_1 \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + C_2 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

# Solutions to non-homogeneous matrix equations

---

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$  where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix} \quad \text{and} \quad \bar{b} = \begin{pmatrix} 2 \\ 0 \\ 2 \end{pmatrix} .$$

# Solutions to non-homogeneous matrix equations

---

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$  where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix} \quad \text{and} \quad \bar{b} = \begin{pmatrix} 2 \\ 0 \\ 2 \end{pmatrix}.$$

- Row reduction gives

$$\left( \begin{array}{ccc|c} 1 & 0 & -1/3 & 2/3 \\ 0 & 1 & 5/3 & 2/3 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

# Solutions to non-homogeneous matrix equations

---

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$  where

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & -2 \\ 2 & 1 & 1 \end{pmatrix} \quad \text{and} \quad \bar{b} = \begin{pmatrix} 2 \\ 0 \\ 2 \end{pmatrix}.$$

- Row reduction gives

$$\left( \begin{array}{ccc|c} 1 & 0 & -1/3 & 2/3 \\ 0 & 1 & 5/3 & 2/3 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

- so  $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$  and  $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$  and  $x_3$  can be whatever.

# Solutions to non-homogeneous matrix equations

---

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$ .
- so  $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$  and  $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$  and  $x_3$  can be whatever.

# Solutions to non-homogeneous matrix equations

---

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$ .
- so  $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$  and  $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3}$$



# Solutions to non-homogeneous matrix equations

---

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$ .
- so  $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$  and  $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$  and  $x_3$  can be whatever.  
$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \quad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$$

# Solutions to non-homogeneous matrix equations

---

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$ .

- so  $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$  and  $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \quad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$$

$$\bar{x} = \frac{C}{3} \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$$

# Solutions to non-homogeneous matrix equations

---

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$ .

- so  $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$  and  $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \quad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$$

$$\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$$

# Solutions to non-homogeneous matrix equations

---

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$ .

- so  $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$  and  $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \quad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$$

$$\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$$

the general solution to  
the homogeneous  
problem

# Solutions to non-homogeneous matrix equations

---

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$ .

- so  $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$  and  $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \quad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$$

$$\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$$

the general solution to  
the homogeneous  
problem

one particular solution  
to nonhomogeneous  
problem

# Solutions to non-homogeneous matrix equations

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$ .

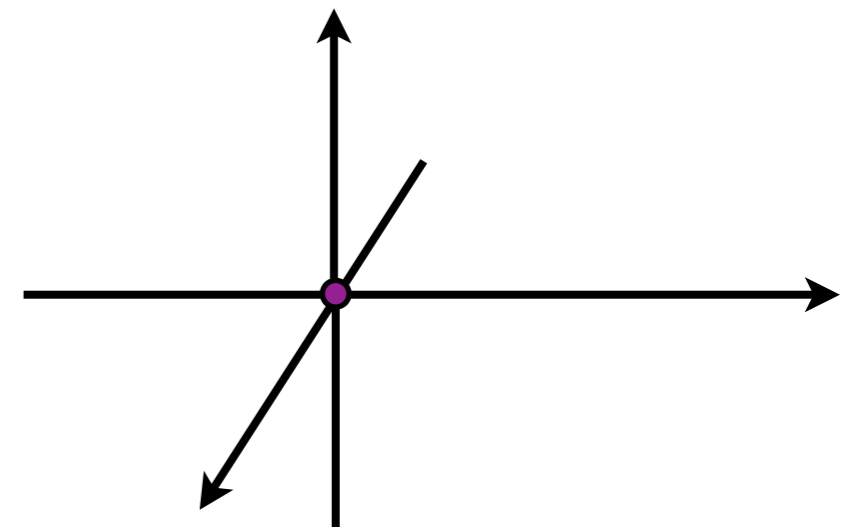
- so  $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$  and  $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \quad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$$

$$\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$$

the general solution to  
the homogeneous  
problem

one particular solution  
to nonhomogeneous  
problem



# Solutions to non-homogeneous matrix equations

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$ .

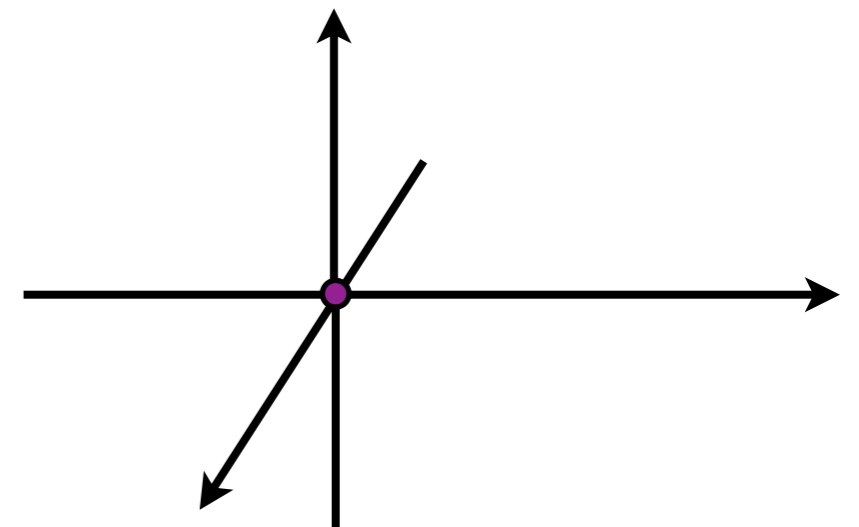
- so  $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$  and  $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \quad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$$

$$\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$$

the general solution to  
the homogeneous  
problem

one particular solution  
to nonhomogeneous  
problem



# Solutions to non-homogeneous matrix equations

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$ .

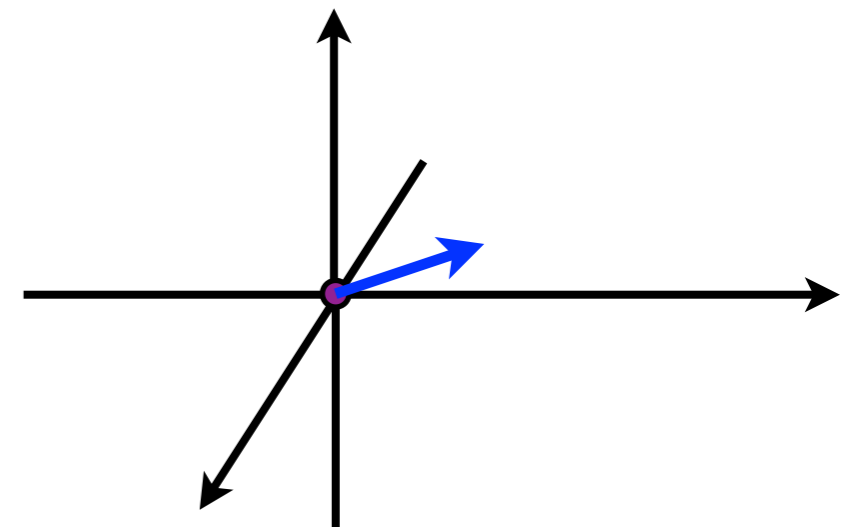
- so  $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$  and  $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \quad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$$

$$\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$$

the general solution to  
the homogeneous  
problem

one particular solution  
to nonhomogeneous  
problem





# Solutions to non-homogeneous matrix equations

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$ .

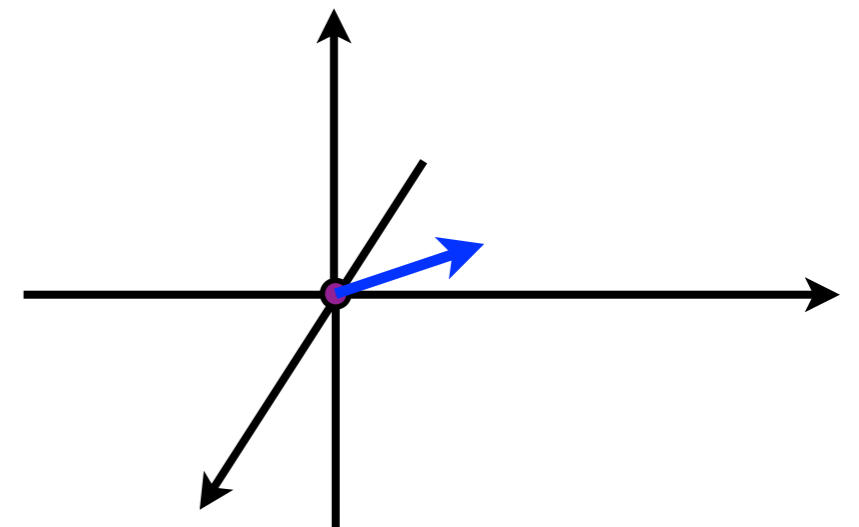
- so  $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$  and  $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \quad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$$

$$\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$$

the general solution to  
the homogeneous  
problem

one particular solution  
to nonhomogeneous  
problem



# Solutions to non-homogeneous matrix equations

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$ .

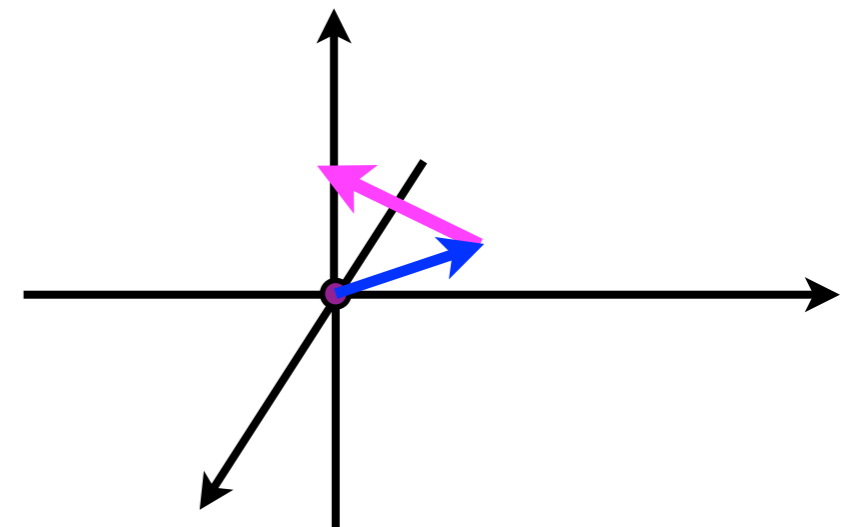
- so  $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$  and  $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \quad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$$

$$\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$$

the general solution to  
the homogeneous  
problem

one particular solution  
to nonhomogeneous  
problem



# Solutions to non-homogeneous matrix equations

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$ .

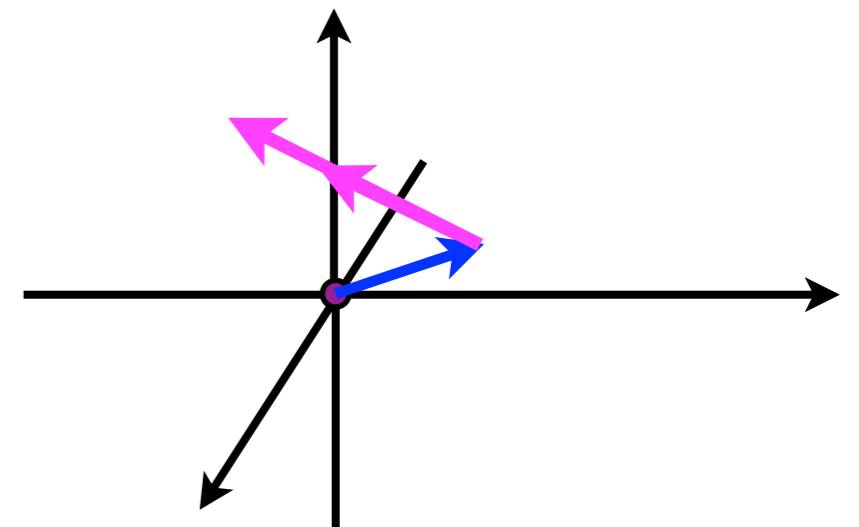
- so  $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$  and  $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \quad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$$

$$\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$$

the general solution to  
the homogeneous  
problem

one particular solution  
to nonhomogeneous  
problem



# Solutions to non-homogeneous matrix equations

- **Example 3.** Solve the equation  $A\bar{x} = \bar{b}$ .

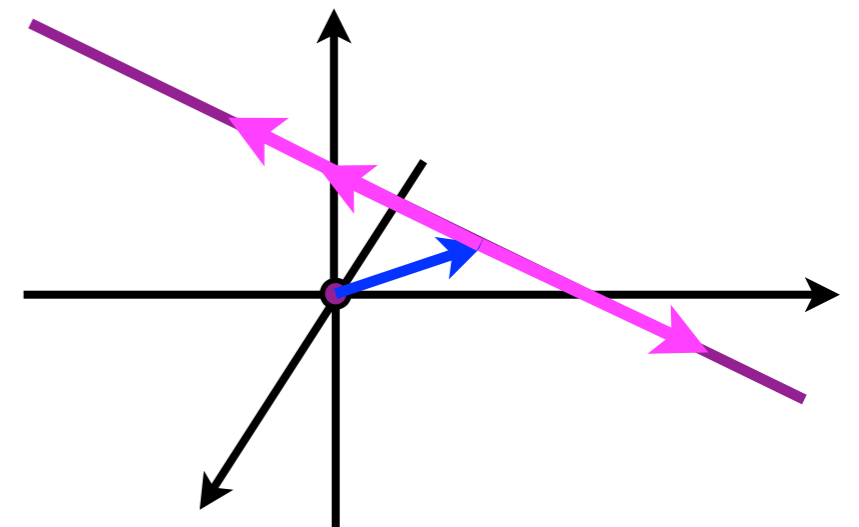
- so  $x_1 - \frac{1}{3}x_3 = \frac{2}{3}$  and  $x_2 + \frac{5}{3}x_3 = \frac{2}{3}$  and  $x_3$  can be whatever.

$$x_1 = \frac{1}{3}x_3 + \frac{2}{3} \quad x_2 = -\frac{5}{3}x_3 + \frac{2}{3}$$

$$\bar{x} = C' \begin{pmatrix} 1 \\ -5 \\ 3 \end{pmatrix} + \begin{pmatrix} 2/3 \\ 2/3 \\ 0 \end{pmatrix}$$

the general solution to  
the homogeneous  
problem

one particular solution  
to nonhomogeneous  
problem



# Solutions to nonhomogeneous differential equations

---

# Solutions to nonhomogeneous differential equations

---

- To solve a nonhomogeneous differential equation:

# Solutions to nonhomogeneous differential equations

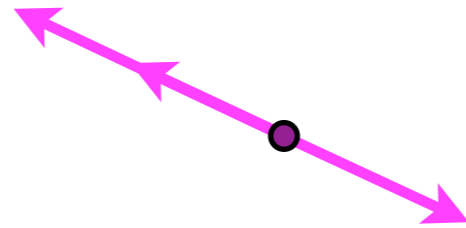
---

- To solve a nonhomogeneous differential equation:
  1. Find the general solution to the associated homogeneous problem,  $y_h(t)$ .

# Solutions to nonhomogeneous differential equations

---

- To solve a nonhomogeneous differential equation:
  1. Find the general solution to the associated homogeneous problem,  $y_h(t)$ .

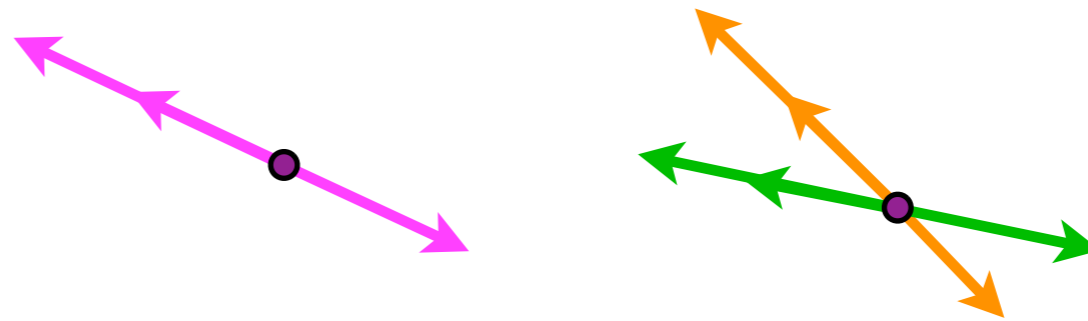




# Solutions to nonhomogeneous differential equations

---

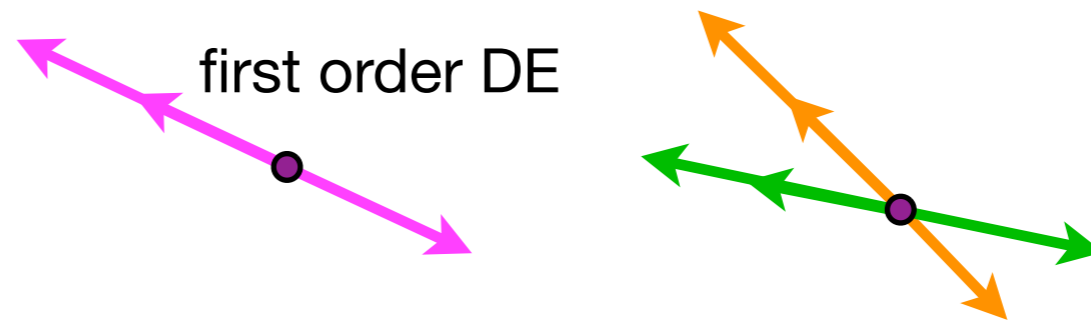
- To solve a nonhomogeneous differential equation:
  1. Find the general solution to the associated homogeneous problem,  $y_h(t)$ .



# Solutions to nonhomogeneous differential equations

---

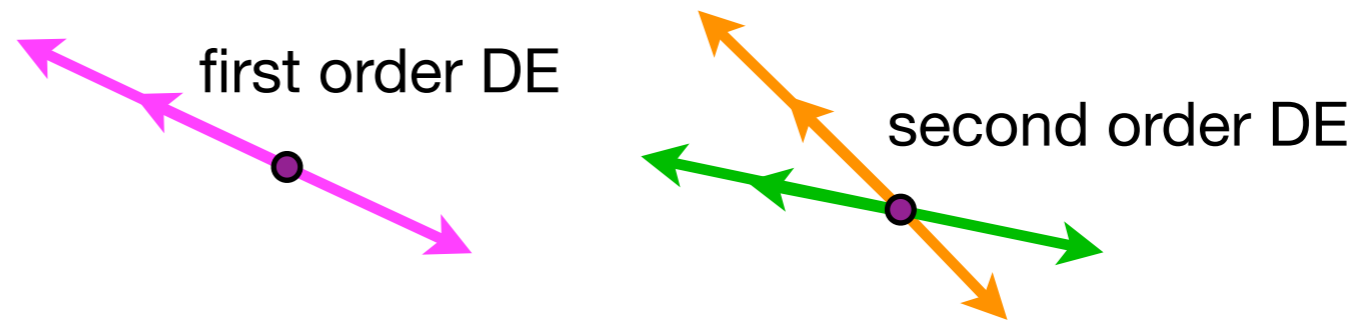
- To solve a nonhomogeneous differential equation:
  1. Find the general solution to the associated homogeneous problem,  $y_h(t)$ .



# Solutions to nonhomogeneous differential equations

---

- To solve a nonhomogeneous differential equation:
  1. Find the general solution to the associated homogeneous problem,  $y_h(t)$ .

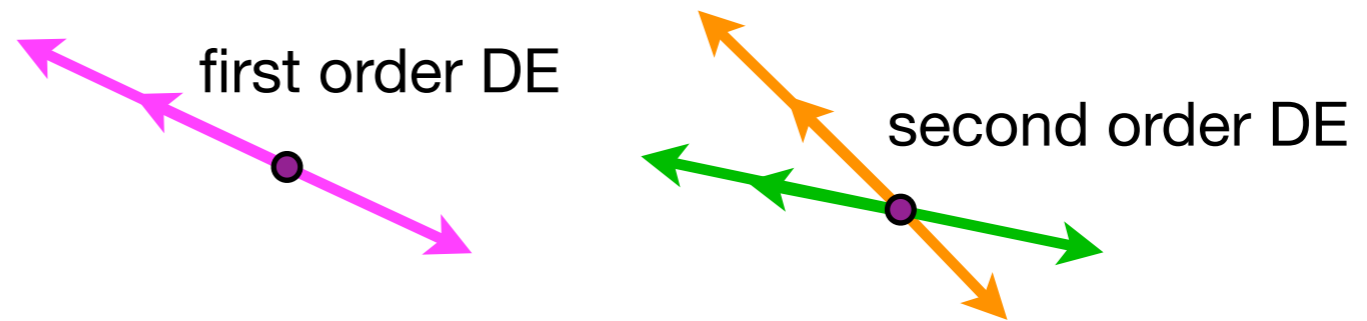


# Solutions to nonhomogeneous differential equations

---

- To solve a nonhomogeneous differential equation:

1. Find the general solution to the associated homogeneous problem,  $y_h(t)$ .



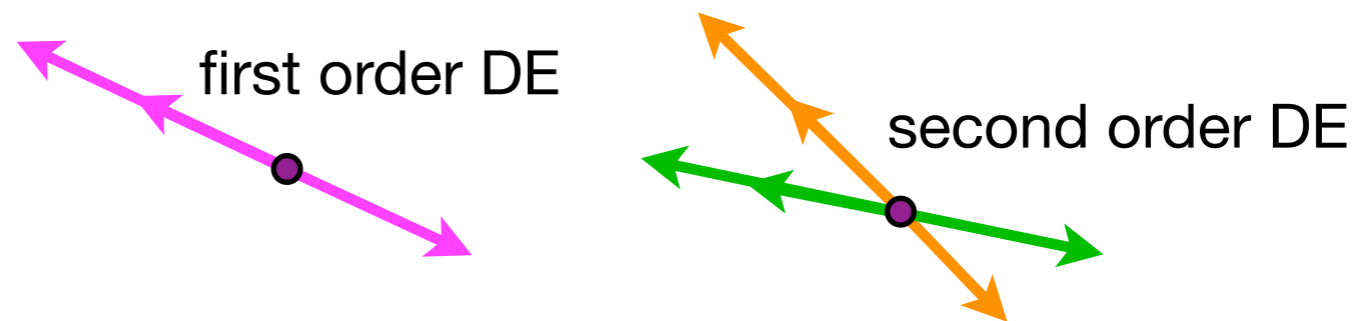
2. Find a particular solution to the nonhomogeneous problem,  $y_p(t)$ .

# Solutions to nonhomogeneous differential equations

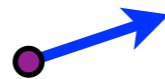
---

- To solve a nonhomogeneous differential equation:

1. Find the general solution to the associated homogeneous problem,  $y_h(t)$ .



2. Find a particular solution to the nonhomogeneous problem,  $y_p(t)$ .

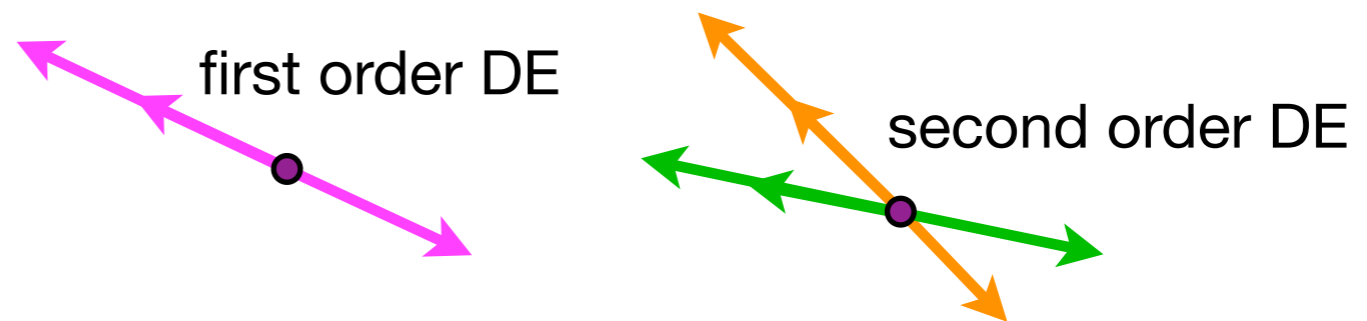


# Solutions to nonhomogeneous differential equations

---

- To solve a nonhomogeneous differential equation:

1. Find the general solution to the associated homogeneous problem,  $y_h(t)$ .



2. Find a particular solution to the nonhomogeneous problem,  $y_p(t)$ .



3. The general solution to the nonhomogeneous problem is their sum:

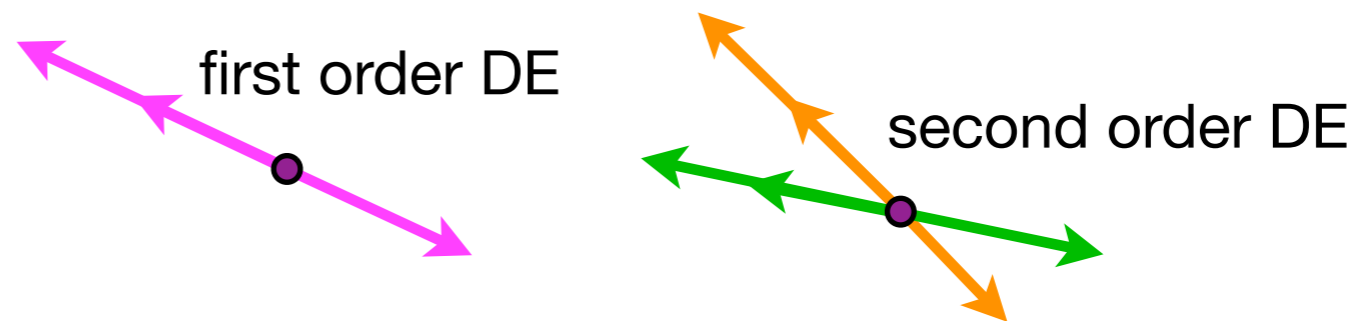
$$y = y_h + y_p = C_1 y_1 + C_2 y_2 + y_p$$

# Solutions to nonhomogeneous differential equations

---

- To solve a nonhomogeneous differential equation:

1. Find the general solution to the associated homogeneous problem,  $y_h(t)$ .

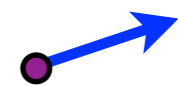


2. Find a particular solution to the nonhomogeneous problem,  $y_p(t)$ .



3. The general solution to the nonhomogeneous problem is their sum:

$$y = y_h + y_p = C_1 y_1 + C_2 y_2 + \underline{y_p}$$

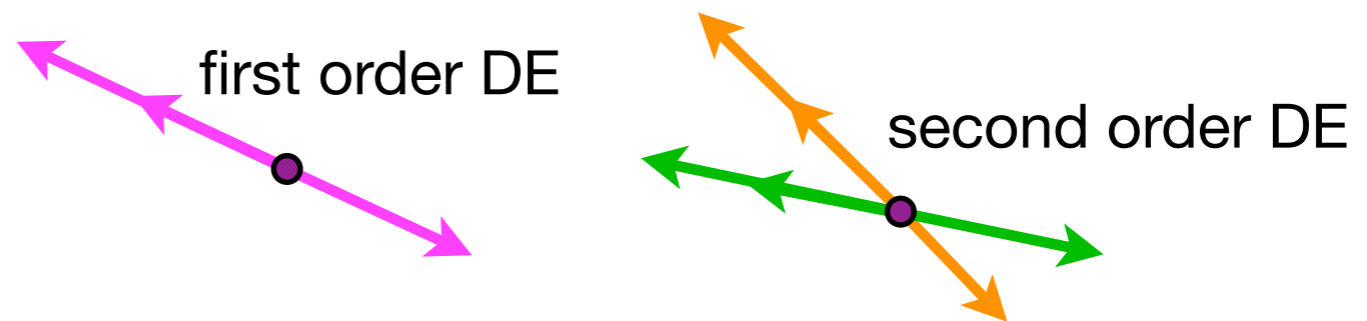


# Solutions to nonhomogeneous differential equations

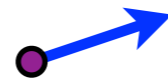
---

- To solve a nonhomogeneous differential equation:

1. Find the general solution to the associated homogeneous problem,  $y_h(t)$ .

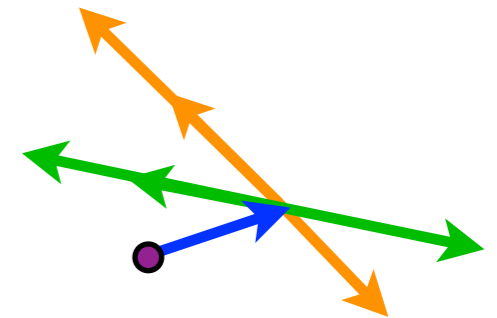


2. Find a particular solution to the nonhomogeneous problem,  $y_p(t)$ .



3. The general solution to the nonhomogeneous problem is their sum:

$$y = y_h + y_p = \underbrace{C_1 y_1}_{\text{orange}} + \underbrace{C_2 y_2}_{\text{green}} + \underbrace{y_p}_{\text{blue}}$$



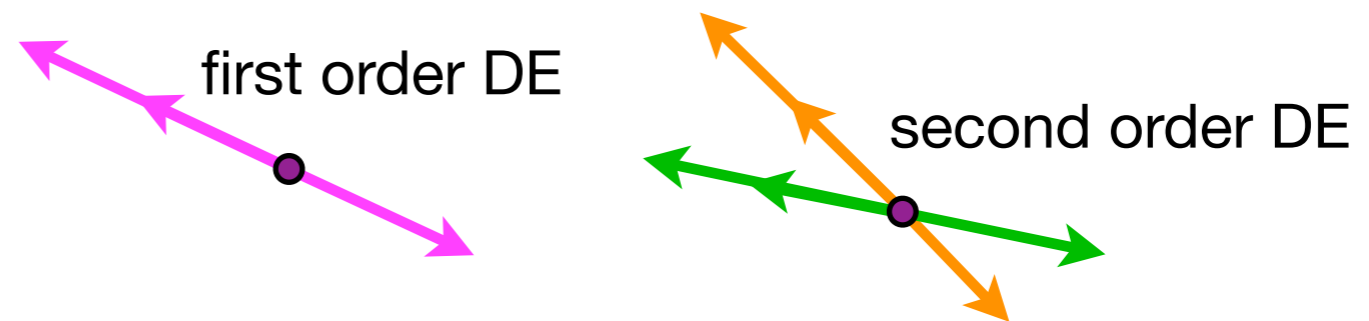


# Solutions to nonhomogeneous differential equations

---

- To solve a nonhomogeneous differential equation:

1. Find the general solution to the associated homogeneous problem,  $y_h(t)$ .

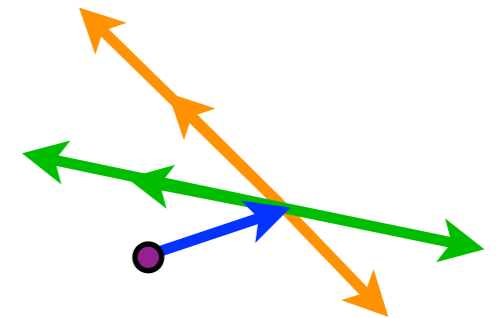


2. Find a particular solution to the nonhomogeneous problem,  $y_p(t)$ .



3. The general solution to the nonhomogeneous problem is their sum:

$$y = y_h + y_p = \underbrace{C_1 y_1}_{\text{orange}} + \underbrace{C_2 y_2}_{\text{green}} + \underbrace{y_p}_{\text{blue}}$$



- For step 2, try “Method of undetermined coefficients”...

# Method of undetermined coefficients (3.5)

---

# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .

# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .

- Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$

# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .
- Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$

$$y_h(t) = C_1 e^t + C_2 e^{-3t}$$

# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .

- Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$

$$y_h(t) = C_1 e^t + C_2 e^{-3t}$$

- Step 2: What do you have to plug in to  $L[\cdot]$  to get  $e^{2t}$  out?

# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .

- Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$

$$y_h(t) = C_1 e^t + C_2 e^{-3t}$$

- Step 2: What do you have to plug in to  $L[\cdot]$  to get  $e^{2t}$  out?

- Try  $y_p(t) = Ae^{2t}$ .

# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .

- Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$

$$y_h(t) = C_1 e^t + C_2 e^{-3t}$$

- Step 2: What do you have to plug in to  $L[\cdot]$  to get  $e^{2t}$  out?

- Try  $y_p(t) = Ae^{2t}$ .

- $L[y_p(t)] = L[Ae^{2t}] =$



# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .

- Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$

$$y_h(t) = C_1 e^t + C_2 e^{-3t}$$

- Step 2: What do you have to plug in to  $L[\cdot]$  to get  $e^{2t}$  out?

- Try  $y_p(t) = Ae^{2t}$ .

- $L[y_p(t)] = L[Ae^{2t}] = \begin{cases} \text{(A) } 5e^{2t} & \text{(C) } 4e^{2t} \\ \text{(B) } 5Ae^{2t} & \text{(D) } 4Ae^{2t} \end{cases}$

# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .

- Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$

$$y_h(t) = C_1 e^t + C_2 e^{-3t}$$

- Step 2: What do you have to plug in to  $L[\cdot]$  to get  $e^{2t}$  out?

- Try  $y_p(t) = Ae^{2t}$ .

- $L[y_p(t)] = L[Ae^{2t}] = \begin{cases} \text{(A) } 5e^{2t} & \text{(C) } 4e^{2t} \\ \star \text{(B) } 5Ae^{2t} & \text{(D) } 4Ae^{2t} \end{cases}$

# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .

- Step 1: Solve the associated homogeneous equation

$$y'' + 2y' - 3y = 0.$$

$$y_h(t) = C_1 e^t + C_2 e^{-3t}$$

- Step 2: What do you have to plug in to  $L[\cdot]$  to get  $e^{2t}$  out?

- Try  $y_p(t) = Ae^{2t}$ .

- $L[y_p(t)] = L[Ae^{2t}] = \begin{cases} \text{(A) } 5e^{2t} & \text{(C) } 4e^{2t} \\ \star \text{(B) } 5Ae^{2t} & \text{(D) } 4Ae^{2t} \end{cases}$

- A is an **undetermined coefficient** (until you determine it).

# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .

# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .
  - Summarizing:

# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .

- Summarizing:

- We know that, for any  $C_1$  and  $C_2$ ,

$$L[C_1 e^t + C_2 e^{-3t}] = 0$$

# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .

- Summarizing:

- We know that, for any  $C_1$  and  $C_2$ ,

$$L[C_1 e^t + C_2 e^{-3t}] = 0$$

- We also know that

$$L[Ae^{2t}] = 5Ae^{2t}$$

# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .

- Summarizing:

- We know that, for any  $C_1$  and  $C_2$ ,

$$L[C_1e^t + C_2e^{-3t}] = 0$$

- We also know that

$$L[Ae^{2t}] = 5Ae^{2t}$$

- Finally, by linearity, we know that

$$L[C_1e^t + C_2e^{-3t} + Ae^{2t}] = 0 + 5Ae^{2t}$$



# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .

- Summarizing:

- We know that, for any  $C_1$  and  $C_2$ ,

$$L[C_1e^t + C_2e^{-3t}] = 0$$

- We also know that

$$L[Ae^{2t}] = 5Ae^{2t}$$

- Finally, by linearity, we know that

$$L[C_1e^t + C_2e^{-3t} + Ae^{2t}] = 0 + 5Ae^{2t}$$

- So what's left to do to find our general solution? Pick  $A = ?$

# Method of undetermined coefficients (3.5)

---

- **Example 4.** Define the operator  $L[y] = y'' + 2y' - 3y$ . Find the general solution to  $L[y] = e^{2t}$ . That is,  $y'' + 2y' - 3y = e^{2t}$ .

- Summarizing:

- We know that, for any  $C_1$  and  $C_2$ ,

$$L[C_1e^t + C_2e^{-3t}] = 0$$

- We also know that

$$L[Ae^{2t}] = 5Ae^{2t}$$

- Finally, by linearity, we know that

$$L[C_1e^t + C_2e^{-3t} + Ae^{2t}] = 0 + 5Ae^{2t}$$

- So what's left to do to find our general solution? Pick  $A = 1/5$ .

# Method of undetermined coefficients (3.5)

---

- **Example 5.** Find the general solution to the equation  $y'' - 4y = e^t$ .

- What is the solution to the **associated homogeneous equation**?

(A)  $y_h(t) = C_1 e^{2t} + C_2 e^{-2t}$

(B)  $y_h(t) = C_1 \cos(2t) + C_2 \sin(2t)$

(C)  $y_h(t) = C_1 e^{2t} + C_2 t e^{2t}$

(D)  $y_h(t) = C_1 \cos(2t) + C_2 \sin(2t) + e^t$

(E) Don't know.

# Method of undetermined coefficients (3.5)

---

- **Example 5.** Find the general solution to the equation  $y'' - 4y = e^t$ .

- What is the solution to the **associated homogeneous equation**?

★ (A)  $y_h(t) = C_1 e^{2t} + C_2 e^{-2t}$

(B)  $y_h(t) = C_1 \cos(2t) + C_2 \sin(2t)$

(C)  $y_h(t) = C_1 e^{2t} + C_2 t e^{2t}$

(D)  $y_h(t) = C_1 \cos(2t) + C_2 \sin(2t) + e^t$

(E) Don't know.

# Method of undetermined coefficients (3.5)

---

- **Example 5.** Find the general solution to the equation  $y'' - 4y = e^t$ .

- What is the form of the particular solution?

(A)  $y_p(t) = Ae^{2t}$

(B)  $y_p(t) = Ae^{-2t}$

(C)  $y_p(t) = Ae^t$

(D)  $y_p(t) = Ate^t$

(E) Don't know

# Method of undetermined coefficients (3.5)

---

- **Example 5.** Find the general solution to the equation  $y'' - 4y = e^t$ .

- What is the form of the particular solution?

(A)  $y_p(t) = Ae^{2t}$

(B)  $y_p(t) = Ae^{-2t}$

★ (C)  $y_p(t) = Ae^t$

(D)  $y_p(t) = Ate^t$

(E) Don't know

# Method of undetermined coefficients (3.5)

---

- **Example 5.** Find the general solution to the equation  $y'' - 4y = e^t$ .
  - What is the value of  $A$  that gives the particular solution  $(Ae^t)$  ?
    - (A)  $A = 1$
    - (B)  $A = 3$
    - (C)  $A = 1/3$
    - (D)  $A = -1/3$
    - (E) Don't know.

# Method of undetermined coefficients (3.5)

---

- **Example 5.** Find the general solution to the equation  $y'' - 4y = e^t$ .
  - What is the value of A that gives the particular solution  $(Ae^t)$  ?
    - (A)  $A = 1$
    - (B)  $A = 3$
    - (C)  $A = 1/3$
    - ★ (D)  $A = -1/3$
    - (E) Don't know.



# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .

- What is the solution to the associated homogeneous equation?

(A)  $y_h(t) = C_1 e^{2t} + C_2 e^{-2t}$

(B)  $y_h(t) = C_1 \cos(2t) + C_2 \sin(2t)$

(C)  $y_h(t) = C_1 e^{2t} + C_2 t e^{2t}$

(D)  $y_h(t) = C_1 e^{2t} + C_2 e^{-2t} + e^t$

(E) Don't know.

# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .

- What is the solution to the associated homogeneous equation?

★ (A)  $y_h(t) = C_1 e^{2t} + C_2 e^{-2t}$

(B)  $y_h(t) = C_1 \cos(2t) + C_2 \sin(2t)$

(C)  $y_h(t) = C_1 e^{2t} + C_2 e^{-2t}$

Same as the last example

(D) Don't know.

# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .
  - What is the form of the particular solution?
    - (A)  $y_p(t) = Ae^{2t}$
    - (B)  $y_p(t) = Ae^{-2t}$
    - (C)  $y_p(t) = Ate^{2t}$
    - (D)  $y_p(t) = Ae^t$
    - (E)  $y_p(t) = Ate^t$
- General rule: when your guess at  $y_p$  makes LHS=0, try multiplying it by  $t$ .<sub>19</sub>

# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .
  - What is the form of the particular solution?
    - (A)  $y_p(t) = Ae^{2t}$   $(Ae^{2t})'' - 4Ae^{2t} = 0 !$
    - (B)  $y_p(t) = Ae^{-2t}$
    - (C)  $y_p(t) = Ate^{2t}$
    - (D)  $y_p(t) = Ae^t$
    - (E)  $y_p(t) = Ate^t$
- General rule: when your guess at  $y_p$  makes LHS=0, try multiplying it by  $t$ .<sub>19</sub>

# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .
  - What is the form of the particular solution?
    - (A)  $y_p(t) = Ae^{2t}$   $(Ae^{2t})'' - 4Ae^{2t} = 0 !$
    - (B)  $y_p(t) = Ae^{-2t}$
    - (C)  $y_p(t) = Ate^{2t}$
    - (D)  $y_p(t) = Ae^t$
    - (E)  $y_p(t) = Ate^t$
  - Simpler example in which the RHS is a solution to the homogeneous problem.
$$y' - y = e^t$$
- General rule: when your guess at  $y_p$  makes LHS=0, try multiplying it by  $t$ .<sub>19</sub>

# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .

- What is the form of the particular solution?

(A)  $y_p(t) = Ae^{2t}$

$$(Ae^{2t})'' - 4Ae^{2t} = 0 !$$

(B)  $y_p(t) = Ae^{-2t}$

(C)  $y_p(t) = Ate^{2t}$

(D)  $y_p(t) = Ae^t$

(E)  $y_p(t) = Ate^t$

- Simpler example in which the RHS is a solution to the homogeneous problem.

$$y' - y = e^t$$
$$e^{-t}y' - e^{-t}y = 1$$

- General rule: when your guess at  $y_p$  makes LHS=0, try multiplying it by  $t$ .<sub>19</sub>

# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .

- What is the form of the particular solution?

(A)  $y_p(t) = Ae^{2t}$

$$(Ae^{2t})'' - 4Ae^{2t} = 0 !$$

(B)  $y_p(t) = Ae^{-2t}$

(C)  $y_p(t) = Ate^{2t}$

(D)  $y_p(t) = Ae^t$

(E)  $y_p(t) = Ate^t$

- Simpler example in which the RHS is a solution to the homogeneous problem.

$$y' - y = e^t$$

$$e^{-t}y' - e^{-t}y = 1$$

$$y = te^t + Ce^t$$

- General rule: when your guess at  $y_p$  makes LHS=0, try multiplying it by  $t$ .<sub>19</sub>

# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .

- What is the form of the particular solution?

(A)  $y_p(t) = Ae^{2t}$

$$(Ae^{2t})'' - 4Ae^{2t} = 0 !$$

(B)  $y_p(t) = Ae^{-2t}$

(C)  $y_p(t) = Ate^{2t}$

(D)  $y_p(t) = Ae^t$

(E)  $y_p(t) = Ate^t$

- Simpler example in which the RHS is a solution to the homogeneous problem.

$$y' - y = e^t$$

$$e^{-t}y' - e^{-t}y = 1$$

$$y = te^t + Ce^t$$

- General rule: when your guess at  $y_p$  makes LHS=0, try multiplying it by  $t$ .<sub>19</sub>



# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .

- What is the form of the particular solution?

(A)  $y_p(t) = Ae^{2t}$

$$(Ae^{2t})'' - 4Ae^{2t} = 0 !$$

(B)  $y_p(t) = Ae^{-2t}$

★ (C)  $y_p(t) = Ate^{2t}$

(D)  $y_p(t) = Ae^t$

(E)  $y_p(t) = Ate^t$

- Simpler example in which the RHS is a solution to the homogeneous problem.

$$y' - y = e^t$$

$$e^{-t}y' - e^{-t}y = 1$$

$$y = te^t + Ce^t$$

- General rule: when your guess at  $y_p$  makes LHS=0, try multiplying it by  $t$ .

# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .
  - What is the value of  $A$  that gives the particular solution  $(Ate^{2t})$ ?
    - (A)  $A = 1$
    - (B)  $A = 4$
    - (C)  $A = -4$
    - (D)  $A = 1/4$
    - (E)  $A = -1/4$

# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .
  - What is the value of A that gives the particular solution  $(Ate^{2t})$ ?

(A)  $A = 1$

$$(Ate^{2t})' = Ae^{2t} + 2Ate^{2t}$$

(B)  $A = 4$

(C)  $A = -4$

(D)  $A = 1/4$

(E)  $A = -1/4$

# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .
  - What is the value of A that gives the particular solution  $(Ate^{2t})$ ?

(A)  $A = 1$

$$(Ate^{2t})' = Ae^{2t} + 2Ate^{2t}$$

(B)  $A = 4$

$$(Ate^{2t})'' = 2Ae^{2t} + 2Ae^{2t} + 4Ate^{2t}$$

(C)  $A = -4$

(D)  $A = 1/4$

(E)  $A = -1/4$

# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .
  - What is the value of A that gives the particular solution  $(Ate^{2t})$ ?

(A)  $A = 1$

$$(Ate^{2t})' = Ae^{2t} + 2Ate^{2t}$$

(B)  $A = 4$

$$(Ate^{2t})'' = 2Ae^{2t} + 2Ae^{2t} + 4Ate^{2t}$$

(C)  $A = -4$

$$= 4Ae^{2t} + 4Ate^{2t}$$

(D)  $A = 1/4$

(E)  $A = -1/4$

# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .
  - What is the value of A that gives the particular solution  $(Ate^{2t})$ ?

(A)  $A = 1$

$$(Ate^{2t})' = Ae^{2t} + 2Ate^{2t}$$

(B)  $A = 4$

$$(Ate^{2t})'' = 2Ae^{2t} + 2Ae^{2t} + 4Ate^{2t}$$

(C)  $A = -4$

$$= 4Ae^{2t} + 4Ate^{2t}$$

(D)  $A = 1/4$

$$(Ate^{2t})'' - 4(Ate^{2t}) =$$

(E)  $A = -1/4$

# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .
  - What is the value of A that gives the particular solution  $(Ate^{2t})$ ?

(A)  $A = 1$

$$(Ate^{2t})' = Ae^{2t} + 2Ate^{2t}$$

(B)  $A = 4$

$$(Ate^{2t})'' = 2Ae^{2t} + 2Ae^{2t} + 4Ate^{2t}$$

(C)  $A = -4$

$$= 4Ae^{2t} + 4Ate^{2t}$$

(D)  $A = 1/4$

$$(Ate^{2t})'' - 4(Ate^{2t}) =$$

(E)  $A = -1/4$

# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .
  - What is the value of A that gives the particular solution  $(Ate^{2t})$ ?

(A)  $A = 1$

$$(Ate^{2t})' = Ae^{2t} + 2Ate^{2t}$$

(B)  $A = 4$

$$(Ate^{2t})'' = 2Ae^{2t} + 2Ae^{2t} + 4Ate^{2t}$$

(C)  $A = -4$

$$= 4Ae^{2t} + 4Ate^{2t}$$

(D)  $A = 1/4$

$$(Ate^{2t})'' - 4(Ate^{2t}) = 4Ae^{2t}$$

(E)  $A = -1/4$



# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .
  - What is the value of A that gives the particular solution  $(Ate^{2t})$ ?

(A)  $A = 1$

$$(Ate^{2t})' = Ae^{2t} + 2Ate^{2t}$$

(B)  $A = 4$

$$(Ate^{2t})'' = 2Ae^{2t} + 2Ae^{2t} + 4Ate^{2t}$$

(C)  $A = -4$

$$= 4Ae^{2t} + 4Ate^{2t}$$

(D)  $A = 1/4$

$$(Ate^{2t})'' - 4(Ate^{2t}) = 4Ae^{2t}$$

(E)  $A = -1/4$

Need:  $= e^{2t}$

# Method of undetermined coefficients (3.5)

---

- **Example 7.** Find the general solution to the equation  $y'' - 4y = e^{2t}$ .
  - What is the value of A that gives the particular solution  $(Ate^{2t})$ ?

(A)  $A = 1$

$$(Ate^{2t})' = Ae^{2t} + 2Ate^{2t}$$

(B)  $A = 4$

$$(Ate^{2t})'' = 2Ae^{2t} + 2Ae^{2t} + 4Ate^{2t}$$

(C)  $A = -4$

$$= 4Ae^{2t} + 4Ate^{2t}$$

★ (D)  $A = 1/4$

$$(Ate^{2t})'' - 4(Ate^{2t}) = 4Ae^{2t}$$

(E)  $A = -1/4$

Need:  $= e^{2t}$

# Method of undetermined coefficients (3.5)

---

- **Example 8.** Find the general solution to  $y'' - 4y = \cos(2t)$ .

- What is the form of the particular solution?

(A)  $y_p(t) = A \cos(2t)$

(B)  $y_p(t) = A \sin(2t)$

(C)  $y_p(t) = A \cos(2t) + B \sin(2t)$

(D)  $y_p(t) = t(A \cos(2t) + B \sin(2t))$

(E)  $y_p(t) = e^{2t}(A \cos(2t) + B \sin(2t))$

# Method of undetermined coefficients (3.5)

---

- **Example 8.** Find the general solution to  $y'' - 4y = \cos(2t)$ .

- What is the form of the particular solution?

★ (A)  $y_p(t) = A \cos(2t)$

(B)  $y_p(t) = A \sin(2t)$

★ (C)  $y_p(t) = A \cos(2t) + B \sin(2t)$

(D)  $y_p(t) = t(A \cos(2t) + B \sin(2t))$

(E)  $y_p(t) = e^{2t}(A \cos(2t) + B \sin(2t))$

# Method of undetermined coefficients (3.5)

---

- **Example 8.** Find the general solution to  $y'' - 4y = \cos(2t)$ .

- What is the form of the particular solution?

★ (A)  $y_p(t) = A \cos(2t)$

(B)  $y_p(t) = A \sin(2t)$

★ (C)  $y_p(t) = A \cos(2t) + B \sin(2t)$

(D)  $y_p(t) = t(A \cos(2t) + B \sin(2t))$

(E)  $y_p(t) = e^{2t}(A \cos(2t) + B \sin(2t))$

Challenge: What small change to the DE makes (D) correct?

# Method of undetermined coefficients (3.5)

---

- **Example 8.** Find the general solution to  $y'' + y' - 4y = \cos(2t)$ .

- What is the form of the particular solution?

(A)  $y_p(t) = A \cos(2t)$

(B)  $y_p(t) = A \sin(2t)$

(C)  $y_p(t) = A \cos(2t) + B \sin(2t)$

(D)  $y_p(t) = t(A \cos(2t) + B \sin(2t))$

(E)  $y_p(t) = e^{2t}(A \cos(2t) + B \sin(2t))$

# Method of undetermined coefficients (3.5)

---

• **Example 8.** Find the general solution to  $y'' + y' - 4y = \cos(2t)$ .

• What is the form of the particular solution?

(A)  $y_p(t) = A \cos(2t)$

(B)  $y_p(t) = A \sin(2t)$

★ (C)  $y_p(t) = A \cos(2t) + B \sin(2t)$

(D)  $y_p(t) = t(A \cos(2t) + B \sin(2t))$

(E)  $y_p(t) = e^{2t}(A \cos(2t) + B \sin(2t))$

# Method of undetermined coefficients (3.5)

---

- **Example 9.** Find the general solution to  $y'' - 4y = t^3$ .

- What is the form of the particular solution?

(A)  $y_p(t) = At^3$

(B)  $y_p(t) = At^3 + Bt^2 + Ct$

(C)  $y_p(t) = At^3 + Bt^2 + Ct + D$

(D)  $y_p(t) = At^3 + Be^{2t} + Ce^{-2t}$

(E) Don't know.



# Method of undetermined coefficients (3.5)

---

- **Example 9.** Find the general solution to  $y'' - 4y = t^3$ .

- What is the form of the particular solution?

(A)  $y_p(t) = At^3$

(B)  $y_p(t) = At^3 + Bt^2 + Ct$

★ (C)  $y_p(t) = At^3 + Bt^2 + Ct + D$

(D)  $y_p(t) = At^3 + Be^{2t} + Ce^{-2t}$

(E) Don't know.

# Method of undetermined coefficients (3.5)

---

- **Example 9.** Find the general solution to  $y'' - 4y = t^3$ .

- What is the form of the particular solution?

(A)  $y_p(t) = At^3$


(B)  $y_p(t) = At^3 + Bt^2 + Ct$

★ (C)  $y_p(t) = At^3 + Bt^2 + Ct + D$

(D)  $y_p(t) = At^3 + Be^{2t} + Ce^{-2t}$

(E) Don't know.

waste of time including  
solution to homogeneous eq.



# Method of undetermined coefficients (3.5)

---

- When RHS is sum of terms:

$$y'' - 4y = \cos(2t) + t^3$$

$$y_p(t) = A \cos(2t) + B \sin(2t) + Ct^3 + Dt^2 + Et + F$$

# Method of undetermined coefficients (3.5)

---

- **Example 10.** Find the general solution to  $y'' + 2y' = e^{2t} + t^3$ .

- What is the form of the particular solution?

(A)  $y_p(t) = Ae^{2t} + Bt^3 + Ct^2 + Dt$

(B)  $y_p(t) = Ae^{2t} + Bt^3 + Ct^2 + Dt + E$

(C)  $y_p(t) = Ae^{2t} + (Bt^4 + Ct^3 + Dt^2 + Et)$

(D)  $y_p(t) = Ae^{2t} + Be^{-2t} + Ct^3 + Dt^2 + Et + F$

(E)  $y_p(t) = Ae^{2t} + Bte^{2t} + Ct^3 + Dt^2 + Et + F$

# Method of undetermined coefficients (3.5)

---

- **Example 10.** Find the general solution to  $y'' + 2y' = e^{2t} + t^3$ .

- What is the form of the particular solution?

(A)  $y_p(t) = Ae^{2t} + Bt^3 + Ct^2 + Dt$

(B)  $y_p(t) = Ae^{2t} + Bt^3 + Ct^2 + Dt + E$

★ (C)  $y_p(t) = Ae^{2t} + (Bt^4 + Ct^3 + Dt^2 + Et)$

(D)  $y_p(t) = Ae^{2t} + Be^{-2t} + Ct^3 + Dt^2 + Et + F$

(E)  $y_p(t) = Ae^{2t} + Bte^{2t} + Ct^3 + Dt^2 + Et + F$

# Method of undetermined coefficients (3.5)

---

- **Example 10.** Find the general solution to  $y'' + 2y' = e^{2t} + t^3$ .

- What is the form of the particular solution?

(A)  $y_p(t) = Ae^{2t} + Bt^3 + Ct^2 + Dt$

(B)  $y_p(t) = Ae^{2t} + Bt^3 + Ct^2 + Dt + E$

★ (C)  $y_p(t) = Ae^{2t} + (Bt^4 + Ct^3 + Dt^2 + Et)$   
 $y_p(t) = Ae^{2t} + t(Bt^3 + Ct^2 + Dt + E)$

(D)  $y_p(t) = Ae^{2t} + Be^{-2t} + Ct^3 + Dt^2 + Et + F$

(E)  $y_p(t) = Ae^{2t} + Bte^{2t} + Ct^3 + Dt^2 + Et + F$

# Method of undetermined coefficients (3.5)

---

- **Example 10.** Find the general solution to  $y'' + 2y' = e^{2t} + t^3$ .

- What is the form of the particular solution?

(A)  $y_p(t) = Ae^{2t} + Bt^3 + Ct^2 + Dt$

(B)  $y_p(t) = Ae^{2t} + Bt^3 + Ct^2 + Dt + E$

★ (C)  $y_p(t) = Ae^{2t} + (Bt^4 + Ct^3 + Dt^2 + Et)$   
 $y_p(t) = Ae^{2t} + t(Bt^3 + Ct^2 + Dt + E)$

(D)  $y_p(t) = Ae^{2t} + Be^{-2t} + Ct^3 + Dt^2 + Et + F$

(E)  $y_p(t) = Ae^{2t} + Bte^{2t} + Ct^3 + Dt^2 + Et + F$

For each wrong answer, for what DE is it the correct form?

# Method of undetermined coefficients (3.5)

---

- **Example 11.** Find the general solution to  $y'' - 4y = t^3 e^{2t}$ .

- What is the form of the particular solution?

(A)  $y_p(t) = (At^3 + Bt^2 + Ct + D)e^{2t}$

(B)  $y_p(t) = (At^3 + Bt^2 + Ct)e^{2t}$

(C)  $y_p(t) = (At^3 + Bt^2 + Ct)e^{2t} + (Dt^3 + Et^2 + Ft)e^{-2t}$

(D)  $y_p(t) = (At^4 + Bt^3 + Ct^2 + Dt)e^{2t}$

(E)  $y_p(t) = (At^4 + Bt^3 + Ct^2 + Dt + E)e^{2t}$



# Method of undetermined coefficients (3.5)

---

- **Example 11.** Find the general solution to  $y'' - 4y = t^3 e^{2t}$ .

- What is the form of the particular solution?

(A)  $y_p(t) = (At^3 + Bt^2 + Ct + D)e^{2t}$

(B)  $y_p(t) = (At^3 + Bt^2 + Ct)e^{2t}$

(C)  $y_p(t) = (At^3 + Bt^2 + Ct)e^{2t} + (Dt^3 + Et^2 + Ft)e^{-2t}$

★ (D)  $y_p(t) = (At^4 + Bt^3 + Ct^2 + Dt)e^{2t}$

(E)  $y_p(t) = (At^4 + Bt^3 + Ct^2 + Dt + E)e^{2t}$

# Method of undetermined coefficients (3.5)

---

- **Example 11.** Find the general solution to  $y'' - 4y = t^3 e^{2t}$ .

- What is the form of the particular solution?

(A)  $y_p(t) = (At^3 + Bt^2 + Ct + D)e^{2t}$

(B)  $y_p(t) = (At^3 + Bt^2 + Ct)e^{2t}$

(C)  $y_p(t) = (At^3 + Bt^2 + Ct)e^{2t} + (Dt^3 + Et^2 + Ft)e^{-2t}$

★ (D)  $y_p(t) = (At^4 + Bt^3 + Ct^2 + Dt)e^{2t}$   
 $y_p(t) = t(At^3 + Bt^2 + Ct + D)e^{2t}$

(E)  $y_p(t) = (At^4 + Bt^3 + Ct^2 + Dt + E)e^{2t}$

# Method of undetermined coefficients (3.5)

---

- Summary - finding a particular solution to  $L[y] = g(t)$ .

# Method of undetermined coefficients (3.5)

---

- Summary - finding a particular solution to  $L[y] = g(t)$ .
  - Include all functions that are part of the  $g(t)$  family (e.g. cos **and** sin)

# Method of undetermined coefficients (3.5)

---

- Summary - finding a particular solution to  $L[y] = g(t)$ .
  - Include all functions that are part of the  $g(t)$  family (e.g. **cos and sin**)
  - If part of the  $g(t)$  family is a solution to the homogeneous (h-)problem, use  $t \times$  ( $g(t)$  family).

# Method of undetermined coefficients (3.5)

---

- Summary - finding a particular solution to  $L[y] = g(t)$ .
  - Include all functions that are part of the  $g(t)$  family (e.g.  $\cos$  **and**  $\sin$ )
  - If part of the  $g(t)$  family is a solution to the homogeneous (h-)problem, use  $t \times$  ( $g(t)$  family).
  - If  $t \times$  (part of the  $g(t)$  family), is a solution to the h-problem, use  $t^2 \times$  ( $g(t)$  family).

# Method of undetermined coefficients (3.5)

---

- Summary - finding a particular solution to  $L[y] = g(t)$ .
  - Include all functions that are part of the  $g(t)$  family (e.g.  $\cos$  **and**  $\sin$ )
  - If part of the  $g(t)$  family is a solution to the homogeneous (h-)problem, use  $t \times (g(t)$  family).
  - If  $t \times$  (part of the  $g(t)$  family), is a solution to the h-problem, use  $t^2 \times (g(t)$  family).
  - For sums, group terms into families and include a term for each.

# Method of undetermined coefficients (3.5)

---

- Summary - finding a particular solution to  $L[y] = g(t)$ .
  - Include all functions that are part of the  $g(t)$  family (e.g.  $\cos$  **and**  $\sin$ )
  - If part of the  $g(t)$  family is a solution to the homogeneous (h-)problem, use  $t \times$  ( $g(t)$  family).
  - If  $t \times$  (part of the  $g(t)$  family), is a solution to the h-problem, use  $t^2 \times$  ( $g(t)$  family).
  - For sums, group terms into families and include a term for each.
  - For products of families, use the above rules and multiply them.



# Method of undetermined coefficients (3.5)

---

- Summary - finding a particular solution to  $L[y] = g(t)$ .
  - Include all functions that are part of the  $g(t)$  family (e.g.  $\cos$  **and**  $\sin$ )
  - If part of the  $g(t)$  family is a solution to the homogeneous (h-)problem, use  $t \times (g(t)$  family).
  - If  $t \times$  (part of the  $g(t)$  family), is a solution to the h-problem, use  $t^2 \times (g(t)$  family).
  - For sums, group terms into families and include a term for each.
  - For products of families, use the above rules and multiply them.
  - If your guess includes a solution to the h-problem, you may as well remove it as it won't survive  $L[ ]$  so you won't be able to determine its undetermined coefficient.