Today

- Introduction to systems of equations
- Direction fields
- Eigenvalues and eigenvectors
- Finding the general solution (distinct e-value case)
- Pre-midterm office hours poll Friday (best time other than 2-3),
 Monday (holiday so buildings locked)



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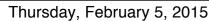
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$$\begin{pmatrix} x \\ v \end{pmatrix}' = \begin{pmatrix} 0 & 1 \\ -\frac{k}{m} & -\frac{\gamma}{m} \end{pmatrix} \begin{pmatrix} x \\ v \end{pmatrix}$$

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- populations of two species (e.g. predator and prey).

As with single equations, we have linear and nonlinear systems:

$$\frac{dx}{dt} = t^2x - y + \cos(2t)$$

$$\frac{dy}{dt} = x + 4\sin(t)y + t^3$$

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 We'll focus on the case in which the matrix has constant entries. And homogeneous, to start. For example,

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Geometric interpretation - direction fields.

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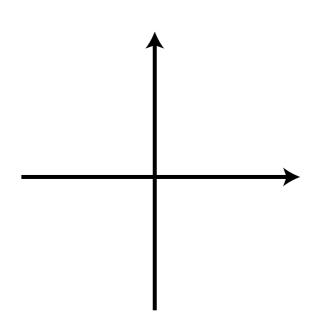
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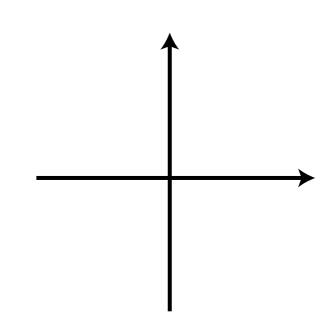
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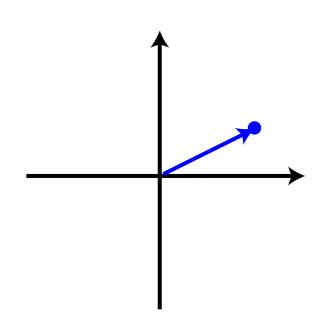
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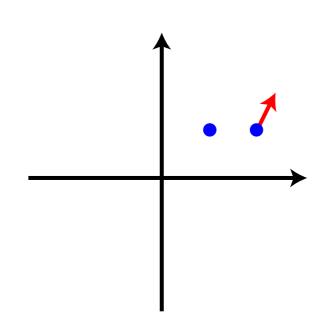
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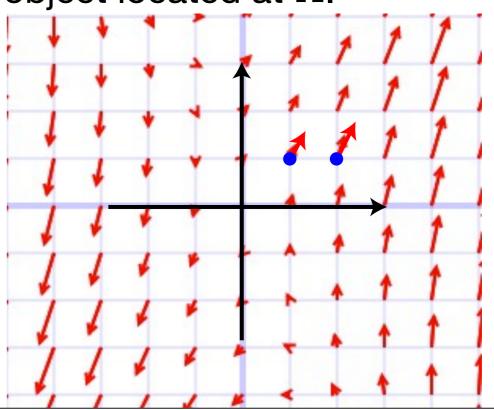
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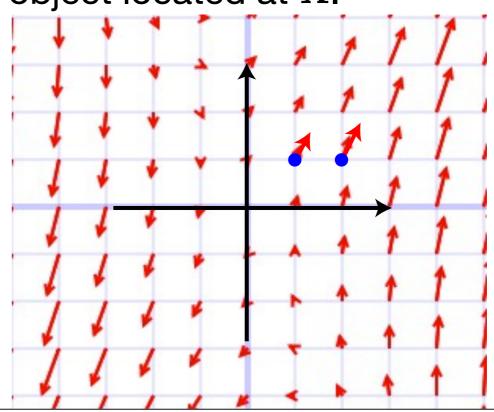
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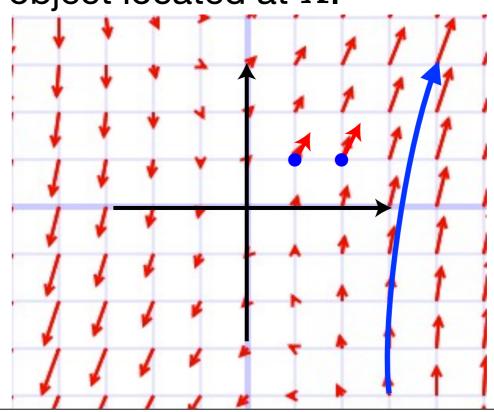
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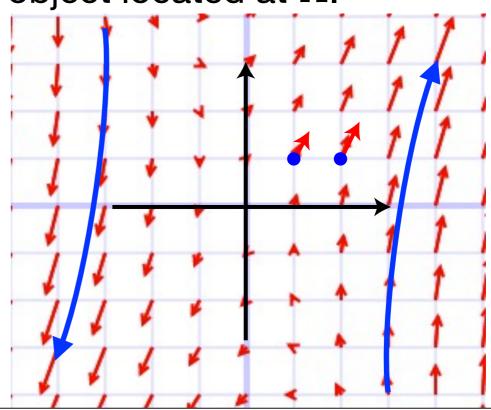
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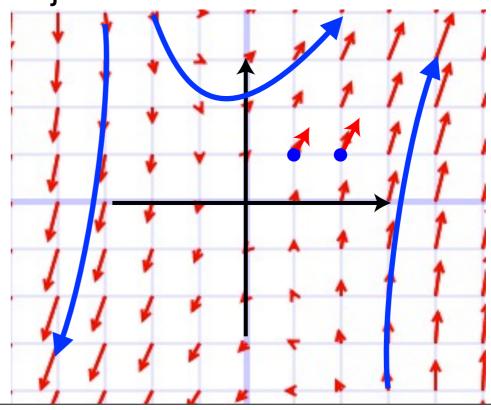
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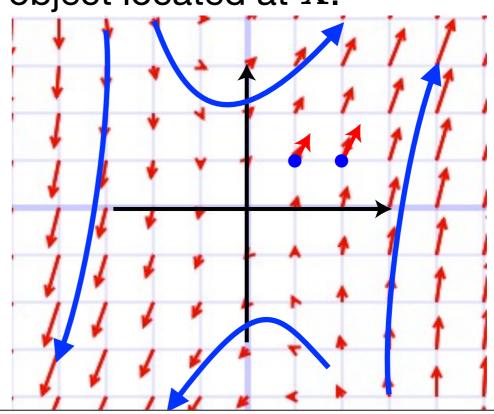
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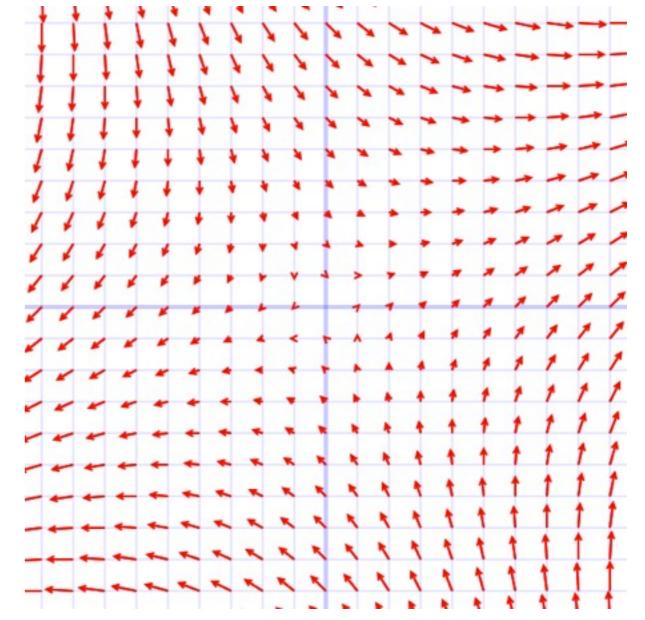
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(C)
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(E) Explain, please.



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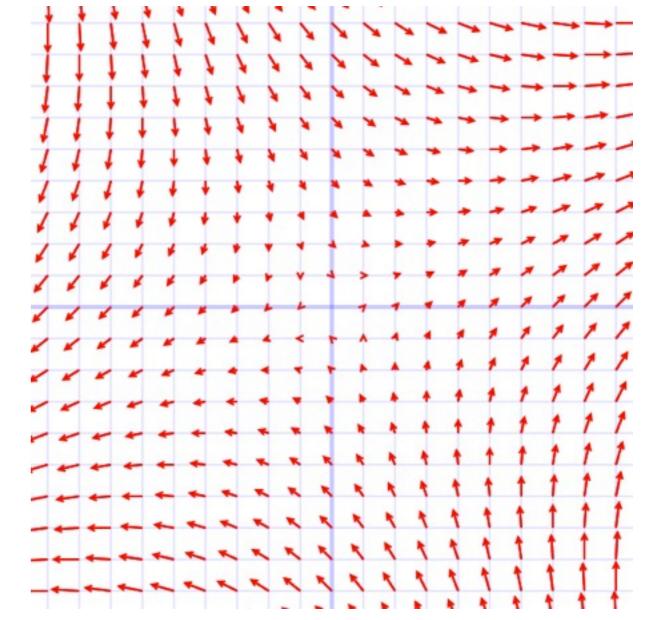
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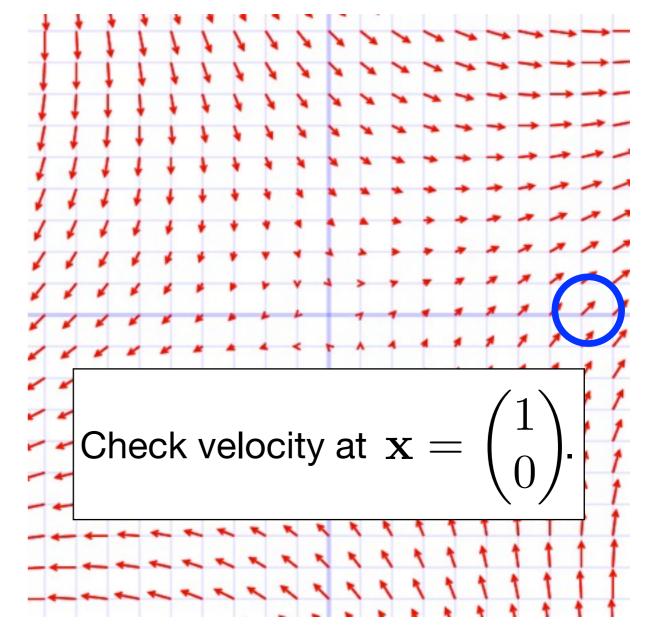
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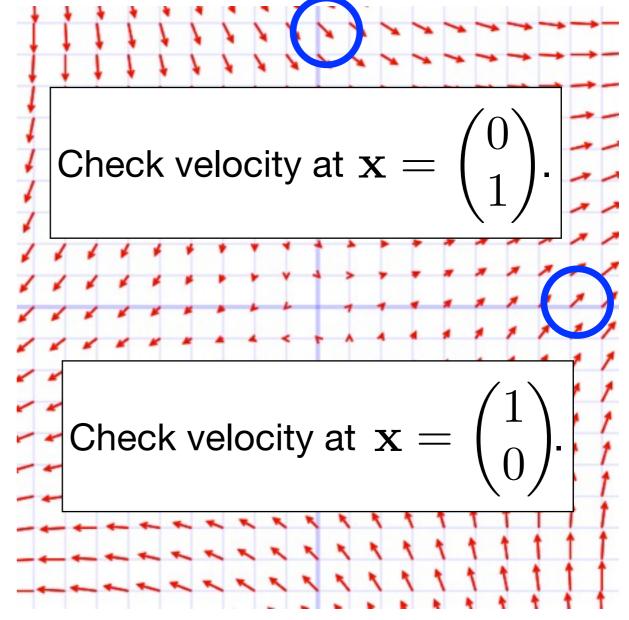
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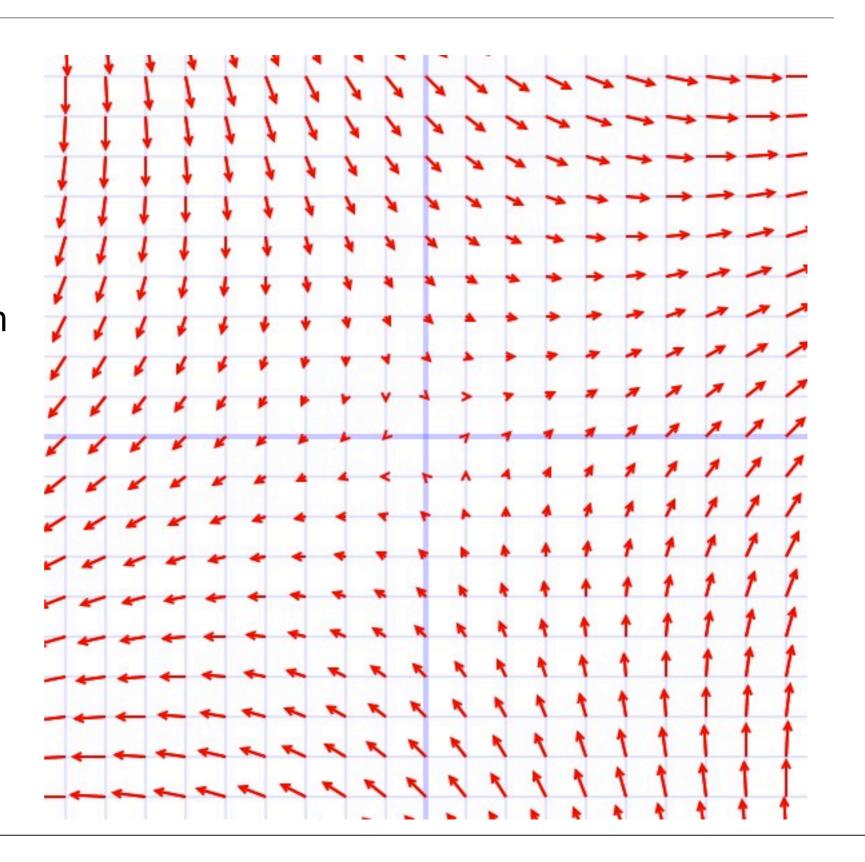
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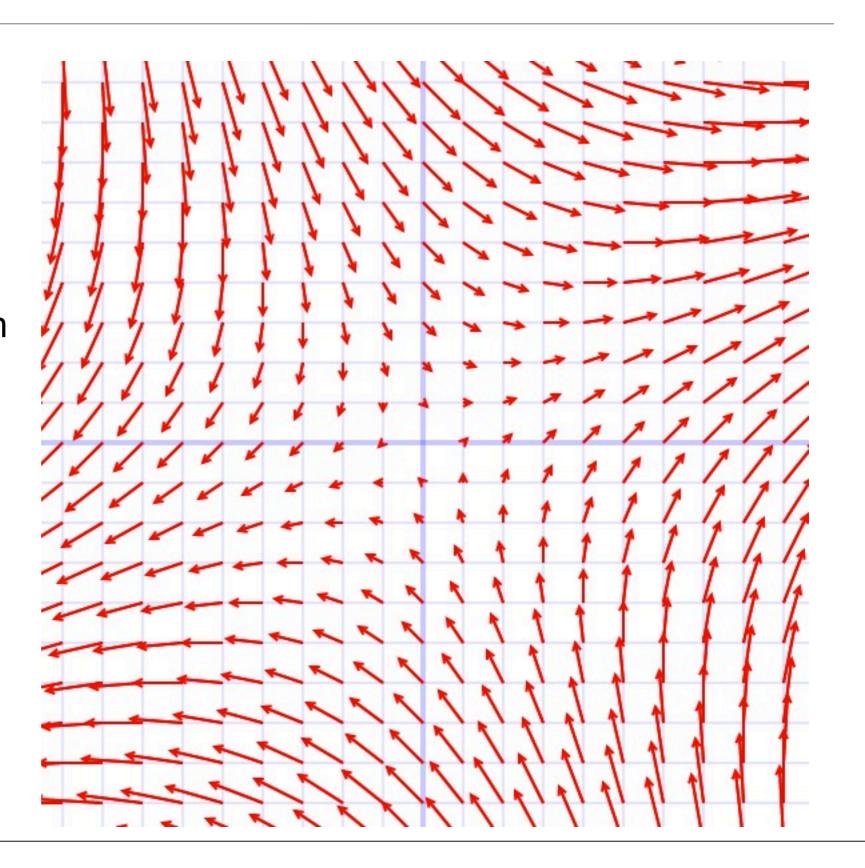
(E) Explain, please.



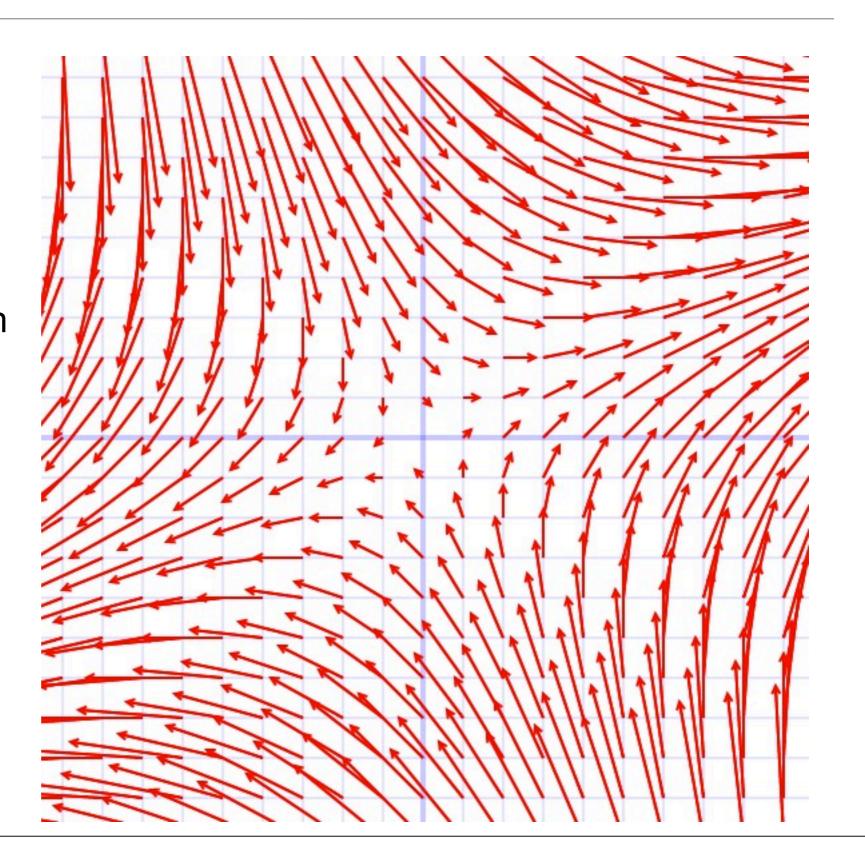
- You should see two "special" directions.
- What are they?
- Directions along which the velocity vector is parallel to the position vector.
- That is,



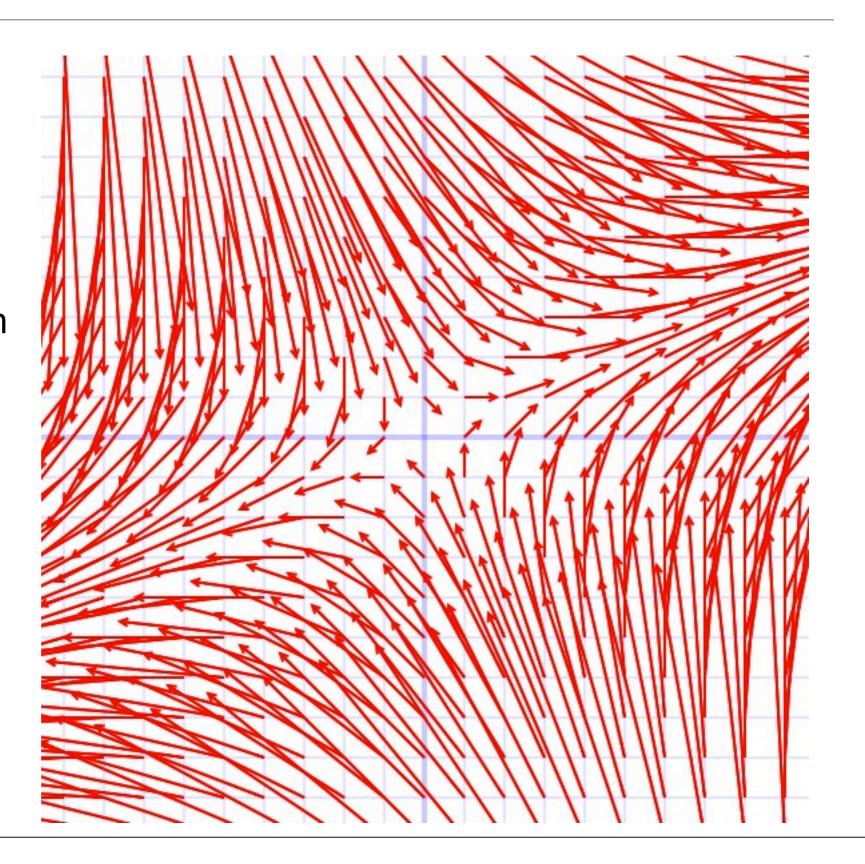
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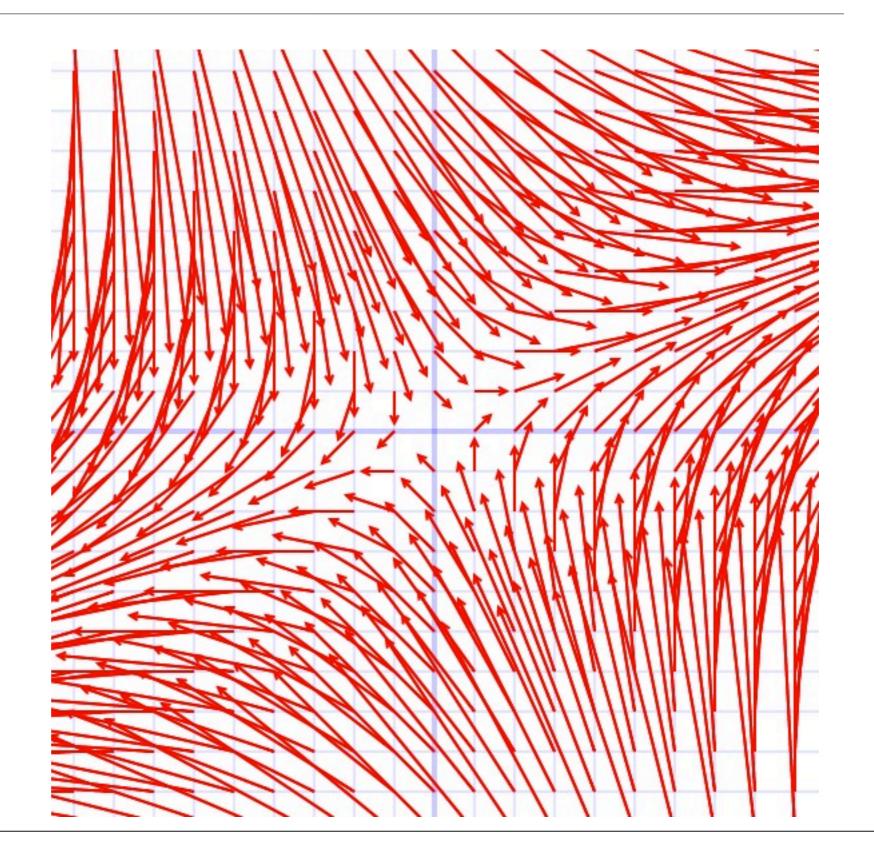
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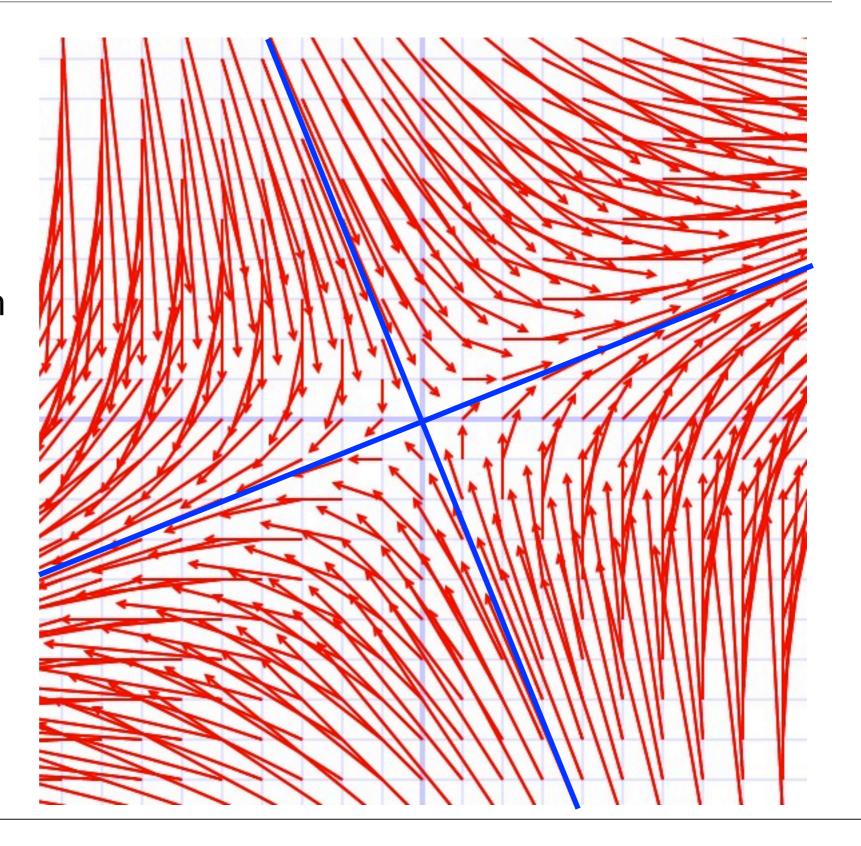
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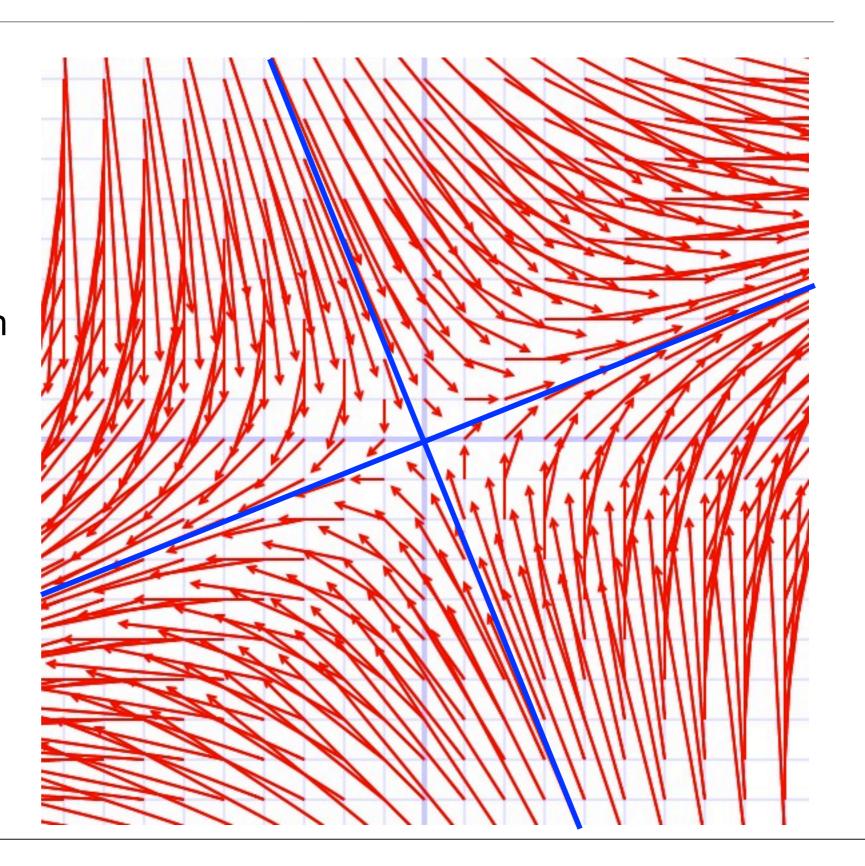
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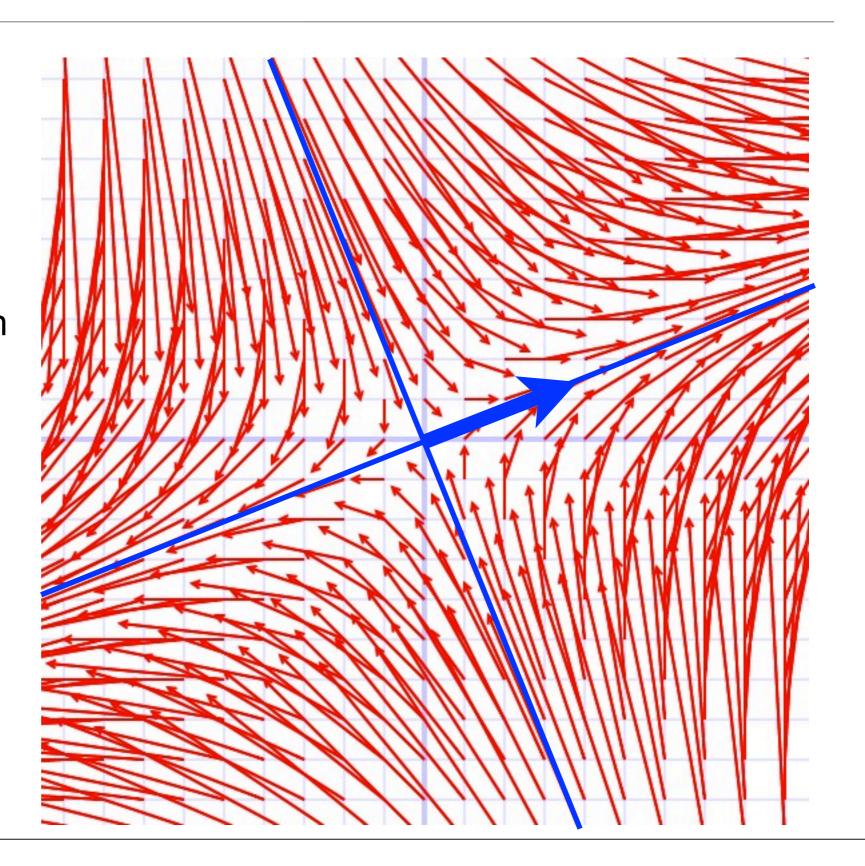
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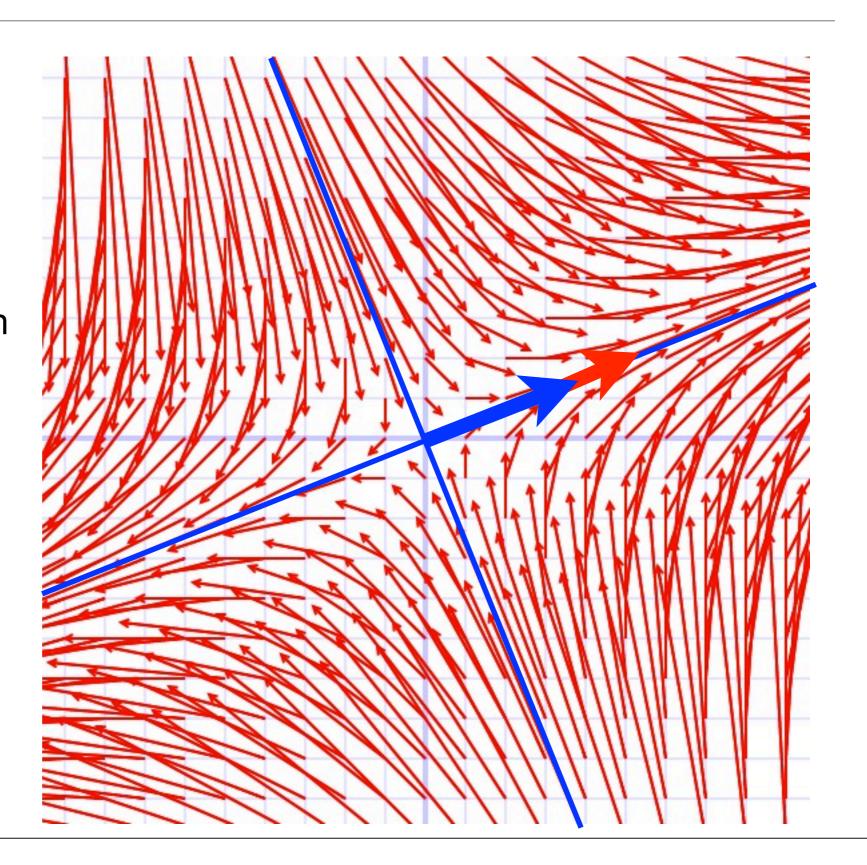
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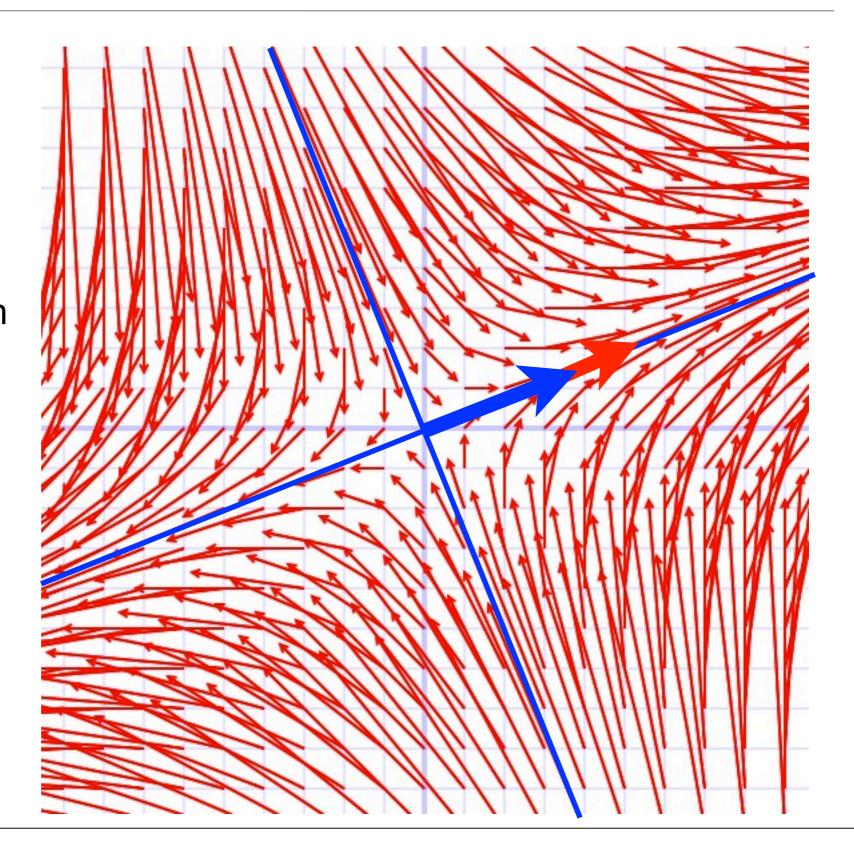
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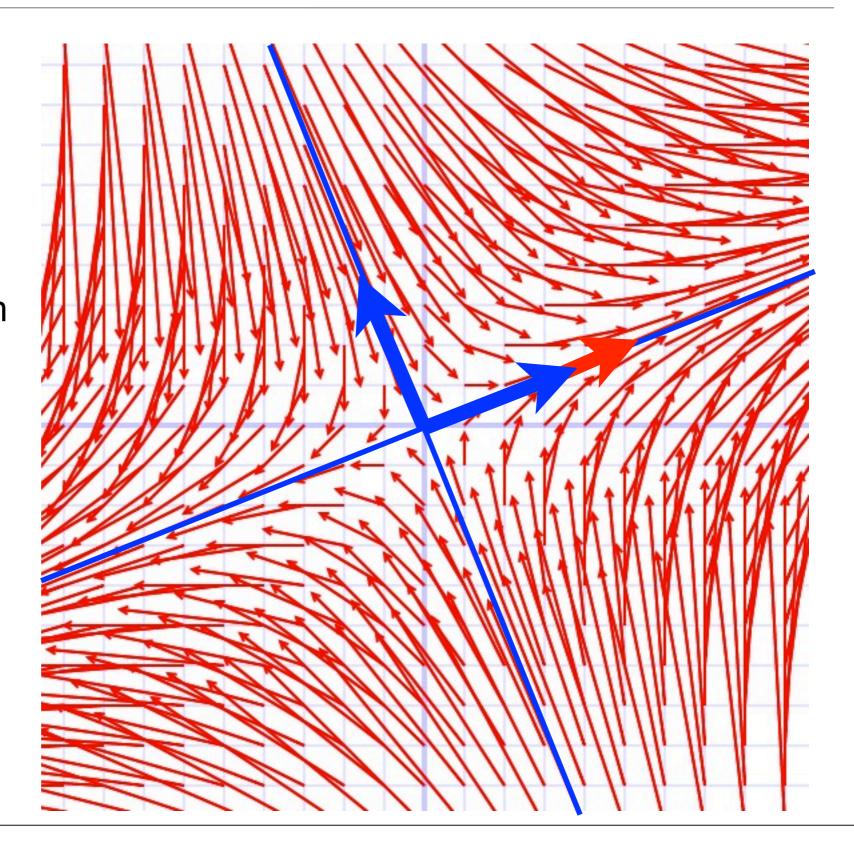
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$$\lambda_1 = \sqrt{2}$$

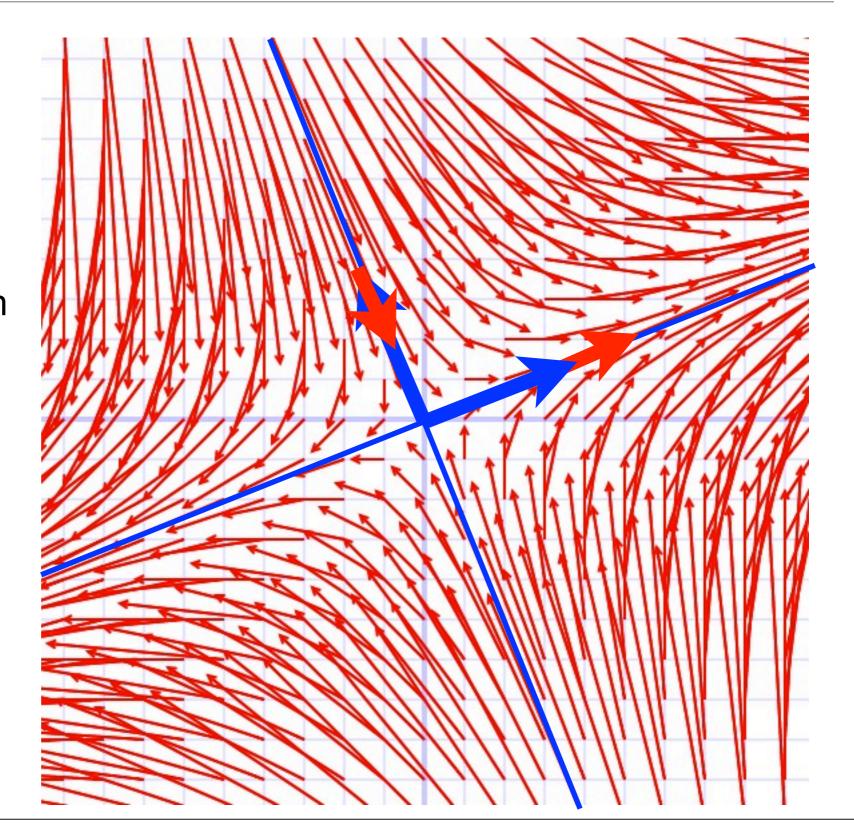
$$\mathbf{v_1} = \begin{pmatrix} 1\\ \sqrt{2} - 1 \end{pmatrix}$$



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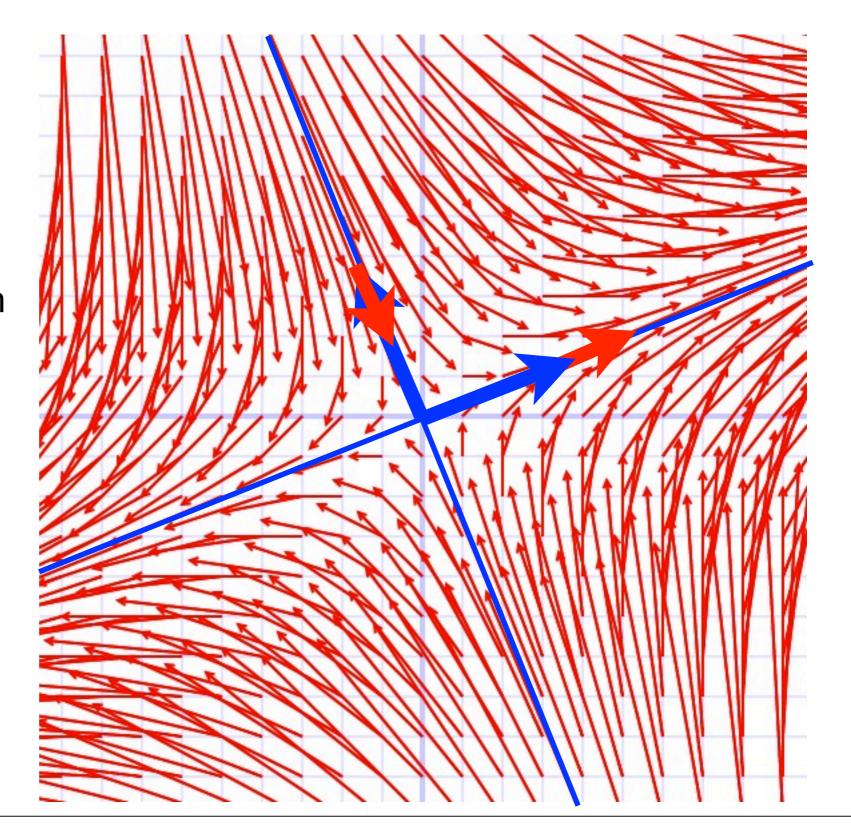
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$$\lambda_2 = -\sqrt{2}$$

$$\mathbf{v_2} = \begin{pmatrix} 1 - \sqrt{2} \\ 1 \end{pmatrix}$$



ullet Find eigenvalues and eigenvectors of $A=egin{pmatrix} 1 & 1 \ 4 & 1 \end{pmatrix}$.

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- What are the eigenvalues of A?
 - (A) 1 and -3
 - (B) -1 and 3
 - (C) 1 and 3
 - (D) -1 and -3
 - (E) Explain, please.

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$$A\mathbf{v} - \lambda \mathbf{v} = \mathbf{0}$$

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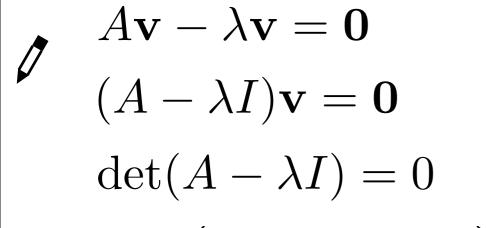
$$(A - \lambda I)\mathbf{v} = \mathbf{0}$$

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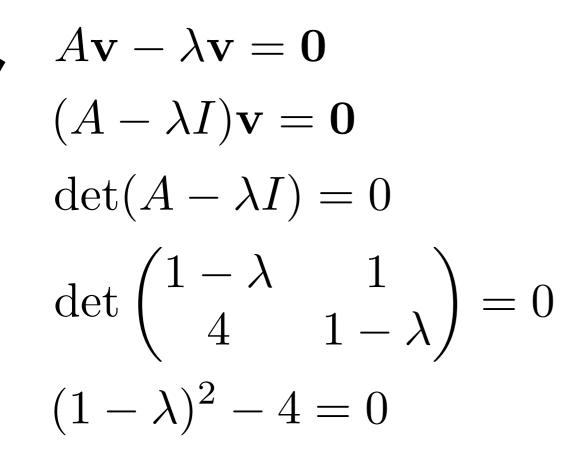
$$A\mathbf{v} - \lambda \mathbf{v} = \mathbf{0}$$
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$$\det(A - \lambda I) = 0$$

- Find eigenvalues and eigenvectors of $A = \begin{pmatrix} 1 & 1 \\ 4 & 1 \end{pmatrix}$.
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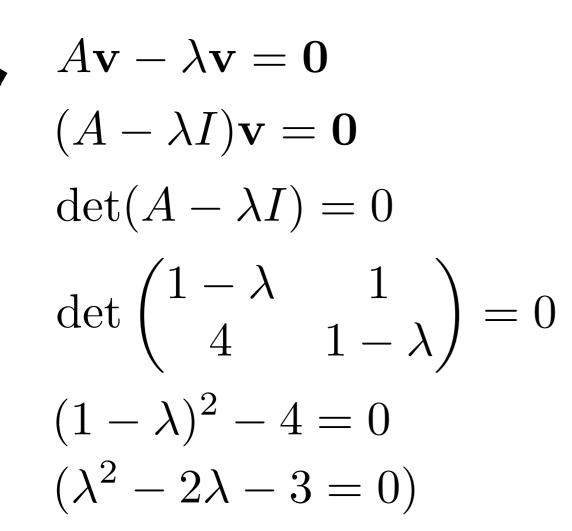


$$\det\begin{pmatrix} 1-\lambda & 1\\ 4 & 1-\lambda \end{pmatrix} = 0$$

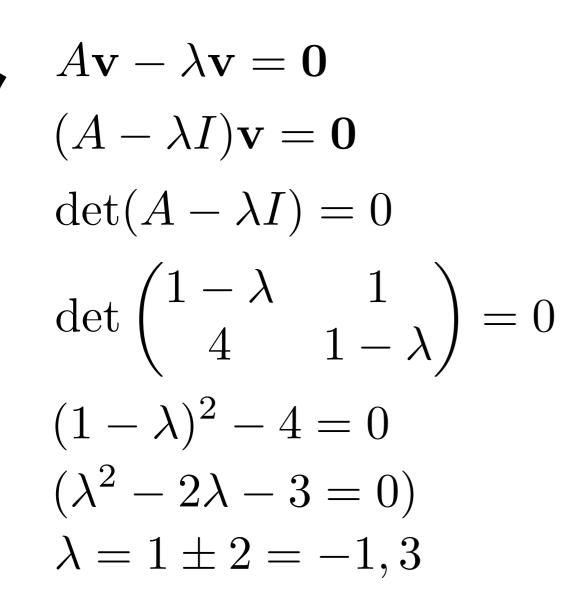
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$$(A - \lambda I)\mathbf{v} = \mathbf{0}$$

$$\det(A - \lambda I) = 0$$

$$\det\begin{pmatrix} 1 - \lambda & 1 \\ 4 & 1 - \lambda \end{pmatrix} = 0$$

$$(A) \quad \mathbf{v_1} = \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

$$(B) \quad \mathbf{v_1} = c \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

$$(C) \quad \mathbf{v_1} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$\lambda = 1 \pm 2 = -1, 3$$

 What are the eigenvectors associated with λ_1 =-1?

(A)
$$\mathbf{v_1} = \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

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$$\det(A - \lambda I) = 0$$

$$\det\begin{pmatrix} 1 - \lambda & 1 \\ 4 & 1 - \lambda \end{pmatrix} = 0 \quad \text{(B)} \quad \mathbf{v_1} = c \begin{pmatrix} 1 \\ -2 \end{pmatrix}$$

$$(1 - \lambda)^2 - 4 = 0$$

 $(\lambda^2 - 2\lambda - 3 = 0)$
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(and any scalar multiple of it)

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 How do we use eigenvalues and eigenvectors to construct a general solution?

• The following is a shortcut approach for 2x2 systems, mostly for insight.

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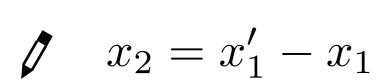


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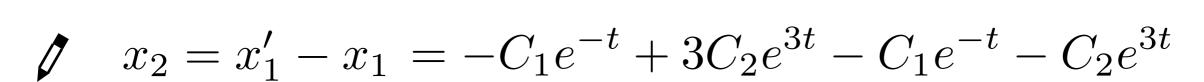


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- Find the general solution to the system of equations

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- Other cases (not enough e-vectors or complex e-values) Thursday.